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12 November 2018

The Amazing Performance of C++17 Parallel Algorithms, is it Possible?



th the addition of Parallel Algorithms in C++17, you can now easily update your "computing" code to benefit from parallel execution. In the article, I'd like to examine one STL algorithm which naturally exposes the idea of independent computing. If your machine has 10-core CPU, can you always expect to get 10x speed up? Maybe more? Maybe less? Let's play with this topic.

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Update 13th Nov: I've applied the comments from r/cpp discussions, used proper ranges for trigonometry/sqrt computations, and some minor changes. The benchmarks were executed another time.



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Intro to Parallel Algorithms

C++17 offers the execution policy parameter that is available for most of the algorithms:

- sequenced policy is an execution policy type used as a unique type to disambiguate parallel algorithm overloading and require that a parallel algorithm's execution may not be parallelized.
 - the corresponding global object is std::execution::seq
- parallel policy is an execution policy type used as a unique type to disambiguate parallel algorithm overloading and indicate that a parallel algorithm's execution may be Shares parallelized.
 - the corresponding global object is std::execution::par
 - parallel unsequenced policy is an execution policy type used as a unique type to disambiguate parallel algorithm overloading and indicate that a parallel algorithm's execution may be parallelized and vectorized.
 - the corresponding global object is std::execution::par unseq

In short:

- use std::execution::seq to execute your algorithm sequential
- use std::execution::par to execute your algorithm in parallel (usually using some Thread Pool implementation)
- use std::execution::par unseq to execute your algorithm in parallel with also ability to use vector instructions (like SSE, AVX)

As a quick example you can invoke std::sort in a parallel way:

```
std::sort(std::execution::par, myVec.begin
      // ^^^^^^^
      // execution policy
```

Please notice that it's so easy just to add parallel execution parameter to an algorithm! But can you always experience a huge performance boost? Is it always faster? Or maybe there are cases where it might slow things down?

Parallel std::transform

In this post I'd like to have a look at std::transform algorithm that potentially might be one of the building blocks of other parallel techniques (along with std::transform_reduce, for_each, scan, sort...).

Our test code will revolve around the following pattern.

```
35 ------
Sharesd::transform(execution_policy, // par, some invec.begin(), invec.end(), outvec.begin(),

ElementOperation);
```

ruming the ElementOperation function doesn't use / method of synchronisation, then the code might /e a good potential to be executed in parallel or even vectorised. Each computation for an element is independent, the order is not important, so the implementation might spawn multiple threads (possibly on a thread pool) to process elements independently.

I'd like to experiment with the following cases.

- size of the vector big or small
- simple transformations that spend time mostly on memory access
- more arithmetic (ALU) operations
- ALU in a more realistic scenario

As you can see, I'd like not only to test the number of elements that is "good" to use a parallel algorithm, but also ALU operations that keep CPU busy.

Other algorithms like sorting, accumulate (in the form of std::reduce) also offers parallel execution, but they require more work (and usually merging steps) to compute the results. So they might be candidates for another article.

Note on Benchmarks

I'm using Visual Studio 2017, 15.8 for my tests - as it's the only implementation in a popular compiler/STL



implementation at the moment (Nov 2018) (GCC on the way!). What's more, I focused only on execution::par as execution::par_unseq is not available in MSVC (works the same way as execution::par).

I have two machines:

- i7 8700 PC, Windows 10, i7 8700 clocked at 3.2 GHz, 6 cores/12 threads (Hyperthreading)
- i7 4720 Notebook, Windows 10, i7 4720, clocked at 2.6GHz, 4 cores/8 threads (Hyperthreading)

the code is compiled in x64, Release more, auto vectorisation is enabled by default, and I've enabled **35** Shares anced instruction set (SSE2), as well as OpenMP (2.0)

e code is located on my github: hub/fenbf/ParSTLTests/TransformTests/TransformT :s.cpp

OpenMP (2.0) I'm only using parallel for loops:

```
pragma omp parallel for
for (int i = 0; ...)
```

I'm running the code section 5 times, and I look at the min numbers.

Warning: The results are shown only to present some rough observations, and please run it on your system/configuration before using it in production. Your requirements and environment might be different than mine.

You can read more about MSVC implementation in this post:

Using C++17 Parallel Algorithms for Better Performance | Visual C++ Team Blog

And here's a recent Billy O'Neil's talk at CppCon 2018 (Billy implemented Parallel STL in MSVC):

https://www.youtube.com/watch?v=nOpwhTbulmk

OK, let's start with some basic examples!

Simple Transformation

Consider a case where you apply a really simple operation on the input vector. It might be a copy or a multiplication of elements.



For example:

My machine has 6 or 4 cores... can I expect to get 4...6x perf of a sequential execution?

Here are the results (time in milliseconds):

Operation	Vector Size	i7 4720 (4 Cores)	i7 8700 (6 Cores)
execution::s	10k	0.002763	0.001924
Shares xecution::p ar	10k	0.009869	0.008983
openmp arallel for	10k	0.003158	0.002246
xecution::s	100k	0.051318	0.028872
execution::p ar	100k	0.043028	0.025664
openmp parallel for	100k	0.022501	0.009624
execution::s eq	1000k	1.69508	0.52419
execution::p	1000k	1.65561	0.359619
openmp parallel for	1000k	1.50678	0.344863

As you see on the faster machine, you need like 1 million elements to start seeing some performance gains. On the other hand on my notebook, all parallel implementations were slower.

All in all, as might guess there's a weak chance we'll any considerable speed-up using such transformations, even when we increase the number of elements.

Why is that?

Since the operations are elementary, CPU cores can invoke it almost immediately, using only a few cycles. However, CPU cores spend more time waiting for the



main memory. So, in that case, they all be mostly waiting, not computing.

Reading or writing to a variable in memory takes only 2-3 clock cycles if it is cached, but several hundred clock cycles if it is not cached

https://www.agner.org/optimize/optimizing
_cpp.pdf

We can give a rough observation that if your algorithm is memory bound, then you cannot expect to have a better performance with the parallel execution.

More Computations

35 Shares ce memory throughput is essential and might slow ngs down... let's increase the number of computations at affect each element.

e idea is that it's better to use CPU cycles rather than end time waiting for memory.

a start, I'll use trigonometry functions, for example, _rt(sin*cos) (those are arbitrary computations, not optimal form, just to keep CPU busy).

We're using sqrt, sin and cos which might take up ~20 per sqrt, ~100 per a trigonometry function. That amount of computation might cover the latency on the memory access.

More about instruction latencies in this great Perf Guide from Agner Fog

Here's the benchmark code:

How about now? Can we get some better perf than our previous attempt?

Here are the results (time in milliseconds):

Operation	Vector	i7 4720 (4	i7 8700 (6
	Size	Cores)	Cores)



	Operation	Vector Size	i7 4720 (4 Cores)	i7 8700 (6 Cores)	
	execution::s	10k	0.105005	0.070577	
	execution::p	10k	0.055661	0.03176	
	openmp parallel for	10k	0.096321	0.024702	
	execution::s	100k	1.08755	0.707048	
	execution::p	100k	0.259354	0.17195	
	openmp nare&rallel for	100k	0.898465	0.189915	
	xecution::s	1000k	10.5159	7.16254	
	xecution::p	1000k	2.44472	1.10099	
	openmp arallel for	1000k	4.78681	1.89017	

Now, we're finally seeing some nice numbers:)

For 1000 elements (not shown here), the timings for parallel and sequential were similar, so above 1000 elements, we can see some improvements for the parallel version.

For 100k elements, the faster machine performs almost 9x faster than the sequential version (similarly for OpenMP version).

For the largest set of a million elements - it's 5x or 8x faster.

For such computations, I could achieve the speed-up that is "linear" to my CPU core count. Which is probably what we should expect.

Fresnel and 3D Vectors

In the section above I've used some "imaginary" computations, but how about some real code?

Let's compute Fresnel equations that describe reflection and refraction of light at uniform planar interfaces. It's a popular technique for generating realistic lightning in 3D games.

$$egin{align} F_{R\parallel} &= \left(rac{\eta_2\cos heta_1 - \eta_1\cos heta_2}{\eta_2\cos heta_1 + \eta_1\cos heta_2}
ight)^2, \ F_{R\perp} &= \left(rac{\eta_1\cos heta_2 - \eta_2\cos heta_1}{\eta_1\cos heta_2 + \eta_2\cos heta_1}
ight)^2. \ F_{R} &= rac{1}{2}(F_{R\parallel} + F_{R\perp}). \ \end{aligned}$$

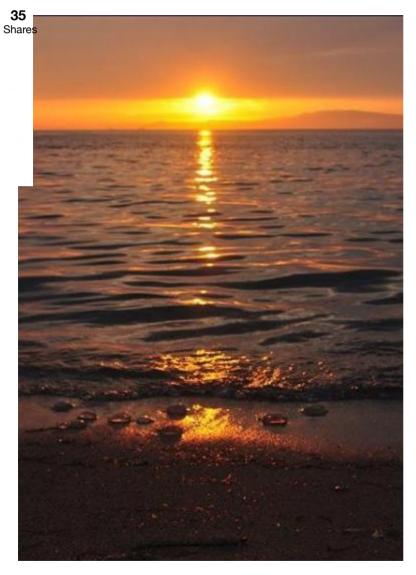


Photo from Wikimedia

As a good reference I've found this great description and the implementation:

Introduction to Shading (Reflection, Refraction and Fresnel) @scratchapixel.com

About Using GLM library



Rather than creating my own implementation, I've used the glm library. I've used it a lot in my OpenGL projects.

The library is available easily through Conan Package Manager, so I'll be using that as well:

The link to the package: https://bintray.com/bincrafters/public-conan/glm%3Ag-truc

Conan file:

```
[requires]
glm/0.9.9.1@g-truc/stable

35 penerators]
Shares
sual_studio
```

I the command line to install the library (it will nerate props file that I can use with my Visual Studio pject)

```
nan install . -s build_type=Release -if
```

The library is header only, so it's also easy to download it manually if you prefer.

The actual code & benchmark

I've adapted the code for glm from scratchapixel.com:

```
// implementation adapted from https://www
float fresnel(const glm::vec4 &I, const gli
{
    float cosi = std::clamp(glm::dot(I, N)
    float etai = 1, etat = ior;
    if (cosi > 0) { std::swap(etai, etat);
    // Compute sini using Snell's law
    float sint = etai / etat * sqrtf(std::)
    // Total internal reflection
    if (sint >= 1)
        return 1.0f;
    float cost = sqrtf(std::max(0.f, 1 - s:
    cosi = fabsf(cosi);
    float Rs = ((etat * cosi) - (etai * co:
               ((etat * cosi) + (etai * cosi)
    float Rp = ((etai * cosi) - (etat * cosi)
               ((etai * cosi) + (etat * co:
```

```
return (Rs * Rs + Rp * Rp) / 2.0f;
}
```

The code uses a few maths instructions, dot product, multiplications, divisions, so that should keep CPU busy as well. Rather than a vector of doubles we're also using 4-element vectors, so the memory used has also increased.

The benchmark:

re are the results (time in milliseconds):

Operation	Vector Size	i7 4720 (4 Cores)	i7 8700 (6 Cores)
xecution::s eq	1k	0.032764	0.016361
execution::p ar	1k	0.031186	0.028551
openmp parallel for	1k	0.005526	0.007699
execution::s eq	10k	0.246722	0.169383
execution::p ar	10k	0.090794	0.067048
openmp parallel for	10k	0.049739	0.029835
execution::s	100k	2.49722	1.69768
execution::p ar	100k	0.530157	0.283268
openmp parallel for	100k	0.495024	0.291609
execution::s	1000k	25.0828	16.9457
execution::p ar	1000k	5.15235	2.33768

Operation	Vector Size	i7 4720 (4 Cores)	i7 8700 (6 Cores)
openmp parallel for	1000k	5.11801	2.95908

With the "real" computations we can see that parallel algorithms offer good performance. On my two Windows machines, for such operations, I could get speed-up that is almost linear to the number of cores.

For all tests I also showed you result from OpenMP and both implementations: MSVC and OpenMP seem to perform similarly.

Summary 35

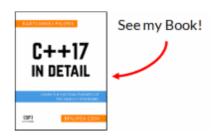
Shares

the article, I've shown three cases where you can rt using parallel execution and parallel algorithms. ile replacing all standard algorithms with just their d::execution::par version might be tempting, it's : always a good way to do that! Each operation that J use inside an algorithm might perform differently 1 be more CPU or Memory bound, and that's why you have to consider each change separately.

Things to remember

- parallel execution will, in general, do more work than the sequential version, it's because the library has to prepare the parallel execution
- it's not only the count of elements that is important but also the number of instructions that keeps CPU busy
- it's best to have tasks that don't depend on each other nor other shared resources
- parallel algorithms offers a straightforward way to spawn work into separate threads
- if your operations are memory bound that you cannot expect much performance increase, or in some cases, the algorithm might be slower
- to get decent performance increase always measure the timings for each problem, as in some cases the results might be completely different

Special Thanks to JFT for help with the article!



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For more references you can also have a look at my other resources about parallel algorithms:

- Fresh chapter in my C++17 In Detail Book about Parallel Algorithms.
- Parallel STL And Filesystem: Files Word Count Example
- Examples of Parallel Algorithms From C++17

Have a look at another article related to Parallel Algorithms: How to Boost Performance with Intel Parallel STL and C++17 Parallel Algorithms

Your Turn

What's the answer to my question from the title? Can **35**Shares get the amazing performance from parallel orithms?

ve you played with the parallel execution? Did it bring expected speed up?

the article I've only touched "simple" parallel orithms - std::transform. Things get even more nplicated when we talk about std::reduce.

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Benjamin Navarro · a year ago

Thanks for the nice article! Any idea why OpenMP better than the std parallel algorithms?

4 ^ | V Reply · Share >



Bartlomiej Filipek Mod → Benjamin Navarro • a ye hello, thanks for the comment! Not sure abimplementation of OpenMP, so I cannot giv answer here. I'll try to investigate..

∧ | ∨ • Reply • Share ›



Stefan Atev - Bartlomiej Filipek • a year a

OpenMP is optimized for finer-grain has less launch overhead than MSV algorithms, so it will be competitive Also, the way it's used here probabl some OpenMP code - schedule(stat chunk size) should be used to optin For example, on memory-bound stu chunk size large enough that you do (so try to have each thread process - 4KB worth of data); you definitely (adjacent threads reading the same (worse, writing to it... if you have load want a dynamic schedule (that has s etc.

Adding schedule(static, 512) to the may show more difference (wild con to test on my machine...)

Anyhow - keep the articles coming! 1 ^ V · Reply · Share ›



Bartlomiej Filipek Mod A Stefan · a year ago

Thanks for the explanation! I openMP so that I have some I could see how the new thin something that's available fo

Billy O'Neil also wrote e nice differences between anonly

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no, but it looks interesting!

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