

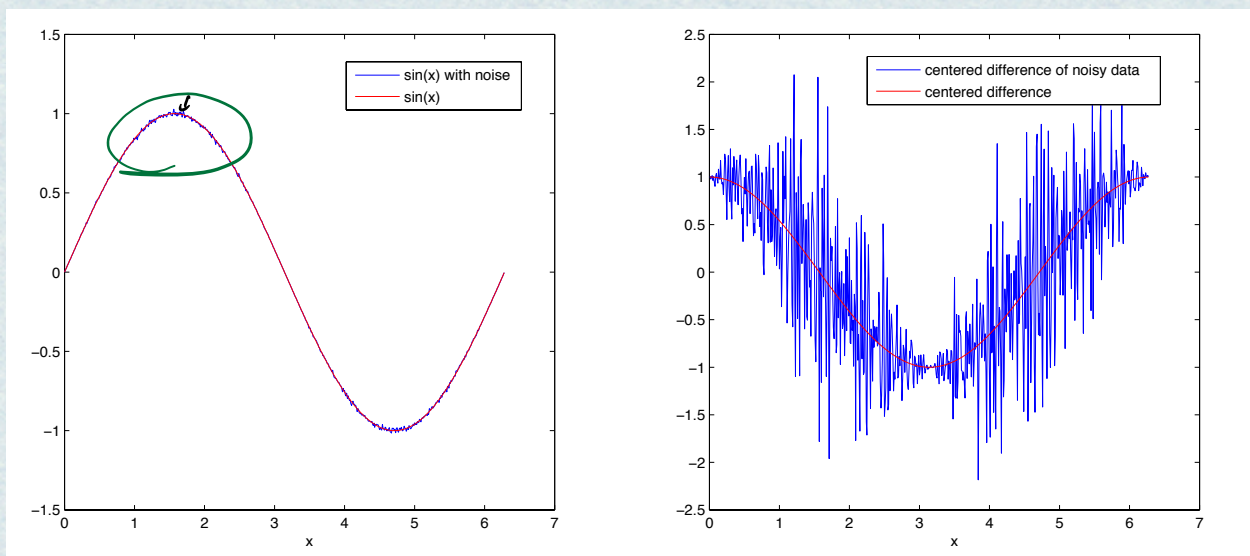
% Example 14.6 -- Figure 14.3 : differentiating noisy data

```
x = 0:.01:2*pi;
l = length(x);
sinx = sin(x);
sinp = (1+.01*randn(1,l)).*sinx;

cosx = (sinx(3:l)-sinx(1:l-2))./.02;
cosp = (sinp(3:l)-sinp(1:l-2))./.02;
err_f = max(abs(sinx-sinp))
err_fp = max(abs(cosx-cosp))

subplot(1,2,1)
plot(x,sinp,x,sinx,'r')
legend('sin(x) with noise', 'sin(x)');
xlabel('x')
%title('sin (x) with 1% noise')

subplot(1,2,2)
plot(x(2:l-1),cosp,x(2:l-1),cosx,'r')
xlabel('x')
legend('centered difference of noisy data', ...
       'centered difference ');
%title('cos (x) by noisy numerical differentiation')
```



using finite difference  
in noisy data will lead to 'large' error !!



## Method of polynomial approximation

Example: Find a one-sided approximation to  $f'(x_0)$  based on  $f(x_0)$ ,  $f(x_0+h)$  and  $f(x_0+2h)$ .

1. Approximate  $f(x)$  by a degree-2 polynomial  $p(x)$  with the given 3 points. Use Newton polynomial.

$$p(x) = c_0 + c_1(x - x_0) + c_2(x - x_0)(x - (x_0 + h)) \quad (11)$$

$$p(x_0) = c_0 = f(x_0) \quad (12)$$

$$p(x_0 + h) = c_0 + c_1h = f(x_0 + h) \quad (13)$$

$$p(x_0 + 2h) = c_0 + c_1(2h) + c_2(2h)(h) = f(x_0 + 2h) \quad (14)$$

Solve the system with substitution or divided differences

$$c_0 = f(x_0)$$

$$c_1 = \frac{f(x_0 + h) - f(x_0)}{h}$$

$$c_2 = \frac{\frac{f(x_0+2h)-f(x_0+h)}{h} - \frac{(f(x_0+h)-f(x_0))}{h}}{2h} = \frac{f(x_0 + 2h) - 2f(x_0 + h) + f(x_0)}{2h^2}$$



Put together

$$p(x) = c_0 + c_1(x - x_1) + c_2(x - x_1)(x - x_2) = f(x_0) + \frac{f(x_0 + h) - f(x_0)}{h}(x - x_0) + \frac{f(x_0 + 2h) - 2f(x_0 + h) + f(x_0)}{2h^2}(x - x_0)(x - x_0 - h)$$

2. Approximate  $f'(x_0)$  by

$$\begin{aligned} p'(x_0) &= c_1 + c_2(x_0 - x_1) + c_2(x_0 - x_2) = c_1 + c_2(-h) \\ &= \frac{f(x_0 + h) - f(x_0)}{h} - \frac{f(x_0 + 2h) - 2f(x_0 + h) + f(x_0)}{2h} \\ &= \frac{-3f(x_0) + 4f(x_0 + h) - f(x_0 + 2h)}{2h} \end{aligned}$$

→ Finite difference differentiation matrices

- Let  $x_i \in [a, b]$  such that  $x_0 = a$ ,  $x_1 = a + h$ ,  $x_i = a + ih$ ,  $\dots$ ,  $x_n = b$ .

- $h = (b - a)/n$ .

- $f(x_i) = f_i$  is the given data.

- If we want to approximate the derivative  $f'(x_i)$  using centered differences,

$$f'_1 = \frac{f_2 - f_0}{2h}, \quad f'_i = \frac{f_{i+1} - f_{i-1}}{2h}, \quad f'_{n-1} = \frac{f_n - f_{n-2}}{2h}.$$

$1 \leq i \leq n-1$

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2h} = \frac{f(x_{i+1}) - f(x_{i-1}))}{2h}$$

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$$\begin{pmatrix} 1 & 2 \\ 0 & \frac{1}{2h} \end{pmatrix} \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} = \begin{pmatrix} f'_1 \\ f'_2 \end{pmatrix}$$



$\frac{1}{2h} (f_{n+1} - f_{n-1}) = f'_n$   $\rightarrow$   $\begin{pmatrix} 0 & \frac{1}{2h} & 0 & \frac{1}{2h} & 0 \end{pmatrix} \begin{pmatrix} f_0 \\ \vdots \\ f_{n-1} \\ f_n \end{pmatrix} = \begin{pmatrix} f'_0 \\ \vdots \\ f'_{n-1} \\ f'_n \end{pmatrix}$   
 $\frac{1}{2h} (f_n - f_{n-2}) = f'_{n-1}$

- Then we can write the operator in matrix-vector form  $\mathbf{f}' = D\mathbf{f}$ , where

$$\mathbf{f} = \begin{bmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f(x_n) \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}, \quad D = \frac{1}{2h} \begin{bmatrix} -1 & 0 & 1 & & \\ & -1 & 0 & 1 & \\ & & \ddots & \ddots & \ddots \\ & & & -1 & 0 & 1 \end{bmatrix}.$$

- Dimensions of vectors and matrices?

- $\mathbf{f}'$  is uniquely determined from  $\mathbf{f}$ .

$$D = \frac{1}{2h} \begin{pmatrix} 0 & 1 & 0 & 0 & \dots \\ -1 & 0 & 1 & 0 & \dots \\ 0 & -1 & 0 & 1 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \\ -1 & 0 & 1 & 0 & \dots \end{pmatrix} \quad (n-1) \times (n-1)$$

- Using backward differences and the condition  $f(x_0) = 0$ ,

$f'(x_0) = \frac{f(x_0) - f(x_{-1})}{h} = D^- f(x_0)$   
 $f'_i = \frac{f_i - f_{i-1}}{h}$   
 $\begin{bmatrix} f'(x_1) + \frac{f(x_0)}{h} \\ f'(x_2) \\ \vdots \\ f'(x_n) \end{bmatrix} = \frac{1}{h} \begin{bmatrix} 1 & & & \\ -1 & 1 & & \\ & \ddots & \ddots & \\ & & -1 & 1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}$

- If we are given  $\mathbf{f}'$  and the initial condition, then we can solve the linear system for  $\mathbf{f}$ .