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File: Source.c, Date: 6/24/2019, Time: 2:40:06 PM
1234567
        This program was created by the
         CodeWizardAVR V3.12 Advanced
        Automatic Program Generator
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        Project : Lamu Lalu Lintas
         Version : 1.2
        Date : 6/24/2019
Author : Rizky Arsyansyah Rinjani & Ilham Alif Ramadhan
Company : STMIK AMIKOM PURWOKERTO
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         Comments: TI 18 S (18.11.0153 & 18.11.0000)
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17
                                   : ATmega16
        Chip type
         Program type
                                   : Application
18
        AVR Core Clock frequency: 12.000000 MHz
190122345678901
        Memory model : Small
         External RAM size
                                   : 0
        Data Stack size
                                   : 256
         #include <mega16.h>
         #include <delay.h>
         // Declare your global variables here
        int merah = 4; // desimal, biner : 0b00000100
int kuning = 2; // desimal biner : 0b00000010
int hijau = 1; // desimal biner : 0b00000001
32334567
3333333333
         void main(void)
         // Declare your local variables here
         // Input/Output Ports initialization
         // Port A initialization
39
40
         // Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=Out Bit1=Out Bit0=Out
         DDRA=(0<<DDA7) | (0<<DDA6) | (0<<DDA5) | (0<<DDA4) | (0<<DDA3) | (1<<DDA2) | (1<<DDA1) | (1<<DDA1) |
         // State: Bit7=T Bit6=T Bit5=T Bit4=T Bit3=T Bit2=0 Bit1=0 Bit0=0
41
         PORTA=(0<<PORTA7) | (0<<PORTA6) | (0<<PORTA5) | (0<<PORTA4) | (0<<PORTA3) | (0<<PORTA2) | (0<<PORTA1) | (0<
42
         PORTAO):
43
44
         // Port B initialization
45
         // Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=Out Bit1=Out Bit0=Out
46
47
         DDRB=(0<<DDB7) | (0<<DDB6) | (0<<DDB5) | (0<<DDB4) | (0<<DDB3) | (1<<DDB2) | (1<<DDB1) | (1<<DDB0);
         // State: Bit7=T Bit6=T Bit5=T Bit4=T Bit3=T Bit2=0 Bit1=0 Bit0=0
         PORTB=(0<<PORTB7) | (0<<PORTB6) | (0<<PORTB5) | (0<<PORTB4) | (0<<PORTB3) | (0<<PORTB2) | (0<<PORTB1) | (0<
48
         PORTBO):
49
50
51
52
53
         // Port C initialization
         // Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=Out Bit1=Out Bit0=Out
         DDRC=(0<<DDC7) | (0<<DDC6) | (0<<DDC5) | (0<<DDC4) | (0<<DDC3) | (1<<DDC2) | (1<<DDC1) | (1<<DDC0);
         // State: Bit7=T Bit6=T Bit5=T Bit4=T Bit3=T Bit2=0 Bit1=0 Bit0=0
         PORTC=(0<<PORTC7) | (0<<PORTC6) | (0<<PORTC5) | (0<<PORTC4) | (0<<PORTC3) | (0<<PORTC2) | (0<<PORTC1) | (0<
54
         PORTCO);
55
56
57
58
59
         // Port D initialization
         // Function: Bit7=In Bit6=In Bit5=In Bit4=In Bit3=In Bit2=Out Bit1=Out Bit0=Out
        DDRD=(0<<DDD7) | (0<<DDD6) | (0<<DDD5) | (0<<DDD4) | (0<<DDD3) | (1<<DDD2) | (1<<DDD1) | (1<<DDD1) | (1<<DDD0); // State: Bit7=T Bit6=T Bit5=T Bit4=T Bit3=T Bit2=0 Bit1=0 Bit0=0
         PORTD=(0<<PORTD7) | (0<<PORTD6) | (0<<PORTD5) | (0<<PORTD4) | (0<<PORTD3) | (0<<PORTD2) | (0<<PORTD1) | (0<
60
         PORTD0);
61
62
63
         // Timer/Counter 0 initialization
         // Clock source: System Clock
64
65
66
67
69
71
         // Clock value: Timer 0 Stopped
         // Mode: Normal top=0xFF
         // OCO output: Disconnected
        TCCR0=(0<<WGM00) | (0<<COM01) | (0<<COM00) | (0<<WGM01) | (0<<CS02) | (0<<CS01) | (0<<CS00);
        TCNT0=0\times00:
        OCR0=0x00;
         // Timer/Counter 1 initialization
72
73
74
75
76
        // Clock source: System Clock
         // Clock value: Timer1 Stopped
        // Mode: Normal top=0xFFFF
        // OC1A output: Disconnected // OC1B output: Disconnected
77
78
79
         // Noise Canceler: Off
        // Input Capture on Falling Edge
// Timer1 Overflow Interrupt: Off
80
         // Input Capture Interrupt: Off
         // Compare A Match Interrupt: Off
         // Compare B Match Interrupt: Off
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        TCCR1A=(0<<COM1A1) | (0<<COM1A0) | (0<<COM1B1) | (0<<COM1B0) | (0<<WGM11) | (0<<WGM10);
88888899999
88888899999
        TCCR1B=(0<<ICNC1) | (0<<ICES1) | (0<<WGM13) | (0<<WGM12) | (0<<CS12) | (0<<CS11) | (0<<CS10);
        TCNT1H=0\times00:
        TCNT1L=0x00;
        ICR1H=0 \times 00;
        ICR1L=0 \times 00;
        OCR1AH=0x00;
        OCR1AL=0 \times 00;
        OCR1BH=0x00;
        OCR1BL=0 \times 00;
        // Timer/Counter 2 initialization
95
        // Clock source: System Clock
96
        // Clock value: Timer2 Stopped
97
        // Mode: Normal top=0xFF
98
99
100
101
102
         // OC2 output: Disconnected
        ASSR=0<<AS2;
        TCCR2=(0<<PWM2) | (0<<COM21) | (0<<COM20) | (0<<CTC2) | (0<<CS21) | (0<<CS21) | (0<<CS20);
        TCNT2=0\times00:
        OCR2=0x00;
103
104
         // Timer(s)/Counter(s) Interrupt(s) initialization
        TIMSK=(0<<OCIE2) | (0<<TOIE2) | (0<<TICIE1) | (0<<OCIE1A) | (0<<OCIE1B) | (0<<TOIE1) | (0<<OCIE0) | (0<
105
        TOTE();
106
107
         // External Interrupt(s) initialization
108
        // INTO: Off
        // INT1: Off
109
110
         // INT2: Off
111
112
113
        MCUCR=(0<<ISC11) | (0<<ISC10) | (0<<ISC01) | (0<<ISC00);
        MCUCSR = (0 << ISC2);
114
        // USART initialization
115
        // USART disabled
\frac{1}{1}6
        UCSRB=(0<<RXCIE) | (0<<TXCIE) | (0<<UDRIE) | (0<<RXEN) | (0<<TXEN) | (0<UCSZ2) | (0<<RXB8) | (0<<TXB8);
118
        // Analog Comparator initialization
        // Analog Comparator: Off
// The Analog Comparator's positive input is
119
120
121
122
         // connected to the AINO pin
        // The Analog Comparator's negative input is
123
        // connected to the AIN1 pin
123
124
125
126
127
128
130
        SFIOR=(0 << ACME);
        // ADC initialization
         // ADC disabled
        ADCSRA=(0<<ADEN) | (0<<ADSC) | (0<<ADATE) | (0<<ADIF) | (0<<ADIE) | (0<<ADPS2) | (0<<ADPS1) | (0<<ADPS0);
131
132
133
134
        // SPI initialization
         // SPI disabled
        SPCR=(0<<SPIE) | (0<<SPE) | (0<<DORD) | (0<<MSTR) | (0<<CPOL) | (0<<CPHA) | (0<<SPR1) | (0<<SPR0);
135
        // TWI initialization
136
         // TWI disabled
137
138
139
        TWCR=(0<<TWEA) | (0<<TWSTA) | (0<<TWSTO) | (0<<TWEN) | (0<<TWIE);
        while (1)
140
141
               PORTA = hijau;
142
143
144
               PORTB = merah;
               PORTC = merah:
               PORTD = merah;
145
146
               delay_ms(200);
147
               PORTA = kuning;
148
               delay ms(50);
149
               PORTA = merah;
150
               delay ms(20);
151
152
153
154
155
               PORTB = hijau;
               delay ms(200);
               PORTB = kuning;
               delay_ms(50);
156
157
158
159
               PORTB = merah;
               delay_ms(20);
               PORTC = hijau;
160
               delay_ms(200);
161
162
163
               PORTC = kuning;
               delay_ms(50);
PORTC = merah;
164
               delay ms(20);
165
166
167
168
               PORTD = hijau;
               delay_ms(200);
PORTD = kuning;
Ī69
               delay_ms(50);
```

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