

Problem Set 6 – due Friday, October 22 by 12:00 PM midnight

The Problem Set has **5 questions** on **3 pages**, with a total maximum credit of **30 points**.

Please turn in well-organized, clearly written solutions (no scrap work).

Problem 1) Line integral of a vector function [6 points]

Consider the vector function $\vec{F}(x, y, z) = \begin{pmatrix} 2y \\ 3yz \\ xz^2 \end{pmatrix}$.

a) Calculate $\vec{\nabla} \times \vec{F}$. Is \vec{F} conservative?

b) Calculate the line integrals $\int_{C_{ab}} d\vec{r} \cdot \vec{F}(\vec{r})$ from $\vec{r}_a = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ to $\vec{r}_b = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ along the curves

1. C_{ab} = straight line from \vec{r}_a to \vec{r}_b .

Hint: Use the parameterization $\vec{r}(t) = t\vec{r}_b$ with curve parameter $t: 0 \rightarrow 1$.

2. C_{ab} = sequence of straight lines $\vec{r}_a \xrightarrow{A} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \xrightarrow{B} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \xrightarrow{C} \vec{r}_b$.

Hint: Use $\int_{C_{ab}} d\vec{r} \cdot \vec{F}(\vec{r}) = \int_A d\vec{r} \cdot \vec{F}(\vec{r}) + \int_B d\vec{r} \cdot \vec{F}(\vec{r}) + \int_C d\vec{r} \cdot \vec{F}(\vec{r})$

and use the following parameterizations for the straight lines A, B, C :

$$\vec{r}_A(t) = \begin{pmatrix} t \\ 0 \\ 0 \end{pmatrix} \text{ with } t: 0 \rightarrow 1; \quad \vec{r}_B(t) = \begin{pmatrix} 1 \\ t \\ 0 \end{pmatrix} \text{ with } t: 0 \rightarrow 1; \quad \vec{r}_C(t) = \begin{pmatrix} 1 \\ 1 \\ t \end{pmatrix} \text{ with } t: 0 \rightarrow 1.$$

3. $C_{ab} : \vec{r}(t) = \begin{pmatrix} t \\ t^2 \\ t^4 \end{pmatrix}$ with $t: 0 \rightarrow 1$.

Problem 2) Curl of a central force field [6 points]

A central force field for a single particle has the general form $\vec{F}(\vec{r}) = F(r) \hat{r}$ where $F(r)$ is a scalar function of the magnitude $r = |\vec{r}|$ and $\hat{r} = \frac{\vec{r}}{r}$ is the unit vector of \vec{r} .

Question: Show that for a central force field: $\vec{\nabla} \times \vec{F} = 0$.

Hint: Write $\vec{F}(\vec{r}) = g(r) \vec{r}$ with $g(r) := \frac{F(r)}{r}$. Use Problem 5c of the previous Problem Set 5

to show $\vec{\nabla} \times \vec{F} = \vec{\nabla} \times (g \vec{r}) = (\vec{\nabla} g) \times \vec{r} + g \vec{\nabla} \times \vec{r}$ (where \vec{F} in Problem 5c of PS 5 is equal to \vec{r} here).

Now use Problems 4c and 5b of the previous Problem Set 5.

Problem 3) Line integral of a central force field [6 points]

a) Consider a time-dependent position vector $\vec{r}(t)$ with magnitude $r(t) = |\vec{r}(t)|$ and unit vector $\hat{r}(t)$.

Show: $\frac{d}{dt} r = \frac{d\vec{r}}{dt} \cdot \hat{r}$

Hint: Use Problem 4e of the previous Problem Set 5 with the choice $f(\vec{r}) = r$.

b) Consider a central force field $\vec{F}(\vec{r}) = F(r) \hat{r}$ as in Problem 2 and the line integral

$$\int_{C_{ab}} d\vec{r} \cdot \vec{F}(\vec{r}) = \int_{C_{ab}} d\vec{r} \cdot \hat{r} F(r) \text{ for an arbitrary curve } C_{ab} \text{ between given points } \vec{r}_a \text{ and } \vec{r}_b.$$

Show: $\int_{C_{ab}} d\vec{r} \cdot \vec{F}(\vec{r}) = \int_{r_a}^{r_b} dr F(r)$ where $r_a = |\vec{r}_a|$ and $r_b = |\vec{r}_b|$. Hint: Use the result of part a)

Is $\vec{F}(\vec{r})$ conservative? Is your conclusion consistent with the result of Problem 2?

Problem 4) Kinetic energy of a rolling hollow spherical shell [6 points]

Consider a hollow spherical shell (e.g. a basketball or a soccer ball) of radius R and mass M rolling on a surface without slipping with linear speed $v = \left| \frac{d}{dt} \bar{\mathbf{R}}_{CM}(t) \right|$, where $\bar{\mathbf{R}}_{CM}(t)$ is the position of the mass center (CM) = sphere center. As shown in class the total kinetic energy of the rolling spherical shell is

$$T = T_{CM} + T_{rot} = \frac{1}{2} M v^2 + \frac{1}{2} I \omega^2$$

where I is the moment of inertia and ω is the angular speed of the rotating spherical shell.

Question: Find T in terms of M and v .

Hint: The moment of inertia of a hollow spherical shell of radius R and mass M about the diameter is given by $I = \frac{2}{3} M R^2$. Use the no-slip condition to relate ω to v .

Problem 5) Energy of a two-dimensional harmonic oscillator [6 points]

Reconsider Problem 1 of Problem Set 4 "Two-dimensional harmonic oscillator: elliptical orbits".

Consider a general elliptical orbit, as given in Eq. (3) of this problem.

a) Find the kinetic energy $T(t) = \frac{1}{2} m [v(t)]^2$.

b) Find the potential energy $U(t) = \frac{1}{2} k [r(t)]^2$ (where $r(t) = |\bar{\mathbf{r}}(t)|$).

c) Find the total energy $E = T(t) + U(t)$, and show that E is constant.

d) Now consider the special case where $b = a$, i.e., a circular orbit of radius a .

Show that in this case both T and U are constant, and $T = U$.