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% Example 14.6 -- Figure 14.3 : differentiating noisy data

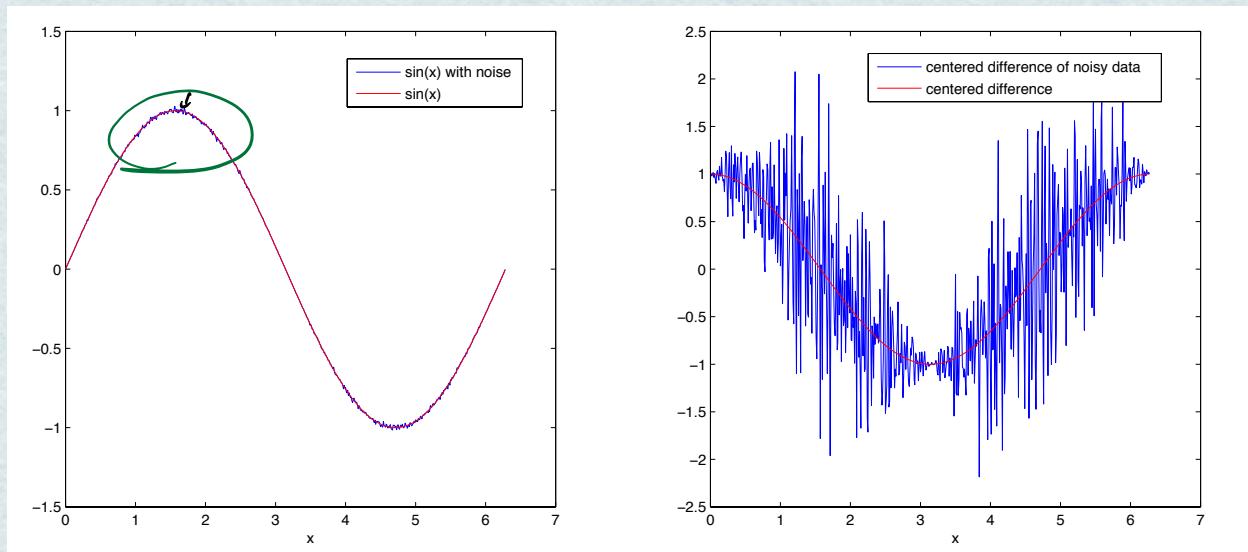
x = 0:.01:2*pi;
l = length(x);
sinx = sin(x);
sinp = (1+.01*randn(1,l)).*sinx;

cosx = (sinx(3:l)-sinx(1:l-2))/.02;
cosp = (sinp(3:l)-sinp(1:l-2))/.02;
err_f = max(abs(sinx-sinp))
err_fp = max(abs(cosx-cosp))

subplot(1,2,1)
plot(x,sinp,x,sinx,'r')
legend('sin(x) with noise', 'sin(x)');
xlabel('x')
%title('sin (x) with 1% noise')

subplot(1,2,2)
plot(x(2:l-1),cosp,x(2:l-1),cosx,'r')
xlabel('x')
legend('centered difference of noisy data', ...
'centered difference ');
%title('cos (x) by noisy numerical differentiation')

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using finite difference
in noisy data will lead to large error!

Method of polynomial approximation

Example: Find a one-sided approximation to $f'(x_0)$ based on $\underbrace{f(x_0)}_{\alpha}$, $\underbrace{f(x_0+h)}_{\beta}$ and $\underbrace{f(x_0+2h)}_{\gamma}$.

1. Approximate $f(x)$ by a degree-2 polynomial $p(x)$ with the given 3 points. Use Newton polynomial.

$$p(x) = c_0 + c_1(x - x_0) + c_2(x - x_0)(x - (x_0 + h)) \quad (11)$$

$$p(x_0) = c_0 = f(x_0) \quad (12)$$

$$p(x_0 + h) = c_0 + c_1h = f(x_0 + h) \quad (13)$$

$$p(x_0 + 2h) = c_0 + c_1(2h) + c_2(2h)(h) = f(x_0 + 2h) \quad (14)$$

Solve the system with substitution or divided differences

$$c_0 = f(x_0)$$

$$c_1 = \frac{f(x_0 + h) - f(x_0)}{h}$$

$$c_2 = \frac{\frac{f(x_0+2h)-f(x_0+h)}{h} - \frac{(f(x_0+h)-f(x_0))}{h}}{2h} = \frac{f(x_0 + 2h) - 2f(x_0 + h) + f(x_0)}{2h^2}$$

Put together

$$p(x) = c_0 + c_1(x - x_1) + c_2(x - x_1)(x - x_2) = f(x_0) + \frac{f(x_0 + h) - f(x_0)}{h}(x - x_0) \\ + \frac{f(x_0 + 2h) - 2f(x_0 + h) + f(x_0)}{2h^2}(x - x_0)(x - x_0 - h)$$

2. Approximate $f'(x_0)$ by

$$p'(x_0) = c_1 + c_2(x_0 - x_1) + c_2(x_0 - x_2) = c_1 + c_2(-h) \\ = \frac{f(x_0 + h) - f(x_0)}{h} - \frac{f(x_0 + 2h) - 2f(x_0 + h) + f(x_0)}{2h} \\ = \frac{-3f(x_0) + 4f(x_0 + h) - f(x_0 + 2h)}{2h}$$

→ Finite difference differentiation matrices

- Let $x_i \in [a, b]$ such that $x_0 = a, x_1 = a + h, x_i = a + ih, \dots, x_n = b$.
- $h = (b - a)/n$.
- $f(x_i) = f_i$ is the given data.

- If we want to approximate the derivative $f'(x_i)$ using centered differences, interior points $x_i : 1 \leq i \leq n-1$

$$f'_1 = \frac{f_2 - f_0}{2h}, \boxed{f'_i = \frac{f_{i+1} - f_{i-1}}{2h}}, f'_{n-1} = \frac{f_n - f_{n-2}}{2h}.$$

$$\boxed{1 \leq i \leq n-1} : f'_i = \frac{f_{i+1} - f_{i-1}}{2h} = \frac{f(x_{i+1}) - f(x_{i-1})}{2h}$$

$$\frac{1}{2h} (f_2 - f_0) = f'_1$$

$$\frac{1}{2h} (f_3 - f_1) = f'_2$$

$$\left(\begin{array}{c} f'_1 \\ f'_2 \\ \vdots \\ f'_{n-1} \end{array} \right) = \left(\begin{array}{c} \frac{1}{2h} (f_2 - f_0) \\ \frac{1}{2h} (f_3 - f_1) \\ \vdots \\ \frac{1}{2h} (f_{n-1} - f_{n-3}) \end{array} \right)$$

$$\frac{1}{2h} (f_{i+1} - f_i) = f'_i \quad \rightarrow \quad \left(\frac{-1}{2h} \circ \frac{1}{2h} \right) \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{pmatrix} = \begin{pmatrix} f'_0 \\ f'_1 \\ \vdots \\ f'_n \end{pmatrix}$$

- Then we can write the operator in matrix-vector form $\mathbf{f}' = D\mathbf{f}$, where

$$\mathbf{f} = \begin{bmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f(x_n) \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}, \quad D = \frac{1}{2h} \begin{bmatrix} -1 & 0 & 1 & & & \\ -1 & 0 & 1 & & & \\ \ddots & \ddots & \ddots & \ddots & & \\ -1 & 0 & 1 & & & \end{bmatrix}.$$

- Dimensions of vectors and matrices?
- \mathbf{f}' is uniquely determined from \mathbf{f} .
- Using backward differences and the condition $f(x_0) = 0$,

$$D = \frac{1}{2h} \begin{pmatrix} 0 & 1 & 0 & 0 & \dots & & \\ -1 & 0 & 1 & & & & \\ 0 & -1 & 0 & 1 & & & \\ & & & & \ddots & & \\ & & & & & 0 & 1 \\ & & & & & -1 & 0 \end{pmatrix} \quad \text{②}$$

$$\begin{aligned} f'(x_0) &= \frac{f(x_0) - f(x_0-h)}{h} = D^{-1} f(x_0) \\ f'_i &= \frac{f_i - f_{i-1}}{h} \end{aligned}$$

$$\begin{bmatrix} f'(x_1) + \frac{f(x_0)}{h} \\ f'(x_2) \\ \vdots \\ f'(x_n) \end{bmatrix} = \frac{1}{h} \begin{bmatrix} 1 & & & & & \\ -1 & 1 & & & & \\ & \ddots & \ddots & & & \\ & & & -1 & 1 & \\ & & & & n & \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}.$$

- If we are given \mathbf{f}' and the initial condition, then we can solve the linear system for \mathbf{f} .