## Derivation Rules in Fialyzer

### fialyzer developers

This file shows derivation rules used in fialyzer.

Our derivation rules are almost same as the original success typings paper\*1's one, but extended by remote call, local call, list, etc.

#### 1. Derivation Rules

Here are the BNFs used in the derivation rules:

```
e ::= v \mid x \mid fn \mid \{e, \dots, e\} \mid \mathtt{let} \ x = e \ \mathtt{in} \ e \mid \mathtt{letrec} \ x = fn, \dots, x = fn \ \mathtt{in} \ e
         \mid e(e, \dots, e) \mid case e of pg \rightarrow e; \dots; pg \rightarrow e end \mid fun f/a \mid [e \mid e] \mid [] \mid fun m: f/a
         | \#\{e \Rightarrow e, \dots, e \Rightarrow e\} | e \#\{e \Rightarrow e, \dots, e \Rightarrow e, e := e, \dots, e := e\} (term)
          0 | 'ok' | ... (constant)
v ::=
x ::= (snip) (variable)
fn ::= fun(x, \dots, x) \to e (function)
pg ::= p \text{ when } g; \dots; g \text{ (pattern with guard sequence)}
         v \mid x \mid \{p, \dots, p\} \mid [p \mid p] \mid [] \mid \#\{e := p, \dots, e := p\}
          v \mid x \mid \{e, \dots, e\} \mid [e \mid e] \mid [] \mid e(e, \dots, e) (guard)
m := e \pmod{\text{module name. a term to be an atom}}
f := e (function name. a term to be an atom)
a := e (arity. a term to be a non_neg_integer)
          none() | any() | \alpha | \{\tau, \dots, \tau\} | (\tau, \dots, \tau) \rightarrow \tau | \tau \cup \tau
         | integer() | atom() | 42 | 'ok' | ... (type)
\alpha, \beta ::= (snip) (type variable)
C ::= (\tau \subseteq \tau) \mid (C \land \cdots \land C) \mid (C \lor \cdots \lor C) \quad (constraint)
A ::= A \cup A \mid \{x \mapsto \tau, \dots, x \mapsto \tau\} (context. mapping of variable to type)
```

Here are the derivation rules:

$$\frac{1}{A \cup \{x \mapsto \tau\} \vdash x : \tau, \emptyset} (VAR)$$

<sup>1</sup> T. Lindahl and K. Sagonas. Practical Type Inference Based on Success Typings. In *Proceedings of the 8th ACM SIGPLAN International Conference on Principles and Practice of Declarative Programming*, pages 167–178. ACM, 2006.

# 1.1. Differences from the original paper

 $\frac{A \vdash e : \tau, C}{A \vdash e \# \{\cdots\} : \mathtt{map}(), (\tau \subseteq \mathtt{map}()) \land C} (\mathtt{MAPUPDATE})$ 

The differences from the derivation rules on the original paper are as follows.

- $\alpha$ ,  $\beta$ , and  $\tau$  are clearly distinguished.  $\tau$  is a type, and  $\alpha$ ,  $\beta$  are type variables.
- LET is fixed:  $e_2$ , not e.
- ABS is modified:  $\tau$  and constrained function are omitted.
- PAT is modified: type of g is boolean(), not true.
- CASE is fixed:  $\tau$ , not  $\tau_i$ . replaced  $p_1\cdots p_n$  with  $pg_1\cdots pg_n$  because these are patterns with guards.
- LOCALFUN is added.
- MFA is added.
- MFAEXPR is added.
- MAPCREATION is added (temporary definition).
- MAPUPDATE is added (temporary definition).
- ...and some variables are  $\alpha$ -converted for understandability.

#### 1.2. Notes

- In  $A \vdash p : \tau, C_p$  of PAT rule, p is not an expression but a pattern. Therefore, we have to convert p to an expression which is the same form of p.
  - This is not described in the original paper.