
HW2

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Dylan Callaway

1

```
close all
clear
clc

torque_req = 10*3/8;
torque_max = 29.5;
V_max = 15;
V_req = V_max*torque_req/torque_max % V

V_req =

    1.9068
```

2

```
clear
clc

K_T = 16.1;
R_coil = 1.33;
% Is R_coil here the total resistance of the coils, or the
% resistance of a single coil that we need to add in parallel to the
% other 2 (N)?
omega_NL = 10300;
V_op = 18; % Assume ideal voltage source/constant voltage.
torque_max = 24.2;
K_e = V_op/omega_NL;
% Assuming the question is asking what the rotational speed is when
the
```

```
% max continuous torque is applied.  
omega = omega_NL - R_coil/K_T/K_e*torque_max % rpm
```

```
omega =
```

```
9.1561e+03
```

3

```
clear  
clc
```

```
omega_NL = 11500;  
torque_stall = 4.47;  
torque = 1.5;  
% Assume constant voltage.  
omega_load = torque/torque_stall*omega_NL % RPM
```

```
omega_load =
```

```
3.8591e+03
```

4

```
clear  
clc
```

```
K_T = 1.657;  
K_e = 1.23;  
R = 20.3;  
V = 14;  
torque = .15;  
dc0 = .25;  
dc1 = .85;  
V0 = dc0*V;  
V1 = dc1*V;  
omega0 = V0/K_e - R/K_e/K_T*torque % KRPM  
omega1 = V1/K_e - R/K_e/K_T*torque % KRPM
```

```
omega0 =
```

```
1.3515
```

```
omega1 =
```

```
8.1808
```

5

```
clear
clc

delay = 8;
T = 25;
Gp = 20/.1; % 20rpm / 10% dc
K_p = 1.2*T/delay/Gp
K_i = .5/delay
K_d = .5*delay
```

```
K_p =

    0.0187
```

```
K_i =

    0.0625
```

```
K_d =

    4
```

Published with MATLAB® R2018b