

Navigation	Forward / Backward	W	S
	Slide Left / Right	A	D
	Ascend / Descend	Q	Z
Robot's camera	Toggle robot's camera	1	
	Take a picture from the robot's camera (save as a image file)	2	
Manual robot control	Rotate right shoulder joint 0	[Shift+[
	Rotate right shoulder joint 1	P	Shift+P
	Rotate right elbow joint 0	O	Shift+O
	Rotate right elbow joint 1	I	Shift+I
	Rotate right wrist joint 0	U	Shift+U
	Rotate right wrist joint 1	Y	Shift+Y
	Rotate right wrist joint 2	T	Shift+T
	Open right gripper	=	
	Close right gripper	-	
	Rotate left shoulder joint 0	'	Shift+'
	Rotate left shoulder joint 1	;	Shift+;
	Rotate left elbow joint 0	L	Shift+L
	Rotate left elbow joint 1	K	Shift+K
	Rotate left wrist joint 0	J	Shift+J
	Rotate left wrist joint 1	H	Shift+H
	Rotate left wrist joint 2	G	Shift+G
	Open left gripper	0	
	Close left gripper	9	
	Rotate head joint (pan)]	Shift+]
	Cycle through facial expressions (screen)	\	
Matlab robot control	Toggle Matlab agent	M	
Tabletop objects	Materialize a large block	B	
	Materialize a stack of small blocks	N	
	Clean up the table	C	