



## Solving Binary Tree Equations

Preorder (solve equation right to left): N, L, R

Inorder: L, N, R

Postorder (solve left to right): L, R, N

## Big-O & Big-Ω

$f(n)=O(g(n))$  if  $0 \leq f(n) \leq cg(n)$

$f(n)=\Omega(g(n))$  if  $0 \leq cg(n) \leq f(n)$

## Arrays

Double array size when full, half the size when quarter full

All operations take  $O(n)$  except for insert

- When the array is full insert necessitates a resize which takes  $O(n)$
- Remove can also take  $O(n)$  if you downsize, but it is not always necessary

Stacks and queues take  $O(n)$  for all operations when implemented as linked lists.  $O(n)$  for all operations except push (and pop if you choose to downsize)

### algorithm BucketSort(A, k)

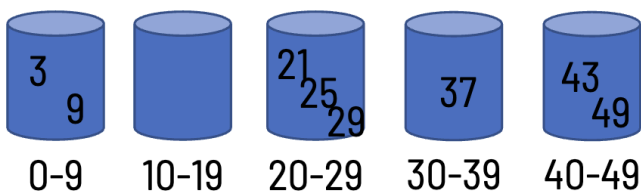
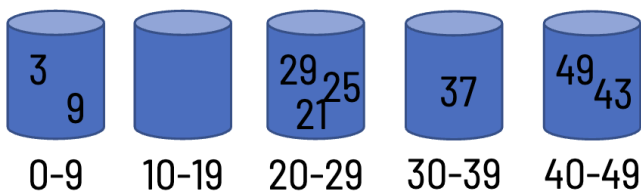
```
let B be an array of k empty buckets
let M be the Max key in A
```

```
for (i = 0, i < n, 1)
  j = floor(k * A[i] / M)
  insert A[i] to bucket B[j]
end for
```

```
for (i = 0, i < k - 1, 1)
  sort the bucket B[i]
end for
```

Concatenate the lists from each bucket into a single array and return it

Sort [29, 25, 3, 49, 9, 37, 21, 43]



Sorted [3, 9, 21, 25, 29, 37, 43, 49]

## Tries

$O(W)$  to add a word,  $W$  is the word length

$O(L)$  to construct a trie,  $L$  is the average word length

Word matching: leaf value = start index of word in text

Suffix trie: used to find substrings & suffixes

PATRICIA: compressed trie, can be represented as indices of the strings (string index, start, end) inclusive

## String Pattern Matching

Brute-force  $O(PT)$ : compare first letter of pattern and text, move the pattern right by one if mismatch

KMP Algorithm  $O(P+T)$ :

- Compute failure function  $O(P)$ : length of the longest prefix that is also a suffix of the pattern string
- On mismatch find corresponding value for the letter of the pattern in failure function
- Go to that letter in the string (not index) and re-compare.
- If there is a mismatch with the first letter of the pattern, shift right by one

### algorithm CountingSort(A, k)

**Step 1:** Array C keeps the number of occurrence for each element in A.

```
{ let C be an array of length k + 1
  fill C with 0s
```

```
let n be the length of array A
```

**Step 2:** Count the occurrences of each item in A. Use  $A[i]$  as the indices of C.

```
{ for (i = 0, i < n, 1)
  C[A[i]] = C[A[i]] + 1
end for
```

**Step 3:** Accumulate the count values in C from left to right.

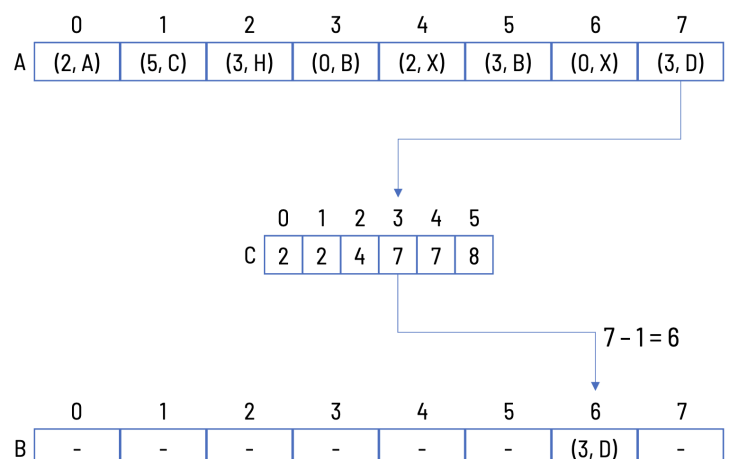
```
{ for (i = 1, i <= k, 1)
  C[i] = C[i] + C[i - 1]
end for
```

```
let B be an array of size n
```

**Step 4:** Use values in C to determine the final index for each element in A.

```
{ for (i = n - 1, i >= 0, -1)
  B[C[A[i]] - 1] = A[i]
  C[A[i]] = C[A[i]] - 1
end for
```

```
return B
```



	Runtime	Height	Description
Quick-find	Find: $O(1)$ Union: $O(v)$		Index is the vertex and the value is the group. Iterate through the vertices and update all members of the same group.
Quick-union	Find & union: $O(v)$	$O(v)$	Index is the vertex and the value is the parent index. The root of the first set points to the second vertex.
Weighted quick-union	Find & union: $O(\log v)$	$O(\log v)$	Smaller tree's root is added to the larger tree's root
Path Compression	Worst: $O(\log v)$ Average: $O(\alpha(v))$		All vertices traversed in find() on both trees are adjusted to point directly to the root of the larger tree

### Proofs

Induction:

1. Let  $P(n)$  = proposition
2. Base Step: show  $P(n)$  holds for initial  $n$  value
3. Inductive step: Assume  $P(k)$  is true and show  $P(k+1)$  is true
4. Inductive hypothesis:  $P(k) = P(n)$
5. Algebra
6. Conclusion

Direct:  $q \Rightarrow p$

Contraposition:  $\neg q \Rightarrow \neg p$

Contradiction:  $p \wedge \neg q$

Counter example: case or proof

- Undirected Graph:  $2 * \text{edges} = \text{sum of vertices degrees}$

### Binary Search Trees (BSTs)

Properties:

- Children:  $2k + 1$  &  $2k + 2$
- Parent:  $\lfloor \frac{k-1}{2} \rfloor$
- Max nodes:  $2^{h+1} - 1$
- Max leaves:  $2^h$
- Max height for complete BST:  $\lfloor \log_2(n) \rfloor$

Insert, delete, and search:

- Average:  $O(\log n)$  if reasonably balanced
- Worst-case:  $O(n)$  if the node DNE or unbalanced

### Graphs

- Simple: no loops/self connections & only one edge between two vertices
- Bipartite: no edge that connects two vertices in the same set (graph can be divided into 2 disjoint sets)
- Eulerian graph: all vertices have an even degree
- Eulerian cycle: a path that uses every edge exactly once
- Articulation Point: vertex whose removal disconnects the graph
- Bridge: edge whose removal disconnects the graph (cannot be contained in a cycle)

### R-B Trees

- No nodes have 2 red links
- All paths have the same number of black branches
- A red node represents a red link to the parent
- Root node is always black
- Insert, delete, and search: Worst-case:  $O(\log n)$

### 2-3 Trees

- All nodes are on the same level
- Worst-case height is max height for complete BST (never taller than min-height for binary tree)
- Insert, delete, and search: Worst-case:  $O(\log n)$
- Max nodes =  $\frac{1}{2} (3^{h+1} - 1)$
- Max keys =  $3^{h+1} - 1$

### MST

- All vertices are connected without cycles & the sum of weights is minimized
- Cut: if there are multiple edges connecting two subgraphs, only the minimum is in the MST
  - Cycle: if there is a cycle, the max-edge is not in the MST

## Algorithms

BFS/DFS: list  $O(v + e)$  time or matrix  $O(v^2)$  time

Topological Sort:  $O(v + e)$

- Maintain an array of the indegree to all vertices. Remove the vertex with an indegree of 0, add it to the topological ordering, and decrease the indegree to all of its neighbors.

Prim's:  $O(e \log v)$  time &  $O(e)$  space

- Add all vertices of the current node to a min-priority queue based on the weight of their minimum discovered in-edge. Pop the lowest weight vertex and update the queue with newly discovered vertices and new minimum in-edges.

Kruskal's:  $O(e \log e)$  time &  $O(e)$  space

- Iterate through a list of edges from min-weight to max-weight and call find on the vertices of the edge. If  $\text{find}(a) \neq \text{find}(b)$  then  $\text{union}(a, b)$ .

Strong connectivity:  $O(v + e)$

- DFS on a starting node. If there is an unvisited node then return false. Reverse the graph. Run DFS from the same starting vertex. If there is an unvisited vertex return false, else return true.

Kasraju's SCC:  $O(v + e)$  time

- Run DFS on nodes in lexicographical order if they are not visited already. Add nodes to a stack as they are completed. Reverse the graph. Repeatedly call DFSMark on the top of the stack if it is not already marked.

Dijkstra's:  $O(e \log v)$  time or  $O(e + (v \log v))$  with Fibonacci heap

- Checking if a vertex is in the queue  $O(1)$
- Resetting values in queue:  $O(e \log v)$ 
  - $O(\log v)$  to update a value, repeat for all adjacent edges ( $e$ ) to a vertex

Bellman-Ford:  $\Theta(v \cdot e)$  time &  $\Theta(v)$  space

- Check the vertices in lexicographical order at most  $v$  times. If the distance to the current node is unknown then skip it, otherwise, update the minimum distance to adjacent nodes. If there are no updates in a pass, end the function early.

DAG Distances:  $O(v + e)$  time

- Topologically sort the graph (assumes graph has no cycles). Iterate through the edges in topological order and update the minimum distance (current distance + edge weight).

Floyd Warshall All Pairs Shortest Path:  $O(v^3)$  time &  $O(v^2)$  space

- Use an adjacency matrix to represent the minimum path weight between two vertices. Start with intermediate paths including no nodes and increment to node  $v - 1$  (include nodes 0, 0-1, 0-2, etc.)

