January 2018, Q1

$$R = C[x, y, z]$$

I = (x, y)

a.) Prove that I is a prime ideal.

b.) Let $J = (x^2, y^2)$. Prove that if $f_1 \dots f_n$ belongs to J, then there is a subset of $\{f_1, \dots, f_n\}$ of at most three polynomials whose product belongs to J.

$$f_{l} - f_{l} \in J \implies f_{l} - f_{l} = f_{l} - f_{l} = f_{l} + f_{l} = f_{l} +$$

If f_1 belongs to J, then we are done. Suppose that this is not the case. In particular, there exist some polynomials a, b in R such that $f_1 = ax + by$ and either a is not divisible by x or b is not divisible by y. Because $f_1 \dots f_n$ belongs to J, there exist polynomials c, d in R such that $ax f_2 \dots f_n + by f_2 \dots f_n = f_1 \dots f_n = cx^2 + dy^2$.

$$\times (\alpha f_{2} \dots f_{n} - c \times) = y^{n} (\alpha f_{2} \dots f_{n})$$

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a, be
$$T \Rightarrow a = ex + 44$$

$$b = hx + iy$$

$$f_i^{\lambda} \in J \quad \text{Proceed by cases. This method is tedious.}$$

$$\text{We can also use the multidegree method.}$$

$$\text{mul+idegrees:} \quad \left(\text{deg}_{x} a + \sum_{i=1}^{2} \text{deg}_{x} \frac{f_{i}}{i+1}, \text{ deg}_{y} \frac{f_{i}}{i+1} + \sum_{i=1}^{2} \text{deg}_{y} \frac{f_{i}}{i+1} \right)$$

$$= \left(2 + de_{2}^{c}\right)^{c}$$
1.) If deg_x(a) = 1, then deg_y(f_2) (after rearranging). Otherwise, deg_x(f_2) = 1.

2.) If $deg_y(b) = 1$, then $deg_x(f_3) = 1$ (after rearranging). Otherwise, $deg_y(f_3) = 1$.

At any rate, the product $f_1 f_2 f_3$ belongs to J. c.) Let $K = (x^2 y^2, x^2 z^2)$. Prove that if $f_1 \dots f_n$ belongs to K, then there is a subset of $\{f_1, \dots, f_n\}$ of at most nine polynomials whose product belongs to K.

$$T_{x, \pm} = (x, \pm), \quad T_{x, \pm$$



August 2016, Q1

Let R be a commutative unital ring with units U(R).

- a.) Prove that U(R) is a multiplicative abelian group.
- b.) Let $R = Z[x]/(x^2)$. Prove that U(R) is isomorphic to $Z \times (Z/2Z)$.

$$R = \{\alpha \overline{x} + b\overline{1} \mid \alpha_1 b \in \mathbb{Z}\}$$

$$(\alpha \overline{x} + b\overline{1})(c\overline{x} + d\overline{1}) = (\alpha d + bc)\overline{x} + bd\overline{1} \in L(R) \iff bd = 1$$

$$\iff b = d = \pm 1$$

$$\mathbf{V}: \mathbf{L}(\mathbf{R}) \rightarrow \mathbf{Z} \times \mathbf{Z}_{\mathbf{a}}$$
Because this is a group homomorphism, we need \varphi(\overline{1}) = (0, 0) and \varphi(\overline{-1}) = (0, 1).

$$-\overline{|} = \alpha \overline{x} - \alpha \overline{x} - \overline{|} = (\alpha \overline{x} + \overline{|})(\alpha \overline{x} - \overline{|})$$

$$(0, 1) = \Psi(-\overline{|}) = \Psi(\alpha \overline{x} + \overline{|}) + \Psi(\alpha \overline{x} - \overline{|})$$

$$= (\alpha, 0) + (-\alpha, 1)$$

$$Z \times \{0\} \cup Z \times \{1\}$$

U(R) = {~x±T | ~∈ Z3

Define $\forall x = 1 = (a, 0)$ and $\forall x = 1 = (-a, 1)$. This is an isomorphism.

January 2018, Q2

Let
$$G = Z \times Z$$
.

a.) Give a nontrivial element (a, b) in G such that G/<(a, b)> is torsion-free.

$$A = \begin{pmatrix} a & b \\ a & b \end{pmatrix} \begin{pmatrix} a & b \\ a & b \end{pmatrix} \begin{pmatrix} a & b \\ a & b \end{pmatrix}$$

$$a = d \cdot g \cdot d \cdot (a \cdot b)$$

$$ab = db \cdot g \cdot d \cdot (a \cdot b)$$

b.) Let
$$H_1 = \langle (a, 0) \rangle$$
 and $H_2 = \langle (0, b) \rangle$. Prove that $G/(H_1 \times H_2) = Z/\langle gcb(a, b) \rangle \times Z/\langle lcm(a, b) \rangle$.

$$A = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ b & 1 & 1 \\ b & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c & 1 & 1 \end{pmatrix} \begin{pmatrix} a & 1 & 1 \\ c$$

The column space of A is $H_1 \times H_2$; the column space of SNF(A) is <gcd(a, b)> x <lcm(a, b)>. By the theory of Smith Normal Form, $G/(H_1 \times H_2)$ is isomorphic to Z/<gcd(a, b)> x Z/<lcm(a, b)>.

$$Z_{\alpha} \times Z_{b} \cong Z_{ab} \quad \text{if } \varsigma_{cd}(\alpha_{1}b) = 1$$

$$\alpha = p_{1}^{e_{1}} \cdots p_{k}^{e_{k}}$$

$$b = p_{1}^{e_{1}} \cdots p_{k}$$

$$\omega = Z_{p_{1}^{e_{1}}} \times Z_{p_{1}^{e_{k}}} \times Z_{$$

