Prediction and Logistic Regression

2022-2-2

Prediction

- Fundamental in modern machine learning approaches to computational linguistics
- Recall that we use our training data to set parameters in a model (train the model)
 and test on test data
- Given some data, e.g., a sentence, we want to predict something about it.
- For example, SPAM vs NOT SPAM or whether a product review is positive or negative

Prediction

- Assume we have a corpus of reviews in which each review is labeled classes of positive (P) or negative (N) sentiment.
- Binary classification problem (2 classes/labels)
- We want to guess P or N (the classes) based only on the review text
- We need a set of features from the review text to make this prediction
- We train a model to predict a class label on its own.

Splitting the Data

- Suppose we have 1,000 labeled reviews
- We can Wet aside ~10% as our development set and ~10% as our test set.
- We use the remaining 80% as our **training set** to train the model
- Researchers shouldn't look at test data (and preferably training data) if possible
- Sets should usually be randomized to prevent biased model
- Training data ideally balanced by classes, but not always possible

Splitting Data

- Alternative called k-fold cross-validation.
 - Run several training and testing sessions over random splits of the data
- Related: leave one out (LOO) evaluation, where you train on all but one test example over the hole dataset
 - Useful when data are small

Training

- Process of making iterative changes to model's parameters to increase its performance
- One common measure of performance is accuracy.

$$accuracy = \frac{correct\ predictions}{all\ predictions}.$$

Training

- In supervised learning we used these labeled examples to train our model.
- The correct labels are called gold standard labels.
- By looking at these labels, we want to **fit** the model to the data, making predictions on unseen test data

Review: The Perceptron

- ullet We know that y=mx+b represents a line in \mathbb{R}^2
- The m represents the slope of the line, while b is the y-intercept -- how much the line is shifted up or down. We'll use w instead of m.
- ullet In linear algebra and statistics parlance, the $oldsymbol{w}$ coefficient is known as a **weight**.

The Perceptron

We can use more terms

$$y = w_1 x_1 + w_2 x_2 + b$$

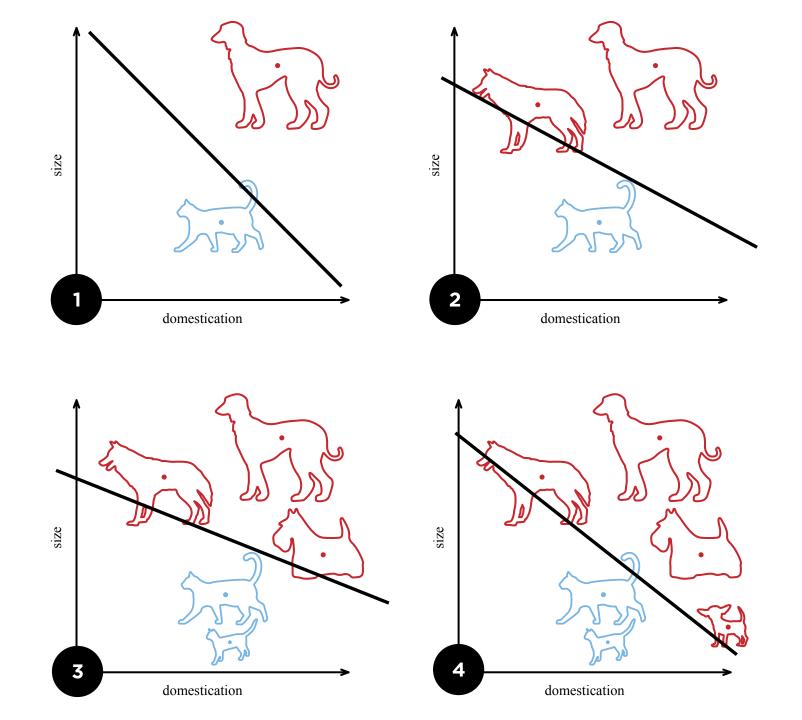
- The weights tell us how much influence a given term will have.
- ullet Every x has a corresponding y

The Perceptron

We can have as weights and variables as we like, allowing us to generalize

$$egin{align} a &= h_{\mathbf{w}}(\mathbf{x}) = \mathbf{w} \cdot \mathbf{x} + b \ &= w_1 x_1 + w_2 x_2 + \dots + w_n x_n + b \ &= \sum_{i=1}^n w_i x_i + b \ \end{gathered}$$

- ullet Equation represents n-1 dimensional hyperplane in \mathbb{R}^n to separate data
- Each weight w_1 coresponds to a **feature** x_i .
- Number of features = number of dimensions



The Perceptron

Prediction algorithm

```
function predict(x)
   return sign(dot(w,x) + b)
```

predicted class =
$$sign(\mathbf{w} \cdot \mathbf{x} + b)$$

Perceptron Learning Algorithm

```
1. Initialize weights vector w to random numbers in [0, 1].
2. for each example (x, y) in D:
    prediction = predict(x)
    if not sign(y) == sign(prediction):
        for each w in weights:
            w = w + y * x
            b = b + y * x
```

- Error-based learning
- If algorithm predicts wrong class, update weights

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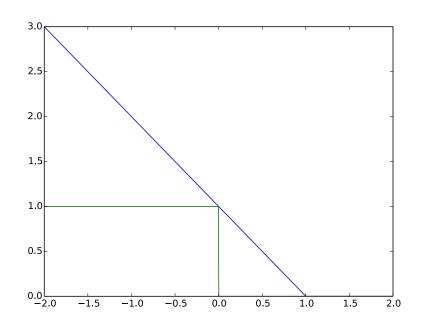
Update Rule for Weights

$$w_i := w_i + \eta y x_i.$$

Perceptron Loss Function

$$egin{aligned} \mathscr{L}(h_{\mathbf{w}}(\mathbf{x}),y) &= \mathscr{L}(p,y) = egin{cases} y-p & ext{if } yp < 0 \ 0 & ext{otherwise} \end{cases} \ &= \max(0,1-yp) \end{aligned}$$

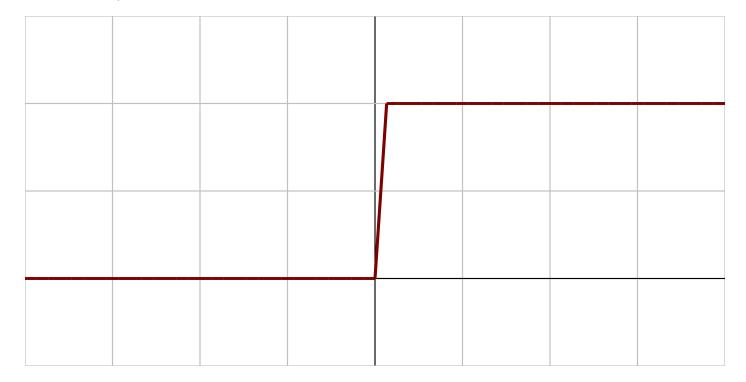
Hinge loss



- Like perceptron, but better
- Perceptron tends to overfit training data
 - \circ Activation a result of pure linear combination
 - In principle, unbounded

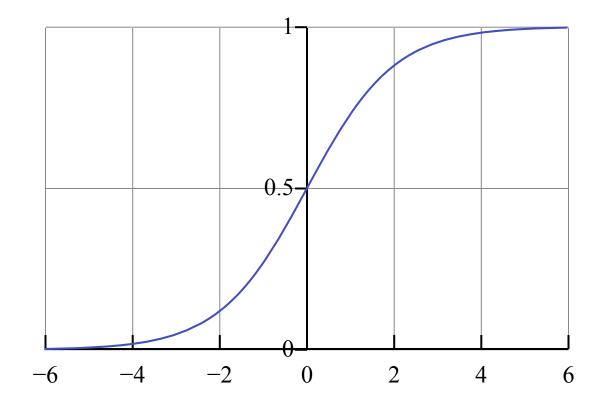
- Using an **activation funtion** bounds the output. For example, the binary step activation function:
- Send $a = \mathbf{w} \cdot \mathbf{x} + b$ through f(t).

$$f(t) = egin{cases} 1 & ext{if } t > 0 \ 0 & ext{otherwise} f \end{cases}$$



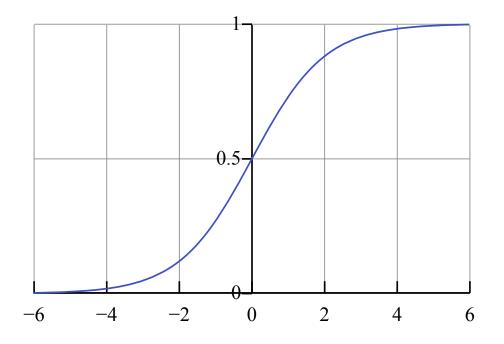
- Binary step function forfeits all information about confidence in prediction
- We can use a smooth version, a **sigmoid** (S-shaped) function called the **logistic function**.

$$\sigma(t)=rac{e^t}{1+e^t}=rac{1}{1+e^{-t}}.$$



• This function gives ua a **probability** of the positive class.

$$egin{aligned} p &= \sigma(\mathbf{w} \cdot \mathbf{x} + b) \ &= rac{1}{1 + \exp[-(\mathbf{w} \cdot \mathbf{x} + b)]} \ &= rac{1}{1 + \exp[-(\sum_{i=1}^n w_i x_i + b)]} \ &= P(y = 1 | \mathbf{w}; \mathbf{x}) \end{aligned}$$



Logistic Regression Prediction Algorithm

- Our prediction and algorithms are slightly changed from those for the Perceptron.
- Classes are now 0 or 1 instead of -1 or 1

```
function classify(x):
    p = predict(x)
    if p < 0.5:
        return 0
    else:
        return 1

function predict(x):
    return logistic(dot(w, x) + b))</pre>
```

- Note: we use **log probabilities** instead of pure probabilities
- Prevents underflow
 - Monotonicity maintained.

$$log(ab) = log(a) + log(b)$$

So,

$$\log[p(x)p(y)] = \log p(x) + \log p(y)$$

Logistic Regression Learning Algorithm

• (Very slightly) different update rule, but same principle

$$w_i := w_i + \eta(y-p)x_i.$$

```
function train(x, y, learning_rate):
1. Initialize weights vector w to 0 in [0, 1].
2. for each example (x, y) in D:
    p = predict(x)
    for each w in weights:
        w = w + learning_rate * (y - p) * x
    b = b + learning_rate * (y - p) * x
```

- In perceptron, update is entirely determined by learning rate η .
- In logistic regression, update is determined by learning rate η and how wrong you

were,
$$y - p$$

- Various names: logistic loss, cross-entropy loss, negative log likelihood
- Entropy is a term from information theory that we'll discuss later
 - Measurement of information content
- Logistic regreission is a discriminative classifier
 - Doesn't have a prior, unlike a generative classifier
 - \circ Directly optimizes P(y|x) over training data

Learns weights that predict

$$rgmax\limits_{y}P(y|\mathbf{x};\mathbf{w})$$

- I.e., maximize the probability that it chooses the correct class, y.
- ullet Only two possible classes, 1 or 0, so $P(y) = 1 P(\neg y)$

 The odds or likelihood that an event e occurs is the probability that it will occur divided by the probability that it won't

$$rac{P(y=1)}{1-P(y=1)} = rac{P(y=1)}{P(y=0)}$$

- Monotonic transformation of probabilities
- Maps probabilities from [0,1] to $[-\infty,\infty]$
 - Reverse of what logistic function does
- Ex: if P(y=1)=.75, then P(y=0)=.25.
 - Odds of class 1 is .75/.25, or 3 to 1.

• Assume $P(y=1)=p=\sigma(\mathbf{w}\cdot\mathbf{x}+b)$ Then,

$$egin{aligned} P(y=0) &= 1-p \ &= 1-\sigma(\mathbf{w}\cdot\mathbf{x}+b) \end{aligned}$$

Or, more compactly,

$$p^y(1-p)^{1-y} = \sigma(\mathbf{w}\cdot\mathbf{x}+b)^y(1-\sigma(\mathbf{w}\cdot\mathbf{x}+b))^{1-y}.$$

Taking the log, we have:

$$y \log p + (1 - y) \log(1 - p)$$

= $y \log \sigma(\mathbf{w} \cdot \mathbf{x} + b) + (1 - y)(1 - \log \sigma(\mathbf{w} \cdot \mathbf{x} + b)),$

which is the log likelihood of a correct answer.

- Our loss function is log likelihood defined over all of our training data.
 - So, we sum over the individual examples' losses in all of our training data for our loss function

$$egin{aligned} \mathscr{L}(\mathbf{x}) &= \sum_{(\mathbf{x},y) \in D} [y \log p + (1-y) \log (1-p)] \ &= \sum_{(\mathbf{x},y) \in D} [y \log \sigma(\mathbf{w} \cdot \mathbf{x}) + (1-y) (1 - \log \sigma(\mathbf{w} \cdot \mathbf{x} + b))], \end{aligned}$$

- Also called cross-entropy loss.
- Cross-entropy between true probability distribution given by $m{y}$ and the model's estimate, $m{p}$.
- Recall, that cross-entropy is defined as

$$H(p,q) = -\sum_{x \in X} p(x) \log q(x).$$

Given m training examples,

$$egin{align} \mathscr{L}(x) &= rac{1}{m} \sum_{i=1}^m H(p_i,q_i) \ &= -rac{1}{m} \sum_{i=1}^m [y \log p + (1-y) \log (1-p)] \ \end{cases}$$

Relationship to log odds

Assume
$$\ln \frac{p}{1-p} = \mathbf{w} \cdot \mathbf{x} + b$$
.
$$\frac{p}{1-p} = e^{\mathbf{w} \cdot \mathbf{x} + b}$$

$$p = (1-p)e^{\mathbf{w} \cdot \mathbf{x} + b}$$

$$p = e^{\mathbf{w} \cdot \mathbf{x} + b} - pe^{\mathbf{w} \cdot \mathbf{x} + b}$$

$$p + pe^{\mathbf{w} \cdot \mathbf{x} + b} = e^{\mathbf{w} \cdot \mathbf{x} + b}$$

$$p(1 + e^{\mathbf{w} \cdot \mathbf{x} + b}) = e^{\mathbf{w} \cdot \mathbf{x} + b}$$

$$p = \frac{e^{\mathbf{w} \cdot \mathbf{x} + b}}{1 + e^{\mathbf{w} \cdot \mathbf{x} + b}}$$

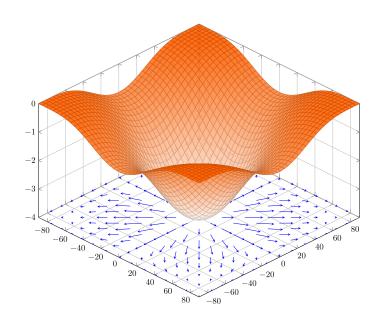
$$p = \frac{1}{1 + e^{-(\mathbf{w} \cdot \mathbf{x} + b)}}$$

Review: Derivatives

- Rate of change or slope of a function
- ullet Given a line, y=mx+b, if $m=rac{\Delta y}{\Delta x}=3/4$, this is the slope.
- Since lines have the same slpoe everywhere, we need only find it once
- For curves, the derivative function gives us the slope.
- Simple rule: If $f(x)=x^2$, then $rac{dy}{dx}=f'(x)=2x$ at an arbitrary point

Partial Derivatives

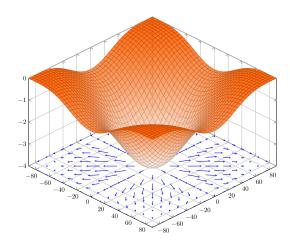
- Given functions of more than one variable, rate of change along one dimension, assuming other ones held constant
 - \circ For f(x,y), when differentiating along x axis, treat y as a constant
 - \circ Written as $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$, etc.



The Gradient

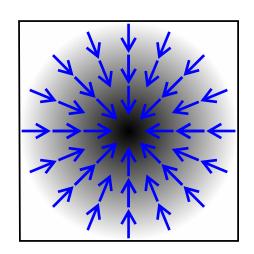
- The **gradient** is a vector of partial derivatives
 - One for each dimension
- ullet Given a function of n variables, the gradient has an partial derivative for very variable.
- Given a function f(x,y,z), the graident of f is

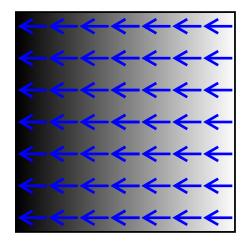
$$abla f = \left[rac{\partial f}{\partial x}, rac{\partial f}{\partial y}, rac{\partial f}{\partial z}
ight].$$



The Gradient

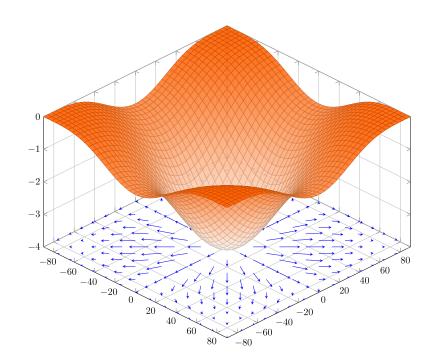
- ullet Gradient describes a **direction** within an n-dimensional space
 - Each element just a number (a slope along one dimension)
 - \circ Key: direction of steepest ascent along the surface of f



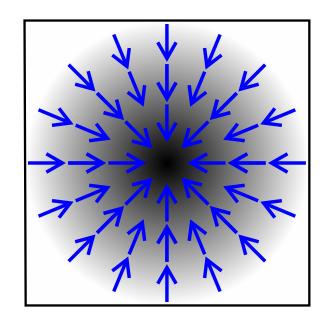


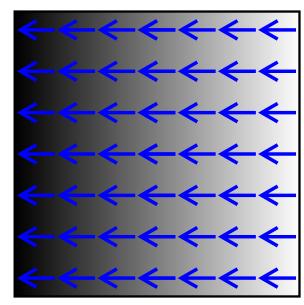
The Gradient

- Intuition:
 - What is the maximum rate at which one can walk up a line?
 - What is the maximum rate at which one can walk up a hill at a given point?
 - What about along a single dimension?



- Intuition:
 - What is the maximum rate at which one can walk up a line?
 - What is the maximum rate at which one can walk up a hill at a given point?
 - What about along a single dimension?
 - The magnitude gradient is just the aggregate of all of the slopes in every direction.





Intuition: Alternate View of the Gradient

$$egin{aligned}
abla f &= rac{\partial f}{\partial x} \mathbf{i} + rac{\partial f}{\partial y} \mathbf{j} + rac{\partial f}{\partial z} \mathbf{k} \ &= rac{\partial f}{\partial x} egin{bmatrix} 1 \ 0 \ 0 \end{bmatrix} + rac{\partial f}{\partial y} egin{bmatrix} 0 \ 1 \ 0 \end{bmatrix} + rac{\partial f}{\partial z} egin{bmatrix} 0 \ 0 \ 0 \ rac{\partial f}{\partial y} \end{bmatrix} \ &= egin{bmatrix} rac{\partial f}{\partial x} \ 0 \end{bmatrix} + egin{bmatrix} 0 \ rac{\partial f}{\partial y} \ rac{\partial f}{\partial z} \end{bmatrix} \ &= egin{bmatrix} rac{\partial f}{\partial x} \ rac{\partial f}{\partial x} \ rac{\partial f}{\partial y} \ ra$$

Gradient

- ullet The magnitude of the gradient |
 abla f| is the **Euclidean distance**, **Euclidean norm** or ℓ^2
- Same distance formula we learned in high school or earlier

$$|
abla f(x,y)| = \sqrt{\left(rac{\partial f}{\partial x}
ight)^2 + \left(rac{\partial f}{\partial y}
ight)^2}. \ |
abla f(x,y,z)| = \sqrt{\left(rac{\partial f}{\partial x}
ight)^2 + \left(rac{\partial f}{\partial y}
ight)^2 + \left(rac{\partial f}{\partial z}
ight)^2},$$

- Goal: Minimize loss/maximize log likelihood or correct answers
- Loss function is **convex**
- If we can walk down the loss function, we can minimize the error on the training data
 - This is what traning is
- ullet Use the negative gradient -|
 abla f| to minimize loss
 - Same as taking the negative partial derivative of every element in gradient vector

Gradient Descent

Recall our loss function is

$$\mathcal{L}(\mathbf{x}) = -[y \log p + (1 - y) \log(1 - p)]$$

= $-[y \log \sigma(\mathbf{w} \cdot \mathbf{x}) + (1 - y)(1 - \log \sigma(\mathbf{w} \cdot \mathbf{x} + b)]$

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= $-[y \log \sigma(\mathbf{w} \cdot \mathbf{x}) + (1 - y)(1 - \log \sigma(\mathbf{w} \cdot \mathbf{x} + b)]$

Its derivative is:

$$egin{aligned} \mathscr{L}\prime(\mathbf{x}) &= \sum_{(x,y)\in D} (y-p)x_i \ &= \sum_{(\mathbf{x},y)\in D} (y-\sigma(\mathbf{w}\cdot\mathbf{x}+\mathbf{b}))x_i \end{aligned}$$

Gradient Descent

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If we remove the summation, we have most of the update rule!

$$(y-p)x_i$$

Gradient Descent

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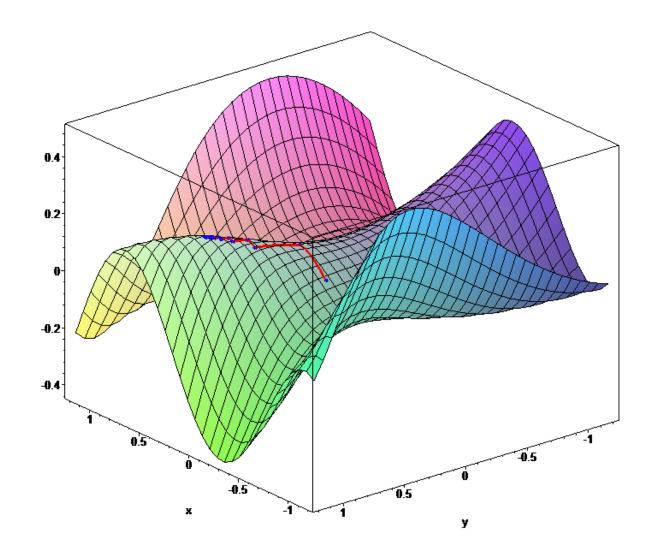
$$(y-p)x_i$$

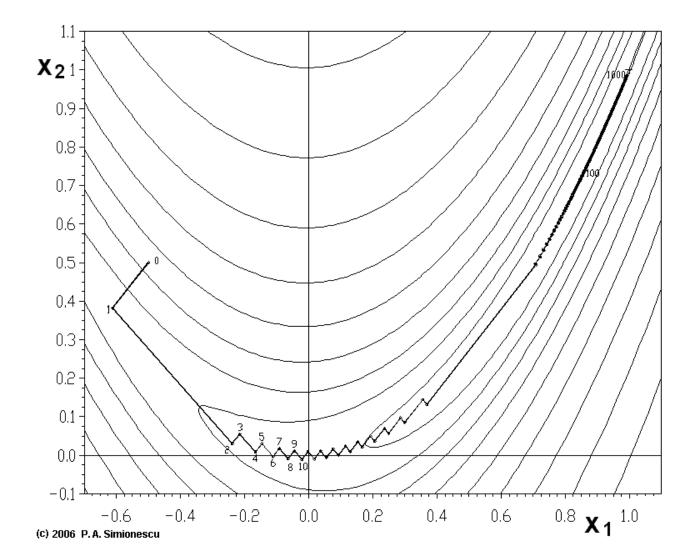
Just add the learning rate:

$$egin{aligned} w_i &:= w_i + \eta (y-p) x_i \ w_i &:= w_i + \eta
abla \mathscr{L} \end{aligned}$$

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abla \mathscr{L} \end{aligned}$$

- ullet The loss function's derivative is our update rule, changes weight w_i by the gradient given by the example!
- The learning rate η is a **hyperparameter** that determines how big of a step we take in the direction of given by the gradient





Stochastic Gradient Descent

- Full gradient descent requires going over all training data for one update
- Instead, we use **stochastic** gradient descent (SGD), which uses a single example from training data to update all parameters on one iteration
- Understanding logistic regression and SGD is crucial for understanding more complex algorithms