

CS 112 – Introduction to Computing II

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Today:

Efficiency of binary trees;
Balanced Trees
2-3 Trees

Next Time:

2-3 Trees continued
B-Trees and External Search



Efficiency of Binary Search Trees

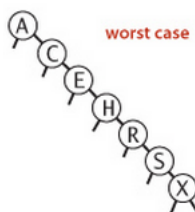


So far, we have seen that the best case for a BST is a perfect triangle, and the worst case is a linked list:

best case

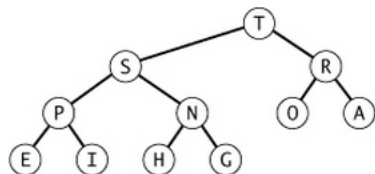


worst case



Of course it may not be possible to get a

perfect triangle, but we can always create a tree in which the leaves are always within two levels of each other:



Best case: $\Theta(\log N)$

Worst case: $\Theta(N)$

What happens on average?

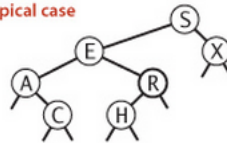
Efficiency of Binary Search Trees



What happens on average? You are doing this as part of Lab 08: The scenario would be modeled on our experiments with average case for sorting:

- Create 1000 **random BSTs** for each size $N = 1, 2, 3, 4, \dots, 100$ (or similar parameters) by creating a random array of size N and then inserting each key into an initially-empty tree;
- Find the **average cost of lookups** in each tree (sum of cost of each node / N);
- This simulates a situation where a random BST is created, then we repeatedly lookup keys (we could alternately do a random series of inserts, lookups, and deletes on a single tree and see what happens – results are similar).

typical case



Cost of paths:

S: 1, E,X: 2, A,R: 3,
C,H: 4

Sum: 19

Average Cost: $19/7 = 2.71$

Your results for Lab 08 should show a “good result” for the average case! ☺

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Balanced BSTs



The next question is always: Can we do better?

Specifically, can we find a way to eliminate the worst case trees, and get **$O(\log N)$** for all operations?

This amounts to the following problem: **Can we restructure the tree during inserts and deletes to prevent imbalanced trees?**

The answer, of course, is YES, and one solution to creating balanced trees is called 2-3 Trees....

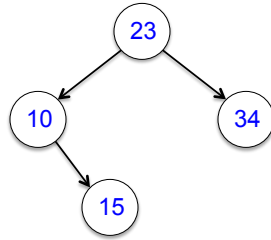
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2-3 Trees

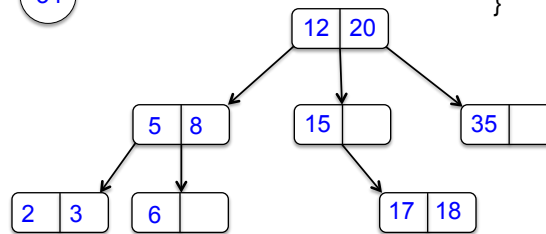


2-3 Trees generalize binary search trees by allowing "wider" nodes that can contain 1 or 2 keys, and 2 or 3 pointers:

Binary Search Tree:



2-3 Tree:



```

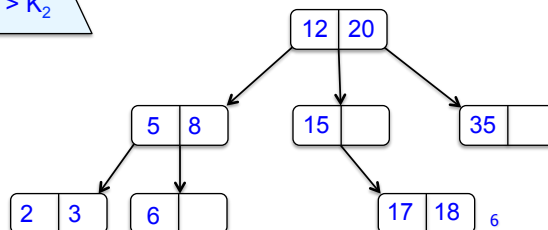
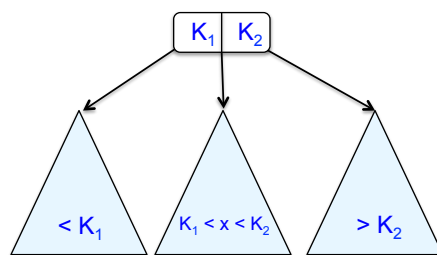
class Node {
    int K1, K2;
    Node left;
    Node mid;
    Node right;
}
  
```

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2-3 Trees



Generalizing the basic idea of binary search trees, we have "trinary search trees" where the two keys divide up the descendent nodes into three instead of two subtrees:

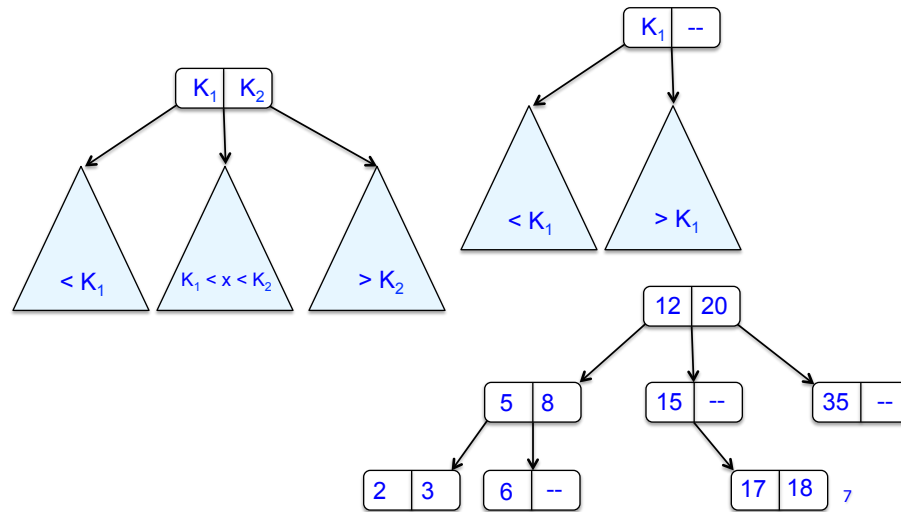


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2-3 Trees



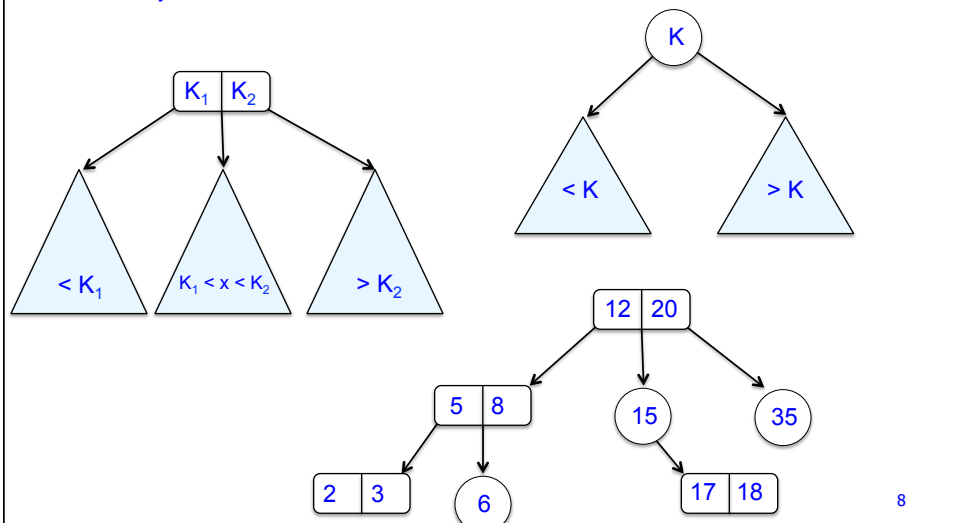
But we may consider normal BST nodes (1 key, 2 pointers) to be a special case, where the second key does not exist:



2-3 Trees



But we may consider normal BST nodes (1 key, 2 pointers) to be a special case, where the second key does not exist, and we will draw these as we would with normal BSTs:

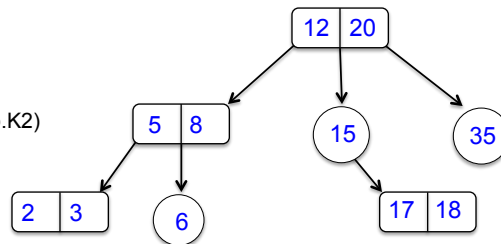


2-3 Trees



Searching such a tree is a simple generalization of search in BSTs: at each node you scan from the left through the two keys and figure out where the search key k might be:

```
boolean member(int k, Node p) {
    if(p == null)
        return false;
    else if(k < p.K1)
        return find(k, p.left);
    else if(k == p.K1)
        return true;
    else if(p.K2 does not exist || k < p.K2)
        return find(k, p.mid);
    else if(k == K2)
        return true;
    else
        return find(k, p.right);
}
```



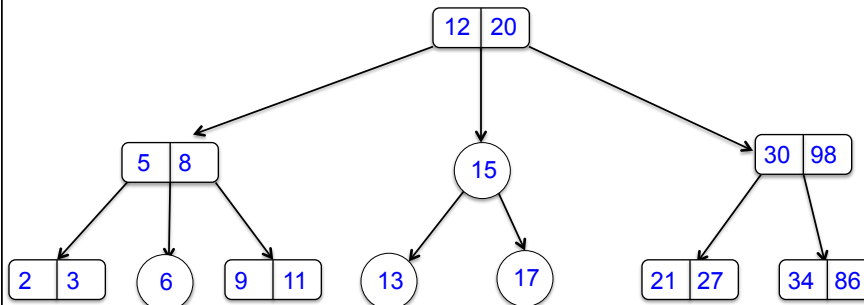
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2-3 Trees



Insertion into a 2-3 tree is a little bit complicated, because we will want to maintain the trees in balanced form (perfect triangles):

A 2-3 tree is **balanced** if every path from the root to a leaf node has the same length; note that nodes may contain 2 keys and 3 pointers, or 1 key and 2 pointers:



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2-3 Trees

**Rules for inserting a new key into a 2-3 tree:**

1. As with BSTs, you search for the key; if you find it, do nothing (don't insert duplicates); if you don't find it, then insert into the leaf node that you last looked in. If there is room, you are done.

Example: Let's insert a 12 into an empty tree; when you insert into an empty tree, you create a new node and insert into the K_1 slot:



2-3 Trees

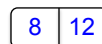
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Example: Let's insert a 12 into an empty tree; when you insert into an empty tree, you create a new node and insert into the K_1 slot:



Now let's insert an 8, which can fit into the node if we move the 12 over:



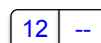
2-3 Trees



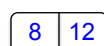
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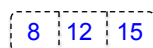
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Next let's insert a 15, which expands the node into an *error node* containing too many keys:



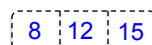
2-3 Trees



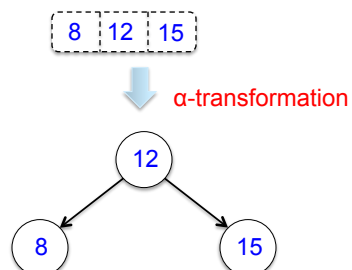
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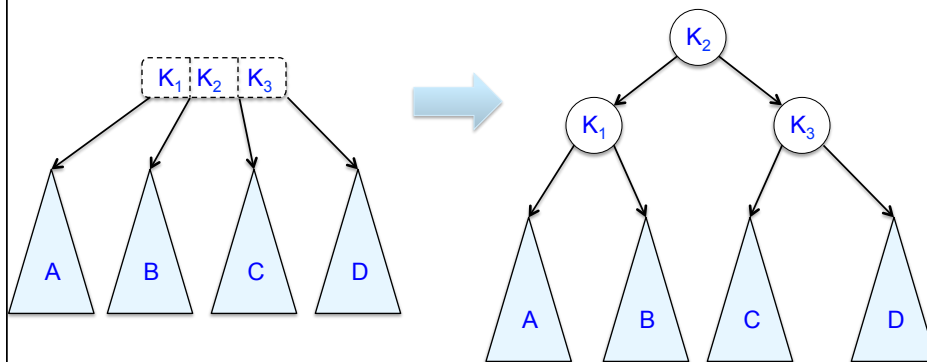
Immediately fix this error by transforming this node into a balanced three-node tree:



2-3 Trees



α -transformation:



The subtrees A – D may be null!

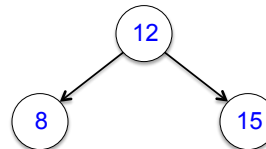
2-3 Trees



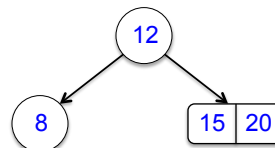
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Immediately fix this error by transforming this node into a balanced three-node tree:



Next let's insert a 20, which expands the right-most leaf node:

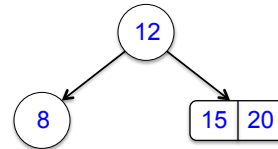


2-3 Trees

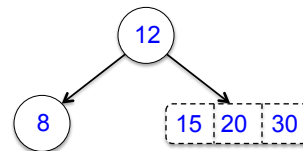

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Next let's insert a 20, which expands the right-most leaf node:



Then let's insert a 30, which creates another error node:

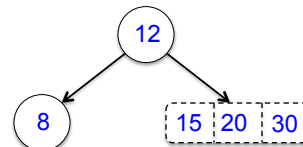


2-3 Trees

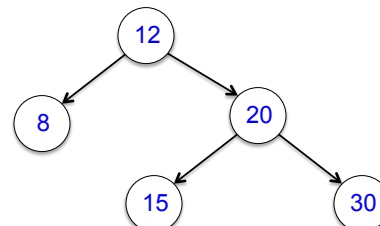

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But we immediately fix the error by using the α -transformation:

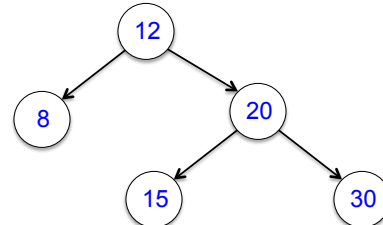


2-3 Trees

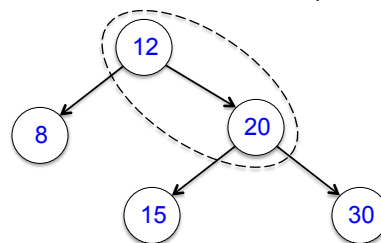
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3. After applying the α -transformation, if there is a parent node, then we must apply the β -transformation to fix the imbalance created by the α -transformation.

But we immediately fix the error by using the α -transformation:



But this is imbalanced, so we will combine the root of the new subtree with the parent node:

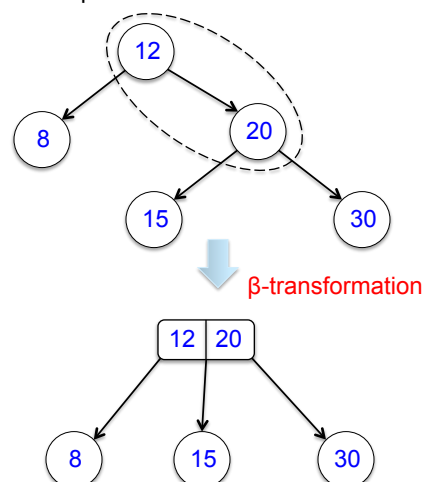


2-3 Trees

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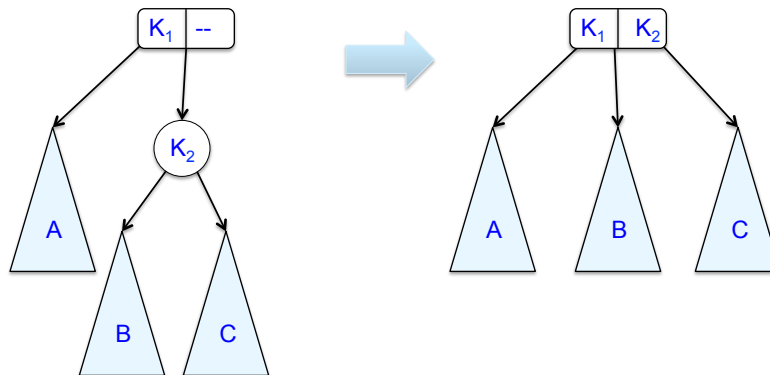
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2-3 Trees



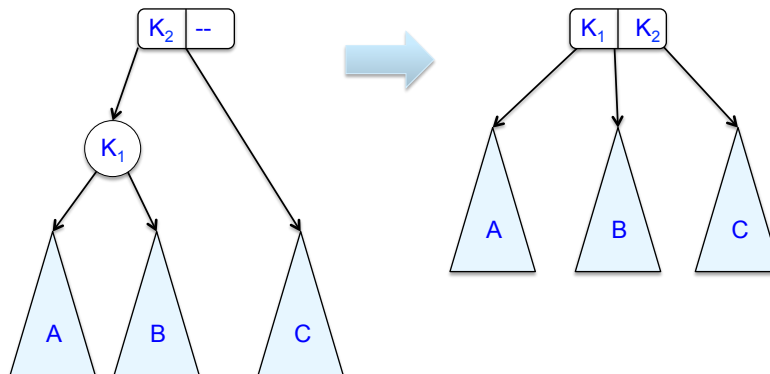
β -transformation(s): If the parent has only 1 key, then insert the root into the parent node and distribute the subtrees accordingly:



2-3 Trees



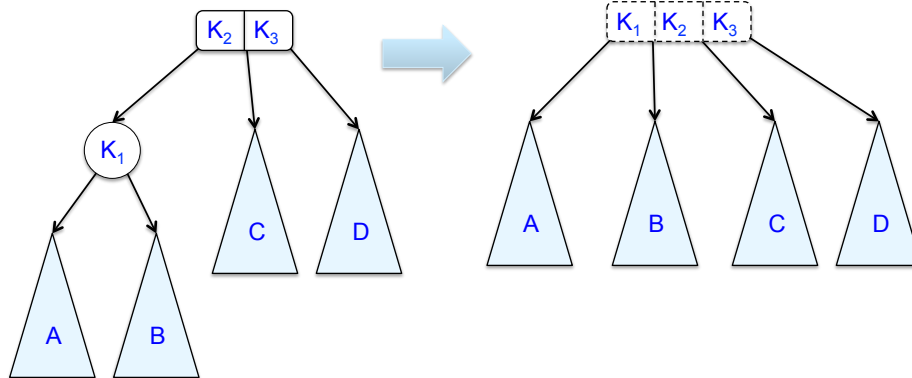
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2-3 Trees



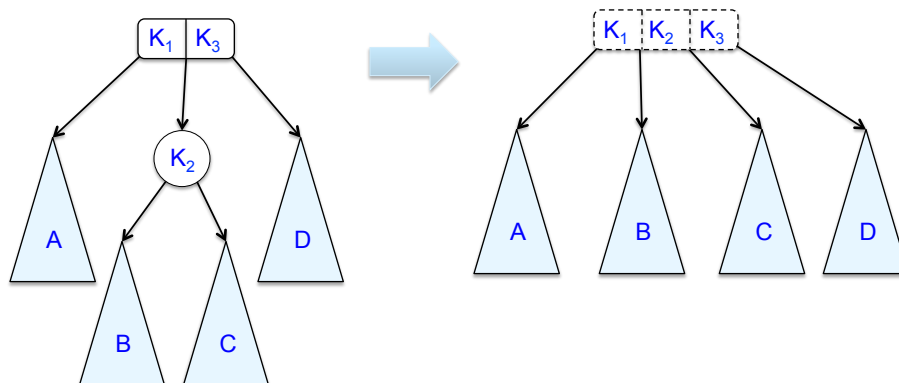
β -transformation(s): If the parent has 2 keys, then create an error node and repeat the α -transformation (you may have to continue apply α - and β -transformations up the tree):



2-3 Trees



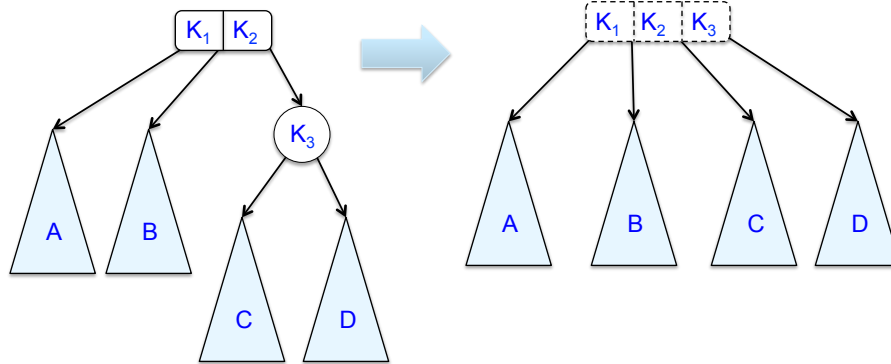
β -transformation(s): If the parent has 2 keys, then create an error node and go back to the α -transformation (you may have to continue apply α - and β -transformations up the tree):



2-3 Trees



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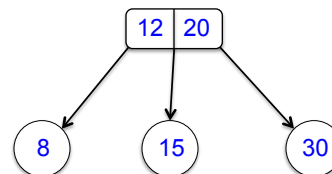
2-3 Trees



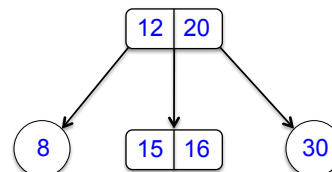
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3. After applying the α -transformation, if there is a parent node, then we must apply the β -transformation to fix the imbalance created by the α -transformation.
4. You may have to continue a series of α - and β -transformations moving up the path to the root, until a balanced tree with no error nodes is obtained.

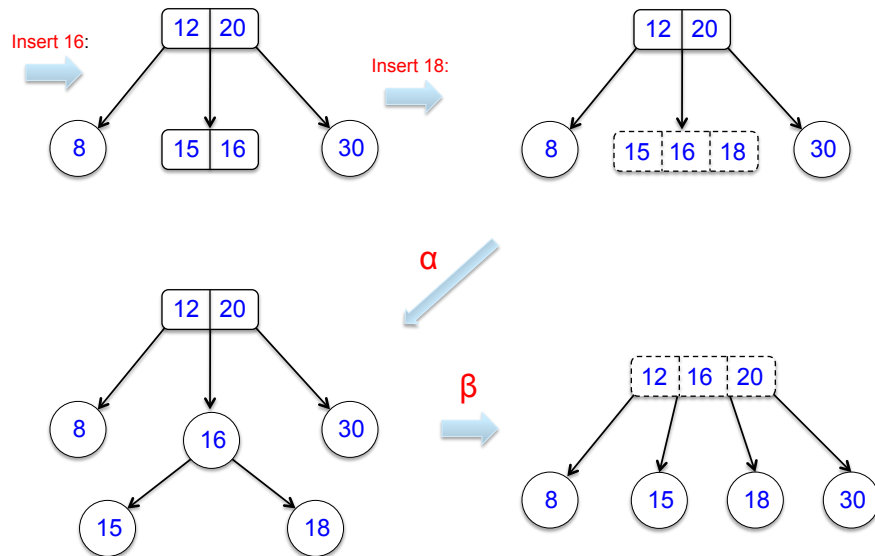
Let's continue with our example....



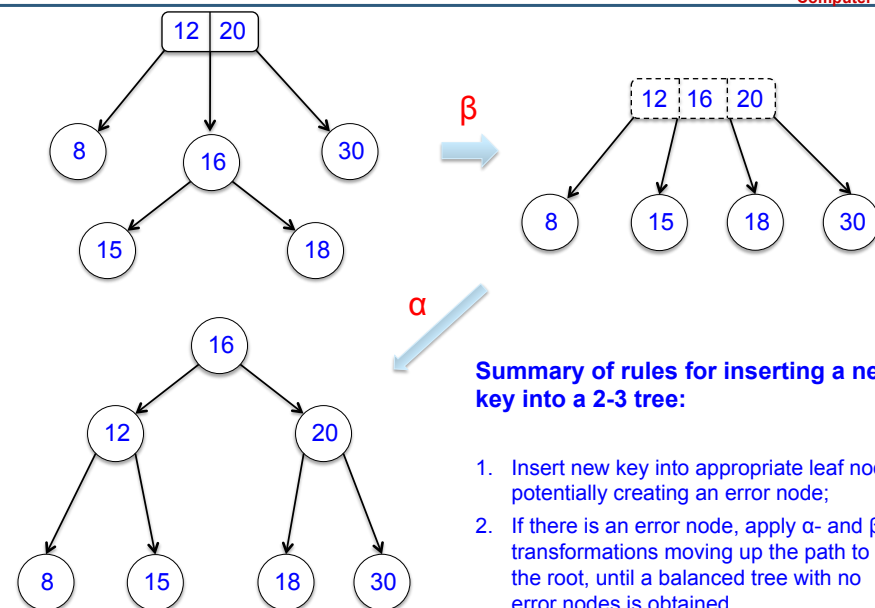
Insert a 16 into the tree:



2-3 Trees



2-3 Trees

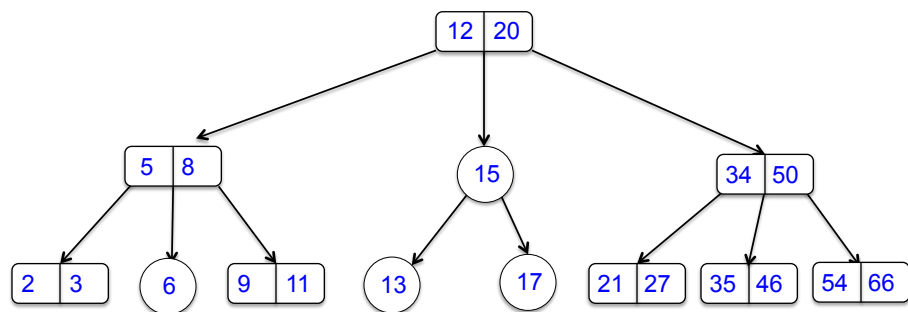


2-3 Trees


Worst-Case Time Complexity of 2-3 Trees (counting the number of comparisons): Member(...)

Consider the following tree:

- What is the cost (# of comparisons) for finding 2?
- How about 27?
- Which keys represent the worst case for this tree?

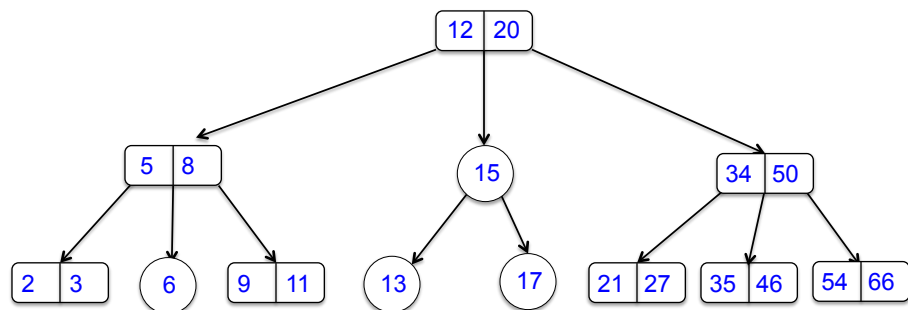


2-3 Trees


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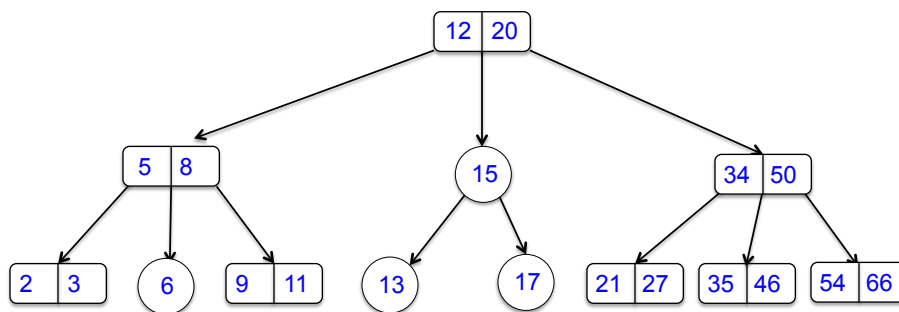
- What is the cost (# of comparisons) for finding 2? 3
- How about 27? 5
- Which keys represent the worst case for this tree? 46 or 66, with 6 comparisons



2-3 Trees


Worst-Case Time Complexity of 2-3 Trees (counting the number of comparisons): Member(...)

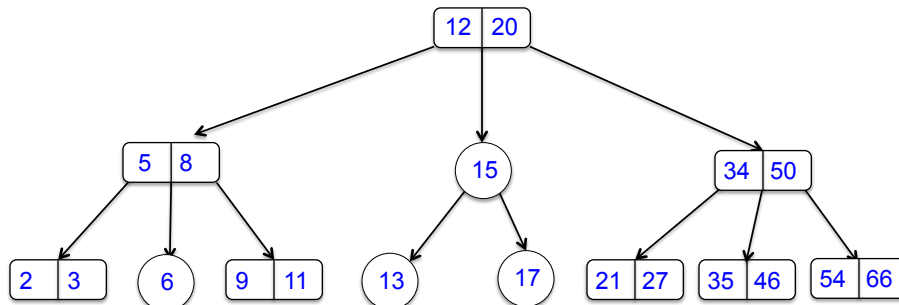
The worst-case for member(...) is to go all the way to a leaf node, and do 2 comparisons at each node; in a balanced tree with N keys, the height is $\Theta(\log N)$, i.e., $C * \log N + \dots$ for some constant C , but if we have to do 2 comparisons at each node, this becomes $2 * C * \log N + \dots$ which is still $\Theta(\log N)$ comparisons.



2-3 Trees


Worst-Case Time Complexity of 2-3 Trees (counting the number of comparisons): Insert(...)

For insert(...), the worst thing that can happen is that you insert the new key at the bottom of the tree, and it causes α - and β -transformations all the way back up the tree. Each transformation takes a constant C amount of work, so the cost is $\Theta(\log N)$ to find the location (as in member(...)), and $C * \Theta(\log N)$ transform the tree back up to the root. $(1 + C) * \Theta(\log N)$ is still $\Theta(\log N)$.



2-3 Trees

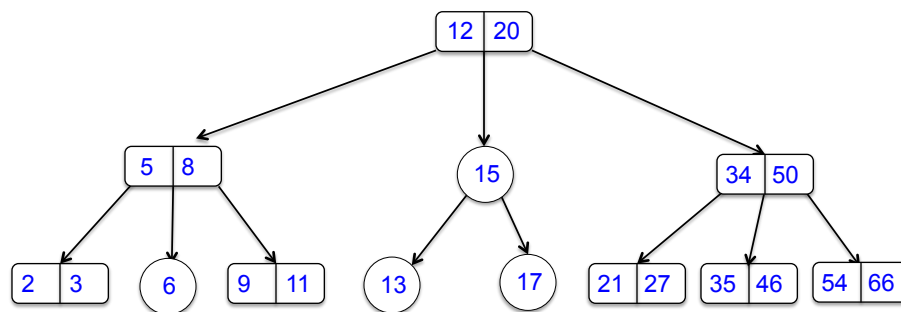


Worst-Case Time Complexity of 2-3 Trees (counting the number of comparisons):

Member(...): $\Theta(\log N)$

Delete(...): $\Theta(\log N)$ (not described)

Insert(...): $\Theta(\log N)$



2-3 Trees



Code Complexity: 2-3 Trees are generally encoded as normal BSTs with two different colored links ("Red-Black Trees"), and the code for insert is not as complicated as you would imagine:

```
private static Node insert(int key, Node t) {
    if (t == null)
        return new Node(key);
    else if (key < t.key) {
        t.left = insert(key, t.left);
        return applyTransformations(t);
    } else if (key > t.key) {
        t.right = insert(key, t.right);
        return applyTransformations(t);
    } else
        return t;
}

private static Node leanRight( Node t ) {
    Node newRoot = t.left;
    t.left = newRoot.right;
    newRoot.right = t;
    newRoot.red = t.red;
    t.red = true;
    return newRoot;
}

private static Node rotateLeft( Node t ) {
    Node newRoot = t.right;
    t.right = t.right.left;
    newRoot.left = t;
    newRoot.red = true;
    newRoot.left.red = false;
    newRoot.right.red = false;
    return newRoot;
}

private static Node applyTransformations( Node t ) {
    if(t == null)
        return null;
    if(t.left != null && t.left.red)
        t = leanRight( t );
    if( t.right != null && t.right.red
        && t.right.right != null && t.right.right.red)
        t = rotateLeft( t );
    return t;
}
```