

# E9 222 Signal Processing in Practice

## Assignment 5

February 11, 2026

Dwaipayan Haldar

### 1. Experiment 1 – Low Pass Gaussian Filter

#### (a) Optimal Gaussian filter for each noisy image

**Ans:** For each noisy image (except `img167.bmp`, used as the reference), a Gaussian filter of size  $11 \times 11$  was applied with  $\sigma \in \{0.1, 1, 2, 4, 8\}$ . The optimal  $\sigma$  was selected as the one minimizing the MSE with respect to the reference image `img167.bmp`.

Image	File	Best $\sigma$	MSE (before)	MSE (after)
Image 1	img125.bmp	0.1	24.77	24.77
Image 2	img6.bmp	0.1	79.70	79.70
Image 3	img108.bmp	1	919.07	185.04
Image 4	img32.bmp	1	1638.51	248.24
Image 5	img137.bmp	8	15423.49	1651.68

Table 1: Optimal Gaussian filter parameters for each noisy image (sorted by increasing noise level). MSE is computed w.r.t. the reference image `img167.bmp`.

Figures 1–5 show the noisy images alongside their denoised versions using the best Gaussian filter.



Figure 1: Image 1 (img125.bmp): Very low noise. Best  $\sigma = 0.1$  (near identity filter). The image is already close to the reference, so minimal smoothing is optimal.



Figure 2: Image 2 (img6.bmp): Low noise. Best  $\sigma = 0.1$ . Slight noise present but still best handled with minimal filtering.



Figure 3: Image 3 (img108.bmp): Moderate noise. Best  $\sigma = 1$ . Visible noise requires moderate smoothing.



Figure 4: Image 4 (`img32.bmp`): Moderate–high noise. Best  $\sigma = 1$ . Heavier noise but the same  $\sigma$  as Image 3 is optimal.

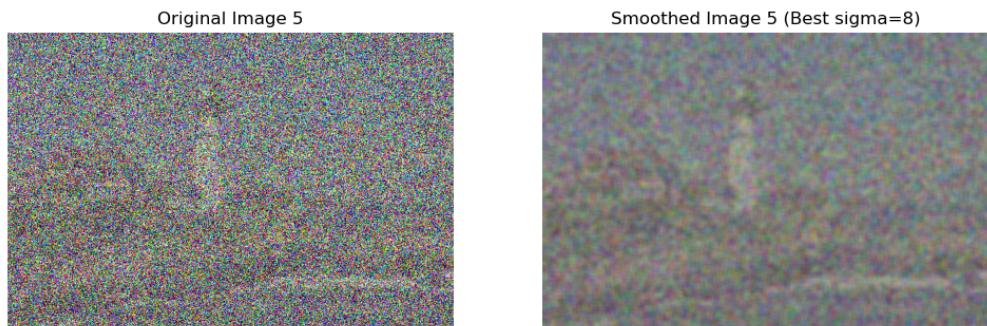


Figure 5: Image 5 (`img137.bmp`): Very high noise. Best  $\sigma = 8$ . The image is severely corrupted, requiring aggressive smoothing.

### (b) Curve: Image index vs optimal $\sigma$

**Ans:** Figure 6 plots the optimal  $\sigma$  against the image index (sorted by increasing noise level).

#### Observations:

- The optimal  $\sigma$  increases monotonically with the noise level of the image. As the noise corruption becomes more severe, the Gaussian filter requires a larger standard deviation (wider spatial support) to suppress the noise effectively.
- For the least noisy images (Images 1 and 2),  $\sigma = 0.1$  is optimal, meaning the filter acts nearly as an identity—preserving image details since there is little noise to remove.

- For the moderately noisy images (Images 3 and 4),  $\sigma = 1$  provides the best trade-off between noise removal and detail preservation.
- For the most corrupted image (Image 5),  $\sigma = 8$  is needed, resulting in heavy blurring. While this removes most noise, it also sacrifices fine image details—highlighting the fundamental limitation of Gaussian filtering, which cannot distinguish between noise and signal.
- The curve shows a generally increasing trend, confirming that **higher noise levels demand stronger (wider) Gaussian smoothing** for optimal MSE performance.

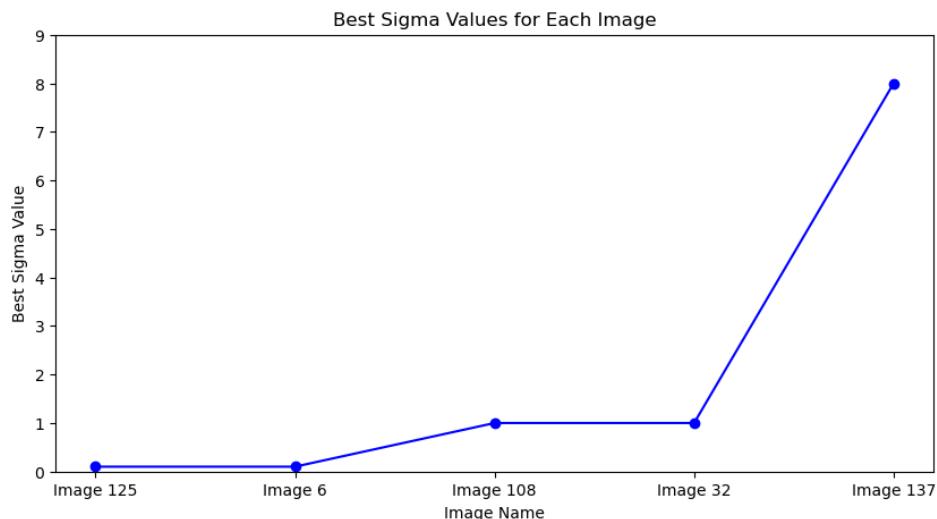


Figure 6: Optimal Gaussian  $\sigma$  vs image index (sorted by increasing noise level). The trend is monotonically increasing: noisier images require larger  $\sigma$  for best MSE.

## 2. Experiment 2 – Bilateral Filter

**Ans:** The bilateral filter was applied to `noisybook.png` with parameters: filter size  $k = 11$ , spatial  $\sigma_s = 1.5$ , and range  $\sigma_I = 0.1$ . A Gaussian filter with  $k = 11, \sigma = 1.5$  (matching the bilateral filter's spatial parameter) was used for comparison. The Gaussian  $\sigma$  was varied and  $\sigma = 1.5$  was selected as it gave a visually comparable level of denoising. Figure 7 shows the results.

**Observations:**

- Both filters successfully reduce the Gaussian noise present in the original noisy image.
- The **bilateral filter preserves edges significantly better** than the Gaussian filter. The text edges in the book cover (“Digital Image Processing”) remain sharp and well-defined after bilateral filtering, whereas the Gaussian filter blurs them noticeably.

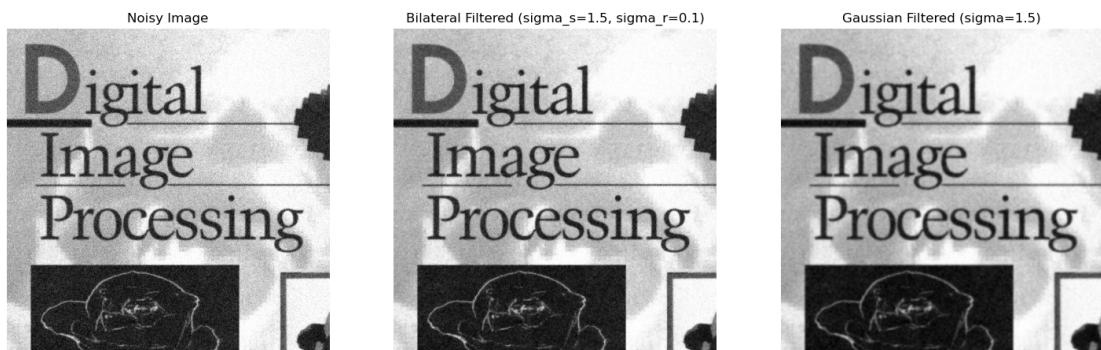


Figure 7: Comparison of bilateral and Gaussian filtering on `noisybook.png`. Left: noisy input. Center: bilateral filtered ( $\sigma_s = 1.5$ ,  $\sigma_r = 0.1$ ). Right: Gaussian filtered ( $\sigma = 1.5$ ). The bilateral filter preserves text edges while the Gaussian filter blurs them.