

Problem Set 3 - Solutions

Problem 1

$$\begin{aligned} a) \quad \vec{F}_g &= -mg \hat{y} = -mg (\sin \phi \hat{r} + \cos \phi \hat{\phi}) \\ &= -mg \sin \phi \hat{r} - mg \cos \phi \hat{\phi} \end{aligned}$$

$$\vec{F}_n = -T_n \hat{r}$$

$$\begin{aligned} \Rightarrow \vec{F} &= \vec{F}_g + \vec{F}_n = (-mg \sin \phi - T_n) \hat{r} \\ &\quad - mg \cos \phi \hat{\phi} \end{aligned}$$

$$\Rightarrow F_r = -mg \sin \phi - T_n, \quad F_\phi = -mg \cos \phi \quad (1)$$

$$b) \text{ Eq. (1.48) with } r = R = \text{const}, \quad \dot{r} = \ddot{r} = 0 :$$

$$F_r = -mR\dot{\phi}^2, \quad F_\phi = mR\ddot{\phi} \quad (2)$$

$$c) \text{ component } F_r \text{ of (1), (2)}$$

$$\Rightarrow -mg \sin \phi - T_n = \underbrace{-mR\dot{\phi}^2}_{\text{centripetal force}}$$

If $F_n = 0$ at top of loop ($\theta = 90^\circ$):

$$\Rightarrow -mg \underbrace{\sin(90^\circ)}_{=1} - \underbrace{F_n}_{=0} = -m R \underbrace{\dot{\theta}^2}_{\left(\frac{v}{R}\right)^2} \quad (v = \dot{\theta} R)$$

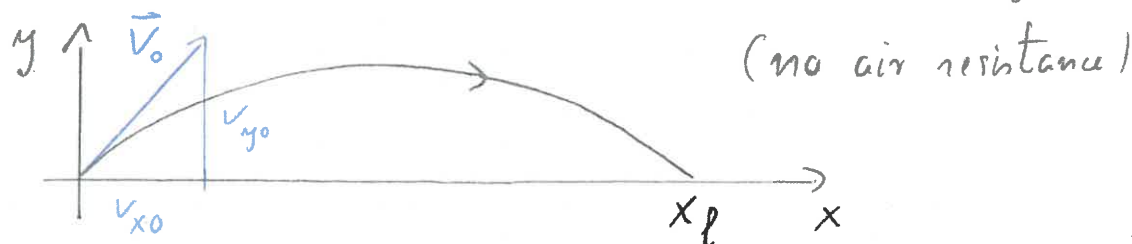
$$\Rightarrow -mg = -m R \left(\frac{v}{R}\right)^2$$

$$\Rightarrow v = v_{\min} = \sqrt{gR}$$

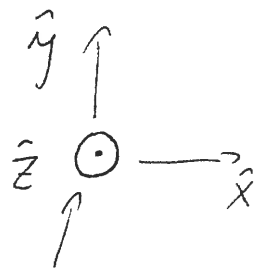
This is the minimum speed of the car
to stay on the track b/c $F_n = 0$ means
that the car is losing contact with the track

Problem 2 Range of projectile

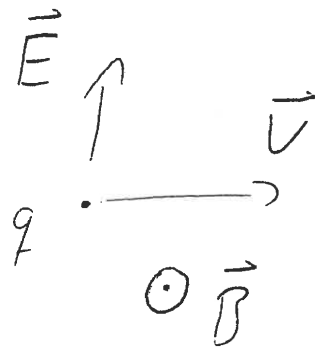
2.15 * Since the only force is the projectile's weight mg , Newton's second law implies that $\vec{r} = g$ and its two components can be integrated twice to give the well-known results $x = v_{x0}t$ and $y = v_{y0}t - \frac{1}{2}gt^2$ (if we take $x_0 = y_0 = 0$). At landing, $y = 0$, which gives the time of flight as $t = 2v_{y0}/g$. The range is just the value of x at this time, namely $x_l = v_{x0}t = 2v_{x0}v_{y0}/g$.



Problem 3



= out of paper plane



$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B} \quad , \quad \vec{E} = E\hat{y}$$

$$\vec{v} \times \vec{B} = (v\hat{x}) \times (B\hat{z}) = vB \underbrace{\hat{x} \times \hat{z}} = -vB\hat{y} = -\hat{y}, \text{ see below}$$

$$\Rightarrow \vec{F} = q \underbrace{(E - vB)}_{=0} \hat{y} \stackrel{!}{=} 0$$

$$\Rightarrow \underline{v = \frac{E}{B}} \quad \text{Application: velocity selector (Wien filter); google it!}$$

products of unit vectors:

$$\hat{x} \cdot \hat{x} = 1, \quad \hat{x} \cdot \hat{y} = 0, \text{ etc}$$

$$\text{in short: } \hat{e}_i \cdot \hat{e}_j = \delta_{ij} := \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

for all $i, j = 1, 2, 3$

$$\hat{x} \times \hat{y} = \hat{z}, \quad \hat{y} \times \hat{z} = \hat{x},$$

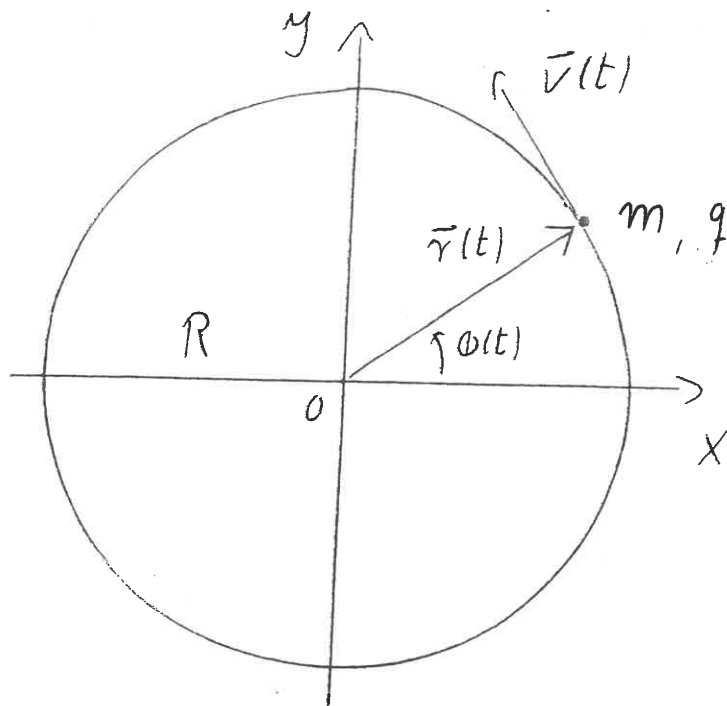
$$\hat{x} \times \hat{x} = 0, \text{ etc.}$$

in short:

$$\hat{e}_i \times \hat{e}_j = \epsilon_{ijk} \hat{e}_k$$

Problem 4

$\otimes \vec{B}$
 \uparrow
 = into plane



$$a) \quad \hat{r} = \cos(\phi) \hat{x} + \sin(\phi) \hat{y}$$

$$\text{with } \phi = \phi(t) = \omega t$$

$$\Rightarrow \frac{d}{dt} \hat{r} = \underbrace{[-\sin(\phi) \hat{x} + \cos(\phi) \hat{y}]}_{\hat{\phi}} \underbrace{\frac{d\phi}{dt}}_{\omega}$$

$$= \omega \hat{\phi} \quad (1)$$

$$\frac{d}{dt} \hat{\phi} = \underbrace{[-\cos(\phi) \hat{x} - \sin(\phi) \hat{y}]}_{-\hat{r}} \underbrace{\frac{d\phi}{dt}}_{\omega}$$

$$= -\omega \hat{r} \quad (2)$$

$$b) \quad \bar{r} = R \hat{r}$$

$$\vec{v} = \frac{d}{dt} \vec{r} = R \frac{d}{dt} \hat{r} \stackrel{(*)}{=} R \omega \hat{\phi}$$

$$\vec{a} = \frac{d}{dt} \vec{v} = R\omega \frac{d}{dt} \hat{\phi} \stackrel{(2)}{=} -R\omega^2 \hat{r} \quad (3)$$

$$\begin{aligned} c) \quad \hat{0} \times \hat{z} &= [-\sin(\theta) \hat{x} + \cos(\theta) \hat{y}] \times \hat{z} \\ &= -\sin(\theta) \underbrace{\hat{x} \times \hat{z}}_{-\hat{y}} + \cos(\theta) \underbrace{\hat{y} \times \hat{z}}_{\hat{x}} \\ &= \cos(\theta) \hat{x} + \sin(\theta) \hat{y} = \hat{r} \quad (4) \end{aligned}$$

$$\Rightarrow \vec{F} = q \vec{v} \times \vec{B} = q R \omega \hat{e} \times \vec{B}$$

$$\uparrow$$

$$= -B \hat{z}$$

$$= - \frac{1}{2} R \omega B \underbrace{\hat{O} \times \hat{Z}}_{= \hat{r}}, \text{ using (4)}$$

$$= -g R \omega B \hat{r} \quad = \text{directed to } O$$

(5) (centripetal force)

$$d) \quad \vec{F} = m \vec{a}$$

$$\Rightarrow -q R \omega B \hat{r} = -m R \omega^2 \hat{r} \quad \text{using (3), (5)}$$

$$\Rightarrow q \cancel{R} \omega B = m \cancel{R} \omega^2$$

$$\Rightarrow \omega = \frac{q B}{m} \quad \text{cyclotron frequency,} \\ \text{independent of } R!$$