

Article

# Method for In-Operando Contamination of Lithium Ion Batteries for Prediction of Impurity-Induced Non-Obvious Cell Damage

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**Abstract:** The safety of lithium-ion batteries within electrified vehicles plays an important role. Hazards can arise from contaminated batteries resulting from non-obvious damages or insufficient production processes. A systematic examination requires experimental methods to provoke a defined contamination. Two prerequisites were required: First, the extent and type of contamination should be determinable to exclude randomness. Second, specimens should work properly before the contamination, enabling realistic behavior. In this study, two experimental methods were developed to allow for the first time a controlled and reproducible application of water or oxygen into 11 single-layer full cells ( $\text{Li}_4\text{Ti}_5\text{O}_{12}/\text{LiCoO}_2$ ) used as specimens during electrical cycling. Electrochemical impedance spectroscopy was used to continuously monitor the specimens and to fit the parameters of an equivalent circuit model (ECM). For the first time, these parameters were used to calibrate a machine-learning algorithm which was able to predict the contamination state. A decision tree was calibrated with the ECM parameters of eight specimens (training data) and was validated by predicting the contamination state of the three remaining specimens (test data). The prediction quality proved the usability of classification algorithms to monitor for contaminations or non-obvious battery damage after manufacturing and during use. It can be an integral part of battery management systems that increases vehicle safety.

**Keywords:** lithium-ion battery; safety; in operando; contamination; electrochemical impedance spectroscopy; equivalent circuit model; machine learning; classification algorithm; decision tree



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## 1. Introduction

As we face the challenges of global warming, a significant reduction in greenhouse gas emissions will be an necessary step. Power train electrification is one way to lower the carbon intensity of transportation [1]. Lithium-ion (Li-Ion) batteries are widely used for power train electrification due to their advantageous characteristics compared to other battery technologies (i.e., high energy and power density [2,3]). The increased application of Li-Ion technology as storage for vehicle propulsion energy is bringing battery safety into focus [4–7] as it comes with a number of downsides. Damage to a Li-Ion battery may lead to severe reactions (i.e., smoke, fire, explosion) [8]. The causes and failure mechanisms for this [9–12], together with the consequences of battery damage [12–23] have been extensively discussed in the literature. In addition to other failure causation, adverse processes due to the contamination of the electrode material [24,25] may not be obvious in the first place and can lead to catastrophic reactions such as thermal runaway. Contamination (i.e., water, oxygen) may be introduced to the cell, i.e., during manufacturing due to the insufficient drying of materials [26,27], the aging of the cell housing [25], or due to defects of the cell housing that may result from mechanical loads on the battery. Moisture attributes in the decomposition of organic electrolytes promote further side reactions and degradation and have

been investigated by several authors [26–32]. Different studies have revealed that moisture has a negative impact on battery performance and lifetime [27,33–36]. Furthermore, oxygen can affect battery performance as degradation reactions occur with the electrolyte and other components [37,38]. The described degradation mechanisms lead to the aging of battery cell components. Subsequently, aging has an impact on the mechanical and crash behavior of a battery cell, which affects the battery cell safety [39]. As the described degradation mechanisms can be safety-relevant, a determination of the contamination state in advance is of interest. For research purposes, a systematic examination must be enabled in the form of an intentional and reproducible contamination. A contamination must be repeatedly applied in adjustable quantities and should not affect the battery cell during normal operation prior to contamination. Methods to provoke, monitor and examine damage, i.e., the internal short circuit (ISC) of lithium ion cells, have been presented in the literature [40–42]. ISCs were intentionally produced by the manipulation of battery cells during production, i.e., an ISC trigger by means of implanted phase change materials [43–45], perforated separator [46,47], or shape memory alloys [48]. Battery cells were contaminated with metal particles during production to provoke ISC by dendrite growth promotion [40,49]. Volck et al. [50] and Santhanagopalan et al. [51] triggered an ISC by applying an external load on a battery cell manipulated with metal particles (i.e., copper or nickel). A main drawback of the mentioned methods which introduce particles is that cell contamination is already present at specimen assembly. The proper principal functionality of the specimen cannot be guaranteed by this. Contamination by battery cell damage will occur during usage. An experimental method should therefore guarantee a trigger during electric cycling without affecting the electrochemical behavior of the battery cell. A method meeting this requirement for in operando contamination with water and oxygen has not been reported in the literature to date. In different studies, measurements were performed to monitor battery cell parameters. Electrochemical impedance spectroscopy (EIS) is a common tool to measure the electrical properties of battery cells, i.e., the state of charge (SOC), state of health (SOH) or fault detection [52–54]. EIS can be used to fit equivalent circuit models (ECMs) which represent the electrochemical behavior of the cell. Different frequency ranges of the measured impedance are attributed to specific circuit elements and chemical processes. The measured battery cell impedance and derived equivalent circuit elements can be processed by machine-learning (ML) algorithms. In the literature, ML has been used to estimate, predict and monitor different battery parameters [55–60], i.e., for SOC estimation, SOH estimation, fault diagnostic and ISC detection.

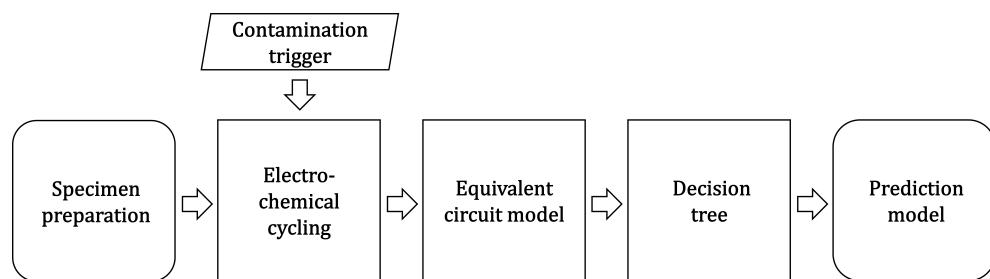
In this paper, a non-destructive method is presented to determine whether a cell is affected by the contamination of the electrode material. As no experimental method fulfilling the requirements (reproducibility, adjustable contaminant quantity, minor effect on electrochemical properties) was found in the literature, we present novel experimental methods for the reproducible application of contaminants (i.e., water, oxygen) during electrochemical cycling. Machine-learning algorithms (i.e., decision tree) were used in the literature to recognize battery degradation. However, the evaluation of a contamination state as such has never previously been conducted with the help of machine-learning algorithms and will be shown within this manuscript. Therefore, two research questions will be answered within this manuscript:

- How can contamination be intentionally introduced and reproducible in a battery cell without affecting its electrochemical behavior beforehand?
- How can a water or oxygen contamination of a battery cell be predicted?

## 2. Method

The effects of different types of contamination (water and oxygen) were examined in a series of novel experiments. Eleven single-layer full battery cells were built and equipped with a contamination trigger. During electrochemical cycling, contamination in the form of water or oxygen was introduced into the specimens. EIS was conducted to evaluate the impedance of the specimen. Additionally, voltage, transferred charge and

Coulombic efficiency was continuously tracked. A set of specimens without contamination was subjected to the same procedure as a reference. Parameters for an ECM were derived from the measurement data. These parameters were used to calibrate a decision tree algorithm able to predict the contamination state of the specimen. The eligibility of the decision tree algorithm to predict specimen contamination and to distinguish between different types of contamination was proofed by a set of validation data. Figure 1 illustrates the approach and was described in detail hereafter.



**Figure 1.** Solving the approach to approve the feasibility of the novel contamination trigger and the ability of a decision tree algorithm to predict a contamination.

### 2.1. Specimen Preparation

Eleven single-layer full battery cells were manually produced to implement a contamination trigger into the battery cells. Lithium titanate oxide  $\text{Li}_4\text{Ti}_5\text{O}_{12}$  (LTO) was chosen for the negative active material. Lithium–cobalt(III)–oxide  $\text{LiCoO}_2$  (LCO) was chosen for the positive active material. The LTO showed negligible cycle aging [61,62]. At 1.55 V vs.  $\text{Li}^+/\text{Li}$  the LTO operating potential is well within the electrochemical stability window of the electrolyte. Consequently, no solid electrolyte interphase (SEI) forms at the LTO electrode and the cell operates within the thermodynamically stable domain. By ruling out the aging effects caused by electrochemical cycling, changes in the electrochemical behavior were explicitly correlated with the effects from contamination (i.e., the degradation of active materials).

Conductive carbon black (TIMCAL SUPER C65) was added to the active material slurry for both electrodes as a conductive additive. An electrode binder (Arkema Kynar® 2801) was used to dissolve active material components. N-Methyl-2-pyrrolidone (NMP) was used as a solvent for electrode preparation. The ratio of 1:1 and 1:3 between the solid electrode components (active material, conductive carbon black and electrode binder) and the NMP was used for the cathode and anode, respectively. A ball mill homogenized the slurry components. The anode slurry was mixed with 3 zirconium dioxide ( $\text{ZrO}_2$ ) balls. The mixing procedure consisted of 3 repetitions over a period of 5 min at a speed of  $300 \text{ min}^{-1}$  and a break of 5 min between the repetitions. The cathode slurry was mixed with 3  $\text{ZrO}_2$  balls. The cathode slurry was milled with three repetitions each 15 min at a speed of  $300 \text{ min}^{-1}$  and a 5 min break between the repetitions.

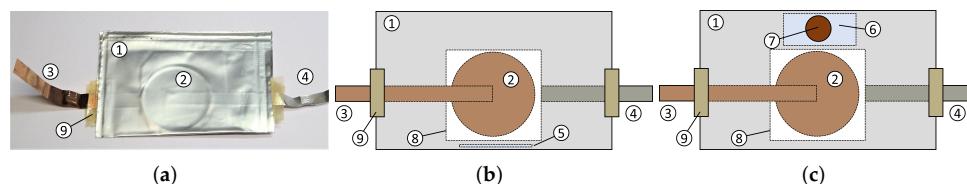
The active material of the cathode was applied on an aluminum foil with a layer thickness of 50  $\mu\text{m}$ . The active material of the anode was applied on a copper foil with a layer thickness of 200  $\mu\text{m}$ . The capacity was limited by the cathode to avoid lithium plating by balancing the electrode masses, accordingly. The coated foils were dried for 12 h at 100 °C in a drying oven. Discs of 28 mm in diameter were punched out of the electrode material. Table 1 lists the contents and layer thickness of the active materials used in this study.

**Table 1.** Chemical composition of the electrode slurry and the applied layer thickness.

	LCO wt%	LTO wt%	Super C65 wt%	Electrode Binder wt%	Layer Thickness μm
Cathode	88.3	-	6.3	5.4	50
Anode	-	80.0	13.0	7.0	200

wt%—weight percentage.

The specimens were assembled in an inert argon atmosphere. All components were first dried to avoid prior moisture contamination. To establish a robust external electrical contact, copper or aluminum stripes were fixed on the electrodes with adhesive tape. A separator (Freudenberg 2226) with a thickness of 0.18 mm and a pore volume of 68% was drenched with 120  $\mu$ L of electrolyte (1 mol LiPF<sub>6</sub> in EC/DMC 1:1 wt%) (BASF Selecti-Lyte™LP30). The separator was placed between the positive and negative electrodes. A pouch foil with 100  $\mu$ m thickness was wrapped around the electrode stack and welded. A hot melt adhesive guaranteed proper tightness in the tab area. Outside the inert atmosphere, the pouch was welded a second time with a vacuum welding machine to guarantee an airtight assembly. Figure 2a shows an assembled and sealed specimen.

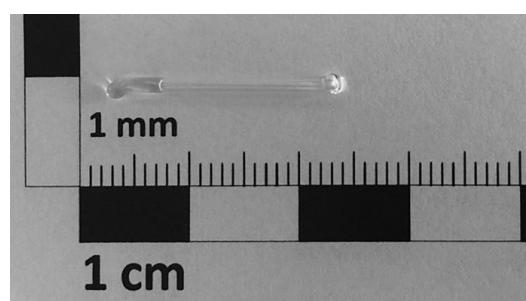


**Figure 2.** Assembled specimen (a) and principle sketches of specimen prepared for contamination with water (b) and oxygen (c). 1—pouch; 2—electrode stack; 3—negative copper tab; 4—positive aluminum tab; 5—glass container; 6—ZrO<sub>2</sub> plate; 7—self-healing injection port; 8—separator; 9—hot melt adhesive. (a) Specimen. (b) Water contamination. (c) Oxygen contamination.

## 2.2. Contamination Trigger

Some specimens were modified to investigate the different contamination triggers as a means of finding novel in operando trigger methods for water or oxygen contamination. A contamination trigger method should provide a repeatable application of different quantities of contaminant with only a minor effect on the battery cell during normal operation.

The precise application of water contamination was realized by applying the desired water quantity to a glass container, as can be seen in Figure 3. A glass container with an open-end was filled with 2  $\mu$ L of water by a high-precision syringe. The glass container was closed by melting the open end by locally heating with a punctual flame. The glass container was placed within the specimen before welding the pouch foil. During the experiment, contamination with water was triggered by breaking the glass container. The principal assembly of the specimens equipped with a glass container for contamination with water can be taken from Figure 2b.



**Figure 3.** Glass container filled with 2  $\mu$ L of water for assembly inside the specimen.

The precise application of contamination with oxygen was realized by external application using a syringe. A ZrO<sub>2</sub> plate was placed inside the specimen next to the electrode stack before the pouch foil was welded. A self-healing injection port (i.e., septum) was glued on the pouch foil in the area of the ceramic plate. By inserting the cannula of the syringe, high-purity oxygen (99.999%) was injected into the cell to trigger contamination. The self-healing injection port prevented further contamination with the environmental atmosphere by closing itself after removing the cannula. The ZrO<sub>2</sub> plate prevented the penetration of the pouch foil on the opposite side. The principal assembly of the specimens equipped with the ZrO<sub>2</sub> plate and the self-healing injection port for contamination with oxygen can be taken from Figure 2c.

In sum, four specimens (No. 01–04) were used as a reference. Specimens No. 03 and No. 04 were equipped with a ZrO<sub>2</sub> plate to investigate its influence on the electrochemical behavior. Four specimens (No. 05–08) were equipped with a glass container for water contamination. Three specimens (No. 09–11) were equipped with a ZrO<sub>2</sub> plate and a self-healing injection port for contamination with oxygen, as can be seen in Table 2.

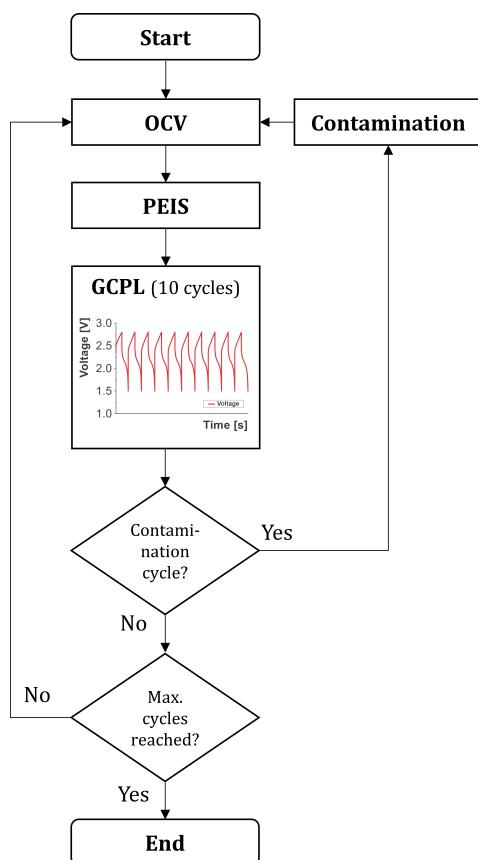
**Table 2.** Test matrix consisting of specimens with corresponding capacity after formation (10 cycles), contamination type and contamination cycle.

Specimen No.	Capacity after Formation mAh	Loops	Contamination	Contamination Cycle
01 *	0.7	50	Reference	-
02	2.4	50	Reference	-
03 *	2.6	11	Reference	-
04	2.2	11	Reference	-
05 *	1.8	11	Water	60
06 *	1.1	11	Water	50
07	2.6	11	Water	50
08 *	1.8	22	Water	110
09 *	2.2	21	Oxygen	100
10 *	1.8	22	Oxygen	110
11 *	2.5	22	Oxygen	110

\* Training data—data set was used as training data for the decision tree, as can be seen in Section 2.5.

### 2.3. Electrochemical Cycling

The specimens were electrochemically cycled by a multichannel electrochemical workstation (Biologic VMP3). The test procedure can be taken from Figure 4. At the beginning, the specimens were in an open circuit voltage (OCV) phase for 12 h. Subsequently, potentiodynamic electrochemical impedance spectroscopy (PEIS) with 10 points per decade at a logarithmic spacing was performed within a frequency of 10 mHz–2 MHz. A sinusoidal voltage signal with an amplitude of 10 mV represented the excitation. At each frequency, an average of four measurement values was used to obtain the impedance. The impedance measurements were performed in the discharged state (0% SOC) of the specimens. Subsequently, 10 cycles of galvanostatic cycling with potential limitation (GPCL) between 1.5 V and 2.8 V were conducted with a current of 1.0 C. The theoretical capacity of each cell was determined with the electrode masses and was used to estimate the charging current of 1.0 C. The estimated charge and discharge rate of 1.0 C was maintained through all cycles. The measured initial capacity in Table 2 was the cell capacity after the formation procedure (after loop 0). The SOH was determined after each cycle of the GPCL by dividing the current capacity by the capacity after formation (first cycle). The Coulombic efficiency for each cycle of the GPCL was determined by dividing the delithiation capacity by the lithiation capacity of the corresponding cycle. After the GPCL phase, the procedure started anew with the OCV phase and the cycle program ended after a certain number of loops (1 loop included 10 GPCL cycles, as can be seen in Figure 4). Loop 0 was not considered in the following analyses, as cell formation took place here.



**Figure 4.** Test procedure for the specimen. OCV—open circuit voltage; PEIS—potentio electrochemical impedance spectroscopy; GCPL—galvanostatic cycling with potential limitation between 1.5 V and 2.8 V consisting of 10 charge and discharge cycles (=1 loop).

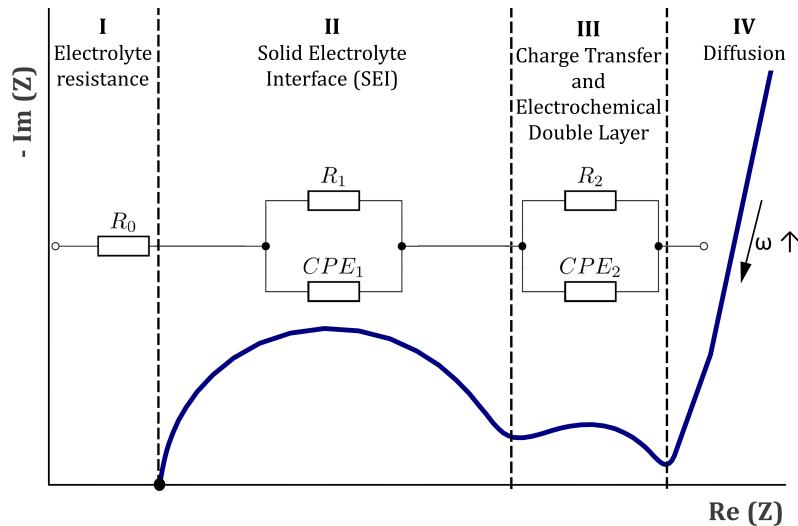
The total number of loops (column “loops” in Table 2) for each specimen and the cycle in which contamination was introduced (column “Contamination cycle” in Table 2) were both varied in the experiment.

#### 2.4. Equivalent Circuit Model

The electrical behavior of a system (i.e., Li-Ion battery) can be simulated using equivalent-circuit models (ECMs). ECMs represent an electrical network consisting of several resistance, capacitance and inductance phase elements which allow an approximation of the electrochemical behavior of battery cells. Further information on ECMs can be found in the literatures [63–68]. The model parameters (i.e., the characteristics of the electrical components) were obtained by calibrating the ECM parameters according to impedance spectra from the measurements. A least square fitting procedure was applied for each specimen and each measurement loop by using the software ZView® [69]. In this study, an ECM consisting of a resistance  $R_0$  and two parallel circuits with a resistance and constant phase element (CPE) ( $R_1$ , CPE<sub>1</sub> and  $R_2$ , CPE<sub>2</sub>), were used, as can be seen in Figure 5. Each component in the ECM reproduces a certain area in the corresponding impedance spectrum of a specimen and can be attributed to certain physical phenomena in the specimen.  $R_0$  defined the position of the spectrum on the abscissa and represents the ohmic resistance of the electrolyte (see “I” in Figure 5). The parallel circuits consisting of a resistance and constant phase element were used to model the semicircular segments in the impedance spectrum. The constant phase element represents a non-ideal capacitor and included two parameters, a linear factor  $T$  and an exponential factor  $P$  [70]:

$$Z_{CPE} = \frac{1}{T * (j * \omega)^P} \quad (1)$$

with  $j$  and  $\omega$  as the imaginary number and angular frequency, respectively. The first parallel circuit with resistance  $R_1$  and constant phase element  $CPE_1$  was correlated with the solid electrolyte interface (SEI) in the literatures [53,63,68,71,72] (see “II” in Figure 5). The second parallel circuit with resistance  $R_2$  and the constant phase element  $CPE_2$  is correlated with the charge transfer resistance and the double-layer capacity in the literature [53,63,68,71,72] (as can be seen in “III” in Figure 5). Inductive or diffusive behavior of the specimens were not taken into account.



**Figure 5.** Schematic illustration of an impedance spectrum in a Nyquist plot and the equivalent circuit model (ECM) used in this study with its correlating impedance segments.

## 2.5. Decision Tree

The recorded impedance every 10 cycles allowed for an examination of the contamination influence. A classification algorithm was used to predict the effect of contamination on the specimens’ behavior. A decision tree was used as the classifier to identify sensitive ECM parameters and to derive threshold values for the ECM parameters. A decision tree algorithm is favorable as the results are simple to interpret and the performance works well with large data sets. An important characteristic of decision trees is that their depth represents the number of branches split off the tree’s root. The less branches are needed to derive a statement, then the more robust its results are. More branches allow more detailed decisions, but specialization reduces universal validity. To find an optimal balance, the smallest tree, which gives reliable results, is preferable, meaning that the tree depth should be kept as low as possible. To support this decision, the contribution of each element of the tree (i.e., the model input parameter) to the final result is expressed as a “feature importance” (FI) value. To set up a decision tree data structure, a special software package (scikit-learn for the Python programming language) was used.

The measurement data sets of the eleven specimens were randomly separated into eight cases (specimens No. 01, No. 03, No. 05, No. 06, No. 08–No.11), that were used to train the decision tree classifier and three cases (specimens No. 02, No. 04 and No. 07) which were used to verify the results, as can be seen in Table 2. The values of the ECM elements were normalized by dividing each of them by its respective value at loop 1 as can be seen in Equation (2).

$$R_{1,normalized}^i = \frac{R_1^i}{R_1^1} \quad (2)$$

with  $i$  indicating the loop index.

A two-stage approach was chosen to find a prediction model. In the first step, the tree depth for decision making was unlimited in order to find the relevant ECM parameters. The input parameters with the greatest sensitivity were chosen according to the feature

importance (FI) obtained by the decision tree. In a second step, ECM parameters allowing a distinction between the types of contamination (i.e., contamination with oxygen or water) were obtained. To unveil the sensitivity of the model parameters for this distinction, the depth of the decision tree was adapted accordingly.

### 3. Results

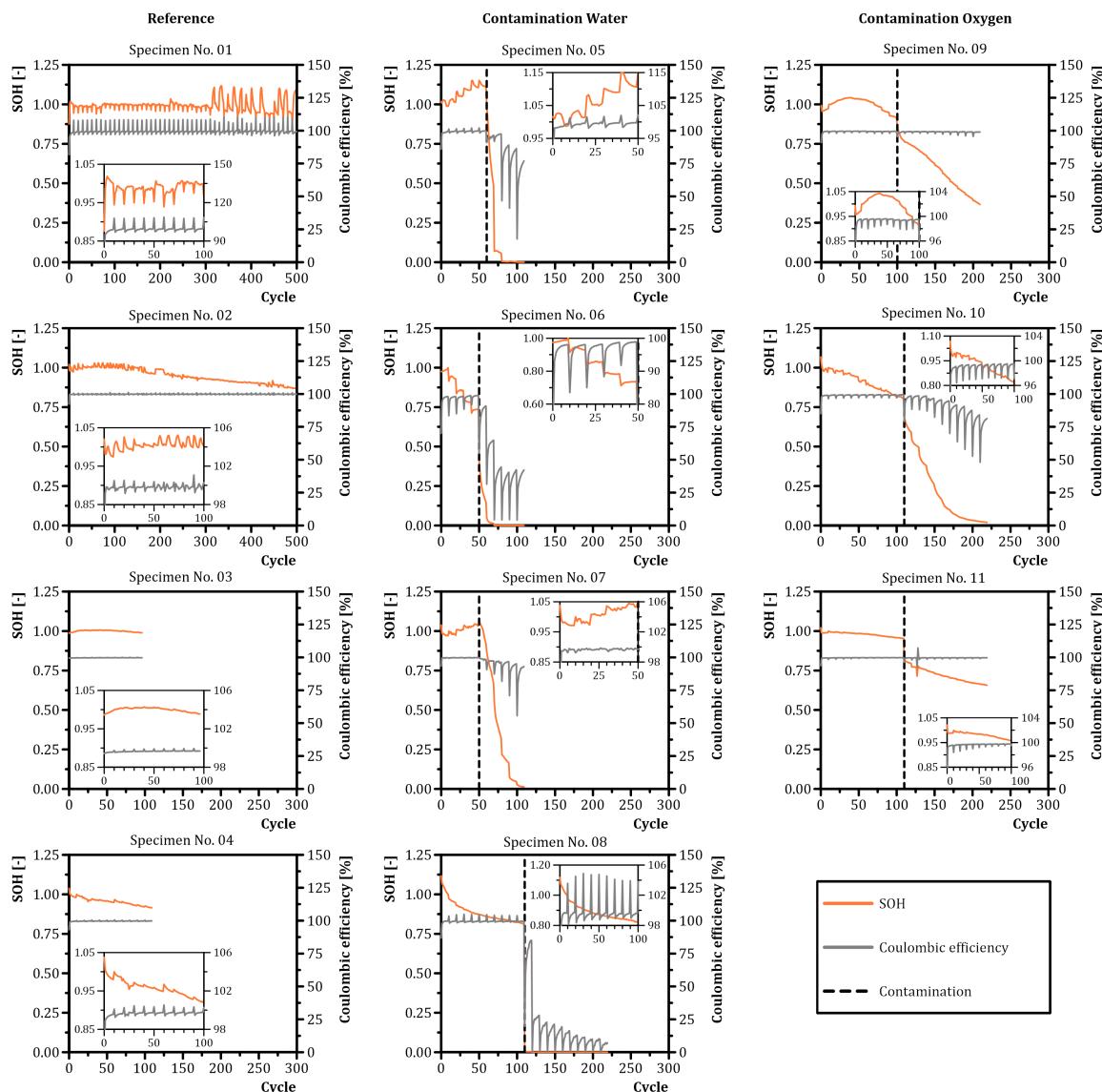
#### 3.1. Electrochemical Cycling

Figure 6 illustrates the SOH and Coulombic efficiency during cycling for different contamination types. Reference specimens No. 01 and No. 02 were subjected to 500 cycles to investigate the aging effects during cycling. Specimen No. 01 indicated peaks in the Coulombic efficiency and drops in the SOH each 10 cycles. A similar behavior was observed for reference specimen No. 02. Reference specimen No. 03 showed no relevant changes in electrochemical behavior in terms of SOH and Coulombic efficiency for 97 cycles. After 97 cycles, specimen No. 03 indicated faulty measurement values with a Coulombic efficiency exceeding 100%. These data were excluded in further analysis. The SOH of reference specimen No. 04 linearly decreased at a consistent Coulombic efficiency of approximately 100%. After contamination with water, a fast drop in the SOH of specimens No. 05 to No. 08 was observed. The Coulombic efficiency showed an erratic course for specimens No. 05, No. 06 and No. 08. Specimen No. 07 had a smooth Coulombic efficiency course before water contamination, changing to an erratic course after contamination with sharp drops each 10 cycles. The Coulombic efficiency dropped for specimens No. 06 and No. 08 after water contamination. Specimens No. 05 and No. 07 reached a Coulombic efficiency of almost 100% even for the electrochemical cycles after contamination. Specimens No. 05, No. 06 and No. 07 showed an erratic course of SOH before contamination with peaks or drops each 10 cycles. The SOH of specimen No. 08 constantly decreased before contamination. After contamination with oxygen, a sharp drop in SOH of specimens No. 09 to No. 11 was observed, followed by a constant decrease in SOH. Specimens No. 10 and No. 11 showed a similar effect as specimen No. 04 (reference specimen equipped with ZrO<sub>2</sub> plate) with a linear decrease in SOH before contamination at a consistent Coulombic efficiency. Specimen No. 09 showed a raising capacity until a peak was reached after 39 cycles and decreased for further cycles before contamination. The Coulombic efficiency stayed almost constant for specimen No. 09–No. 11. After contamination, the Coulombic efficiency of specimen No. 10 started to decrease with sharp drops each 10 cycles.

The EIS measurements revealed further information about the effect of contamination and the influence of a contamination on the electrochemical properties of specimens. Except from specimens No. 05, No. 06 and No. 10, all specimens showed two semicircles in the impedance spectrum of the corresponding impedance measurement, as can be seen in Figure 7. The second semicircle degenerated to an almost linear section for specimens No. 03, No. 09 and No. 11.

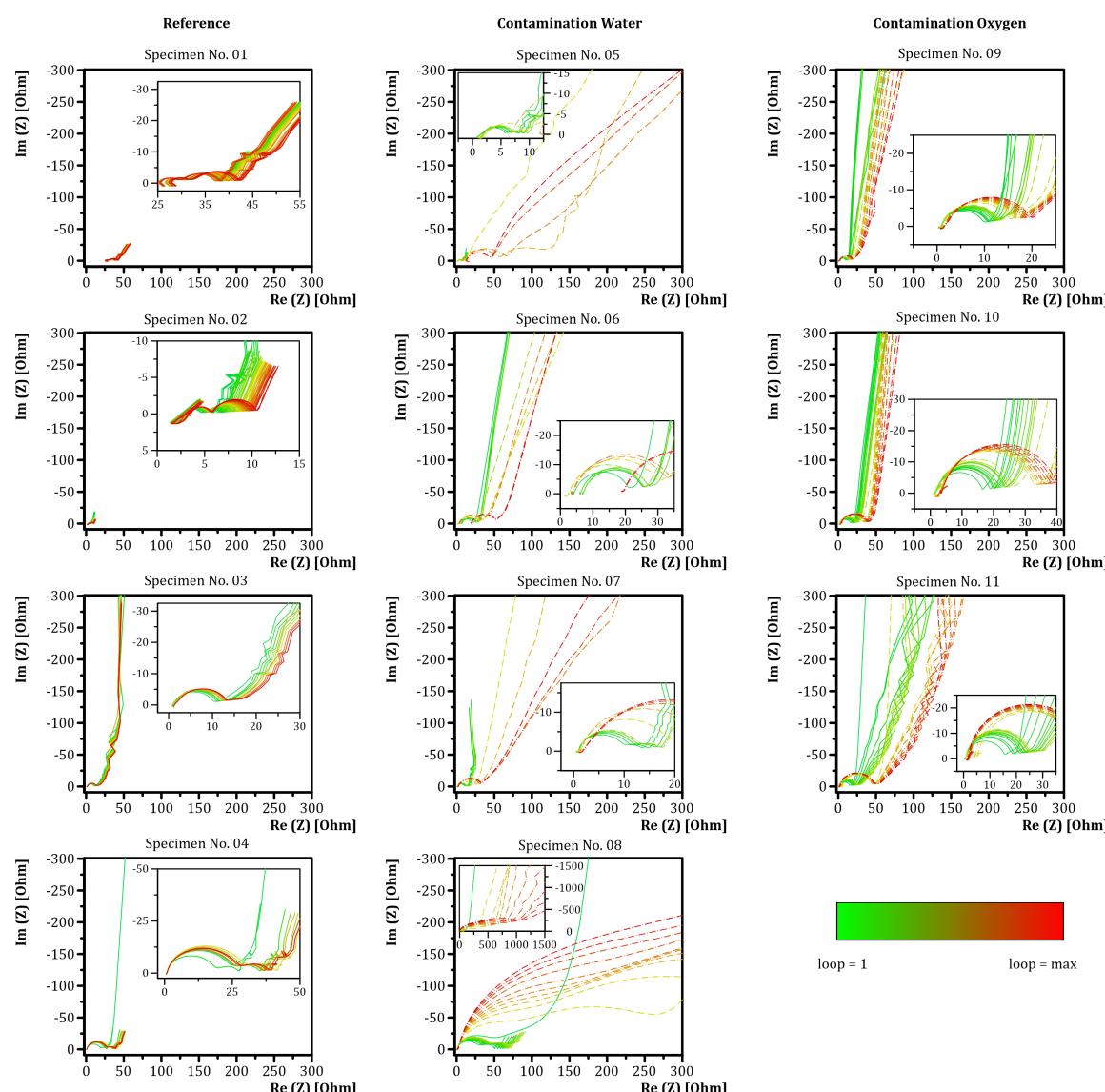
The reference specimens No. 01–No. 03 indicated minor changes during cycling. Minor changes of the intercept with the abscissa were observed during cycling. Specimen No. 04 showed increased semicircle diameters after 20 cycles (loop 2) with minor changes during further cycling. Noise was observed for specimens No. 01 and No. 04 at low frequencies indicated by a zig zag curve. Specimens contaminated with water (No. 05–No. 08) showed an increase in diameter of the second semicircle after contamination. Specimens No. 05 and No. 06 indicated changes in the intersection with the abscissa. Specimen No. 05 indicated a shift of the intersection with the abscissa towards higher values. Specimen No. 06 had a shift towards lower values after contamination increasing afterwards (loop 9). Additionally, reduced slopes of the linear part of the impedance spectra in the low frequency range were observed after contamination. Specimens No. 07 and No. 08 indicated minor changes of the intersection with the abscissa. Specimens No. 09–No. 11 contaminated with oxygen showed slighter changes in electrochemical behavior compared to the specimens contaminated with water. The intersection with the abscissa did not change to a relevant extent after contamination. The intersection with the abscissa shifted towards higher

values for specimen No. 11 at 10 cycles after contamination (loop 11) that faded after 20 further cycles (loop 13). The diameter of the first semicircle slightly increased before contamination and significantly afterwards for specimens No. 09–No. 11. The degenerated second semicircle of specimens No. 09 and No. 11 flattened after contamination. The slope of the linear part of the impedance spectra in the low frequency range decreased for specimens No. 09–No. 11.



**Figure 6.** State of health (SOH) and Coulombic efficiency over the number of cycles for different contamination types. First column—reference specimens. Second column—specimens with water contamination. Third column—specimens with oxygen contamination. Dashed vertical lines indicate the contamination initiation cycle.

In summary, the reference specimens showed no qualitative change (i.e., change in curve shape) in the electrochemical impedance spectra during electrochemical cycling. A continuous shift of the curves during electrochemical cycling towards higher impedance values was observed. The water-contaminated specimens indicated the fast degeneration of the electrochemical impedance spectra after contamination, seen as large changes in the semicircle's diameters and change in curve shapes. A similar behavior was observed for specimens contaminated with oxygen. The semicircle's diameters increased subsequently after contamination but not to the same extent as water-contaminated specimens.



**Figure 7.** Electrochemical impedance spectra for specimens during cycling. First column—reference specimens. Second column—specimens with water contamination. Third column—specimens with oxygen contamination. A lower limit was indicated by the first loop. The upper limit can be taken from Table 2. The dashed line represents specimens after contamination.

### 3.2. Equivalent Circuit Model

The obtained EIS measurements were fitted with the ECM parameters shown in Figure 5. The numerical values of the ECM parameters of each specimen can be taken from the supplementary material. Average  $\chi^2$ , describes the goodness of fit, was within the guideline of a value below  $6 \times 10^{-3}$  for good fit except from the fitting results of specimens No. 07, No. 08 and No. 10 before contamination, as can be seen in Table 3. For specimen No. 10, doubtful fitting results of the EIS measurements were obtained before contamination. After contamination, a  $\chi^2$  of  $2.24 \times 10^{-3}$  represented good fit.

### 3.3. Decision Tree

Two variants for contamination prediction were investigated: In the first, two classes “no contamination” (0) and “contamination” (1) were distinguished. In the second, three classes “no contamination” (0), “contamination—oxygen” (1) and “contamination—water” (2) were distinguished. For each variant, the feature importance ( $FI$ ) of the model input parameters was examined in first place, as can also be seen in Appendix A.

### 3.3.1. Contamination Recognition (Tree Depth = 1)

Without tree depth limitation  $R_{1,normalized}$  achieved the highest feature importance  $FI = 0.92$  for a classification between “no contamination” (0) and “contamination” (1), as can be seen in Figure A1. The parameter with the second highest feature importance was  $CPE_{1,normalized} - P$  with  $FI = 0.03$ . In order to predict the classes “no contamination” (0) and “contamination” (1), the maximum depth of the decision tree classifier was set to one with  $R_{1,normalized}$  as the main criterion. This led to the prediction of “no contamination” (0) as long as  $R_{1,normalized} \leq 1.693$  is true. Figure A2 shows the decision tree for this variant. Three data points out of 169 were falsely classified in this configuration.

**Table 3.** Average goodness of fit expressed in terms of  $\chi^2$  for the fitted EIS measurements with the equivalent circuit with the ECM parameters  $R_0$ ,  $R_1$ ,  $R_2$ ,  $CPE_1$  and  $CPE_2$ .

Specimen No.	Contamination	Average $\chi^2$ before Contamination	Average $\chi^2$ after Contamination
01	Reference	$1.06 \times 10^{-4}$	-
02	Reference	$5.90 \times 10^{-4}$	-
03	Reference	$1.93 \times 10^{-3}$	-
04	Reference	$6.49 \times 10^{-4}$	-
05	Water	$1.46 \times 10^{-3}$	$2.20 \times 10^{-4}$
06	Water	$1.79 \times 10^{-4}$	$2.09 \times 10^{-4}$
07	Water	$6.99 \times 10^{-3}$	$1.56 \times 10^{-3}$
08	Water	$8.03 \times 10^{-3}$	$4.04 \times 10^{-3}$
09	Oxygen	$2.58 \times 10^{-3}$	$2.37 \times 10^{-3}$
10	Oxygen	$1.17 \times 10^{-2}$	$2.24 \times 10^{-3}$
11	Oxygen	$7.94 \times 10^{-4}$	$3.10 \times 10^{-4}$

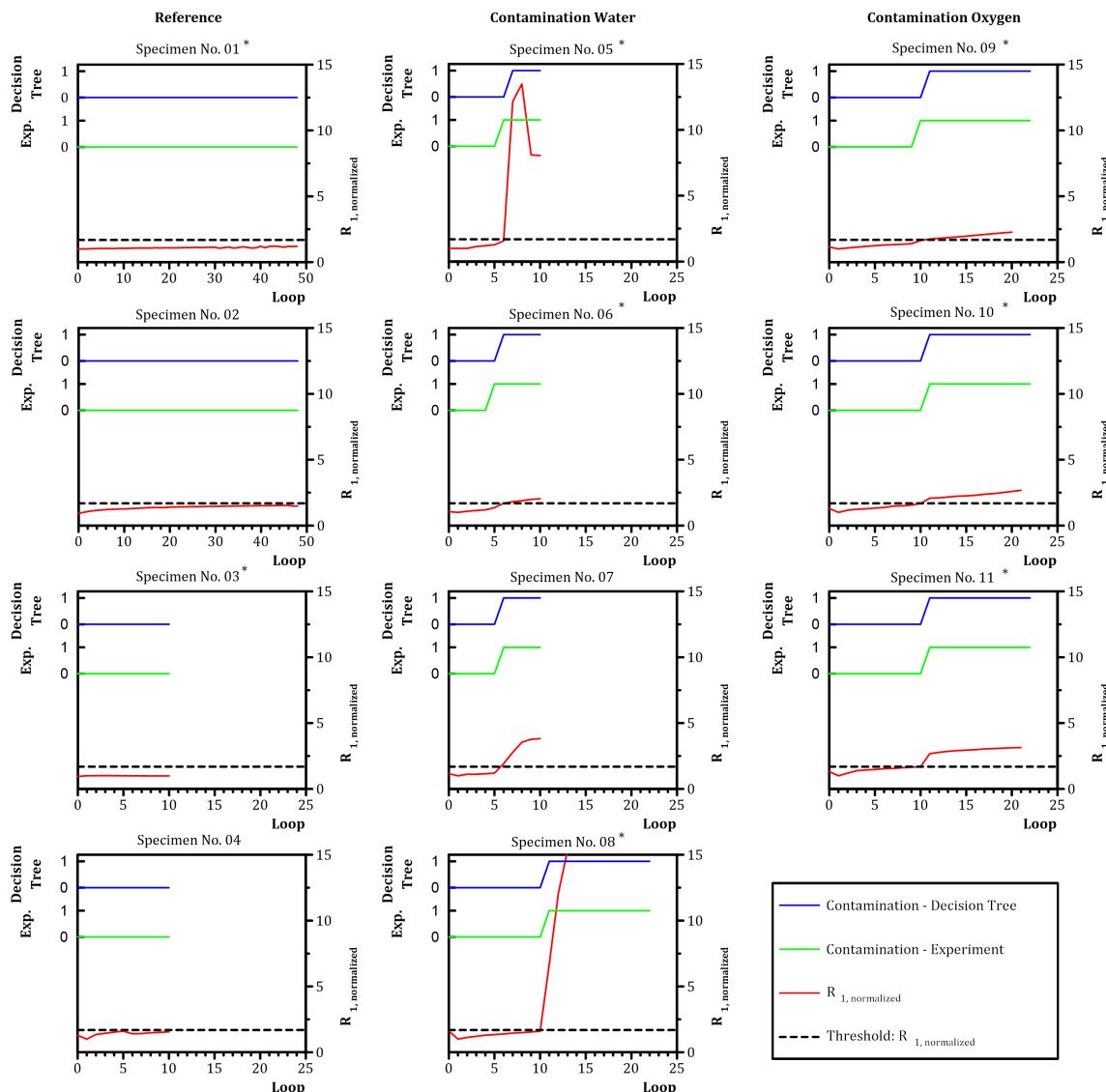
Figure 8 shows the evolution of criterion  $R_{1,normalized}$  (red line) over all measurement data sets. The threshold for  $R_{1,normalized}$  for a class split in the decision tree is symbolized by “Threshold R1, normalized” (black-dashed line). The activation of the contamination in the experiment was marked as “contamination–target” (green line). The prediction of contamination from the decision tree algorithm is marked as “contamination–prediction” (blue line).

The left column “Reference” in Figure 8 shows the data for specimens without contamination (specimens No. 01–04).  $R_{1,normalized}$  showed a reasonably constant course over cycling. The contamination indicator “Contamination–Experiment” and the decision tree classification “Contamination–Decision Tree” both stayed at “no contamination” (0). The algorithm correctly assigned the contamination state for specimens No. 01 and No. 03 and performed a correct prediction for specimens No. 02 and No. 04. The middle column “Contamination Water” in Figure 8 shows the data for specimens with water contamination (specimens No. 05–08). Contamination was activated at loop 5 for specimens No. 05, No. 06 and No. 07 and at loop 11 for specimen No. 08, indicated by the green line switching to “contamination” (1). The contamination of specimens No. 05 and No. 06 was assigned with a delay of one loop by the algorithm. The contamination assignment of specimen No. 08 was accurate. The contamination of specimen No. 07 was correctly predicted. The right column “contamination oxygen” in Figure 8 shows the data for specimens with oxygen contamination (specimens No. 09–11). Contamination was activated at loop 10 for specimen No. 09 and at loop 11 for specimens No. 10 and No. 11. The assignment of the contamination of specimen No. 09 was delayed by one loop. The assignment of the algorithm for specimens No. 10 and No. 11 was correct.

### 3.3.2. Contamination Type Differentiation (Tree Depth = 2)

As  $R_{1,normalized}$  was identified as the most relevant model parameter to recognize contamination. A further criterion was needed to distinguish different types of contamination. The data sets, which were classified as “contamination” (1) in the step before, were now

separated into the classes “contamination—oxygen” (1) and “contamination—water” (2). Therefore, the maximum depth of the decision tree was set to two.



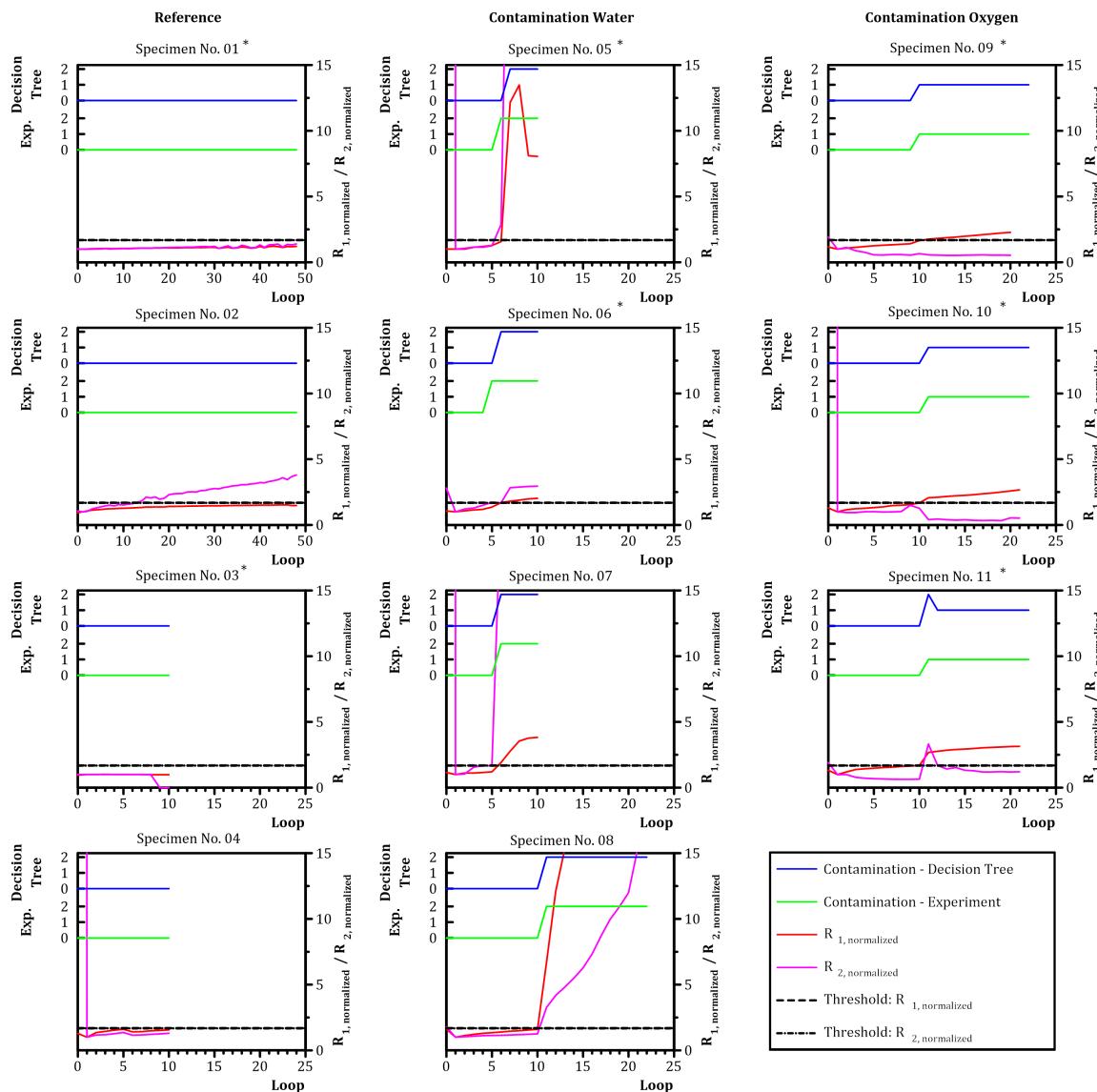
**Figure 8.** Prediction of classes “no contamination” (0) and “contamination” (1) with a decision tree of depth = 1 based on  $R_{1,\text{normalized}}$ . Blue—decision tree; green—experiment. \* Training data—data set was used as training data for the decision tree.

In the next step,  $R_{2,\text{normalized}}$  and  $CPE_{1,\text{normalized}} - P$  were found to distinguish between the classes “contamination—oxygen” (1) and “contamination—water” (2).  $CPE_{1,\text{normalized}} - P$  was able to classify one data point into the class “contamination—oxygen” with a threshold of 0.465, see Figure A3.  $R_{2,\text{normalized}}$  was able to distinguish between the classes “contamination—oxygen” (1) and “contamination—water” (2) with one false classification. The threshold value for  $R_{2,\text{normalized}}$  was 1.681. The threshold value for  $R_{1,\text{normalized}}$  was 1.693 as before. The decision tree calculated for this variant is shown in Figure A3. Figure 9 shows the evolution of criteria  $R_{1,\text{normalized}}$  (red line) and  $R_{2,\text{normalized}}$  (magenta line) over all measurement data sets. The threshold for  $R_{1,\text{normalized}}$  is symbolized by “Threshold R1, normalized” (black dashed line) while threshold for  $R_{2,\text{normalized}}$  is symbolized by “Threshold R2, normalized” (black dotted-dashed line). As before, the activation of the contamination in the experiment was marked as “Contamination—Experiment” (green line). The decision tree classification is indicated by “Contamination—Decision Tree” (blue line).

The left column “Reference” in Figure 9 shows the data for specimens without contamination (specimens No. 01–04). Specimen No. 04 revealed a high  $R_{2,\text{normalized}}$  value for loop 0 changing to  $R_{2,\text{normalized}} = 1$  for loop 1 as loop 1 was used for normalization. The contamination status was assigned correct for every value by the decision tree.

The middle column “Contamination Water” in Figure 9 shows the data for specimens with water contamination (specimens No. 05–08). The contamination of specimens No. 05 and No. 06 was assigned by the algorithm with a delay of one loop. The contamination assignment of specimen No. 08 was accurate. A contamination of specimen No. 07 was correctly predicted.

The right column “Contamination Oxygen” in Figure 9 shows the data for specimens with oxygen contamination (specimens No. 09–11). The algorithm falsely assigned a contamination with water for specimen No. 11, but changed to the correct value, indicating a contamination with oxygen one loop later. The assignment of the algorithm for specimens No. 09 and No. 10 was correct.



**Figure 9.** Prediction of classes “no contamination” (0), “contamination—oxygen” (1) and “contamination—water” (2) with a decision tree of a depth of two based on  $R_{1,\text{normalized}}$ ,  $CPE_{1,\text{normalized}} - P$  and  $R_{2,\text{normalized}}$ . Blue—decision tree. Green—experiment. \* Training data—data set was used as training data for the decision tree.

#### 4. Discussion

Novel methods for *in situ* contamination with different contaminants were presented within this study. Eleven single-layer full battery cells were produced in a glove box and monitored with electrochemical impedance spectroscopy during cycling. Seven of these specimens were contaminated with water or oxygen during cycling. In this investigation, aging was excluded as far as possible by choosing LTO/LCO as the active material. The impedance data obtained were fitted with equivalent circuit elements and used in a normalized form to train a decision tree for contamination classification and prediction. Water contamination was achieved by breaking a water-filled glass container placed within the specimen before sealing. Oxygen contamination was achieved by application via a syringe. A self-healing injection port glued to the specimen guaranteed further contamination by closing itself after removing the syringe. A ZrO<sub>2</sub> plate prevented the penetration of the pouch foil with the syringe.

##### 4.1. Limitations

Manually produced single-layer full battery cells were used in this study for flexibility in terms of chemistry and to avoid the safety risks of high-energy battery cells. The necessary adaptions on the specimen to implement the contamination trigger were large in terms of size. It is expected that the electrochemical behavior of commercial battery cells will not be affected by these adaptions in the same magnitude as was observed in this study. The chemistry used (Li<sub>4</sub>Ti<sub>5</sub>O<sub>12</sub>/LiCoO<sub>2</sub>) was chosen to exclude the aging effects. The presented classification algorithm has to be validated when aging is overlaid with contamination. Additionally, a small number of specimens did not allow statistical statements to be made. In the case of more data being available and with the spread of electrochemical parameters being lower between the specimens, more sophisticated methods would be available, i.e., a recurrent neural network. Additionally, the effect of the contaminant quantity was not observed within this study. The water quantity used for contamination was unlikely to be found in a realistic scenario. A relatively high amount of water was used in this study to maximize the effects of the water contamination. The contamination prediction quality for smaller water quantities should be evaluated in further studies.

##### 4.2. Contamination Trigger

The electrochemical properties were sensitive to the necessary adaptions (glass container or ZrO<sub>2</sub> plate) and refer to the possible chemical side reactions and disturbances. The glass container seemed to affect the electrochemical properties of the specimens with water contamination (specimens No. 05–08) before contamination by affecting the SOH during cycling. The observed sensitivity of the specimens' electrochemical behavior on the glass container is considered small compared to the changes by the contamination itself, as can be seen in Figure 6. The ZrO<sub>2</sub> plate was also observed to affect the electrochemical cycling behavior and SOH of the specimens before contamination. While ZrO<sub>2</sub> is often used as a surface coating material for cathode electrodes and is reported to be stable and relatively inert, it is still able to react with lithium ions and form a Li<sub>2</sub>ZrO<sub>3</sub> phase, resulting in capacity fade [73]. The defined requirements for the contamination trigger method (the application of different contamination quantities, repeatability, simple release and minor effect on the battery cell during normal operation) were met except for the minor effect on the battery cell during normal operation. For commercial battery cells, it is expected that the effect of the contamination trigger method itself is minor as the size of the disturbance is small compared to the battery cell size.

##### 4.3. Electrochemical Cycling

As was intended by the choice of the active material, the minor aging of the reference specimens (No. 01–04) was indicated by minor changes in the SOH and Coulombic efficiency during cycling. Additionally, minor changes of the intercept with the abscissa of the impedance spectrum corresponded to a low change in electrolyte resistance during cycling.

The Coulombic efficiency showed a rather erratic course for every specimen. Drops or peaks were observed every 10 cycles, correlating with the OCV phase with a relaxation time of 12 h after the galvanostatic cycling with potential limitation (GCPL). The relaxation time led to an increased capacity for one subsequent cycle possibly explaining the drops and peaks. Specimens contaminated with water (No. 05–08) showed clearly electrochemical behavior changes in terms of SOH, Coulombic efficiency and impedance. The impedance spectra of the water-contaminated specimens had a growing second semicircle, indicating a growing charge transfer resistance. Water ingress and oxygen ingress in pouch cells are known to significantly deteriorate cell performance and lead to a degradation of SOH [27]. In the environment of the Li-Ion cell, water is thermodynamically unstable. The electrochemical stability window of water is only 1.23 V, which is significantly narrower than the voltage of Li-Ion batteries and the voltage of the tested specimens. While hydrogen and oxygen may be generated in the process, when water and oxygen are in trace quantities, complex electrode reactions occur at the electrodes which involve solvents and salt. In addition to electrochemical decomposition, water may spontaneously react with several components of the cell. For instance, traces of water will result in the hydrolysis of the hexafluorophosphate ( $\text{PF}_6^-$ ) ion with the formation of hydrofluoric acid (HF) [31,36,74]. HF is a highly corrosive gas that will react with both active materials and current collectors. While the electrochemical decomposition of water is a relatively fast process, the formation of HF through  $\text{PF}_6^-$  hydrolysis is a slow process. Specimens contaminated with oxygen showed slower degradation compared to the specimens contaminated with water. In the impedance, the first semicircle's diameter slightly increased before contamination, but subsequently, the increase was significant, indicating a growing SEI on the cathodic electrode (cathodic SEI) or the formation of additional passivation layers. This can be attributed to oxidative reactions of the current collectors, electrolyte and active material (cathode). Additionally, diffusion decreased after contamination, considering the slope at a low frequency range of the EIS measurements. Indeed, the oxygen reduction reaction is known (from fuel-cells research) to proceed at notoriously slow rates in the absence of suitable catalysts. Thus, it is not surprising that water contamination shows a pronounced and immediate effect, while oxygen contamination leads to a slower response, simply because it is very likely that the oxygen reduction reaction has sluggish kinetics under experimental conditions. In general, a faulty battery cell within a battery module might lead to safety-relevant changes in the system behavior. The continuously dropping capacity of a contaminated battery cell leads to an unbalance in the battery module, promoting the further accelerated aging of the other included battery cells. The complete failure of individual battery cells should be avoided to guarantee the safe operation of a battery system. State-of-the-art monitoring methods (i.e., internal resistance monitoring, voltage monitoring) might not be applicable to the detection of contaminated battery cells (i.e., no change of internal resistance was observed after contamination).

#### 4.4. Decision Tree

The specimens had a wide dispersion in terms of electrochemical properties. This made the normalization of ECM parameters necessary. This issue can be attributed to the manual manufacturing process of specimens. The chemical side reactions include SEI growth and oxidative reactions leading to the growth of the first semicircle which is represented by  $R_1$  and  $CPE_1$ . The ECM parameter  $R_1$  was therefore expected to be the most sensitive model parameter.  $CPE_{1,\text{normalized}} - P$  was only able to classify one data point into the class “contamination–oxygen” (1).  $CPE_1 - P$  was also obtained by the shape of the first semicircle which was also affected by  $R_1$ . By including  $R_1$  in the decision, the relevant information about the first semicircle was already available, leading to no more additional information by including  $CPE_1 - P$ .  $R_2$  correlated with the second semicircle and provided further information about the impedance spectrum and was therefore usable to distinguish the type of contamination. The classification showed an offset in some cases that may result from the fact that, every 10 cycles, an impedance spectrum was measured. The changes in

the electrochemical behavior were thus not tracked for 10 electrochemical cycles. A more frequent impedance measurement would result in the continuous tracking of the effect of contamination on the electrochemical behavior of a specimen and gain more insights into the involved degradation mechanisms.

## 5. Conclusions

The methods described and demonstrated in this work are suitable for an *in operando* contamination of commercial battery cells, allowing for the repeatable application of contaminants of different quantities with only a minor impact on the battery cell operation. The quantification of the observed changes in the impedance spectrum with the ECM parameters and corresponding thresholds proved eligible for monitoring the contamination status. In the following, the conclusions drawn from the presented study are listed.

- Novel methods were found to apply different contaminants (i.e., water, oxygen) in *in operando* with minor effects on battery performance.
- The chemical kinetics of the oxygen contamination were slow compared to the water contamination.
- The first semicircle's diameter in the Nyquist plot increased after contamination, indicating the growing SEI or formation of additional passivation layers.
- A decision tree based on ECM parameters from EIS measurements was able to detect the contamination of a specimen.
- The ECM parameter  $R_1$  in the normalized form ( $R_{1,normalized}$ ) was identified as the most sensitive model parameter for contamination recognition.
- The ECM parameter  $R_2$  in the normalized form ( $R_{2,normalized}$ ) was able to distinguish the contamination type (oxygen or water).

Combination with other advanced monitoring and evaluation tools such as the density of relaxation times (DRT) may improve prediction quality and allow for a reduction in the frequency range needed to be tested by EIS. The definition of single frequencies or small frequency ranges for contamination determination would enable the continuous tracking of the contamination state. In future research, the influence of cell chemistry on the contamination behavior and changes in ECM elements should be investigated. The prediction capability of the described method for overlaid aging and degradation mechanisms still has to be validated. Industrially produced battery cells only show a narrow spread and should be used for the further testing and validation of the contamination classification method. By applying the results of this paper on commercial Li-Ion cells, a method for real-time monitoring could be established which will increase the safety of battery modules.

**Supplementary Materials:** The following are available at <https://www.mdpi.com/article/10.3390/batteries8040035/s1>.

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**Conflicts of Interest:** The authors declare no conflict of interest.

## Abbreviations

The following abbreviations are used in this manuscript:

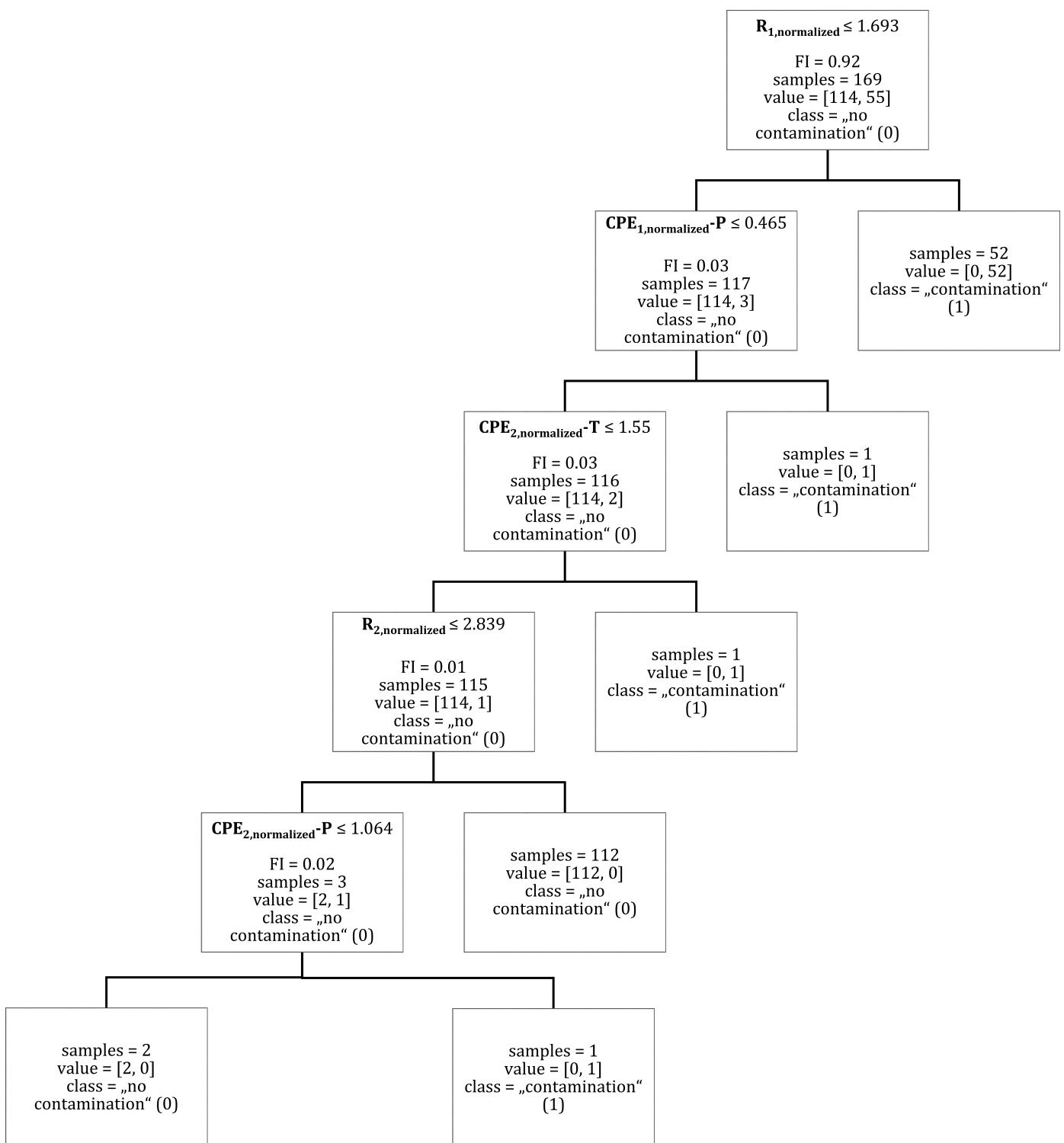
C	C-rate
CPE	Constant phase element
DRT	Distribution of relaxation times
ECM	Equivalent circuit model
EIS	Electrochemical impedance spectroscopy
FI	Feature importance
GCPL	Galvanostatic cycling with potential limitation
HF	Hydrofluoric acid
ISC	Internal short circuit
LCO	Lithium–cobalt(III)–oxide ( $\text{LiCoO}_2$ )
Li-Ion	Lithium ion
$\text{LiPF}_6$	Lithium hexafluorophosphate
LTO	Lithium titanate oxide ( $\text{Li}_4\text{Ti}_5\text{O}_{12}$ )
ML	Machine-learning
NMP	N-Methyl-2-pyrrolidone
OCV	Open circuit voltage
$\text{PF}_6^-$	Hexafluorophosphate
PEIS	Potentio electrochemical impedance spectroscopy
SEI	Solid electrolyte interphase
SOC	State of charge
SOH	State of health
$\text{ZrO}_2$	Zirconium dioxide

## Appendix A

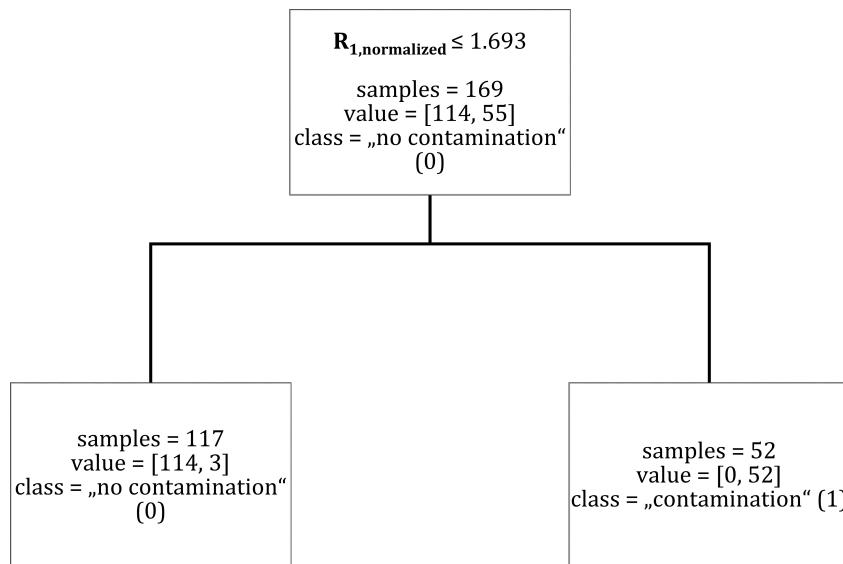
In the following, the results of a decision tree algorithm with the ECM parameters are illustrated. Different tree depths allow for an examination of the parameter and feature importance for contamination prediction. Figure A1 illustrates the classification results of a decision tree without tree depth limitation.

The results of a decision tree classifier with a tree depth limitation of one can be taken from Figure A2.

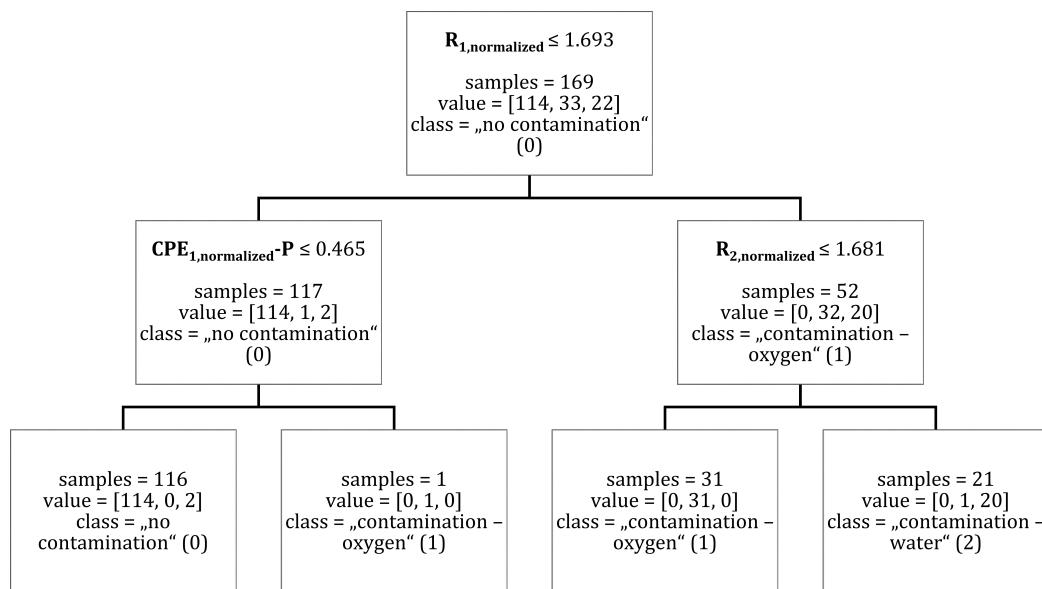
The results of a decision tree classifier with a tree depth limitation of two can be taken from Figure A3.



**Figure A1.** Feature importance (FI) and the classification of data points into the classes “no contamination” (0) and “contamination” (1) for a decision tree without depth limitation. Brackets indicate (“no contamination” (0) and “contamination” (1)).



**Figure A2.** Classification of data points into the classes “no contamination” (0) and “contamination” (1) for a decision tree with tree depth = 1. Brackets indicate (“no contamination” (0), “contamination” (1)).



**Figure A3.** The classification of data points into the classes “no contamination”, “contamination—oxygen” and “contamination—water” for a decision tree of depth = 2. Brackets indicate (“no contamination” (0), “contamination—oxygen” (1), “contamination—water” (2)).

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