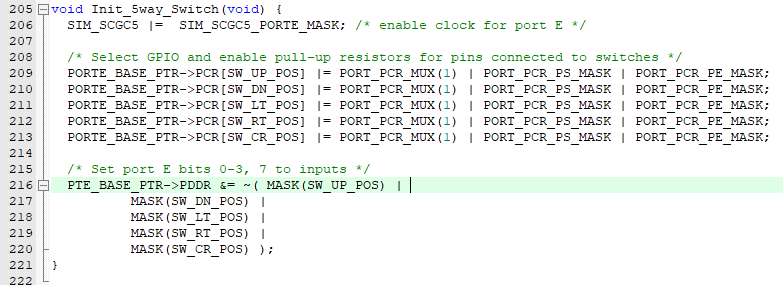
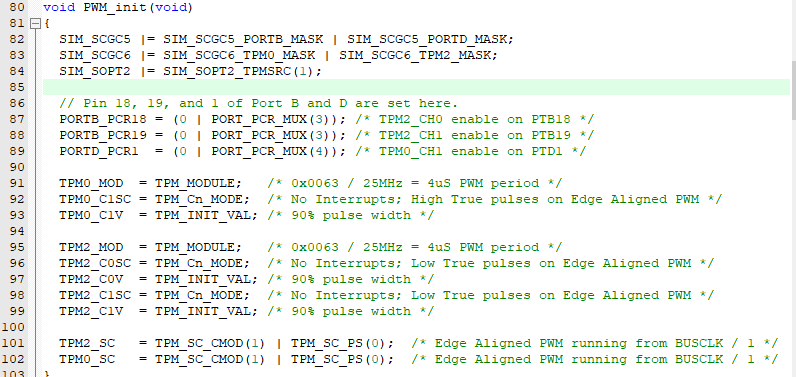
Freedom Touch Software

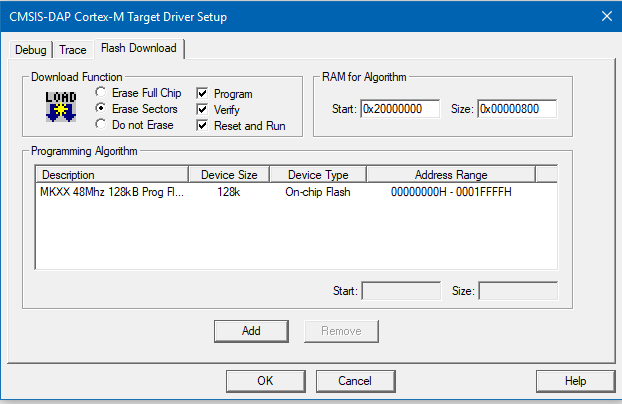
<https://www.nxp.com/support/developer-resources/evaluation-and-development-boards/freedom-development-boards/adaptors/touch-software:FREESCALE-TOUCH-SOFTWARE>

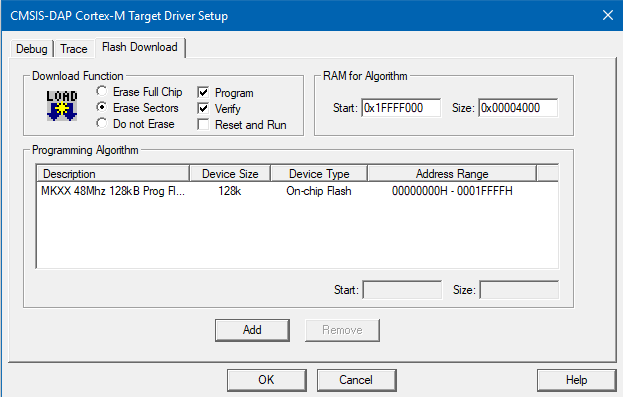
RTOS – Real-time operating system is an operating system intended to serve real-time applications that process data as it comes in, typically without buffer delays.

With PWM\_Init() and Init\_RGB\_LEDs, we have two conflicting pins and ports…





From complicated project



In events.c there is a function called TSS1\_fCallBack1(TSS\_CONTROL\_ID u8ControlId)

