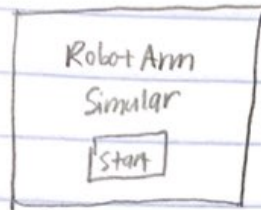
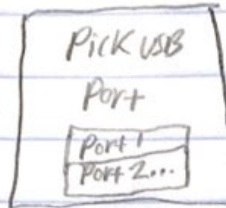


# TPI storyboard



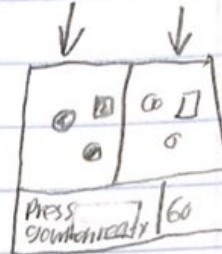
Start screen



Selecting port  
for Arduino



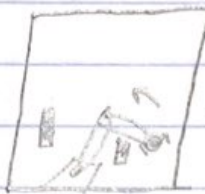
livedepth ~~live~~ live camera view



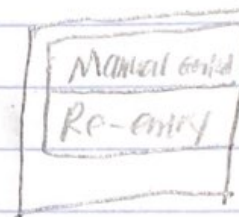
User selects  
when they want scan  
to run



User types in  
points they want  
to arm to go  
between



Robot arm  
moves between  
points while avoiding  
obstacles and keeps  
off the floor



User is prompted  
whether they want  
search to run  
again or try  
manual control



If manual  
control is chosen,  
the user can  
move the arm  
using computer  
input