

# Background and Implementation

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## Background

Our automatic differentiation package relies on the elegant arithmetic of dual numbers to compute derivatives of complicated real-valued functions in terms of the derivatives of their simpler pieces.

A *dual number* is a symbol of the form  $z = a + \epsilon b$ , where  $a, b \in \mathbb{R}$ ;  $a$  is called the *real part* of  $z$  and  $b$  is called the *dual part* of  $z$ . We denote the set of all dual numbers by  $\mathbb{D}$ . Dual numbers can be added and multiplied according the following formulas:

$$\begin{aligned}(a_1 + \epsilon b_1) + (a_2 + \epsilon b_2) &= (a_1 + a_2) + \epsilon(b_1 + b_2), \\ (a_1 + \epsilon b_1)(a_2 + \epsilon b_2) &= (a_1 a_2) + \epsilon(a_1 b_2 + a_2 b_1).\end{aligned}$$

The beauty of using dual numbers to compute derivatives of real-valued functions lies in the following construction: Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a differentiable function. From  $f$  we can define a function  $f_* = F : \mathbb{D}^n \rightarrow \mathbb{D}^m$  whose  $i$ th component  $F_i : \mathbb{D}^n \rightarrow \mathbb{D}$  is given by

$$F_i(x_1 + \epsilon p_1, \dots, x_n + \epsilon p_n) = f_i(x) + \epsilon D_p f_i(x),$$

where  $x = (x_1, \dots, x_n)$ ,  $p = (p_1, \dots, p_n)$ , and  $D_p f_i(x)$  is the directional derivative of  $f_i$  in the direction of  $p$ , evaluated at  $x$ . We call  $f_*$  the *augmentation* of  $f$ . The sum, product, and chain rules of calculus combine with the operations of addition and multiplication of dual numbers in an extremely nice way. Specifically, let  $f, g : \mathbb{R}^n \rightarrow \mathbb{R}^m$  and let  $h : \mathbb{R}^m \rightarrow \mathbb{R}^k$ . Then we have

$$\begin{aligned}(f + g)_* &= f_* + g_* \\ (fg)_* &= f_* g_* \\ (h \circ f)_* &= h_* \circ f_*.\end{aligned}$$

## Implementation and Use

Our package `AutomaticDifferentiation` contains a class `DualNumber`, instances of which can be added and multiplied using standard Python syntax. Instances of `DualNumber` have two attributes, `real` and `dual`, which are the real and dual parts respectively.

`AutomaticDifferentiation` also contains augmentations of standard functions such as `sin`, `cos`, `exp`, and `log`. Suppose we wish to compute the first partial derivative of the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  given by

$$f(x_0, x_1) = \sin(3x_0 + 2x_1)$$

at the point  $x = (4, 5)$ . To do so, we would use the following code:

```
import AutomaticDifferentiation as ad

x = [4,5]
p = [1,0]

dual_output = ad.sin(DualNumber(3,0) * DualNumber(x[0],p[0])
                     + DualNumber(2,0) * DualNumber(x[1],p[1]))

derivative = dual_output.dual
```