Spring School 2024 @Izukawana

Moduli stabilization on (for/at/in?) supersymmetric magnetized D9-brane model

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*I will speak in Japanese though this slide is written in English.

Topics

- Reviewing the senior thesis
- Reporting progress and difficulties I met

Introduction

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in its 4d effective field theory.

Such a field is called **moduli fields**.

Moduli stabilization

The metrics in 10-dimensional spacetime are dynamical fields:

$$\begin{split} \mathrm{d}s^{10} &= G_{MN}(X) \mathrm{d}X^M \mathrm{d}X^N \\ &= g_{\mu\nu}(x,y) \mathrm{d}x^\mu \mathrm{d}x^\nu + g_{mn}(x,y) \mathrm{d}y^m \mathrm{d}y^n \end{split}$$

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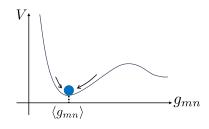
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How?

What we have to do is just

- Write down the potential for moduli (e.g. g_{mn})
- Compute the minimum and identify the value $\langle q_{mn} \rangle$



These procedures are called **moduli stabilization**.

Purpose of our study

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We will discuss the moduli stabilization on magnetized torus model.

Magnetized torus model

Torus compactification and Magnetic flux

Torus compactification

• Compactifying 6d extra dimensions for three tori $(T^2)^3$.



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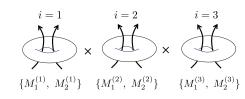
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Magnetic flux

Assigning the magnetic flux

$$M_a^{(i)} \ (a=1,2)$$

for two gauge fields on each tori.



By magnetic fluxes in an extra dimension, moduli $\mathcal{A}^{(i)}(x)$ obtain its potential $V^{(D)}$.



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Potential by magnetic fluxes

$$F^{MN}F_{MN} = F^{\mu
u}F_{\mu
u} + F^{mn}F_{mn} + \cdots$$

$$m{V^{(D)}} = \pi^2 \prod_i \mathcal{A}^i imes \left\{ \left(\sum_i rac{M_1^{(i)}}{\mathcal{A}^{(i)}}
ight)^2 + \left(\sum_i rac{M_2^{(i)}}{\mathcal{A}^{(i)}}
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$$\longrightarrow rac{M_a^{(1)}}{\langle \mathcal{A}^{(1)}
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Relation of the VEVs $\langle \mathcal{A}^{(1)} \rangle$, $\langle \mathcal{A}^{(2)} \rangle$, $\langle \mathcal{A}^{(3)} \rangle$

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The ratios of the moduli's VEVs are determined by the fluxes potential.

Summary so far

• We could stabilize the moduli and obtain the ratio of its VEVs $\langle \mathcal{A}^{(1)} \rangle / \langle \mathcal{A}^{(2)} \rangle$ & $\langle \mathcal{A}^{(1)} \rangle / \langle \mathcal{A}^{(3)} \rangle$.

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$$T \propto \langle \mathcal{A}^{(1)} \rangle, \langle \mathcal{A}^{(2)} \rangle, \langle \mathcal{A}^{(3)} \rangle$$

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- But the **overall factor** *T* is undetermined.

$$T \propto \langle \mathcal{A}^{(1)} \rangle, \langle \mathcal{A}^{(2)} \rangle, \langle \mathcal{A}^{(3)} \rangle$$

Introducing a potential that has a different origin than the magnetic fluxes to stabilize overall factor T.

Determination of the overall factor

F-term potential

Effective potential for moduli T

- Its effective theory remains supersymmetric.
- Supersymmetric action is determined
 by super potential W and Kähler potential K.
- We will study the following potential now[3]:

$$egin{cases} W = w_0 - Ae^{-aT} + BX \ K = -3\ln(T+ar{T}) + |X|^2 \end{cases}$$

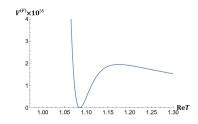
Introducing a new scalar field X and w_0, A, B, a are parameters.

F-term potential

*We set the Planck constant as $M_{\rm Pl}$ ($\sim 2.4 \times 10^{18}$ GeV) = 1.

Scalar potential

$$V^{(F)}=e^K(K^{Iar{J}}(D_IW)(D_{ar{J}}ar{W})-3|W|^2)$$
 s $\left\{egin{aligned} D_IW&\equiv\partial_IW+K_IW\ K^{Iar{J}}: & ext{inverse matrix of }K_{Iar{J}} \end{aligned}
ight.$ $(I=X,T)$



Parameters

$$w_0\sim 2.17 imes 10^{-18}\ ,\ a=4\pi^2\ ,\ A=1\ ,\ B=e^{-4\pi^2}$$
 and $\langle X
angle=\sqrt{3}-1$
$$\to \langle T
angle\sim 1.085$$

Report progresses

In my senior thesis, we

- fix the value of the fluxes $M_a^{(i)}$
- ullet and compute the area of the tori $\langle \mathcal{A}^{(i)}
 angle \ (i=1,2,3).$

Report progresses

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- and compute the area of the tori $\,\langle {\cal A}^{(i)} \rangle\,\,(i=1,2,3).\,\,$ During this vacation I mainly

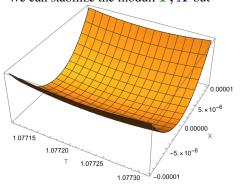
During this vacation, I mainly studied the F-term potential more general form:

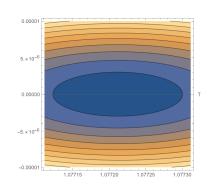
$$egin{cases} W = w_0 - Ae^{-aT} + B \dot{e}^{-bT} X \ K = -3 \ln(T + ar{T}) + |X|^2 - rac{1}{\Lambda^2} |X|^4 \end{cases}$$

Wavy factors are the difference from the previous one.

Report progresses

We can stabilize the moduli T, X but \cdots





Parameters

$$A=B=1, a=b=4\pi^2, w_0=10^{-17}, \Lambda=10^{-4} \ \longrightarrow \ \langle T \rangle \sim 1.07, \ \langle X \rangle \sim 10^{-8}, \ V_{\min} \sim -10^{-35}$$

Difficulites

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- But it is difficult (at least for me) since
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to choose the parameters and find the minimum for each time.



I want to find more efficient ways to search the set of parameters.

$$\underline{\text{e.g.}} \quad \frac{\partial V}{\partial T} = \frac{\partial V}{\partial X} = 0 \quad \& \quad \frac{\partial V}{\partial a} = \frac{\partial V}{\partial b} = \frac{\partial V}{\partial A} = \frac{\partial V}{\partial B} = \frac{\partial V}{\partial w_0} = 0$$

(I tried it but it seems not to converge the Newtonian method...)

Summary & Future Works

Summary

- Discussing moduli stabilization in magnetized torus model
- ullet Determining the ratio of the moduli by potential $V^{(D)}$ with fluxes
- ullet Stabilizing the overall moduli T by potential $V^{(F)}$ that has a different origin

Future Works

- [new!] Finding more efficient ways to search the set of parameters.
- Discussing soft SUSY breaking and mass of supersymmetric particles, etc.

Reference

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