



paths.Option[Ensemble(paths.AllOutXEnsemble(C7eq|alpha_n))];

```
trial_resising=resising.split(step.trials[0].trajectory)
```

trajec_tory=recrossing_steps[0].active[0].trajec_tory

paths.Length Ensemble(1) & paths.AllInXEnsemble(alpha_r);

```
recrsing_steps=[step for step in steps
```


#define function to identify and record sightings

paths.Length& paths.AllIndexEnumerable(C7eq)

```
return len(trial_reportings) > 0 & step.accepted
```

```
storage=paths.AnalysisStorage('tps_file.nc')
```

recrossing = paths.SequntialEnsemble([

print len(recurring_steps) # output

important paths
open paths
link paths

C7eq=storange.volumes['C7eq']


```
def accepted_during(step):
```

`alpha_r=storange.volumes['alpha_r']`

#lookatthefirsttrajecory

if accepted_during(step)]

#findall relevant MC steps

#loadstatesfromstorage

#creating the environment

