

```
1  import os
2  import glob
3  import time
4  import RPi.GPIO as GPIO
5  import sys
6  import shutil
7  GPIO.setwarnings(False)
8
9  GPIO.setmode(GPIO.BCM)
10 GPIO.setup(25, GPIO.IN, pull_up_down = GPIO.PUD_UP)
11 while(GPIO.input(25)):
12     time.sleep(0.05)
13 GPIO.setup(17, GPIO.OUT)
14 GPIO.setup(6, GPIO.OUT)
15 GPIO.setup(5, GPIO.OUT)
16 GPIO.output(17, 0)
17 GPIO.output(6, 0)
18 time.sleep(0.15)
19 GPIO.output(17, 1)
20 GPIO.output(6, 1)
21 time.sleep(0.25)
22 GPIO.output(17, 0)
23 GPIO.output(6, 0)
24 time.sleep(0.15)
25 GPIO.output(17, 1)
26 GPIO.output(6, 1)
27 time.sleep(0.25)
28 GPIO.output(17, 0)
29 GPIO.output(6, 0)
30 GPIO.output(5, 1)
31 os.system("sudo reboot")
32
```