Number	Short Description	Threat	Vulnerability	Measures	Impact	Probability	Proposed Approach
	Machine						
MS-1.001	Dangerous voltages	Parts may become energized	Wires/cables are loose	Never work under power	High	Low	Have specialized people work on it
MS-1.002	Collisions	Collisions between robot and objects or people	Insufficient safety sensors or shielding around the robot	Install light curtains or enclosure around the robot	High	Moderate	Place screens around the workplace with light curtains for entrances
MS-1.003	Crushing hazards	Crushing hazards with moving parts	Insufficient shielding of moving parts	Use of shields, safe working distance	High	Moderate	Place physical shielding and conduct periodic inspections
MS-1.004	Speed	High speeds can cause parts to come loose	Incorrect setting causes excessive speed	Add speed control to a specific zone	High	Moderate	Lower speed when interacting with humans
MS-1.005	Software	Software errors may cause unexpected movements	Software is not fully tested for safety	Regular software updates and testing	High	Low	Frequently perform software testing and updates
MS-1.006	External influences (Moisture or dust)	Failures due to moisture or dust	Moisture can damage electronics, dust can block moving parts	Use of enclosures and maintenance planning	Moderate	Moderate	Regular maintenance and cleaning, install in a conditioned environment
MS-1.007	Hardware failure	Unexpected component failure	Components may wear out or malfunction	Preventive maintenance, diagnostic systems	High	Low	Regular maintenance and timely replacement of worn-out parts
MS-1.008	Overloading on cobots	Cobot gets overloaded and malfunctions	Objects are too heavy or incorrect workload calculation	Set maximum load, force limits	Moderate	Low	Monitor and control workload limits
MS-1.009	Maintenance access	Accidents during maintenance work	No lockout during maintenance	Use of lock-out/tag-out systems	High	Moderate	Implement lockout systems and safety procedures

	Personal						
		Can be dangerous when no supervisor is present	Lack of training/guidance	Always work under the	High	High	Have students complete assignments to
PR-2.001	Inexperience	Can be dangerous when no supervisor is present	Lack of training/guidance	supervision of a mentor	High	Tilgii	broaden their knowledge under supervision
			Project timeline and quality	Make plans with buffer time			Reassign tasks as needed and account for buffer
		ITeam members can be absent for an indefinite period	may be jeopardized	and take over tasks when	Moderate	High	time in the planning
PR-2.002	Illness and absence		iliay be jeopardized	necessary			time in the planning
		Miscommunication between team members	The final project may differ	Write down everything	Moderate	Moderate	Use checklists/rubrics and take minutes of all
PR-2.003	Communication errors		from the original plan	discussed and reflect on it	Moderate	Moderate	meetings and key decisions
		Errors during robot/cobot operation	Poor training or unclear	Train students under mentor	High	Moderate	Create good interfaces and assignments and
PR-2.004	Incorrect operation		materials	supervision			perform periodic evaluations

	Other						
			Scope change or waiting for			I Moderate	Inventory management and encure feet delivery
		Lack of access to necessary resources for completing	materials can cause time	List and order all necessary	Moderate		Inventory management and ensure fast delivery
OR-3.001	Availability of resources	the task	pressure	items in advance			when needed
		A (large) part of the project needs to be completely		Assess whether the change	Madarata	Hirdh	Always have changes reviewed by multiple
OR-3.002	Change in scope	adjusted	Time pressure	has serious consequences	Moderate	High	people
				Clear planning with realistic	Low	High	Weekly meetings with updates, and ask for help
OR-3.003	Time pressure	Working faster can compromise safety and quality	Can lead to errors	deadlines			when needed