

Final Exam – due today by 12:00 PM midnight

The exam has **4 problems** on **4 pages**. The maximum credit of the exam is **320 points**.

Please submit your exam as a single file (not multiple files) using blackboard,
Course Materials / Final Exam.

Problem 1) Sphere rolling on track [80 points]

A solid sphere of mass $M = 1\text{ kg}$ with gravitational potential energy $U(y) = Mgy$ rolls without slipping on the track shown below, starting from rest at point A. Here y is the height of the bottom of the sphere over ground and $g = 9.8 \frac{\text{m}}{\text{s}^2}$ is Earth's acceleration of gravity.

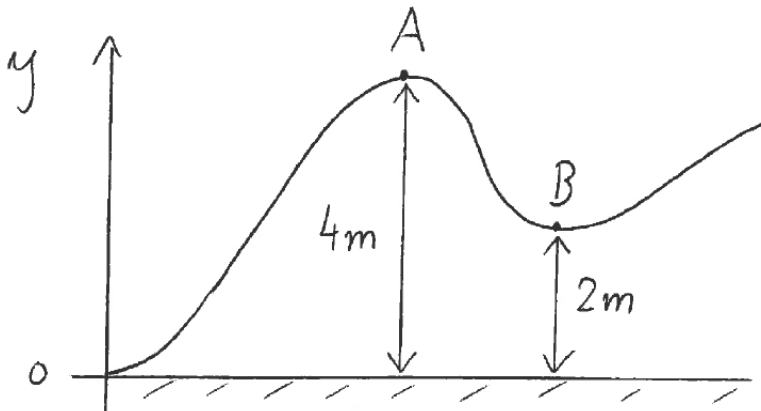
1. Assume that the sphere is rolling with linear speed v .

Show that the total kinetic energy of the sphere is $T = \frac{7}{10}Mv^2$.

Hint: The moment of inertia of a solid sphere of mass M and radius R is $I = \frac{2}{5}MR^2$.

Use the no-slip condition $\omega = \frac{v}{R}$ where ω is the angular velocity of the rolling sphere.

2. Find the total mechanical energy, E , in units of joules (J), of the sphere.
3. Find the linear speed, v , of the sphere at point B.



Problem 2) Line integral of a vector function [80 points]

Consider the vector function $\vec{F}(x, y, z) = \begin{pmatrix} yz \\ xz \\ xy \end{pmatrix}$.

1. Calculate $\vec{\nabla} \times \vec{F}$. Is \vec{F} conservative?

2. Consider the scalar function $U(x, y, z) = -xyz$. Show: $\vec{F} = -\vec{\nabla} U$.

3. Use the result from part 2 to find the line integral $\int_C d\vec{r} \cdot \vec{F}(\vec{r})$ along an arbitrary curve

$C: O \rightarrow \vec{P}$ from the origin $O = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ to an arbitrary point $\vec{P} = \begin{pmatrix} X \\ Y \\ Z \end{pmatrix}$ (see figure below).

Hint: It is not required to calculate the line integral. You may directly express $\int_C d\vec{r} \cdot \vec{F}(\vec{r})$

in terms of U by interpreting \vec{F} as a force and U as the associated potential energy.



Problem 3) Kepler problem [80 points]

Consider a planet of mass m with position vector $\vec{r}(t) = r(t) \hat{r}(t)$ moving in the xy - plane.

The planet is subject to the attractive gravitational force towards the star at the origin O of

the xy - plane. The potential energy of the planet is $U(r) = -\frac{k}{r}$ with a constant $k > 0$.

1. Find the angular momentum $\vec{L} = \vec{r} \times \vec{p}$ of the planet using polar coordinates.

Hint: Use $\vec{r} = r \hat{r}$, $\vec{p} = m \frac{d}{dt} \vec{r}$, $\frac{d}{dt} \hat{r} = \dot{\phi} \hat{\phi}$, and $\hat{r} \times \hat{\phi} = \hat{z}$. Result: $\vec{L} = L_z \hat{z}$ with $L_z = m r^2 \dot{\phi}$.

2. Find the force $\vec{F} = -\vec{\nabla} U(r)$ on the planet.

3. Find the Lagrange function $\mathcal{L}(r, \dot{r}, \dot{\phi}) = T - U$ for the two coordinates r, ϕ .

4. Find the Euler-Lagrange (EL) equation for ϕ (the ϕ - equation) for the Lagrange function found in part 3. Show that the ϕ - equation implies that L_z from part 1 is conserved.

5. Find the EL equation for r (the r - equation) for the Lagrange function found in part 3.

Show that the r - equation can be brought into the form $m \ddot{r} = -\frac{d}{dr} U_{\text{eff}}(r)$ with the

effective potential $U_{\text{eff}}(r) = -\frac{k}{r} + \frac{L_z^2}{2m} \frac{1}{r^2}$ with L_z from part 1.

6. Qualitatively sketch the effective potential $U_{\text{eff}}(r)$ found in part 5 as a function of r .

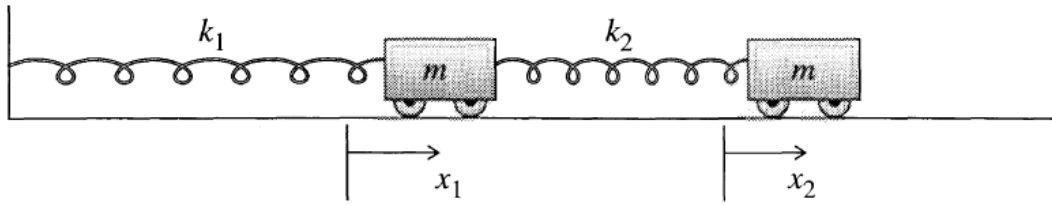
7. Consider the special case of a circular orbit with constant radius R . The radius R

corresponds to the minimum of $U_{\text{eff}}(r)$ found in part 5. Use the condition

$\left. \frac{d}{dr} U_{\text{eff}}(r) \right|_{r=R} = 0$ to find the (constant) angular velocity $\omega = \dot{\phi}$ of the circular orbit.

Problem 4) Two carts connected by springs [80 points]

Two carts with equal mass m can move on a horizontal track. The left cart is attached to a fixed wall by a spring with force constant k_1 and the two carts are attached to each other by a spring with force constant k_2 . Assume that $k_1 = 3k_2/2$ by writing $k_1 = 3k$ and $k_2 = 2k$ (with the same constant k for both carts). The displacements from the equilibrium positions of the two carts are x_1 and x_2 , respectively (see figure below).



1. Find the Lagrange function $\mathcal{L}(x_1, x_2, \dot{x}_1, \dot{x}_2)$ of the system.
2. Bring the Lagrange function to the form $\mathcal{L} = \frac{1}{2} \dot{\vec{x}} \cdot M \dot{\vec{x}} - \frac{1}{2} \vec{x} \cdot K \vec{x}$ with the vector $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$ and identify the mass matrix M and spring matrix K .

Result: $M = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix}$, $K = \begin{pmatrix} 5k & -2k \\ -2k & 2k \end{pmatrix}$.

3. Find the two eigenfrequencies ω_1, ω_2 from $\det(K - \omega^2 M) = 0$.
4. Find the associated eigenvectors \vec{v}_1, \vec{v}_2 from $(K - \omega^2 M) \vec{v} = 0$ with $\omega = \omega_1$ and $\omega = \omega_2$, respectively. Describe the normal modes of the system associated with these eigenvectors.