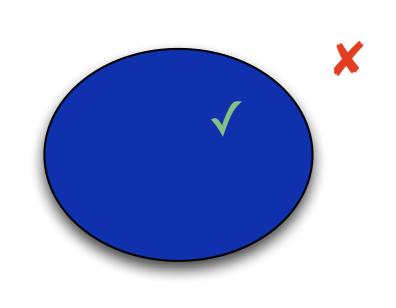
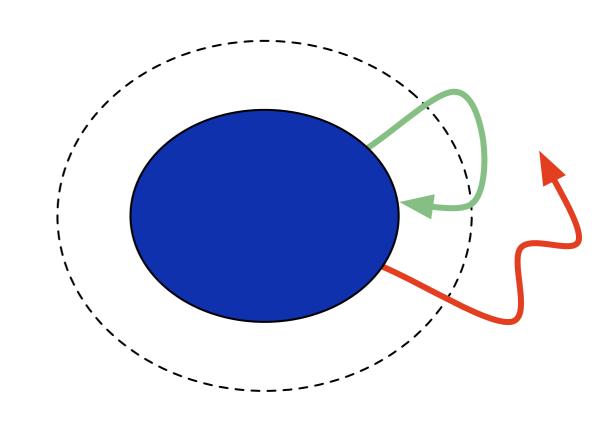
## Volumes and Ensembles





Volume: any frame is either "in" or not

(states, interfaces)

Ensemble: any trajectory is either "in" or not

(path ensembles)

## PathMovers

