## Problem Set 4 – due Friday, October 1 by 12:00 PM midnight

The Problem Set has **5 questions** on **3 pages**, with a total maximum credit of **30 points**. Please turn in well-organized, clearly written solutions (no scrap work). Questions 2 and 3 are taken from the textbook.

**Problem 1**) Two-dimensional harmonic oscillator: elliptical orbits [10 points]

Consider a two-dimensional harmonic oscillator with mass m and spring constant k in the xy-plane. We treat this system using Cartesian coordinates. The position vector of the mass is  $\vec{\mathbf{r}}(t) = x(t)\hat{\mathbf{x}} + y(t)\hat{\mathbf{y}}$  and the harmonic restoring force on the mass is  $\vec{\mathbf{F}} = -k\vec{\mathbf{r}}$ .

a) Using Newton's 2nd law,  $\vec{\mathbf{F}} = m \frac{d^2}{dt^2} \vec{\mathbf{r}}$ , derive explicitly the following (independent) differential equations (DEs) for the components x(t) and y(t):

$$\ddot{x} = -\Omega^2 x , \quad \ddot{y} = -\Omega^2 y , \tag{1}$$

where  $\Omega = \sqrt{k/m}$ .

Note: We here use the notation  $\Omega$  instead of  $\omega$  to avoid confusion, because  $\Omega$  is different from the time-dependent angular velocity  $\omega(t) = \frac{d}{dt}\phi(t)$  where  $\phi(t)$  is the azimuthal angle of the elliptical orbit (see figure next page).  $\omega = \frac{d}{dt}\phi = \sqrt{k/m} = \text{const.}$  only holds for the special case of a spherical orbit (with a = b = R in figure next page, cp. PS 2, P5).

b) Show that the DEs (1) are solved by

$$x(t) = a\cos(\Omega t), \quad y(t) = b\sin(\Omega t)$$
 (2)

where a > 0, b > 0 are constant amplitudes (without loss of generality we can assume  $a \ge b$ ).

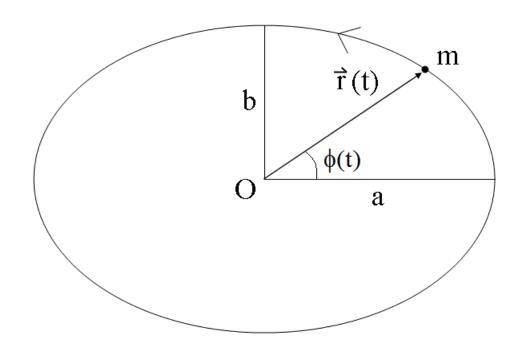
c) The components x(t), y(t) in Eq. (2) correspond to the following orbit in the xy - plane:

$$\vec{\mathbf{r}}(t) = a\cos(\Omega t)\hat{\mathbf{x}} + b\sin(\Omega t)\hat{\mathbf{y}} . \tag{3}$$

Show that the orbit is an ellipse with long axis a and short axis b (see figure below).

Hint: Show that x(t), y(t) fulfill the equation of an ellipse:  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ .

- d) Find the velocity vector  $\vec{\mathbf{v}}(t) = \frac{d}{dt}\vec{\mathbf{r}}(t) = v_x(t)\hat{\mathbf{x}} + v_y(t)\hat{\mathbf{y}}$ , and the speed  $v(t) = |\vec{\mathbf{v}}(t)|$ . Indicate in the figure at what points along the ellipse the speed v(t) is largest and smallest.
- e) Find the angular momentum  $\vec{\ell} = m\vec{\mathbf{r}}(t) \times \vec{\mathbf{v}}(t)$ . (Result:  $\vec{\ell} = abm\Omega \hat{\mathbf{z}}$ )
- f) The result in e) implies that  $\bar{\ell}$  is conserved. Why is this to be expected?



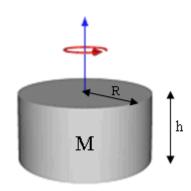
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- 2) Taylor, Problem 3.25 (page 102) "A particle of mass m is moving ..." [5 points]
- 3) Taylor, Problem 3.30 (page 103) "Consider a rigid body rotating ..." [5 points]

Problem 4) Moment of inertia of a solid cylinder [6 points]

Find the moment of inertia I of a solid cylinder of radius R and mass M spinning around its center axis.

Instruction: Replace the expression in Eq. (3.31),  $I = \sum_{\alpha=1}^{N} m_{\alpha} \rho_{\alpha}^{2}$ , by an integral using a uniform mass density  $\mu_{0} = \frac{M}{V}$  (similarly as we did before in Eq. (3.13)). Show:



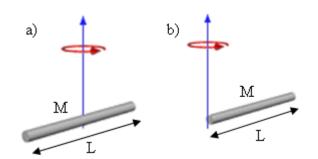
$$I = \mu_0 \int_{V} \left[ \rho(\vec{\mathbf{r}}) \right]^2 dV \tag{1}$$

where  $\rho(\vec{\mathbf{r}})$  is the radial distance from the rotation *axis* (not from the origin O!) of the point  $\vec{\mathbf{r}}$  in the body. In cylindrical polar coordinates the volume element is given by  $dV = d\rho\rho\,d\phi\,dz$  and Eq. (1) reads for the cylinder:  $I = \mu_0 \int_0^R d\rho\,\rho \int_0^{2\pi} d\phi \int_0^h dz\,\rho^2 = \mu_0 2\pi h \int_0^R d\rho\,\rho^3$ . Evaluate the integral and use  $M = \mu_0 V = \mu_0 \pi R^2 h$ . (Result:  $I = \frac{1}{2}MR^2$ )

## **Problem 5**) Moment of inertia of a rod [4 points]

Find the moment of inertia I of a thin rod of length L and mass M

- a) spinning around the center axis;
- b) spinning around the end.



Hint: Put the rod on the *x*-axis and use  $I = \mu_0 \int_{\text{rod}} \left[ \rho(x) \right]^2 dx$  where  $\rho(x)$  is the radial distance from the rotation axis of the point *x* along the rod.  $\mu_0 = M/L$  is the mass *per length* of the rod.