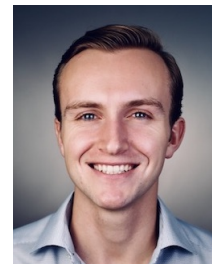


Dylan L Randle

[Website](#) • [LinkedIn](#) • [GitHub](#) • [Scholar](#)



SUMMARY

Artificial intelligence (AI) scientist, engineer, and leader with 5+ years experience and proven track record building and deploying AI systems for robotics, computer vision, and natural language processing.

EXPERIENCE

Amazon Robotics

Senior Applied Scientist

North Reading, MA, USA

Apr 2024 – Present

- Developing closed-loop AI policy learning systems for dexterous bimanual robotic manipulation using imitation and reinforcement learning
- Demonstrated capabilities to Jeff Bezos, Andy Jassy, and Amazon Board of Directors

Senior Data Scientist

Apr 2023 – Apr 2024

- Developed AI systems for robotic manipulation (grasp generation, damage prediction, box packing)
- Delivered performance improvements of +35% and savings of \$10 million/year

Data Scientist II

Jul 2020 – Apr 2023

- Developed learned path planning optimization system for large-scale mobile robot fleets
- Published paper demonstrating +15% throughput improvement and potential \$150 million/year savings

Data Scientist I

Jun 2019 – Aug 2019

- Developed AutoML system for training, evaluating, and interpreting ML models trained on trillion-row robotics datasets
- Used by multiple scientists to speed up research and analysis workflows

Hubdoc

Data Scientist

Toronto, ON, Canada

Feb 2017 – Jul 2018

- Started and led ML team from ideation to acquisition for \$70 million USD
- Developed NLP AI system for automated data extraction from financial documents
- Reduced data extraction time from hours to seconds

EDUCATION

Harvard University

Master of Science in Data Science (GPA: 4.0)

Cambridge, MA, USA

Aug 2018 – May 2020

- Thesis: "Unsupervised Neural Network Methods for Solving Differential Equations"
- Recognized with Scholarship in Applied Computation and Distinction in Teaching
- Research and coursework focused on machine learning

University of California, Berkeley

Bachelor of Science in Industrial Engineering & Operations Research (GPA: 3.9)

Berkeley, CA, USA

Aug 2012 – May 2016

- Recognized with High Honors (*magna cum laude*) and Frank Kraft Award
- Inducted into Phi Beta Kappa, Tau Beta Pi, Alpha Pi Mu
- Coursework focused on statistics and optimization

PUBLICATIONS

- **Demonstrating Multi-Suction Item Picking at Scale via Multi-Modal Learning of Pick Success.** C Wang, J van Baar, C Mitash, S Li, **D Randle**, W Wang, S Sontakke, K E Bekris, K Katyal. RSS 2025.
- **MuST: Multi-Head Skill Transformer for Long-Horizon Dexterous Manipulation with Skill Progress.** K Gao, F Wang, E Aduh, **D Randle**, J Shi. ICRA 2024.
- **Learning Object Properties Using Robot Proprioception via Differentiable Robot-Object Interaction.** PY Chen, C Liu, P Ma, J Eastman, D Rus, **D Randle**, Y Ivanov, W Matusik. ICRA 2024.
- **Avoiding Object Damage in Robotic Manipulation.** E Aduh, F Wang, **D Randle**, K Wang, P Shah, C Mitash, M Nambi. IROS 2024.
- **DEQGAN: Learning the Loss Function for PINNs with Generative Adversarial Networks.** B Bullwinkel*, **D Randle***, P Protopapas, D Sondak. ICML 2022, AI for Science.

TECHNICAL SKILLS

- **Languages:** Python, C++, Javascript/Typescript, SQL
- **Libraries:** PyTorch, Keras/Tensorflow, OpenCV, Open3D, Pandas, NumPy, SciPy, Scikit-Learn, React
- **Platforms:** AWS, Docker, Firebase, Linux, MacOS