Chapter 2

Vector analysis in special relativity

2.1 Definition of a vector

2.2 Vector algebra

2.3 The four-velocity

An object's four velocity, denoted \vec{U} , is the vector tangent to its world line, with unit length. This means it extends one unit in time, and zero in space, so it is timelike.

For an accelerated particle (which we have not considered up to now), we may not be able to define an inertial frame, but we can define a **momentarily comoving reference frame** (MCRF) which, as the name suggests, moves with the same velocity as the observer for an infinitesimal period of time. We can therefore construct a continuous sequence of MCRFs for any object. If an object has MCRF \mathcal{O} , then its four-velocity is defined to be the basis vector \vec{e}_0 .

2.4 The four-momentum

Analogous to the three-momentum, we define the four-momentum to be

$$\vec{p} = m\vec{U}. \tag{Schutz 2.19}$$

It has components

$$\vec{p} \xrightarrow{\mathcal{O}} (E, p^1, p^2, p^3).$$
 (Schutz 2.20)

Calling p^0 "E" is no accident, it is in fact the energy. There is an interesting consequence to this: since vectors are invariant with respect to reference frame, but vector components are not, this means that the four-momentum does not change in different reference frames, but the energy does. One example would be

the doppler effect, which causes the color (or energy) of a photon to shift depending on the radial velocity of the source and observer.

2.5 Scalar product

$$\vec{A} \cdot \vec{B} = -(A^0 B^0) + (A^1 B^1) + (A^2 B^2) + (A^3 B^3)$$

2.6 Applications

2.7 Photons

 $\vec{x} \cdot \vec{x} = 0$, so we cannot define \vec{U} for photons. We can, however, define \vec{p} . Since $\vec{p} \cdot \vec{p} = -m^2$, and photons are massless, we have $\vec{p} \cdot \vec{p} = 0$.

2.8 Further reading

2.9 Exercises

2 Identify the free and dummy indices in the following equations, and write equivalent expressions with different indices. Also, write how many equations are represented by each expression.

Note, I will express the set of free indices by \mathcal{F} and the set of dummy indices as \mathcal{D} , and I will use the original index names.

(a)
$$A^{\alpha}B_{\beta} = 5 \implies A^{\beta}B_{\alpha} = 5$$
 (16 equations, $\mathcal{F} = \{\alpha, \beta\}, \mathcal{D} = \emptyset$)

(b)
$$A^{\bar{\mu}} = \Lambda^{\bar{\mu}}_{\ \nu} A^{\nu} \implies A^{\bar{\nu}} = \Lambda^{\bar{\nu}}_{\ \mu} A^{\mu}$$
 (4 equations, $\mathcal{F} = \{\bar{\mu}\}, \mathcal{D} = \{\nu\}$).

(c)
$$T^{\alpha\mu\lambda}A_{\mu}C_{\lambda}^{\ \gamma} = D^{\gamma\alpha} \implies T^{\eta\phi\theta}A_{\phi}C_{\theta}^{\ \zeta} = D^{\zeta\eta} \ (16 \text{ equations}, \ \mathcal{F} = \{\alpha, \gamma\}, \ \mathcal{D} = \{\mu, \lambda\})$$

(d)
$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu} = G_{\mu\nu} \implies R_{\chi\epsilon} - \frac{1}{2}g_{\chi\epsilon} = G_{\chi\epsilon}$$
 (16 equations, $\mathcal{F} = \{\mu, \nu\}, \mathcal{D} = \emptyset$)

4 Given vectors $\vec{A} \to_{\mathcal{O}} (5, -1, 0, 1)$ and $\vec{B} \to_{\mathcal{O}} (-2, 1, 1, -6)$, find the components in \mathcal{O} of

(a)
$$-6\vec{A} \to_{\mathcal{O}} (-30, 6, 0, -6)$$

(b)
$$3\vec{A} + \vec{B} \to_{\mathcal{O}} (13, -2, 1, -3)$$

(c)
$$-6\vec{A} + 3\vec{B} \rightarrow_{\mathcal{O}} (-36, 9, 3, -24)$$

6 Draw a spacetime diagram from \mathcal{O} 's reference frame. There are two other frames, $\bar{\mathcal{O}}$ and $\bar{\mathcal{O}}$, which are each moving with velocity 0.6 in the +x direction from each respective frame. Plot each frame's basis vectors, as observed by \mathcal{O} .

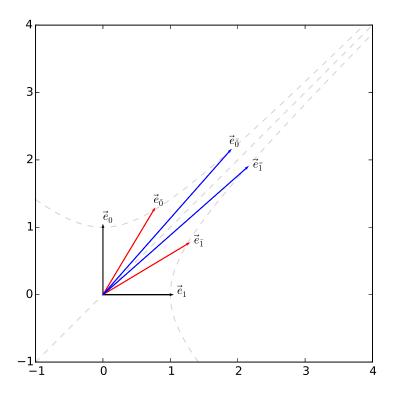


Figure 2.1: Exercise 6

See Figure 2.1.

 ${\bf 9}$ Prove, by writing out all the terms that

$$\sum_{\bar{\alpha}=0}^{3} \left(\sum_{\beta=0}^{3} \Lambda^{\bar{\alpha}}{}_{\beta} A^{\beta} \vec{e}_{\bar{\alpha}} \right) = \sum_{\beta=0}^{3} \left(\sum_{\bar{\alpha}=0}^{3} \Lambda^{\bar{\alpha}}{}_{\beta} A^{\beta} \vec{e}_{\bar{\alpha}} \right)$$

$$\begin{split} \sum_{\bar{\alpha}=0}^{3} \left(\sum_{\beta=0}^{3} \Lambda^{\bar{\alpha}}{}_{\beta} A^{\beta} \vec{e}_{\bar{\alpha}} \right) &= \sum_{\bar{\alpha}=0}^{3} \left(\Lambda^{\bar{\alpha}}{}_{0} A^{0} \vec{e}_{\bar{\alpha}} + \Lambda^{\bar{\alpha}}{}_{1} A^{1} \vec{e}_{\bar{\alpha}} + \Lambda^{\bar{\alpha}}{}_{2} A^{2} \vec{e}_{\bar{\alpha}} + \Lambda^{\bar{\alpha}}{}_{3} A^{3} \vec{e}_{\bar{\alpha}} \right) \\ &= \Lambda^{\bar{0}}{}_{0} A^{0} \vec{e}_{\bar{0}} + \Lambda^{\bar{0}}{}_{1} A^{1} \vec{e}_{\bar{0}} + \Lambda^{\bar{0}}{}_{2} A^{2} \vec{e}_{\bar{0}} + \Lambda^{\bar{0}}{}_{3} A^{3} \vec{e}_{\bar{0}} \\ &+ \Lambda^{\bar{1}}{}_{0} A^{0} \vec{e}_{\bar{1}} + \Lambda^{\bar{1}}{}_{1} A^{1} \vec{e}_{\bar{1}} + \Lambda^{\bar{1}}{}_{2} A^{2} \vec{e}_{\bar{1}} + \Lambda^{\bar{1}}{}_{3} A^{3} \vec{e}_{\bar{1}} \\ &+ \Lambda^{\bar{2}}{}_{0} A^{0} \vec{e}_{\bar{2}} + \Lambda^{\bar{2}}{}_{1} A^{1} \vec{e}_{\bar{1}} + \Lambda^{\bar{2}}{}_{2} A^{2} \vec{e}_{\bar{2}} + \Lambda^{\bar{2}}{}_{3} A^{3} \vec{e}_{\bar{2}} \\ &+ \Lambda^{\bar{3}}{}_{0} A^{0} \vec{e}_{\bar{3}} + \Lambda^{\bar{3}}{}_{1} A^{1} \vec{e}_{\bar{3}} + \Lambda^{\bar{3}}{}_{2} A^{2} \vec{e}_{\bar{3}} + \Lambda^{\bar{3}}{}_{3} A^{3} \vec{e}_{\bar{3}} \\ &= \Lambda^{\bar{0}}{}_{0} A^{0} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{0} A^{0} \vec{e}_{\bar{1}} + \Lambda^{\bar{2}}{}_{0} A^{0} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{0} A^{0} \vec{e}_{\bar{3}} \\ &+ \Lambda^{\bar{0}}{}_{1} A^{1} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{1} A^{1} \vec{e}_{\bar{1}} + \Lambda^{\bar{2}}{}_{1} A^{1} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{1} A^{1} \vec{e}_{\bar{3}} \\ &+ \Lambda^{\bar{0}}{}_{1} A^{2} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{1} A^{1} \vec{e}_{\bar{1}} + \Lambda^{\bar{2}}{}_{2} A^{2} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{1} A^{1} \vec{e}_{\bar{3}} \\ &+ \Lambda^{\bar{0}}{}_{3} A^{3} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{3} A^{3} \vec{e}_{\bar{1}} + \Lambda^{\bar{2}}{}_{2} A^{2} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{3} A^{3} \vec{e}_{\bar{3}} \\ &+ \Lambda^{\bar{0}}{}_{3} A^{3} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{3} A^{3} \vec{e}_{\bar{1}} + \Lambda^{\bar{2}}{}_{3} A^{3} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{3} A^{3} \vec{e}_{\bar{3}} \\ &= \sum_{\beta=0}^{3} \left(\Lambda^{\bar{0}}{}_{\beta} A^{\beta} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{\beta} A^{\beta} \vec{e}_{\bar{0}} + \Lambda^{\bar{1}}{}_{\beta} A^{\beta} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{\beta} A^{\beta} \vec{e}_{\bar{2}} + \Lambda^{\bar{3}}{}_{\beta} A^{\beta} \vec{e}_{\bar{3}} \right) \\ &= \sum_{\beta=0}^{3} \left(\sum_{\beta=0}^{3} \Lambda^{\bar{\alpha}}{}_{\beta} A^{\beta} \vec{e}_{\bar{0}} \right)$$

11 Let $\Lambda^{\bar{\alpha}}{}_{\beta}$ be the matrix of the Lorentz transformation from \mathcal{O} to $\bar{\mathcal{O}}$, given in Equation 1.12. Let \vec{A} be an arbitrary vector with components (A^0, A^1, A^2, A^3) in frame \mathcal{O} .

(a) Write down the matrix of $\Lambda^{\nu}_{\bar{\mu}}(-v)$.

Intuitively, it should appear the same as $\Lambda^{\bar{\alpha}}{}_{\beta}$, but with the negative signs removed. More rigorously, it is given by the matrix inverse of $\Lambda^{\bar{\alpha}}{}_{\beta}$, as their product should be the identity matrix. I have used a computer algebra system (Wolfram Alpha) to take the inverse of this matrix symbolically, confirming my suspicion:

$$\Lambda^{\nu}_{\ \overline{\mu}}(-v) = \begin{pmatrix} \gamma & v\gamma & 0 & 0 \\ v\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

(b) Find $A^{\bar{\alpha}}$ for all $\bar{\alpha}$.

$$\begin{split} A^{\bar{\alpha}} &= \Lambda^{\bar{\alpha}}{}_{\beta} A^{\beta} \\ A^{\bar{0}} &= \gamma (A^0 - v A^1) \\ A^{\bar{1}} &= \gamma (A^1 - v A^0) \\ A^{\bar{2}} &= A^2 \\ A^{\bar{3}} &= A^3 \end{split}$$

(c) Verify Equation 2.18 by performing the sum for all values of ν and α . To simplify things, I do this via matrix multiplication

$$\begin{split} \Lambda^{\bar{\alpha}}{}_{\beta}(v)\Lambda^{\nu}{}_{\bar{\mu}}(-v) &= \begin{pmatrix} \gamma^2 - v^2\gamma^2 & v\gamma^2 - v\gamma^2 & 0 & 0 \\ v\gamma^2 - v\gamma^2 & \gamma^2 - v^2\gamma^2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} \gamma^2(1-v^2) & 0 & 0 & 0 \\ 0 & \gamma^2(1-v^2) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\ &= \delta^{\nu}{}_{\alpha} \\ &= \delta^{\nu}{}_{\alpha} \end{split}$$

- (d) Write down the Lorentz transformation matrix from $\bar{\mathcal{O}}$ to \mathcal{O} , justifying each term. It should just be $\Lambda^{\nu}_{\bar{\mu}}(-v)$. I'm not sure what else to say at this point.
- (e) Using the result from part (d), find A^{β} from $A^{\bar{\alpha}}$. How does this relate to Equation 2.18?

$$\begin{split} \Lambda^{\beta}{}_{\bar{\alpha}}A^{\bar{\alpha}} &= \begin{pmatrix} \gamma & v\gamma & 0 & 0 \\ v\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \gamma(A^0 - vA^1) \\ \gamma(A^1 - vA^0) \\ A^2 \\ A^3 \end{pmatrix} = \begin{pmatrix} \gamma^2(A^0 - vA^1) + v\gamma^2(A^1 - vA^0) + 0 + 0 \\ v\gamma^2(A^0 - vA^1) + \gamma^2(A^1 - vA^0) + 0 + 0 \\ A^2 \\ A^3 \end{pmatrix} \\ &= \begin{pmatrix} A^0(\gamma^2 - v^2\gamma^2) + A^1(v\gamma^2 - v\gamma^2) \\ A^0(v\gamma^2 - v^2\gamma^2) + A^1(\gamma^2 - v\gamma^2) \\ A^2 \\ A^3 \end{pmatrix} = \begin{pmatrix} A^0(\gamma^2 - v^2\gamma^2) \\ A^1(\gamma^2 - v^2\gamma^2) \\ A^2 \\ A^3 \end{pmatrix} = \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix} = A^\beta \end{split}$$

Since $A^{\bar{\alpha}}=\Lambda^{\bar{\alpha}}{}_{\beta}(v),$ this goes to show that $\Lambda^{\nu}{}_{\bar{\beta}}(-v)\Lambda^{\bar{\beta}}{}_{\alpha}(-v)A^{\lambda}=A^{\lambda} \implies \Lambda^{\nu}{}_{\bar{\beta}}(-v)\Lambda^{\bar{\beta}}{}_{\alpha}(-v)=\delta^{\nu}{}_{\alpha}.$

(f) Verify in the same manner as (c) that

$$\Lambda^{\nu}{}_{\bar{\beta}}(v)\Lambda^{\bar{\alpha}}{}_{\nu}(-v)=\delta^{\bar{\alpha}}{}_{\bar{\beta}}$$

My matrix multiplication approach will just give me the same result as before. Perhaps another approach was intended?

(g) Establish that

$$\begin{split} \vec{e}_{\alpha} &= \Lambda^{\bar{\beta}}{}_{\alpha} \vec{e}_{\bar{\beta}} = \Lambda^{\bar{\beta}}{}_{\alpha} \Lambda^{\nu}{}_{\bar{\beta}} \vec{e}_{\nu} = \delta^{\nu}{}_{\alpha} \vec{e}_{\nu} \\ A^{\bar{\beta}} &= \Lambda^{\bar{\beta}}{}_{\alpha} A^{\alpha} = \Lambda^{\bar{\beta}}{}_{\alpha} \Lambda^{\alpha}{}_{\bar{\mu}} A^{\bar{\mu}} = \delta^{\bar{\beta}}{}_{\bar{\mu}} A^{\bar{\mu}} \end{split}$$

14 The following matrix gives a Lorentz transformation from \mathcal{O} to $\bar{\mathcal{O}}$:

$$\begin{pmatrix}
1.25 & 0 & 0 & 0.75 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0.75 & 0 & 0 & 1.25
\end{pmatrix}$$

(a) What is the velocity of $\bar{\mathcal{O}}$ relative to \mathcal{O} ?

This would correspond to a Lorentz boost along the z-axis, meaning

$$\Lambda^{\bar{\alpha}}{}_{\beta}(v) = \left(egin{array}{cccc} \gamma & 0 & 0 & -v\gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -v\gamma & 0 & 0 & \gamma \end{array}
ight),$$

and thus we have $\gamma = 1.25$ and $-v\gamma = 0.75$. Solving for v, we get

$$-v\gamma = \frac{3}{4} \implies v = -\frac{3}{4\gamma} = -\frac{3\cdot 4}{4\cdot 5} = -\frac{3}{5}.$$

So $\bar{\mathcal{O}}$ is moving with speed 0.6 relative to the -z-axis of \mathcal{O} .

(b) What is the inverse matrix to the given one?

Numerically, it comes out to be

$$\begin{pmatrix} 1.25 & 0 & 0 & -0.75 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -0.75 & 0 & 0 & 1.25 \end{pmatrix},$$

which makes sense, when you consider that the inverse matrix should be a Lorentz transformation with the velocity negated.

(c) Find the components in \mathcal{O} of $\vec{A} \to_{\bar{\mathcal{O}}} (1, 2, 0, 0)$.

$$\vec{A} \xrightarrow{\mathcal{O}} \begin{pmatrix} 1.25 & 0 & 0 & -0.75 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -0.75 & 0 & 0 & 1.25 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1.25 \\ 2 \\ 0 \\ -0.75 \end{pmatrix}$$

15

(a) Compute the four-velocity components in \mathcal{O} of a particle whose speed is v in the +x-direction relative to \mathcal{O} , using the Lorentz transformation.

$$\vec{U} = \vec{e}_{\bar{0}}$$

$$U^{\alpha} = \Lambda^{\alpha}_{\ \bar{\beta}} (\vec{e}_{\bar{0}})^{\bar{\beta}} = \Lambda^{\alpha}_{\bar{0}},$$

$$U^{0} = \gamma$$

$$U^{1} = v\gamma$$

$$U^{2} = U^{3} = 0$$

(b) Generalize to arbitrary velocities v, where |v| < 1.

$$\Lambda^{\alpha}{}_{\bar{\beta}}(\boldsymbol{v}) = \begin{pmatrix} \gamma & \gamma v_x & \gamma v_y & \gamma v_z \\ \gamma v_x & \gamma & 0 & 0 \\ \gamma v_y & 0 & \gamma & 0 \\ \gamma v_z & 0 & 0 & \gamma \end{pmatrix}.$$

$$U^0 = \gamma \quad U^1 = \gamma v_x \quad U^2 = \gamma v_y \quad U^3 = \gamma v_z$$

(c) Use this result to express v as a function of the components $\{U^{\alpha}\}$.

$$egin{aligned} oldsymbol{v} &= v_x ec{e}_1 + v_y ec{e}_2 + v_z ec{e}_3 \ v_i &= rac{U^i}{\gamma} \ oldsymbol{v} &= rac{1}{\gamma} U^i ec{e}_i \end{aligned}$$

(d) Find the three-velocity v of a particle with four-velocity components (2,1,1,1).

$$U^0=\gamma=2,$$
 and $U^i=1,$ so
$$\label{eq:volume} {m v}=\frac{1}{2} \vec{e_i}$$

17

Not sure how to approach this problem.

- (a) Prove that any timelike vector \vec{U} for which $U^0 > 0$ and $\vec{U} \cdot \vec{U} = -1$ is the four-velocity of *some* world line.
- (b) Use this to prove that for any timelike vector \vec{V} there is a Lorentz frame in which the \vec{V} has zero spatial components.
- 19 A body is uniformly accelerated if the four-vector \vec{a} has constant spatial direction and magnitude, $\vec{a} \cdot \vec{a} = \alpha^2 \ge 0$.
- (a) Show that this implies the components of \vec{a} in the body's MCRF are all constant, and that these are equivalent to the Galilean "acceleration".

We normalize the vector \vec{a} by dividing each of its terms by the magnitude of the vector, so

$$\frac{a^{\lambda}}{\alpha}$$
.

Since α is constant, and also the *direction* is constant, this means that the above expression is *also* constant, as the normalized components tell you about the direction. If we multiply a constant by a constant, we should still get a constant, so we multiply the above expression by α , getting a^{λ} to be constant.

In the MCRF of an object, $d\tau = dt$, and so we can write

$$\vec{a} = \frac{d\vec{U}}{dt} = \left(0, \frac{dU^1}{dt}, \frac{dU^2}{dt}, \frac{dU^3}{dt}\right),$$

which is analogous to the Galilean acceleration.

(b) A body is uniformly accelerated with $\alpha = 10 \,\mathrm{m/s^2}$. It starts from rest, and falls for a time t. Find its speed as a function of t, and find the time to reach v = 0.999.

$$\vec{U} \underset{\text{MCRF}}{\rightarrow} (1, 0, 0, 0)$$

$$\vec{\sigma} (\gamma, \gamma v, 0, 0)$$

$$\frac{d\vec{U}}{d\tau} \underset{\text{MCRF}}{\rightarrow} (0, \alpha, 0, 0)$$

$$\vec{\sigma} (\gamma, \gamma \alpha, 0, 0)$$

$$U^{x} = \int_{0}^{t} \frac{dU^{x}}{d\tau} d\tau = \int_{0}^{t} \gamma \alpha \frac{dt}{\gamma} = \int_{0}^{t} \alpha dt = \alpha t$$

$$= \gamma v = \frac{v}{\sqrt{1 - v^{2}}}$$

$$v^{2} = (\alpha t)^{2} (1 - v^{2}) = (\alpha t)^{2} - (\alpha t v)^{2}$$

$$v^{2} = \frac{(\alpha t)^{2}}{1 + (\alpha t)^{2}} \Longrightarrow v = \sqrt{\frac{(\alpha t)^{2}}{1 + (\alpha t)^{2}}}$$

To find the time to reach v=0.999, we go back to the expression $\gamma v=\alpha t$, solve for t, and substitute for v and α . Note that in natural units, $\alpha=10\,\mathrm{m/s^2}c^{-2}\approx 1.11\times 10^{-16}\,\mathrm{m^{-1}}$

$$t = \frac{v}{\alpha\sqrt{1 - v^2}} = \frac{0.999}{1.11 \times 10^{-16} \,\mathrm{m}^{-1} \sqrt{1 - 0.999^2}} \approx 2.01 \times 10^{17} \,\mathrm{m}.$$

24 Show that a positron and electron cannot annihilate to form a single photon, but they can annihilate to form two photons.

We consider the center of momentum frame, where $\sum \vec{p}_{(i)} \rightarrow_{\text{CM}} (E_{\text{total}}, 0, 0, 0)$. Without loss of generality, we assume that the velocities of the two particles are equal and opposite, such that

$$\vec{p}_{e^+} \rightarrow_{\text{CM}} m_e(\gamma, \gamma v, 0, 0), \qquad \qquad \vec{p}_{e^-} \rightarrow_{\text{CM}} m_e(\gamma, -\gamma v, 0, 0).$$

The photon they create will have to have a momentum of $\vec{p}_{\gamma,\text{single}} \rightarrow_{\text{CM}} (h\nu, h\nu, 0, 0)$. By conservation of four-momentum, we have

$$\begin{split} \vec{p}_{e^+} + \vec{p}_{e^-} &= \vec{p}_{\gamma, \rm single} \\ (\vec{p}_{e^+} + \vec{p}_{e^-}) \cdot (\vec{p}_{e^+} + \vec{p}_{e^-}) &= \vec{p}_{\gamma, \rm single} \cdot \vec{p}_{\gamma, \rm single} \\ (\vec{p}_{e^+} \cdot \vec{p}_{e^+}) + (\vec{p}_{e^-} \cdot \vec{p}_{e^-}) + (\vec{p}_{e^+} \cdot \vec{p}_{e^-}) &= 0 \\ -m_e^2 - m_e^2 - m_e^2 &= 0 \implies m_e = 0! \end{split}$$

Since we know that m_e is in fact non-zero, this cannot possibly happen.

Now consider the scenario wherein two photons are created, moving in opposite directions. Then they would have momenta: $\vec{p}_{\gamma,1} \to_{\text{CM}} (h\nu, h\nu, 0, 0)$ and $\vec{p}_{\gamma,2} \to_{\text{CM}} (h\nu, -h\nu, 0, 0)$. Invoking conservation of four-

momentum as before, we get

$$\begin{split} \vec{p}_{e^+} + \vec{p}_{e^-} &= \vec{p}_{\gamma,1} + \vec{p}_{\gamma,2} \\ (\vec{p}_{e^+} + \vec{p}_{e^-}) \cdot (\vec{p}_{e^+} + \vec{p}_{e^-}) &= (\vec{p}_{\gamma,1} + \vec{p}_{\gamma,2}) \cdot (\vec{p}_{\gamma,1} + \vec{p}_{\gamma,2}) \\ -3m_e^2 &= (\vec{p}_{\gamma,1} \cdot \vec{p}_{\gamma,1}) + (\vec{p}_{\gamma,1} \cdot \vec{p}_{\gamma,2}) + (\vec{p}_{\gamma,2} \cdot \vec{p}_{\gamma,2}) \\ &= 0 + (-h^2 \nu^2 - h^2 \nu^2) + 0 = -2h^2 \nu^2. \end{split}$$

so we end up with $3m_e^2 = 2h^2\nu^2$, meaning two photons are produced with $E^2 = \frac{3}{2}m_e^2$, which is entirely reasonable.

25

(a) Consider a frame $\bar{\mathcal{O}}$ moving with a speed v along the x-axis of \mathcal{O} . Now consider a photon moving at an angle θ from \mathcal{O} 's x-axis. Find the ratio of its frequency in $\bar{\mathcal{O}}$ and in \mathcal{O} .

We must first construct the particle's four-momentum. In the case where the photon was moving along the x-axis (see Section 2.7), it had been found that the four-momentum was

$$\vec{p} \xrightarrow{\mathcal{O}} (E, E, 0, 0),$$

as this satisfied

$$\vec{p} \cdot \vec{p} = -E^2 + E^2 = 0.$$
 (Schutz 2.37)

Now that the photon is moving at an angle θ from the x-axis, we need to redistribute the 3-momentum accordingly. No specification was given as photon's angle in the y- or z-axis, so without loss of generality, I assume it is constrained to the x-y plane. This means we can write the four-momentum as

$$\vec{p} \xrightarrow{\mathcal{O}} (E, E \cos \theta, E \sin \theta, 0),$$

which you can easily confirm satisfies $\vec{p} \cdot \vec{p} = 0$.

Now we may apply the Lorentz transformation $\Lambda^{\bar{0}}{}_{\alpha}(v)$ to find the photon's energy as observed by $\bar{\mathcal{O}}$, and from that the frequency.

$$p^{\bar{0}} = \bar{E} = \Lambda^{\bar{0}}{}_{\alpha} p^{\alpha} = \gamma p^{0} - v \gamma p^{1} + 0 + 0 = \gamma E - v \gamma E \cos \theta$$

$$\implies h \bar{\nu} = \gamma h \nu - v \gamma h \nu \cos \theta$$

$$\implies \frac{\bar{\nu}}{\nu} = \gamma - v \gamma \cos \theta = \frac{1 - v \cos \theta}{\sqrt{1 - v^{2}}}$$

(b) Even when the photon moves perpendicular to the x-axis ($\theta = \pi/2$) there is a frequency shift. This is the transverse Doppler shift, which is a result of time dilation. At which angle θ must the photon move such that there is no Doppler shift between \mathcal{O} and $\bar{\mathcal{O}}$?

To do this, we simply set $\bar{\nu}/\nu = 1$, and solve for θ .

$$1 = \frac{1 - v \cos \theta}{\sqrt{1 - v^2}} \implies \cos \theta = 1 - \sqrt{1 - v^2}$$
$$\implies \theta = \pm \arccos\left(1 - \sqrt{1 - v^2}\right)$$

(c) Now use Equations 2.35 and 2.38 to find $\bar{\nu}/\nu$.

Recall that $\vec{U} \to_{\mathcal{O}} (\gamma, v\gamma, 0, 0)$. Using Equation 2.35 we have

$$\bar{E} = h\bar{\nu} = -(E, E\cos\theta, E\sin\theta, 0) \cdot (\gamma, v\gamma, 0, 0)$$

$$= -(-(E\gamma) + E\gamma v\cos\theta) = E\gamma(1 - v\cos\theta) = h\nu\gamma(1 - v\cos\theta)$$

$$\frac{\bar{\nu}}{\nu} = \frac{1 - v\cos\theta}{\sqrt{1 - v^2}}$$

26 Calculate the energy required to accelerate a particle of rest mass m > 0 from speed v to speed $v + \delta v$ $(\delta v \ll v)$, to first order in δv . Show that it would take infinite energy to accelerate to c.

From the four-momentum we have $E_v = m\gamma$, and from that

$$E_{v+\delta v} = \frac{m}{\sqrt{1 - (v + \delta v)^2}}.$$

If we do a Taylor expansion on $(1 - (v + \delta v)^2)^{-1/2}$ we get

$$\frac{1}{\sqrt{1-v^2}} + \frac{v\,\delta v}{(1-v^2)^{3/2}} + \mathcal{O}\Big(v^2\Big),$$

so

$$E_{v+\delta v} \approx \frac{m}{\sqrt{1-v^2}} + \frac{mv \, \delta v}{(1-v^2)^{3/2}}$$
$$\Delta E = E_{v+\delta v} - E_v \approx \frac{mv \, \delta v}{(1-v^2)^{3/2}} = m\gamma^3 v \, \delta v \,.$$

As $v \to c$, $\gamma \to \infty$ and therefore $\Delta E \to \infty$.

- **30** A rocket ship has four-velocity $\vec{U} \to_{\mathcal{O}} (2,1,1,1)$, and it passes a cosmic ray with four-momentum $\vec{p} \to \mathcal{O}(300,299,0,0) \times 10^{-27} \text{kg}$. Compute the energy of the ray as measured by the rocket, using two different methods.
- (a) Find the Lorentz transformation from \mathcal{O} to the rocket's MCRF, and from that find the components $p^{\bar{\alpha}}$. The Lorentz transformation for a boost in the x, y, and z directions is given by

$$\Lambda^{ar{eta}}_{\phantom{ar{lpha}lpha}lpha} = egin{pmatrix} \gamma & \gamma v_x & \gamma v_y & \gamma v_z \ \gamma v_x & \gamma & 0 & 0 \ \gamma v_y & 0 & \gamma & 0 \ \gamma v_z & 0 & 0 & \gamma \end{pmatrix}.$$

If we write out the terms of

$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \gamma & \gamma v_x & \gamma v_y & \gamma v_z \\ \gamma v_x & \gamma & 0 & 0 \\ \gamma v_y & 0 & \gamma & 0 \\ \gamma v_z & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 1 \\ 1 \end{pmatrix},$$

then we are left with a system of equations

$$1 = \gamma(2 + v_x + v_y + v_z),$$

$$0 = \gamma(2v_x + 1),$$

$$0 = \gamma(2v_y + 1),$$

$$0 = \gamma(2v_z + 1).$$

Since γ may never be zero, we divide the last 3 terms by γ to obtain

$$2v_i + 1 = 0 \implies v_i = -\frac{1}{2},$$

and plugging into the first equation gives $\gamma = 2$. From this we see that our Lorentz transformation matrix is

$$\Lambda^{\bar{\beta}}_{\ \alpha} = \begin{pmatrix} 2 & -1 & -1 & -1 \\ -1 & 2 & 0 & 0 \\ -1 & 0 & 2 & 0 \\ -1 & 0 & 0 & 2 \end{pmatrix}.$$

Now to find the energy as observed by the rocket, we need to find $\bar{E} = p^{\bar{0}}$

$$\begin{split} p^{\bar{0}} &= \Lambda^{\bar{0}}{}_{\alpha} p^{\alpha} = 2 p^0 - p^1 - p^2 - p^3 \\ &= (2 \cdot 300 - 1 \cdot 299 - 1 \cdot 0 - 1 \cdot 0) \times 10^{-27} \text{kg} = 3.01 \times 10^{-25} \, \text{kg} = \bar{E} \end{split}$$

(b) Use Schutz's Equation 2.35.

$$\bar{E} = -\vec{p} \cdot \vec{U}_{\text{obs}} = -(-(300 \cdot 2) + (299 \cdot 1) + (0 \cdot 1) + (0 \cdot 1)) \times 10^{-27} \text{kg}$$
$$= 3.01 \times 10^{-25} \text{kg}$$

(c) Which is quicker? Why?

Using Equation 2.35 was much quicker, as it was derived to handle this special case.

32 Consider a particle with charge e and mass m, which begins at rest, but scatters a photon with frequency ν_i (Compton scattering). The photon comes off at an angle θ from the direction of the initial photon's path. Use conservation of four-momentum to find the scattered photon's frequency, ν_f .

We will invoke: conservation of four-momentum and $\vec{p} \cdot \vec{p} = -m^2$. \vec{p}_i and \vec{p}_f denote the initial and final

photon, and \vec{p}_e and $\vec{p}_{e'}$ denote the electron before and after collision.

$$\begin{split} \vec{p}_i & \xrightarrow{\mathcal{O}} \left(E_i, E_i, 0, 0 \right) \\ \vec{p}_e & \xrightarrow{\mathcal{O}} \left(m, 0, 0, 0 \right) \\ \vec{p}_f & \xrightarrow{\mathcal{O}} \left(E_f, E_f \cos \theta, E_f \sin \theta, 0 \right) \\ \vec{p}_i + \vec{p}_e & = \vec{p}_f + \vec{p}_{e'} \\ \vec{p}_{e'} & = \vec{p}_i + \vec{p}_e - \vec{p}_f \\ \vec{p}_{e'} & = \vec{p}_i + \vec{p}_e - \vec{p}_f \right) \cdot \left(\vec{p}_i + \vec{p}_e - \vec{p}_f \right) \\ -m^2 & = \vec{p}_i \cdot \vec{p}_i + \vec{p}_e \cdot \vec{p}_e + \vec{p}_f \cdot \vec{p}_f + 2(\vec{p}_i \cdot \vec{p}_i - \vec{p}_i \cdot \vec{p}_f - \vec{p}_e \cdot \vec{p}_f) \\ & = 0 - m^2 + 0 + 2(\vec{p}_i \cdot \vec{p}_i - \vec{p}_i \cdot \vec{p}_f - \vec{p}_e \cdot \vec{p}_f) \\ & = 0 - m^2 + 0 + 2(\vec{p}_i \cdot \vec{p}_i - \vec{p}_i \cdot \vec{p}_f - \vec{p}_e \cdot \vec{p}_f) \\ & = -E_i m - (-E_i E_f + E_i E_f \cos \theta) + E_f m \\ & = m(E_f - E_i) + E_i E_f (1 - \cos \theta) \\ m(E_i - E_f) & = E_i E_f (1 - \cos \theta) \\ mh(\nu_i - \nu_f) & = h^2 \nu_i \nu_f (1 - \cos \theta) \\ & \frac{\nu_i - \nu_f}{\nu_i \nu_f} & = h \frac{1 - \cos \theta}{m} \\ & \frac{1}{\nu_f} - \frac{1}{\nu_i} & = h \frac{1 - \cos \theta}{m} \\ & \frac{1}{\nu_f} & = \frac{1}{\nu_i} + h \frac{1 - \cos \theta}{m} \end{split}$$