

The goal of this lecture is to complete the proof of the “local stable manifold theorem.” Recall the setting:

- (i)  $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$  is a Morse function with exactly one critical point at  $0 \in \mathbb{R}^n$ ,
- (ii)  $g$  is a Riemannian metric on  $\mathbb{R}^n$ ,
- (iii)  $\text{grad}_{\varphi, g} =: \text{grad}$  is the gradient vector field associated to  $g$  and  $\varphi$  – recall that  $\text{grad}$  is determined by the relation  $g(\text{grad}, X) = d\varphi(X)$ , for all vector fields  $X$ .
- (iv) The stable set  $S$  is defined to be the set of all  $x \in \mathbb{R}^n$  so that the negative gradient flow line starting at  $x$  converges to 0.

**Local Stable Manifold Theorem.** There is an open neighborhood  $U$  around 0 so that  $U \cap S$  is a smooth submanifold of  $U$ .

Recall the strategy for proving this theorem. We identify  $S$  with the set of gradient flow lines  $\mathbb{R}_{\geq 0} \rightarrow \mathbb{R}^n$  converging to 0, and make the following crucial observation: If  $\gamma \in W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$  satisfies the following equation

$$(*) \quad \gamma'(t) + \text{grad} \circ \gamma = 0,$$

then  $\gamma$  is  $C^\infty$  smooth, and conversely, if  $\gamma$  is a gradient flow line converging to 0, then  $\gamma$  lies in  $W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$  and  $\gamma$  satisfies  $(*)$ . In other words, if we define

$$s : W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \rightarrow L^2(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \text{ by } s(\gamma) = \gamma'(t) + \text{grad} \circ \gamma,$$

then  $s^{-1}(0) = S$ . This was established in the previous lecture. Here are three exercises related to the content of the previous lecture.

**Exercise 1** (Rellich Embedding). Let  $\gamma \in C_c^\infty$ . Prove that for  $t \geq 0$

$$\gamma(t)e^{-t} = \int_t^\infty \gamma(s)e^{-s} - \gamma'(s)e^{-s} ds,$$

and deduce that

$$|\gamma(t)| \leq \sqrt{2} \|\gamma\|_{W^{1,2}([t, \infty), \mathbb{R}^n)}$$

In particular,

$$(*) \quad \|\gamma\|_{C^0} \leq \sqrt{2} \|\gamma\|_{W^{1,2}}.$$

By density of  $C_c^\infty$  functions in  $W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$ , prove that  $W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \subset C^0(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$ . Moreover, conclude that  $|\gamma(t)| \rightarrow 0$  as  $t \rightarrow \infty$ . Applying the bound  $(*)$  to the derivatives of  $\gamma$ , conclude that

$$W^{k,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \subset C^{k-1}(\mathbb{R}_{\geq 0}, \mathbb{R}^n),$$

and that  $\|\gamma\|_{C^{k-1}} \leq C \|\gamma\|_{W^{k,2}}$ .

**Exercise 2.** Show that if  $X : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a  $C^{0,1}$  function (i.e. Lipshitz), and  $X(0) = 0$ , then the map  $\gamma \mapsto X \circ \gamma$  sends  $L^2(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$  to  $L^2(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$ .

More generally, if  $X$  is a  $C^{k,1}$  function with  $X(0) = 0$ , then  $\gamma \mapsto X \circ \gamma$  sends  $W^{k,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$  to  $W^{k,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$ . Hint: for both claims, it suffices to prove it first for smooth  $\gamma$ , and then use the density of smooth functions in  $W^{k,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$ .

**Exercise 3.** Conclude that if  $\gamma \in W^{k,2}$  satisfies the gradient flow line equation  $(*)$ , then  $\gamma \in W^{k+1,2}$ . Conclude that if  $\gamma \in W^{1,2}$  satisfies  $(*)$ , then  $\gamma \in W^{k,2}$  for all  $k$ . By the Rellich embedding  $W^{k,2} \subset C^{k-1}$ , conclude that  $W^{1,2}$  solutions of  $(*)$  are  $C^\infty$  smooth.

Now we turn to some new material. We will show that  $s^{-1}(0)$  is a manifold via the inverse function theorem for Banach spaces.

**Definition 1.** Let  $U \subset X$  and  $V \subset Y$  be open subspaces of Banach spaces  $X, Y$ . A map  $A : U \rightarrow V$  is **differentiable** at  $u \in U$  provided there is a bounded linear transformation  $dA_u : X \rightarrow Y$  so that

$$\lim_{\xi \rightarrow 0} \frac{\|A(u + \xi) - A(u) - dA_u(\xi)\|_Y}{\|\xi\|_X} = 0.$$

While this definition uses the norms on  $X, Y$ , it is clear that it only depends on the equivalence classes of the norms.

The map  $A : U \rightarrow V$  is **continuously differentiable** if  $u \mapsto dA_u \in \text{Hom}(X, Y)$  is a continuous function, where the latter is given the topology induced by the “operator norm.” The set of continuously differentiable functions is denoted  $C^1(U, V)$ .

A map  $A$  is  $C^k(U, V)$ ,  $k \geq 1$ , if  $dA$  is  $C^{k-1}(U, \text{Hom}(X, Y))$ .

In the appendix to this lecture, we define the terms **Banach manifold** and the **tangent bundle** of a Banach manifold.

**Inverse Function Theorem.** Let  $X, Y$  be Banach manifolds, and suppose  $A : X \rightarrow Y$  is a  $C^k$  map so that  $dA_x$  is an isomorphism (i.e. is continuous in the natural topologies on  $TX_x$  and  $TY_{A(x)}$ ). Then there are neighborhoods  $U \ni x$  and  $V \ni y$  so that  $A$  maps  $U$  to  $V$  diffeomorphically.

The derivatives of the vector field  $\text{grad}$  appear in the statement of the next claim. Thinking of  $\text{grad}$  is a function  $\mathbb{R}^n \rightarrow \mathbb{R}^n$ , it certainly has a derivative  $d\text{grad}_x : \mathbb{R}^n \rightarrow \mathbb{R}^n$  at all points  $x \in \mathbb{R}^n$  (warning: here we are *not* thinking of  $\text{grad}$  as a map  $\mathbb{R}^n \rightarrow T\mathbb{R}^n$  when we take its derivative). Similarly, we will denote the (symmetric) second derivative matrix by

$$dd\text{grad}_x : \mathbb{R}^n \otimes \mathbb{R}^n \rightarrow \mathbb{R}^n.$$

This is not a coordinate invariant notion.

It is clear that if  $x, y$  are two points of  $\mathbb{R}^n$ , then

$$\text{grad}(x + y) - \text{grad}(x) = \left[ \int_0^1 d\text{grad}_{x+sy} ds \right] \cdot y,$$

where we interpret the expression in the braces as a matrix  $\mathbb{R}^n \rightarrow \mathbb{R}^n$ .

**Claim 2.** The map  $s : W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \rightarrow L^2(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$  defined by  $s(\gamma) = \gamma' + \text{grad} \circ \gamma$  is a  $C^1$  map, and its derivative is given by

$$ds_\gamma(\eta)(t) = \eta'(t) + d\text{grad}_{\gamma(t)} \cdot \eta(t)$$

**Proof.** We begin by computing

$$s(\gamma + \eta)(t) - s(\gamma)(t) = \eta'(t) + \text{grad}(\gamma(t) + \eta(t)) - \text{grad}(\gamma(t)) = \eta'(t) + \left[ \int_0^1 d\text{grad}_{\gamma(t) + s\eta(t)} ds \right] \cdot \eta(t).$$

Hence,

$$s(\gamma + \eta)(t) - s(\gamma)(t) - ds_\gamma(\eta) = \left[ \int_0^1 d\text{grad}_{\gamma(t) + s\eta(t)} - d\text{grad}_{\gamma(t)} ds \right] \cdot \eta(t).$$

It follows that

$$\|s(\gamma + \eta)(t) - s(\gamma)(t) - ds_\gamma(\eta)\|_{L^2} \leq \left\| \int_0^1 d\text{grad}_{\gamma(t) + s\eta(t)} - d\text{grad}_{\gamma(t)} ds \right\|_{C^0} \|\eta\|_{L^2}.$$

We compute

$$\int_0^1 d\text{grad}_{\gamma(t) + s\eta(t)} - d\text{grad}_{\gamma(t)} ds = \left[ \int_0^1 \int_0^1 sdd\text{grad}_{\gamma(t) + rs\eta(t)} dr ds \right] \cdot \eta(t),$$

and hence

$$\left\| \int_0^1 d\text{grad}_{\gamma(t) + s\eta(t)} - d\text{grad}_{\gamma(t)} ds \right\|_{C^0} \leq \left\| \int_0^1 \int_0^1 sdd\text{grad}_{\gamma(t) + rs\eta(t)} dr ds \right\|_{C^0} \|\eta\|_{C^0}.$$

Since  $dd\text{grad}$  is a continuous function, and  $\gamma(t) + rs\eta(t)$  is a bounded function of  $t$  (i.e. for  $\|\eta\|_{C^0} \leq 1$ , we can suppose that  $\|\gamma + rs\eta\|_{C^0} \leq R$  for some large  $R$ ) we conclude some  $C$  independent of  $t$  and  $\eta$ ,  $\|\eta\|_{C^0} \leq 1$ , so that

$$\left\| \int_0^1 \int_0^1 sdd\text{grad}_{\gamma(t) + rs\eta(t)} dr ds \right\|_{C^0} \leq C,$$

and hence

$$\|s(\gamma + \eta)(t) - s(\gamma)(t) - ds_\gamma(\eta)\|_{L^2} \leq C \|\eta\|_{L^2} \|\eta\|_{C^0} \leq C' \|\eta\|_{W^{1,2}}^2,$$

where we have used the fact that  $\|-\|_{C^0} \leq c\|-\|_{W^{1,2}}$  and  $\|-\|_{L^2} \leq \|-\|_{W^{1,2}}$ . It follows that  $s$  is differentiable and its derivative at  $\gamma$  is  $ds_\gamma$ .

It is easy to show that  $ds_\gamma$  is a bounded function  $W^{1,2} \rightarrow L^2$ . Finally we show that  $\gamma \rightarrow ds_\gamma$  is continuous.

Given two curves  $\gamma_1, \gamma_2$ , we compute

$$ds_{\gamma_1 + \gamma_2}(\eta) - ds_{\gamma_1}(\eta) = d\text{grad}_{\gamma_1(t) + \gamma_2(t)} \cdot \eta(t) - d\text{grad}_{\gamma_1(t)} \cdot \eta(t).$$

Arguing as we did above, we conclude

$$ds_{\gamma_1 + \gamma_2}(\eta) - ds_{\gamma_1}(\eta) = \left[ \int_0^1 dd\text{grad}_{\gamma_1(t) + s\gamma_2(t)} ds \cdot \gamma_2(t) \right] \cdot \eta(t),$$

and similarly to the computations above we conclude

$$\|ds_{\gamma_1+\gamma_2}(\eta) - ds_{\gamma_1}(\eta)\|_{L^2} \leq \left\| \int_0^1 ddgrad_{\gamma_1(t)+s\gamma_2(t)} ds \right\|_{C^0} \|\gamma_2(t)\|_{W^{1,2}} \|\eta(t)\|_{W^{1,2}}.$$

We thereby obtain an estimate on the operator norm

$$\|ds_{\gamma_1+\gamma_2} - ds_{\gamma_1}\| \leq C \|\gamma_2(t)\|_{W^{1,2}},$$

where, for  $\gamma_2$  close to  $\gamma_1$ ,  $C$  depends only on  $\|\gamma_1\|_{C^0}$  and  $\|ddgrad\|_{C^0(B)}$  for some large ball  $B$ . It follows that

$$\lim_{\gamma_2 \rightarrow 0} \|ds_{\gamma_1+\gamma_2} - ds_{\gamma_1}\| = 0,$$

and so we have shown that  $\gamma \rightarrow ds_\gamma$  is continuous. This completes the proof of the claim.  $\square$

**Exercise 4.** Prove that  $ds_\gamma : W^{1,2} \rightarrow L^2$  is a bounded linear operator. Hint: if  $M$  is a bounded continuous matrix valued function, and  $\eta$  is in  $L^2$ , then  $\|M\eta\|_{L^2} \leq \|M\|_{C^0} \|\eta\|_{L^2}$ .

Our plan now is to show that the derivative of  $s$  at the zero solution  $0 \in W^{1,2}$  is a Fredholm operator. In fact, we will be able to show that  $ds_0$  is a surjective operator, and we will be able to explicitly identify the kernel of  $ds_0$  as the finite dimensional space spanned the positive eigenvalues of the Hessian of  $\varphi$ .

**Definition 3.** The **Hessian** of a function  $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$  at  $x$  is the bilinear form made of the second partial derivatives  $\text{Hess}_x = \partial_i \partial_j \varphi(x) dx_i \otimes dx_j$ . If  $x$  is a critical point, then  $\text{Hess}_x$  is coordinate independent.

In the presence of the metric  $g$ , we can define an endomorphism  $\text{Hess}_x^g : \mathbb{R}^n \rightarrow \mathbb{R}^n$  by

$$g(-, \text{Hess}_x^g(-)) = \text{Hess}_x(-, -).$$

**Lemma 4.** Let  $\text{grad} = \text{grad}_{\varphi, g}$  be the gradient vector field of  $\varphi$ , and suppose  $0$  is a critical point of  $\varphi$ . Then

$$d\text{grad}_0 = \text{Hess}_0^g \in \text{Hom}(\mathbb{R}^n, \mathbb{R}^n).$$

**Proof.** Let  $g = \sum_{k,j} g_{kj} dx^k \otimes dx^j$ , and write  $\text{grad} = \sum_k a_k \partial_k$ . Then

$$\partial_j \varphi = g(\text{grad}, \partial_j) = \sum_k a_k g_{kj} \implies \partial_i \partial_j \varphi = \sum_k g_{kj} \partial_i a_k + \sum_k a_k \partial_i g_{kj}.$$

Evaluating at  $x = 0$ , where  $a \equiv 0$ , we conclude

$$(1) \quad \partial_i \partial_j \varphi(0) = \sum_k g_{kj} \partial_i a_k = g(\partial_j, d\text{grad}_0(\partial_i))$$

Now we compute

$$(2) \quad g(\partial_j, \text{Hess}_0^g(\partial_i)) = \text{Hess}_0(\partial_i, \partial_j) = \partial_i \partial_j \varphi(0),$$

comparing (1) and (2), we conclude that  $d\text{grad}_0 = \text{Hess}_0^g$ , as desired.  $\square$

Now the fact that  $\varphi$  is a Morse function says precisely that  $\text{Hess}_0$  is a non-degenerate bilinear form. It follows that  $\text{Hess}_0^g$  is a  $g$ -self-adjoint operator, and hence has an eigenbasis

$v_1, \dots, v_n$ , with eigenvalues  $\lambda_1, \dots, \lambda_n$ , where we suppose that

$$\lambda_1 \leq \dots \leq \lambda_p < 0 < \lambda_{p+1} \leq \dots \leq \lambda_n.$$

The number  $p$  is precisely the **Morse index** of the critical point (i.e. the index of the bilinear form  $\text{Hess}_0$ ). Let's agree to call  $H_+$  the subspace spanned by  $v_{p+1}, \dots, v_n$ .

Define a map  $F : W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \rightarrow L^2(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \oplus H_+$  by

$$F(\gamma) = (s(\gamma), \pi_+ \gamma(0)).$$

Note that evaluating a curve  $\gamma$  at 0 is a continuous linear map, and hence  $\gamma \mapsto \pi_+ \gamma(0)$  is a smooth function  $W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n) \rightarrow H_+$ .

**Proposition 5.**  $dF_0$  is an isomorphism  $W^{1,2} \rightarrow L^2 \oplus H_+$ .

**Proof.** It suffices to prove that  $dF_0$  is a bijection, thanks to the open mapping theorem. The derivative of  $F$  at 0 is given by the formula

$$dF_0(\eta) = (\eta' + \text{Hess}_0 \cdot \eta, \pi_+ \eta(0)).$$

This follows from Claim 2, and the fact that  $\eta \mapsto \pi_+ \eta(0)$  is linear.

First we prove that  $dF_0$  is injective. It is convenient to write  $\eta$  as  $\eta = \sum \eta_i v_i$ , where the  $\eta_i$  are now  $W^{1,2}$  functions  $\mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$ . Suppose that  $dF_0(\eta) = 0$ . This is equivalent to

$$\eta'_i(t) = -\lambda_i \eta_i(t) \text{ for } i = 1, \dots, n \text{ and } \eta_{p+1}(0) = \dots = \eta_n(0).$$

Simple elliptic bootstrapping proves that  $\eta_1, \dots, \eta_n$  are  $C^\infty$  functions. In fact, it is clear that

$$\eta_i(t) = \eta_i(0) e^{-\lambda_i t}.$$

Since  $\eta_i$  is assumed to be integrable, we must have  $\eta_1(0) = \dots = \eta_p(0) = 0$ , otherwise  $\eta$  would blow up exponentially. Since we assume  $\eta_{p+1}(0) = \dots = \eta_n(0) = 0$ , we conclude that  $\eta$  is identically 0. It follows that  $dF_0$  is injective.

Now we prove that  $dF_0$  is surjective. Given  $\xi \in L^2$  and  $c_{p+1}, \dots, c_n \in H_+$ , we want to define  $\eta$  so that

$$\eta_i(t) + \lambda_i \eta_i(t) = \xi_i(t),$$

and  $\eta_i(0) = c_i$  for  $i > p$ . Define

$$\eta_i(t) = -e^{-\lambda_i t} \int_t^\infty e^{\lambda_i s} \xi_i(s) ds \text{ for } i = 1, \dots, p,$$

and define

$$\eta_i(t) = e^{-\lambda_i t} c_i + e^{-\lambda_i t} \int_0^t e^{\lambda_i s} \xi_i(s) ds \text{ for } i = p+1 = \dots = n.$$

We check that this is well-defined, i.e. the resulting  $\eta$  is indeed in  $W^{1,2}$ . First we will check that  $\eta$  is in  $L^2$ . Let  $\rho$  be some test function. Then for  $i = 1, \dots, p$ , we compute

$$\int_0^\infty \eta_i(t) \rho(t) dt = - \int_0^\infty \int_t^\infty e^{\lambda_i(s-t)} \rho(t) \xi_i(s) ds dt = - \int_0^\infty \int_0^\infty e^{\lambda_i z} \rho(t) \xi_i(z+t) dz dt.$$

where we have made the change of coordinates  $z = s - t$ . Now we switch the order of integration:

$$\int_0^\infty \int_0^\infty e^{\lambda_i z} \rho(t) \xi_i(z+t) dz dt = \int_0^\infty e^{\lambda_i z} \int_0^\infty \rho(t) \xi_i(z+t) dt dz.$$

We estimate

$$\left| \int_0^\infty \rho(t) \xi_i(z+t) dt \right| \leq \|\rho\|_{L^2} \|\xi_i\|_{L^2},$$

and hence

$$\left| \int_0^\infty \eta_i(t) \rho(t) dt \right| = \left| \int_0^\infty e^{\lambda_i z} \int_0^\infty \rho(t) \xi_i(z+t) dt dz \right| \leq \|e^{\lambda_i z}\|_{L^1} \|\rho\|_{L^2} \|\xi_i\|_{L^2} = C \|\rho\|_{L^2}.$$

Since  $\lambda_i < 0$ , the  $L^1$  norm of  $e^{\lambda_i z}$  is finite. We conclude that  $\eta_i$  is in  $L^2$  since pairing it with test functions defines a bounded transformation  $L^2 \rightarrow L^2$  (here we use reflexivity of  $L^2$ ).

**Remark.** It is easy to show that  $\eta$  is given by a convolution of  $\xi$  with an integrable kernel. It follows that  $\eta$  is in  $L^2$  by Young's inequality. Our argument essentially reproves Young's inequality in our specific setting.

**Exercise 5.** Prove that  $\eta_i$  is in  $L^2$  for  $i = p+1, \dots, n$ .

Having established that  $\eta$  is in  $L^2$ , we check that  $\eta'_i + \lambda_i \eta_i = \xi_i$  holds weakly in  $L^2$ . Suppose  $i = 1, \dots, p$ . To check that an equation holds weakly, we pair with a test function  $\rho$ . By definition of “weak” we have

$$\int_0^\infty (\eta'_i(t) + \lambda_i \eta_i(t)) \rho(t) dt = \int_0^\infty \eta_i(t) (\lambda_i \rho(t) - \rho'(t)) dt.$$

We write

$$\int_0^\infty \eta_i(t) (\lambda_i \rho(t) - \rho'(t)) dt = \int_0^\infty \int_t^\infty e^{\lambda_i(s-t)} \xi_i(s) (\rho'(t) - \lambda_i \rho(t)) ds dt.$$

Now we change the order of integration:

$$\int_0^\infty \int_t^\infty e^{\lambda_i(s-t)} \xi_i(s) (\rho'(t) - \lambda_i \rho(t)) ds dt = \int_0^\infty \xi_i(s) e^{\lambda_i s} \left[ \int_0^s e^{-\lambda_i t} (\rho'(t) - \lambda_i \rho(t)) dt \right] ds.$$

We compute

$$\int_0^s e^{-\lambda_i t} (\rho'(t) - \lambda_i \rho(t)) dt = \int_0^s \frac{d}{dt} [e^{-\lambda_i t} \rho(t)] dt = e^{-\lambda_i s} \rho(s),$$

where we use the fact that  $\rho$  is a test function, and hence is compactly supported in  $(0, \infty)$ .

It follows that

$$\int_0^\infty (\eta'_i(t) + \lambda_i \eta_i(t)) \rho(t) dt = \int_0^\infty \xi_i(s) e^{\lambda_i s} \left[ \int_0^s e^{-\lambda_i t} (\rho'(t) - \lambda_i \rho(t)) dt \right] ds = \int_0^\infty \xi_i(s) \rho(s) ds,$$

which demonstrates that  $\eta'_i + \lambda_i \eta_i = \xi_i$  holds weakly (for  $i = 1, \dots, p$ ).

**Exercise 6.** Show that  $\eta'_i + \lambda_i \eta_i = \xi_i$  holds weakly for  $i = p+1, \dots, n$ .

Now since  $\eta_i$  and  $\xi_i$  are in  $L^2$ , and  $\eta'_i = \xi_i - \lambda_i \eta_i$ , we conclude that the weak derivative of  $\eta_i$  is in  $L^2$  and hence  $\eta_i$  is in  $W^{1,2}$ .

Finally, it is clear that  $\eta_i(0) = c_i$  for  $i = p+1, \dots, n$ . Thus it follows that  $dF_0\eta = (\xi, c)$ , and hence  $dF_0$  is surjective. This completes the proof that  $dF_0$  is an isomorphism.  $\square$

By the inverse function theorem, it follows that  $F$  is a  $C^1$  diffeomorphism in some neighborhood of 0. In fact, one can show without too much additional work that the map  $s$  is  $C^\infty$  (because  $\text{grad}$  is a smooth vector field). For the details involved, the reader is referred to Chris Wendl's "Lectures on Holomorphic Curves," pages 85-87. It then follows that  $F$  is a smooth diffeomorphism on some neighborhood of 0.

Consider the composite function

$$\begin{array}{ccccccc} H_+ & \longrightarrow & 0 \oplus H_+ & \xrightarrow{F^{-1}} & W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^N) & \xrightarrow{\text{ev}_0} & \mathbb{R}^n \\ & & & & \searrow & \nearrow & \\ & & & & \Phi & & \end{array}$$

The map  $\Phi$  is smooth and defined on small some disk  $D(r) \subset H_+$ . Since  $\pi_+\Phi(x) = x$ , we conclude that  $\Phi$  is a section of the orthogonal projection  $\pi_+$  (over  $D(r)$ ), and hence  $\Phi$  defines a smooth submanifold of  $\mathbb{R}^n$  (a graph over  $D(r)$ ).

It is clear that the unique gradient flow line starting at any point  $\Phi(x) \in \Phi$  converges to 0 (by our construction). Indeed, the flow line starting at  $\Phi(x)$  is  $F^{-1}(0, x)$ . The next lemma will establish that the graph  $\Phi$  is precisely the stable set near 0.

**Lemma 6.** There is a neighborhood  $U$  of 0 so that any flow line starting in  $U$  and converging to 0 actually starts on  $\Phi \cap U$ .

**Proof.** First we claim that any trajectory  $\gamma : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}^n$  converging to 0 satisfies  $\gamma(t) \in \Phi$  for  $t$  sufficiently large. We will use the result that any gradient flow line converging to 0 is automatically in  $W^{1,2}$  (cf. Exercise 7).

Consider the elements  $\gamma_T \in W^{1,2}(\mathbb{R}_{\geq 0}, \mathbb{R}^n)$  given by  $\gamma_T(t) = \gamma(t+T)$ . It is clear that  $\gamma_T$  is still a gradient flow line, and moreover, that  $\|\gamma_T\|_{W^{1,2}} \rightarrow 0$  as  $T \rightarrow \infty$ , since

$$\|\gamma_T\|_{W^{1,2}} = \|\gamma|_{[T, \infty)}\|_{W^{1,2}}.$$

Since our map  $F$  is a diffeomorphism on a small neighborhood of 0, we conclude that  $\gamma_T$  eventually enters the domain where  $F$  is a diffeomorphism, and hence  $\gamma_T = F^{-1}(0, x)$  for some  $x$  (here  $x$  depends on  $T$ ). Therefore  $\gamma_T(0) \in \Phi$ , hence  $\gamma(T) \in \Phi$ . This proves that  $\gamma$  eventually enters  $\Phi$ .

Next, pick a bounded open set  $U'$  of 0 with the property that so that  $\overline{\Phi \cap U'} \subset \Phi$ . By compactness of  $\overline{\Phi \cap U'} \subset \Phi$ , it follows that there is  $\delta > 0$  so that for every  $x \in \Phi \cap U'$ , the flow line through  $x$  can be defined on  $[-\delta, \infty)$ , and that this flow line remains on  $\Phi$ . In other words, we can extend the flow line backwards in time by  $\delta$ , while remaining on the graph  $\Phi$ .

To establish the conclusion of the lemma, we will use the following we claim: there is a smaller open set  $U \subset U'$  with the following property: every trajectory which starts in  $U$  either remains in  $U'$  forever, or leaves  $U'$  and never comes back inside  $U$  (a similar statement

is proved on page 50 of Milnor's notes on the h-cobordism theorem). This claim is proved in Exercise 8.

Assuming this result, we can complete the proof of the lemma. If  $\gamma$  is a gradient flow line starting in  $U$  and  $\gamma$  converges to 0, then clearly  $\gamma$  cannot leave  $U'$ . Look at the set of times  $t$  so that  $\gamma(t) \in \Phi$ . Since  $\gamma \rightarrow 0$ , we know that  $\gamma(t)$  is eventually in  $\Phi$ , so this set of times is non-empty. Either (case 1)  $\gamma(0) \in \Phi$ , or (case 2) there is some time  $t > \delta$  so  $\gamma(t) \in \Phi$  and  $\gamma(t - \delta) \notin \Phi$ . However, since  $\gamma(t) \in \Phi \cap U'$ , we conclude that the flow line through  $\gamma(t)$  can be extended backwards in time by amount  $\delta$  *while remaining on  $\Phi$* . Therefore  $\gamma(t - \delta) \in \Phi$ , and so case 2 cannot happen. It follows that  $\gamma(0) \in \Phi$ , and since  $\gamma(0) \in U$ ,  $\gamma(0) \in \Phi \cap U$ . We have shown that every flow line starting in  $U$  converging to 0 must start on  $\Phi \cap U$ , as desired.  $\square$

**Corollary 7.** Let  $S$  denote the stable set of 0, and let  $U$  be the open set furnished by the preceding lemma. Then  $S \cap U = \Phi \cap U$ , and so we have shown that  $S$  is a manifold near 0. The dimension of  $S \cap U$  is equal to  $\dim \Phi = n - p$ , where  $p$  is the Morse index of the critical point.  $\square$

Here are the two exercises used in the proof of Lemma 6.

**Exercise 7.** Let  $\text{grad} : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be the gradient vector field. We will use the fact that  $\text{grad}(0) = 0$  and  $d\text{grad}_0$  is an isomorphism. Suppose that  $\gamma : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}^n$  is a flow line converging to 0.

- (a) Prove that  $\gamma$  is in  $L^2$  if and only if  $\text{grad} \circ \gamma$  is in  $L^2$ . Hint: show that

$$|\gamma(t)| < c |\text{grad} \circ \gamma(t)|$$

for  $t$  sufficiently large, for some  $c > 0$ .

- (b) Prove that  $\text{grad} \circ \gamma$  is in  $L^2$  using the relation

$$\frac{d}{dt}(\varphi \circ \gamma) = -g(\text{grad} \circ \gamma, \text{grad} \circ \gamma).$$

- (c) Now that we know that  $\gamma$  is in  $L^2$ , conclude that  $\gamma'$  is also in  $L^2$  using the gradient flow line equation.

- (d) Conclude that any flow line  $\gamma$  converging to 0 is actually in  $W^{1,2}$ .

**Exercise 8.** Given a bounded open neighborhood  $U'$  of 0, one can always find a smaller open set  $U \subset U'$  so that every trajectory  $\gamma$  starting in  $U$  either remains in  $U'$ , or leaves  $U'$  and never returns to  $U$ .

- (a) Pick  $U''$  compactly supported in  $U'$  around 0 so that  $g(\text{grad}, \text{grad}) > b$  on  $U' \setminus U''$ . Pick  $U_\epsilon \subset U''$  so that  $\max_{U_\epsilon} \varphi - \min_{U_\epsilon} \varphi < \epsilon$ . Using the fact that

$$\frac{d}{dt}\varphi(t) = -g(\text{grad}, \text{grad}),$$

conclude that any trajectory starting and ending in  $U_\epsilon$  must spend time less than  $b^{-1}\epsilon$  in  $U' \setminus U''$ .



(b) Since  $\partial U''$  is compact and contained in  $U'$ , conclude a minimum amount of time needed to flow from  $\partial U''$  to  $\mathbb{R}^n \setminus U'$ .

(c) Conclude that we can pick  $\epsilon$  small enough so that any flow starting and ending in  $U_\epsilon$  cannot leave  $U'$ . Taking  $U = U_\epsilon$  proves the claim.

## Appendix

**Definition 8.** For  $k \geq 1$ , a  $C^k$  **Banach manifold**  $\mathcal{X}$  is a topological space covered by open sets homeomorphic to open subsets of Banach spaces, where the transitions functions are  $C^k$  maps. More precisely, a Banach manifold comes equipped with a maximal atlas of coordinate charts:  $c : U_c \subset \mathcal{X} \rightarrow c(U) \subset X_c$ , where  $X_c$  is a Banach space,  $c : U_c \rightarrow c(U)$  is homeomorphism onto an open set, and so that the transition homeomorphism

$$\rho_{21} = c_2 \circ c_1^{-1} : c_1(U_1 \cap U_2) \rightarrow c_2(U_1 \cap U_2)$$

is a  $C^k$  map.

We define a continuous map  $A : \mathcal{X} \rightarrow \mathcal{Y}$  between  $C^k$  Banach spaces to be  $C^r$  ( $r \leq k$ ) if  $c_2 \circ A \circ c_1^{-1}$  is a  $C^r$  map, for all choices of coordinates  $c_1, c_2$  around  $x$  and  $A(x)$  respectively.

**Definition 9** (the tangent bundle). For the purposes of this definition, let's agree to say that a Banach space is a topological vector space equipped with an equivalence class of complete metrics defining its topology.

For  $k \geq 1$ , let  $\mathbf{BMan}_k$  be the category of  $C^k$  Banach manifolds, with  $C^k$  maps between them, let  $\mathbf{BSpace}_k$  be the category of Banach spaces with  $C^k$  maps between them, and let  $\mathbf{Bun}_k$  be the category of Banach space bundles over Banach manifolds. A morphism in  $\mathbf{Bun}_k$  between bundles  $E_1 \rightarrow B_1$  and  $E_2 \rightarrow B_2$  is a pair  $(f, F)$  such that  $f : B_1 \rightarrow B_2$  is a  $C^k$  map and  $F$  is a  $C^{k-1}$  section of the Banach space bundle  $\mathrm{Hom}(B_1, f^*E_2) \rightarrow B_1$ .

There is a functor  $\tau : \mathbf{BSpace}_k \rightarrow \mathbf{Bun}_k$  sending a Banach space  $X$  to the trivial bundle  $\tau(X) = X \times X \rightarrow X$ , and which sends a morphism  $f : X \rightarrow Y$  to the pair  $(f, df)$ , where  $df$  is the  $C^{k-1}$  section of  $\mathrm{Hom}(\tau(X), f^*\tau(Y)) = \mathrm{Hom}(X, Y) \times X \rightarrow X$ .

The tangent bundle functor  $T : \mathbf{BMan}_k \rightarrow \mathbf{Bun}_k$ , is defined by three axioms:

(i) We require  $T(f : X \rightarrow Y) = (f, df)$ , i.e.  $T(f)$  is a bundle map “over  $f$ ” (where we abuse notation and use the symbol  $d$  for  $T$  as well as for  $\tau$ ).

(ii) The following diagram should commute up to a natural isomorphism  $T \circ j \rightarrow \tau$ :

$$\begin{array}{ccc} \mathbf{BSpace}_k & \xrightarrow{\tau} & \mathbf{Bun}_k \\ \downarrow j & & \uparrow T \\ \mathbf{BMan}_k & & \end{array}$$

where  $j$  is the obvious inclusion functor  $\mathbf{BSpace}_k \rightarrow \mathbf{BMan}_k$ . This natural isomorphism should be thought of as part of the data of  $T$ .

(iii) If  $i : U \rightarrow M$  is the inclusion of an open set, then the map  $di : TU \rightarrow i^*TM$  is an isomorphism.

It is not very hard to show that this determines  $T$  up to unique natural isomorphism, i.e. if  $T'$  is another such functor then there is a unique natural isomorphism  $T \rightarrow T'$  so that

$$\begin{array}{ccc} \tau & \longrightarrow & T' \circ j \\ \downarrow & & \nearrow \\ T \circ j & & \end{array}$$

commutes.