# 4. ARIMA forecasting

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Description: Demonstration of time series stationarization with Box-Cox transformation and ARIMA time series forecasting. (Inspired on a DataCamp course, own notes and solutions.)

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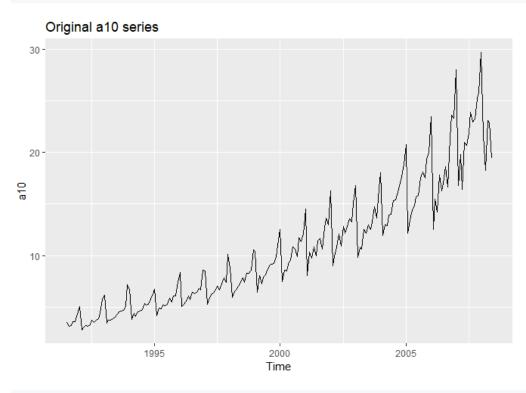
Reference: Guerrero, V.M. (1993) Time-series analysis supported by power transformations. Journal of Forecasting, 12, 37-48.

### **Box-Cox transformations**

Some forecasting methods, like exponential smoothing account for non-stationarity in time series using equations for trend and seasonality. However, generally speaking forecasting works best with stationary time series. There can be different levels of stationarity, but stationarity often involves a more-or-less constant mean and variance over the duration of the time series. Box-Cox transformations can help stabilize a time series by reducing the non-stationarity, which we will do below for a series of monthly anti-diabetic drug sales in Australia from 1991 to 2008.

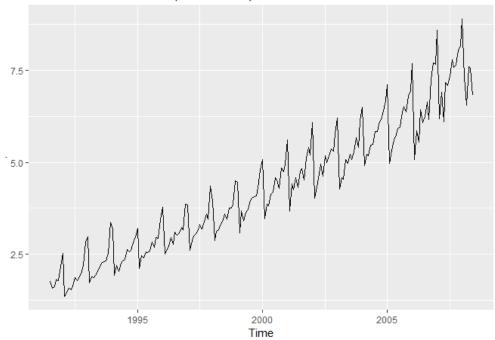
```
# Load package
library(fpp2)

# Plot the series
autoplot(a10) +
    ggtitle("Original a10 series")
```



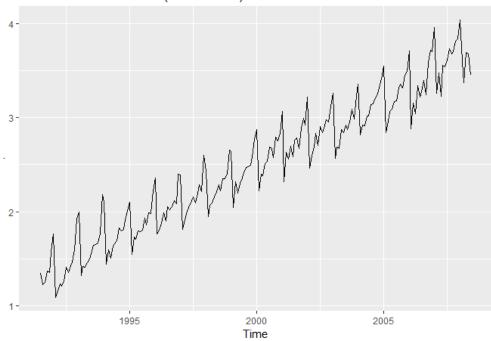
```
# Four values of lambda in Box-Cox
a10 %>% BoxCox(lambda = 0.5) %>% autoplot() + ggtitle("Box-Cox transformation (lamba = 0.5)")
```

### Box-Cox transformation (lamba = 0.5)

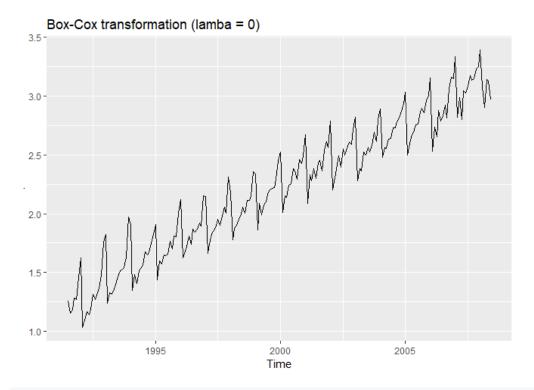


a10 %>% BoxCox(lambda = 0.1) %>% autoplot() + ggtitle("Box-Cox transformation (lamba = 0.2)")

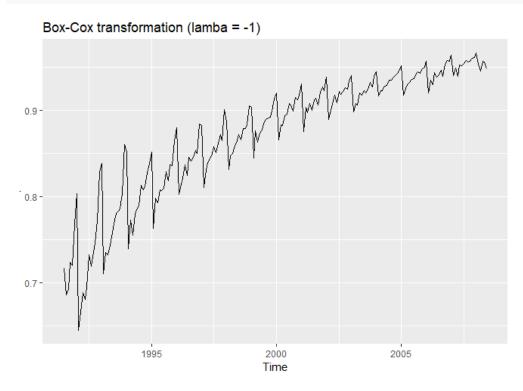
### Box-Cox transformation (lamba = 0.2)



a10 %>% BoxCox(lambda = 0) %>% autoplot() + ggtitle("Box-Cox transformation (lamba = 0)")







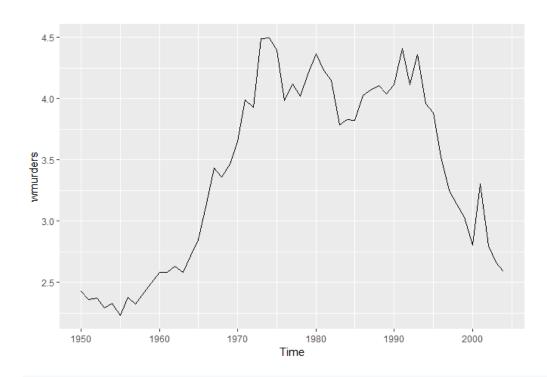
In the original series (above), the amplitude of variations around the rising trend increases with time. Or, in terms of stationarity, the variance increases with time. A Box-Cox transformation with lamba = 0.5 stabilizes the variance somewhat, but the variance still increases toward the end of the series. A Box-Cox transformation with lamba = -1 attains the opposite effect. The amplitude at the beginning of the series is now greater than at the end. Lamba = 0.2 gives a good result, but improvement is still possible.

We can use Guerrero's (1993) method to automatically select the Box-Cox transformation parameter resulting in the smallest coefficient of variation of the transformed series.

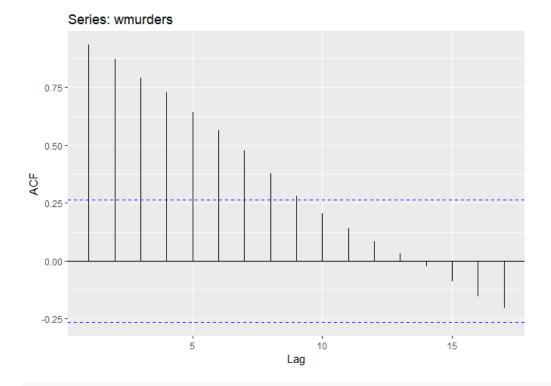
## [1] 0.1313326

# Non-seasonal differencing for stationarity

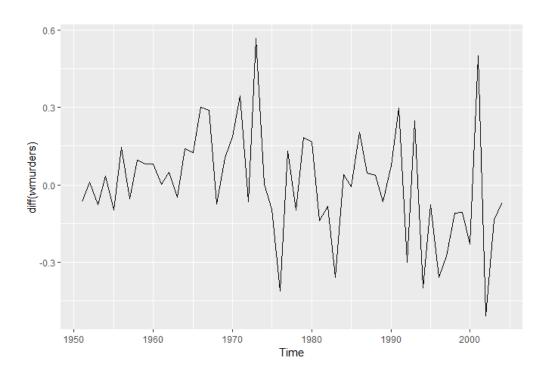
# Plot US female murder rate
autoplot(wmurders)



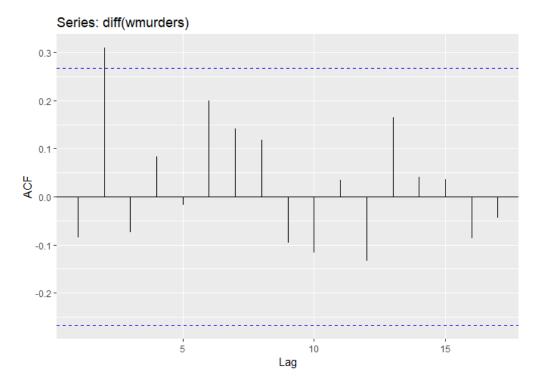
# Plot ACF
ggAcf(wmurders)



# Plot differenced murder rate
autoplot(diff(wmurders))



# Plot ACF of differenced murder rate
ggAcf(diff(wmurders))



This time series has no significant seasonality but a strong autocorrelation for shorter lags (above). Lag-1 differencing yields a more stable series that is by approximation stationary. However, the ACF of the differenced series does not look like that of white noise because some values exceed the range marked by the blue lines. Some amount of autocorrelation remains for short lags.

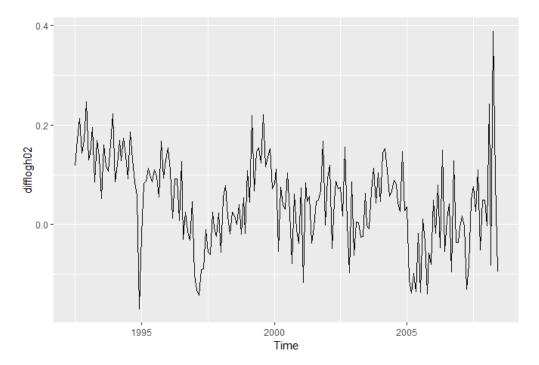
### Seasonal differencing for stationarity

The Box-Cox transformation was useful in stabilizing the level of seasonality, improving the stationarity of variance. However, this does not deal with intracycle variations in level associated with seasonality. Now we will use the time series of monthly corticosteroid drug sales in Australia from July 1991 to June 2008, and apply seasonal differencing to remove the non-stationarity associated with seasonality.

```
# Plot h02 data
autoplot(h02) +
  ggtitle("Original h02 series")
```

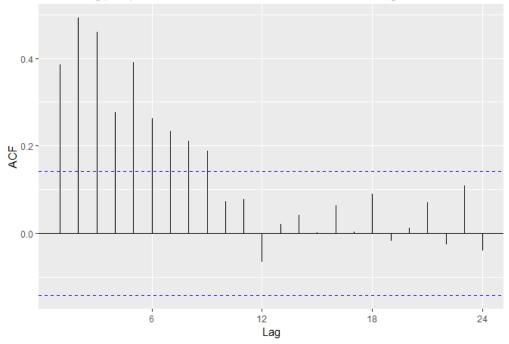
# Original h02 series 1.25 1.00 2005 Time

```
# Take logs and seasonal differences of h02
difflogh02 <- diff(log(h02), lag = 12)
# Plot difflogh02
autoplot(difflogh02)</pre>
```



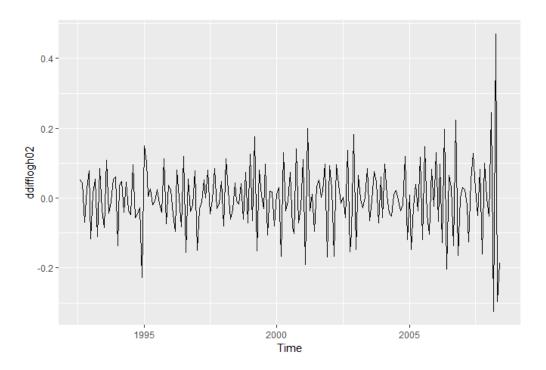
```
# Plot ACF
ggAcf(difflogh02) +
ggtitle("ACF of log(h02) series after 12-month seasonal differencing")
```

### ACF of log(h02) series after 12-month seasonal differencing



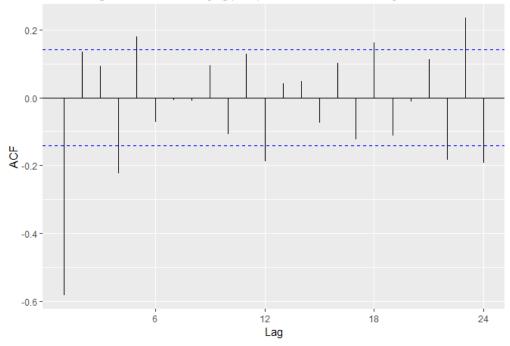
Seasonal differencing of the log-transformed series removed the annual seasonality. This is illustrated by the ACF (above) where the autocorrelation for the 12-month lag is no longer significant. Next, we can improve the non-seasonal stability by taking the lag-1 differences of the seasonally differenced log-transformed series that we created (below).

```
# Take lag-1 difference
ddifflogh02 <- diff(difflogh02, lag = 1)
autoplot(ddifflogh02)</pre>
```



```
# Plot ACF
ggAcf(ddifflogh02) +
   ggtitle("ACF of lag-1 differences of [log(h02) 12-month differenced]")
```





After log-transformation, 12-month seasonal differencing, and lag-1 differencing of the series, autocorrelation has disappeared for most lags (above). The resulting series is more stable now that we have rendered it approximately stationary. However, as in the case for the non-seasonal differencing example, the residuals do not look like white noise. In fact, there is still significant autocorrelation for shorter lags that could not be rendered stationary with seasonal differencing. This is a job for ARIMA (autoregressive integrated moving average) models.

### **ARIMA** models

Autoregressive Integrated Moving Average (ARIMA) models use the lag and shift of in time series data to predict future patterns. The model was first proposed in 1976 and has gained popularity in economic forecasting and short-term business performance forecasting. To understand how ARIMA works, we need to discuss its predecessors because ARIMA combines components of these earlier models.

- Autoregressive (AR) models: multiple regression using lagged observations as predictors.
- Moving Average (MA) models: multiple regression using lagged residuals (errors) as predictors.
- Autoregressive Moving Average (ARMA) models: multiple regression using both lagged observations and lagged residuals as predictors. Accepts only stationary data.
- Autoregressive Integrated Moving Average (ARIMA{p,d,q}) models: This is generalization of the ARMA model with differencing. This allows ARIMA to account for non-stationarity in the data. The ARIMA parameters (p,d,q) are non-negative integers describing the autoregressive, differencing, and moving average terms:
  - o p: order of the autoregressive (AR) model, i.e. the number of lagged observations
  - o d: degree of differencing (I), i.e. the number of differenced observations
  - o q: order of the moving-average (MA) (or seasonal) model

In addition to (p,d,q), ARIMA models can also include intercepts or constants (c), in some cases referred to as the "drift".

Here are the most common ARIMA model configurations:

- ARIMA(0,0,0): white noise model
- ARIMA(0,0,1): first-order moving average (MA) model. Same as MA(1)
- ARIMA(0,1,0): random walk (if this model uses a constant c it describes a random walk with drift). Same as I(1). This is essentially a stochastic process.
- ARIMA(0,1,1) without constant: simple exponential smoothing

- ARIMA(0,1,1) with constant: simple exponential smoothing with growth
- ARIMA(0,1,2): Damped Holt's model
- ARIMA(0,2,1) or (0,2,2) without constant: linear exponential smoothing
- ARIMA(0,2,2): double exponential smoothing
- ARIMA(0,3,3): triple exponential smoothing
- ARIMA(1,0,0): first-order autoregressive model. If the series is stationary and autocorrelated, and can be predicted as a multiple of the last value (plus constant). Same as AR(1)
- ARIMA(1,1,0): differenced first-order autoregressive model. Used if the errors of the random walk model are autocorrelated but without seasonality.
- ARIMA(1,1,2) without constant: damped-trend linear exponential smoothing
- ARIMA(2,1,1): second order autoregressive, first order moving average, differenced once

auto.arima(): The auto.arima() function in the forecast package for R can automatically select the best ARIMA model. It conducts a search over possible models within a set of constraints, and returns the best ARIMA model according to the AIC<sub>C</sub> (or AIC or BIC) value.

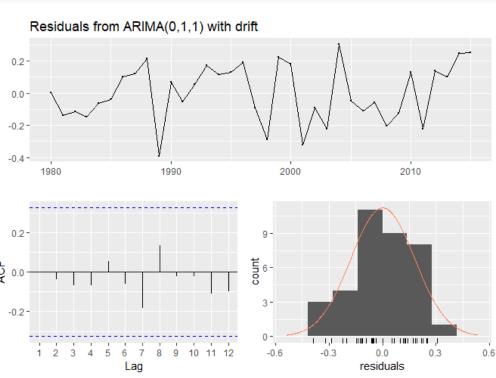
Note that  $AIC_C$  values, like MSE and other performance metrics, can only be compared between models of the same class. This means that you:

- Cannot compare ARIMA AIC<sub>C</sub> with ETS AIC<sub>C</sub>
- Cannot compare AIC<sub>C</sub>s for ARIMA models with different degrees of differencing (d).

Next, we will fit an automatic ARIMA model to the international visitors to Australia series.

```
# Fit an automatic ARIMA model
fit <- auto.arima(austa)

# Check that the residuals look like white noise
checkresiduals(fit)</pre>
```



```
##
## Ljung-Box test
##
```

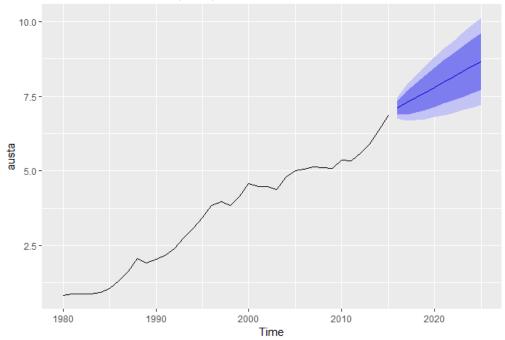
```
## data: Residuals from ARIMA(0,1,1) with drift
## Q* = 2.297, df = 5, p-value = 0.8067
##
## Model df: 2. Total lags used: 7
```

```
# Summarize the model
summary(fit)
```

```
## Series: austa
## ARIMA(0,1,1) with drift
##
## Coefficients:
##
         ma1 drift
##
        0.3006 0.1735
## s.e. 0.1647 0.0390
##
## sigma^2 estimated as 0.03376: log likelihood=10.62
## AIC=-15.24 AICc=-14.46 BIC=-10.57
##
## Training set error measures:
                       ME
                               RMSE MAE
                                                           MAPE
                                                                     MASE
## Training set 0.0008313383 0.1759116 0.1520309 -1.069983 5.513269 0.7461559
                      ACF1
## Training set -0.000571993
```

```
# Plot forecasts of fit
fit %>% forecast(h = 10) %>% autoplot()
```

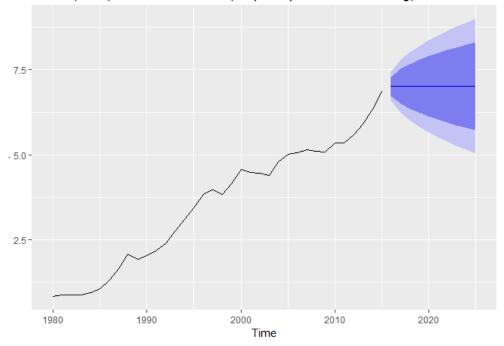




auto.arima() selected an ARIMA(0,1,1) model with drift based on the lowest AIC<sub>C</sub> value. This codes indicates a simple exponential smoothing with growth.

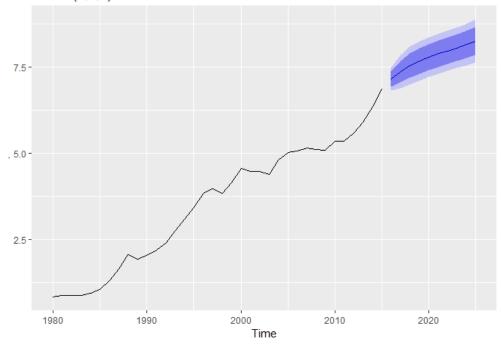
```
austa %>% Arima(order = c(0,1,1), include.constant = FALSE) %>% forecast() %>% autoplot() + ggtitle("ARIMA(0,1,1) model with no drift (simple exponential smoothing)")
```

ARIMA(0,1,1) model with no drift (simple exponential smoothing)



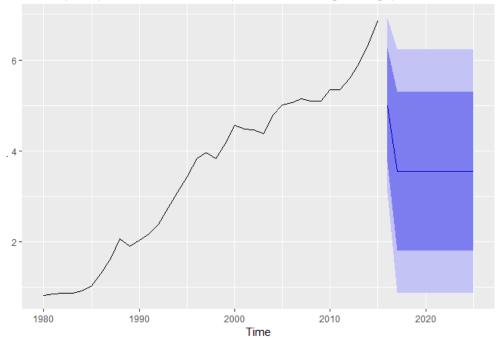
```
austa %>% Arima(order = c(2,1,3), include.constant = TRUE) %>% forecast() %>% autoplot() +
    ggtitle("ARIMA(2,1,3) model with drift")
```

### ARIMA(2,1,3) model with drift



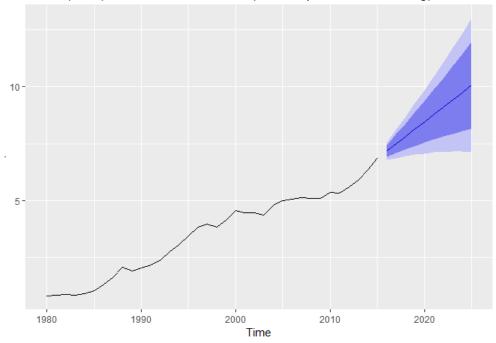
```
austa %>% Arima(order = c(0,0,1), include.constant = TRUE) %>% forecast() %>% autoplot() + ggtitle("ARIMA(0,0,1) model with constant (first-order moving average)")
```

### ARIMA(0,0,1) model with constant (first-order moving average)



```
austa %>% Arima(order = c(0,2,1), include.constant = FALSE) %>% forecast() %>% autoplot() + ggtitle("ARIMA(0,2,1) model with no constant (linear exponential smoothing)")
```





Not all of these models make sense. The ARIMA(0,1,1) model disregards the trend in the series. There is not enough data to justify the use of an ARIMA(2,1,3) model—that model is overparameterized. The ARIMA(0,0,1) model is just as unhelpful as the ARIMA(0,1,1) model. It only use the historical mean value for all forecasts, and does not take advantage of the variance in the series. ARIMA(0,1,1) with drift and ARIMA(0,2,1) seem to provide the best forecasts of these five models.

### Comparing auto.arima() and ets() on non-seasonal data

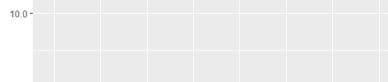
```
# Set up forecast functions
fets <- function(x, h) {
  forecast(ets(x), h = h)
farima <- function(x, h) {</pre>
  forecast(auto.arima(x), h = h)
# Compute CV errors
e1 <- tsCV(austa, fets, h = 1)
e2 <- tsCV(austa, farima, h = 1)
# Compute MSE
mean(e1^2, na.rm = TRUE)
```

## [1] 0.05623684

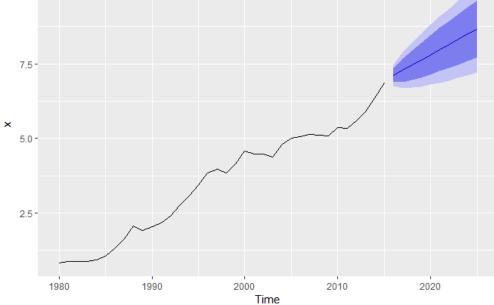
```
mean(e2^2, na.rm = TRUE)
```

## [1] 0.04336277

```
# Plot 10-year forecasts using the best model class
austa %>% farima(h = 10) %>% autoplot()
```

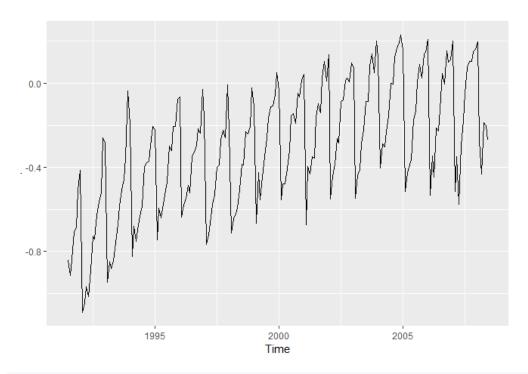


Forecasts from ARIMA(0,1,1) with drift



### Seasonal ARIMA models

Seasonal ARIMA models are denoted ARIMA(p,d,q)(P,D,Q) $_{\rm m}$ , where m equals the number of time step for each season, and (P,D,Q) describe the autoregressive, differencing, and moving average terms of the seasonal equations included in the ARIMA model.

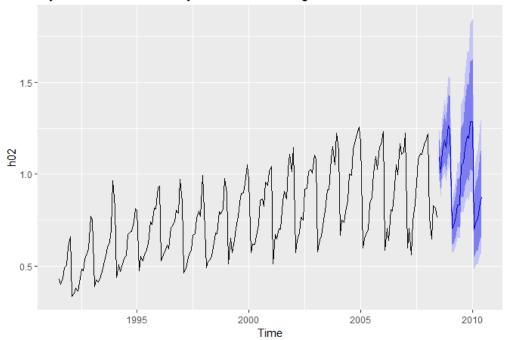


```
# Fit a seasonal ARIMA model
fit <- auto.arima(h02, lambda = 0)
# Summarize
summary(fit)</pre>
```

```
## Series: h02
## ARIMA(2,1,1)(0,1,2)[12]
## Box Cox transformation: lambda= 0
##
## Coefficients:
    ar1
##
                 ar2
                               sma1
                        ma1
                                         sma2
##
       -1.1358 -0.5753 0.3683 -0.5318 -0.1817
## s.e. 0.1608 0.0965 0.1884 0.0838 0.0881
##
## sigma^2 estimated as 0.004278: log likelihood=248.25
## AIC=-484.51 AICc=-484.05 BIC=-465
##
## Training set error measures:
                      ME
                            RMSE
                                       MAE MPE
                                                         MAPE
## Training set -0.003931805 0.0501571 0.03629816 -0.5323365 4.611253
                  MASE
## Training set 0.5987988 -0.003740267
```

```
# Plot 2-year forecasts
fit %>% forecast(h = 24) %>% autoplot() +
   ggtitle("2 year forecast of monthly corticosteroid drug sales in Australia")
```

### 2 year forecast of monthly corticosteroid drug sales in Australia



auto.arima() found that the ARIMA(2,1,1)(0,1,2) model provided the best fit for the monthly series of corticosteroid drug sales in Australia (above). The (p,d,q) = (2,1,1) parameter set represents a second order autoregressive, first order moving average model, differenced once to induce stationarity. The (P,D,Q) = (0,1,2) parameter set indicates that a Damped Holt's model was used to model the seasonal part of the ARIMA model.

Another example (below) illustrates ARIMA forecasting of quarterly retail in the 17 countries of the Euro area. This time, rather than conduction a stepwise model selection we force auto.arima() to search over all models. More calculations are needed for a full search but it can result in a better model. However, it appears that in this case the stepwise selection already identified the best model.

```
# Find ARIMA model for euretail
fit1 <- auto.arima(euretail)
summary(fit1)</pre>
```

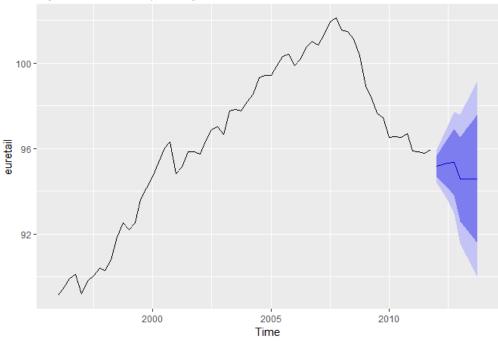
```
## Series: euretail
## ARIMA(0,1,3)(0,1,1)[4]
##
## Coefficients:
##
        ma1
                  ma2
                          ma3
##
        0.2630 0.3694 0.4200 -0.6636
## s.e. 0.1237 0.1255 0.1294
##
## sigma^2 estimated as 0.156: log likelihood=-28.63
## AIC=67.26 AICc=68.39 BIC=77.65
##
## Training set error measures:
##
                       ME
                              RMSE
                                         MAE
                                                     MPE
                                                              MAPE
## Training set -0.02965298 0.3661147 0.2787802 -0.02795377 0.2885545
##
                   MASE
## Training set 0.2267735 0.006455781
```

```
# Don't use a stepwise search
fit2 <- auto.arima(euretail, stepwise = FALSE)
summary(fit2)</pre>
```

```
## Series: euretail
## ARIMA(0,1,3)(0,1,1)[4]
##
## Coefficients:
## ma1 ma2 ma3
                            sma1
     0.2630 0.3694 0.4200 -0.6636
## s.e. 0.1237 0.1255 0.1294 0.1545
## sigma^2 estimated as 0.156: log likelihood=-28.63
## AIC=67.26 AICc=68.39 BIC=77.65
##
## Training set error measures:
##
                    ME RMSE
                                    MAE
                                            MPE
                                                        MAPE
## Training set -0.02965298 0.3661147 0.2787802 -0.02795377 0.2885545
##
                MASE ACF1
## Training set 0.2267735 0.006455781
```

```
# Compute 2-year forecasts
fit2 %>% forecast(h = 8) %>% autoplot() +
   ggtitle("2 year forecast of quarterly retail trade: Euro area")
```

### 2 year forecast of quarterly retail trade: Euro area



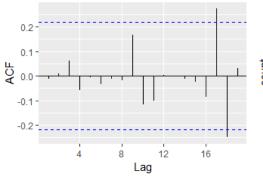
# Comparison of auto.arima() and ets() on seasonal data

```
# Create training series
train <- window(qcement, start = c(1988, 1), end = c(2007, 4))

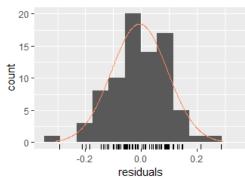
# Fit ARIMA and ETS model
fit1 <- auto.arima(train)
fit2 <- ets(train)

# Check white noise residuals
checkresiduals(fit1)</pre>
```

# Residuals from ARIMA(1,0,1)(2,1,1)[4] with drift 0.3 0.2 0.1 0.0 -0.1 -0.2 -0.3 1990 1995 2000 2005

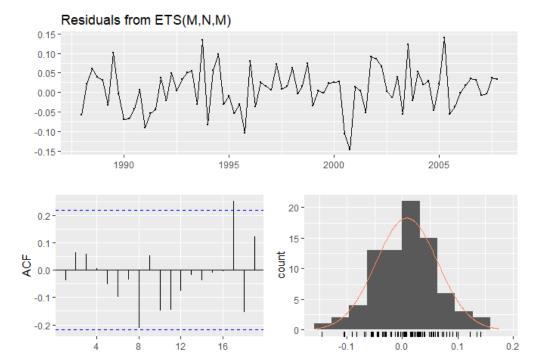


Lag



```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(1,0,1)(2,1,1)[4] with drift
## Q* = 3.3058, df = 3, p-value = 0.3468
##
## Model df: 6. Total lags used: 9
```

 ${\tt checkresiduals}({\tt fit2})$ 



```
##
## Ljung-Box test
```

residuals

```
##
## data: Residuals from ETS(M,N,M)
## Q^* = 6.3457, df = 3, p-value = 0.09595
## Model df: 6. Total lags used: 9
# Forecast
fc1 <- forecast(fit1, h = 25)</pre>
fc2 <- forecast(fit2, h = 25)</pre>
# Compare RMSE
\verb"accuracy"(fc1, qcement")
                             RMSE MAE MPE
##
                      ME
## Training set -0.006205705 0.1001195 0.07988903 -0.6704455 4.372443
## Test set -0.158835253 0.1996098 0.16882205 -7.3332836 7.719241
##
             MASE ACF1 Theil's U
## Training set 0.5458078 -0.01133907 NA
## Test set 1.1534049 0.29170452 0.7282225
\verb"accuracy"(fc2, qcement")
                              RMSE
                       ME
                                        MAE
                                                    MPE
## Training set 0.01406512 0.1022079 0.07958478 0.4938163 4.371823
## Test set -0.13495515 0.1838791 0.15395141 -6.2508975 6.986077
               MASE ACF1 Theil's U
## Training set 0.5437292 -0.03346295 NA
```

The ETS model gives the best performance with a lower RMSE for the test set than the ARIMA model. However, the difference in performance is small, and both models do a good job given that the autocorrelation of residuals closely resembles that of white noise.

## Test set 1.0518075 0.53438371 0.680556