Template

```
#include<bits/stdc++.h>
#define pb push_back
#define mp make_pair
#define fs first
#define sd second
using namespace std;
typedef long long II;
typedef unsigned long long ull;
typedef pair<II,II> pl;
typedef vector<II> vI;
typedef vector<pair<|I,|I>> v|I;
typedef vector<pair<|I,pl>> vIII;
typedef priority_queue < ll, vector < ll>, greater < ll>> minh;
const int N = 1e6 + 3, Mod = 1e9 + 7;
const int maxN=1e3+3;
void solve(){
}
int main(){
        ios_base::sync_with_stdio(false);
        cin.tie(nullptr);
        cout.tie(nullptr);
        int t=1;
```

Data Structres

```
#include<bits/stdc++.h>
using namespace std;
typedef vector<int> vi;
const int N=1e6+3, Mod=1e9+7;
const int maxN=1e4+2;
//union find disjoint set
class dsu{
      private:
             vl p, rank, setSize;
             int numSets;
      public:
             dsu(int n){
                    setSize.assign(n,1);
                    numSets=n;
                    rank.assign(n,0);
                    p.assign(n,0);
                    for(int i=0;i<n;i++)p[i]=i;</pre>
             }
             int findP(int i){
                    return (p[i]==i)?i:findP(p[i]);
             }
             bool isSameP(int a, int b){
                    return findP(a)==findP(b);
             }
             void unite(int a, int b){
                    if(!isSameP(a,b)){
                           numSets--;
                           int x=findP(a);
                           int y=findP(b);
                           if(rank[x]>rank[y]){
```

```
p[y]=x;
                                 setSize[x]+=setSize[y];
                          }else{
                                 p[x]=y;
                                 setSize[y]+=setSize[x];
                                 if(rank[x]==rank[y])rank[y]++;
                          }
                    }
             }
             int totSets(){
                    return numSets;
             }
             int sizeOfSet(int i){
                    return setSize[findP(i)];
             }
};
//segment tree (single update)
int a[maxN]; //tree source
struct info {
      int 1, r, f1, fr, sz;
      long long tot;
} d[maxN * 4]; //tree storage
info operator + (info a, info b) {
      info c;
      c.l = a.l;
      c.r = b.r;
      c.sz = a.sz + b.sz;
      c.fl = (a.fl == a.sz \&\& a.r <= b.l) ? (a.fl + b.fl) : a.fl;
      c.fr = (b.fr == b.sz && a.r <= b.l) ? (b.fr + a.fr) : b.fr;
```

```
c.tot = a.tot + b.tot + ((a.r \le b.l) ? (111 * a.fr * b.fl) : 0);
      return c;
} //merging two datas (ans)
void build(int k, int l, int r) \{ //(1,1,n) \}
      if (1 == r) {
             d[k] = (info) \{a[1], a[1], 1, 1, 1, 111\};
      } else {
             int mid = (1 + r) / 2;
             build(k * 2, 1, mid);
             build(k * 2 + 1, mid + 1, r);
             d[k] = d[k * 2] + d[k * 2 + 1]; //operator +
      }
}
//rebuild, only with node x, change the array directly
void update(int k, int l, int r, int x) { //(1,1,n,node)
      if (1 == r) {
             d[k] = (info) {a[l], a[l], 1, 1, 1, 1ll};
      } else {
             int mid = (1 + r) / 2;
             if (x \leftarrow mid) update(k * 2, 1, mid, x);
             else update(k * 2 + 1, mid + 1, r, x);
             d[k] = d[k * 2] + d[k * 2 + 1]; //operator +
      }
}
info query(int k, int l, int r, int x, int y) { //(1,1,n,leftq,rightq)
      if (1 == x \&\& r == y) {
             return d[k];
      } else {
```

```
int mid = (1 + r) / 2;
             if (y \leftarrow mid) return query(k * 2, 1, mid, x, y);
             else if (x > mid) return query(k * 2 + 1, mid + 1, r, x, y);
             else return query(k * 2, l, mid, x, mid) + query(k * 2 + 1, mid + 1, r,
mid + 1, y); //operator +
      }
}
//fenwick tree
class fenwick{
      private:
             vl ft;
      public:
             fenwick(int n){
                    ft.assign(n+1,0);
             }
             int rsq(int b){
                    int ret=0;
                    for(;b;b-=(b&(-b)))ret+=ft[b];
                    return ret;
             }
             int rsq(int a,int b){
                    return rsq(b)-(a==1?0:rsq(a-1));
             }
             void update(int i, int val){
                    for(;i<(int)ft.size();i+=(i&-i))ft[i]+=val;</pre>
             }
};
```

Algorithms

```
//Binary Search
11 binser(ll 1,ll r,ll val){
       if(l>=r)return 1;
       11 \text{ mid}=(1+r)/2;
       //printf(".%d",mid);
       if(arr[mid]==val)return mid;
       if(arr[mid]>val&&arr[mid-1]<val)return mid;</pre>
       if(arr[mid]>val) return binser(l,mid-1,val);
       if(arr[mid]<val) return binser(mid+1,r,val);</pre>
}
//fast C(N,K)
int n, k;
long long fact[N], invf[N], inv[N];
long long modpow(long long x, long long y) {
    long long ret = 1;
    while (y > 0) {
        if (y \& 1) ret = (ret * x) % Mod;
        y >>= 1;
        x = (x * x) \% Mod;
    }
    return ret;
}
void preprocess() {
    fact[0] = invf[0] = 1;
    for (int i = 1; i < N; i++) {
        fact[i] = (fact[i - 1] * i) % Mod;
        invf[i] = modpow(fact[i], Mod - 2);
        inv[i]=modpow(i,Mod-2);
```

```
}

long long C(int a, int b) {
   if (a < b) return 0;
   long long ret = (fact[a] * invf[a - b]) % Mod;
   ret = (ret * invf[b]) % Mod;
   return ret;
}

//Dijkstra</pre>
```

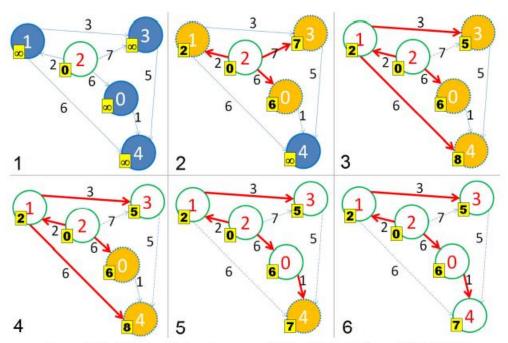


Figure 4.17: Dijkstra Animation on a Weighted Graph (from UVa 341 [47])

//Bellman Ford

//Floyd Warshall

//Articulation Point

```
void articulationPointAndBridge(int u) {
  dfs_low[u] - dfs_num[u] - dfsNumberCounter++; // dfs_low[u] <- dfs_num[u]
  for (int j = 0; j < (int)AdjList[u].size(); <math>j++) {
   ii v = AdjList[u][j];
   if (dfs_num[v.first] == UNVISITED) {
                                                            // a tree edge
      dfs_parent[v.first] = u;
     if (u == dfsRoot) rootChildren++; // special case if u is a root
      articulationPointAndBridge(v.first);
     if (dfs_low[v.first] >= dfs_num[u])
                                                // for articulation point
       articulation_vertex[u] = true;
                                          // store this information first
      if (dfs_low[v.first] > dfs_num[u])
                                                             // for bridge
       printf(" Edge (%d, %d) is a bridge\n", u, v.first);
      dfs_low[u] - min(dfs_low[u], dfs_low[v.first]); // update dfs_low[u]
    else if (v.first != dfs_parent[u]) // a back edge and not direct cycle
      dfs_low[u] = min(dfs_low[u], dfs_num[v.first]); // update dfs_low[u]
```

//Tarjan SCC

```
void tarjanSCC(int u) {
 dfs_low[u] = dfs_num[u] = dfsNumberCounter++; // dfs_low[u] <= dfs_num[u]
 S.push_back(u); // stores u in a vector based on order of visitation
 visited[u] = 1;
 for (int j = 0; j < (int)AdjList[u].size(); <math>j++) {
   ii v = AdjList[u][j];
   if (dfs_num[v.first] == UNVISITED)
     tarjanSCC(v.first);
   if (visited[v.first])
                                                   // condition for update
     dfs_low[u] = min(dfs_low[u], dfs_low[v.first]); }
 if (dfs_low[u] == dfs_num[u]) { // if this is a root (start) of an SCC
   printf("SCC %d:", ++numSCC); // this part is done after recursion
   while (1) {
     int v = S.back(); S.pop_back(); visited[v] = 0;
     printf(" %d", v);
     if (u == v) break; }
   printf("\n");
```

```
//Toposort, lexicographically smallest (inside main)
      11 n,m; cin>>n>m;
      for(int i=0;i<m;i++){</pre>
             11 x,y; cin>>x>>y;
             adj[x].pb(y);
             w[y]++;
      }
      vl ans;
      priority_queue <11, vector<11>, greater<11>>pq;
      for(ll i=1;i<=n;i++){</pre>
             if(w[i])continue;
             pq.push(i);
      }
      while(!pq.empty()){
             11 idx=pq.top(); pq.pop();
             ans.pb(idx);
             for(auto v: adj[idx]){
                    w[v]--;
                    if(!w[v])pq.push(v);
             }
      }
// Cycle-finding DFS
11 adj[maxN];
11 w[maxN];
int visit[maxN];
vl path;
ll ans=0;
void dfs(ll i){
      path.pb(i);
      visit[i]=1;
```

```
if(visit[adj[i]]==1){
             int n=path.size()-1;
             11 ret=w[path[n]];
             while(path[n]!=adj[i]){
                    ret=min(ret,w[path[n]]); //or pb to cycle list
                    n--;
             }
             ret=min(ret,w[path[n]]);
             ans+=ret;
      }
      if(visit[adj[i]]==0){
             dfs(adj[i]);
      }
      visit[i]=2;
}
//Bipartite (Color 1,2)
vl adj[maxN];
int col[maxN];
int cnt[3];
bool f=1;
int xxor(int a){
      if(a==1)return 2;
      else return 1;
}
bool dfs(int u){
      for(auto v:adj[u]){
             if(col[v]==0){
                    col[v]=xxor(col[u]);
```

} } }

```
cnt[col[v]]++;
                    if(!dfs(v))return 0;
             }
             else if(col[v]!=xxor(col[u])){
                    f=0;
                    return 0;
             }
      }
      return 1;
}
//KMP String
 #define MAX_N 100010
 char T[MAX_N], P[MAX_N];
                                                   // T = text, P = pattern
 int b[MAX_N], n, m; // b = back table, n = length of T, m = length of P
                                  // call this before calling kmpSearch()
 void kmpPreprocess() {
   int i = 0, j = -1; b[0] = -1;
                                                         // starting values
                                        // pre-process the pattern string P
  while (i < m) {
     while (j \ge 0 \&\& P[i] != P[j]) j = b[j]; // different, reset j using b
     i++; j++;
                                         // if same, advance both pointers
     b[i] = j; // observe i = 8, 9, 10, 11, 12, 13 with j = 0, 1, 2, 3, 4, 5
 } }
                              // in the example of P = "SEVENTY SEVEN" above
 void kmpSearch() { // this is similar as kmpPreprocess(), but on string T
   int i = 0, j = 0;
                                                         // starting values
   while (i < n) {
                                                 // search through string T
     while (j >= 0 && T[i] != P[j]) j = b[j]; // different, reset j using b
     i++; j++;
                                          // if same, advance both pointers
     if (j == m) {
                                               // a match found when j == m
       printf("P is found at index %d in T\n", i - j);
       j = b[j];
                                   // prepare j for the next possible match
```

Math

//Floyd's Hare and Turtle

//Grundy Nim

is a losing state).

Let G(u) be the Grundy number of a pile with u stones. The Grundy number of a terminal state is 0; otherwise, G(u) is recursively defined as the **minimum excludant** of the Grundy numbers of all the states it points to. We usually write minimum excludant as **mex**, and it basically means "return the smallest nonnegative integer that is **not** in this set." Let's consider a basic example, such as the Nim game where you can only take a square number of stones from a pile. If there is a pile with 5 stones, then we can take $1^2=1$ stone and transition to a pile with 4 stones, or take $2^2=4$ stones and transition to a pile with 1 stone. So, G(5)=mex(G(5-1),G(5-4))=mex(G(4),G(1))=mex(2,1)=0. So, it turns out that a pile with 5 stones in it is a loss state (you can verify the values of G(4) and G(1) for yourself, but even without Grundy numbers, you should be able to see why 5 stones

How about when there are multiple piles though? Amazingly, we can apply the same strategy we did earlier for Nim, except on the Grundy numbers. The important Sprague-Grundy theorem states that these games are equivalent to playing Nim, but instead of getting the Nim-sum by taking the XOR of the piles, we take the XOR of their Grundy numbers.

Let's consider that square number Nim again. We see that the Grundy numbers for 0,1,2,3,4,5,6 are 0,1,0,1,2,0,1, respectively. You can verify this. Therefore, if we have a game state with piles of 1,2,3,4,6 stones, the Nim-sum of this game is $G(1) \oplus G(2) \oplus G(3) \oplus G(4) \oplus G(6) = 1 \oplus 0 \oplus 1 \oplus 2 \oplus 1 = 3$, which is non-zero, therefore the first player has a winning strategy.

//Catalan Numbers

5.4.3 Catalan Numbers

First, let's define the *n*-th Catalan number—written using binomial coefficients notation ${}^{n}C_{k}$ above—as: $Cat(n) = ({}^{(2\times n)}C_{n})/(n+1)$; Cat(0) = 1. We will see its purpose below.

If we are asked to compute the values of Cat(n) for several values of n, it may be better to compute the values using bottom-up Dynamic Programming. If we know Cat(n), we can compute Cat(n+1) by manipulating the formula like shown below.

```
\begin{split} Cat(n) &= \frac{2n!}{n!\times n!\times (n+1)}.\\ Cat(n+1) &= \frac{(2\times (n+1))!}{(n+1)!\times (n+1)!\times ((n+1)+1)} = \frac{(2n+2)\times (2n+1)\times 2n!}{(n+1)\times n!\times (n+1)\times n!\times (n+2)} = \frac{(2n+2)\times (2n+1)\times ...[2n!]}{(n+2)\times (n+1)\times ...[n!\times n!\times (n+1)]}.\\ \text{Therefore, } Cat(n+1) &= \frac{(2n+2)\times (2n+1)}{(n+2)\times (n+1)}\times Cat(n).\\ \text{Alternatively, we can set } m=n+1 \text{ so that we have: } Cat(m) = \frac{2m\times (2m-1)}{(m+1)\times m}\times Cat(m-1). \end{split}
```

⁹Binomial is a special case of polynomial that only has two terms.

Catalan numbers are found in various combinatorial problems. Here, we list down some of the more interesting ones (there are several others, see **Exercise 5.4.4.8***). All examples below use n = 3 and $Cat(3) = \binom{(2\times3)}{3}/(3+1) = \binom{6}{3}/4 = 20/4 = 5$.

1. Cat(n) counts the number of distinct binary trees with n vertices, e.g. for n=3:



- 2. Cat(n) counts the number of expressions containing n pairs of parentheses which are correctly matched, e.g. for n = 3, we have: ()()(), ()(()), (())(), ((())), and (()()).
- 3. Cat(n) counts the number of different ways n+1 factors can be completely parenthesized, e.g. for n=3 and 3+1=4 factors: {a, b, c, d}, we have: (ab)(cd), a(b(cd)), ((abc)(d), and a((bc)d).
- 4. Cat(n) counts the number of ways a convex polygon (see Section 7.3) of n + 2 sides can be triangulated. See Figure 5.1, left.
- 5. Cat(n) counts the number of monotonic paths along the edges of an $n \times n$ grid, which do not pass above the diagonal. A monotonic path is one which starts in the lower left corner, finishes in the upper right corner, and consists entirely of edges pointing rightwards or upwards. See Figure 5.1, right and also see Section 4.7.1.

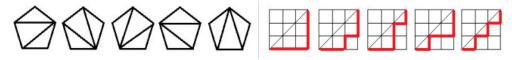


Figure 5.1: Left: Triangulation of a Convex Polygon, Right: Monotonic Paths