NOTE: I was unable to process my image data with the code through Sourcetree. Planning to get help during class on 11/22. Committed files straight from my computer to github.

## Skills Inventory:

### Shapes

- 1. line, ellipse, rect, triangle, quad, arc, curve
- draw hallway background
- 2. fill, stroke, strokeWeight, noFill, noStroke, color
- draw ghosts
- 3. Modes: CORNER, CORNERS, CENTER, RADIUS
- draw hallway background

# System

- 4. setup(), draw()
- draw background and set canvas size to 400x400
- 5. background(), random(), noise()
- set background color to black

### Loops

- 16. for loop, while loop
- loop ghosts floating in the background using a for loop
- 17. A nested loop
- traverse an array for values within the above loop

### **Functions**

- 24. Pass by reference (objects): declare and use a function that takes an object as an argument
- create an array object that stores background ghost x position values. call the array in a function that draws the ghosts and builds on the array input

## Classes/objects

- 28. Write a class with a constructor function
- call a subclass that draws the ghosts in the main class
- 29. Use the keyword new to instantiate an object
- create a class that draws the ghosts

#### Lists

- 33. Initialize and populate an array
- write an array for ghost movement
- 34. Initialize and populate an ArrayList
- the above array contains a list of x locations
- 35. Manage a set of objects with an array or ArrayList
- the ghosts move based on the above values, which are traversed and added to list
- 36. Use an ArrayList method: size(), get(), remove(), contains()
- use size to traverse the length of the array

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#### Vectors

- 38. Use the PVector class
- regulate ghost movement using pvector
- 39. Do some basic physics: use position, velocity, and acceleration (due to gravity) vectors
- x location, speed, and distance = velocity of ghosts
- 40. Find the direction and distance between two points
- use velocity
- 41. Create a random 2D vector
- the ghost movement vector takes random y location values

## Plan:

