### HW 4 Dingying Lu

## 1. Parameter tuning

The accuracy for different combinations of learning rate  $\eta$  and  $\lambda$  of logistic loss and hinge loss is shown below.

(1) Logistic loss

η	0.0001	0.001	0.01	0.1
0.1	0.95	0.85	0.85	0.8
0.3	0.95	0.9	0.75	0.75
1	0.95	0.85	0.7	0.6

For logistic loss, we find that the combination of  $\eta=0.001, \lambda=1, \eta=0.01, \lambda=0.1, \eta=0.1, \lambda=0.3$  generate relatively better performance. So we report the loss of each iteration for these three combinations in Logistic.txt.

(2) Hinge loss

$\eta$	0.0001	0.001	0.01	0.1
0.1	0.7	0.8	0.75	0.9
0.3	0.7	0.8	0.9	0.75
1	0.9	0.9	0.65	0.6

For hinge loss, we find that the combination of  $\eta=0.0001, \lambda=1, \eta=0.0001, \lambda=0.3, \eta=0.0001, \lambda=0.1$  generate relatively better performance. So we report the loss of each iteration for these three combinations in Hinge.txt.

#### 2. Results on test data

After tuning the parameters on development data, we choose  $\eta=0.0001$ ,  $\lambda=1$  for logistic loss,  $\eta=0.001$ ,  $\lambda=1$  for hinge loss. And the accuracy is shown as below.

### (1) Logistic loss

$\frac{\eta}{\lambda}$	0.0001
1	0.8529

#### (2) Hinge loss

$\eta$	0.001
1	0.8235

# 3. Inspecting the model

```
Sentence (negative):
[array([u'CALC'],
      dtype='<U4'), array([u'CALC'],</pre>
      dtype='<U4')]
Picture (positive):
[array([u'LDLPFC'],
      dtype='<U6'), array([u'LDLPFC'],</pre>
      dtype='<U6'), array([u'CALC'],</pre>
      dtype='<U4'), array([u'LDLPFC'],</pre>
      dtype='<U6'), array([u'CALC'],</pre>
      dtype='<U4'), array([u'CALC'],</pre>
      dtype='<U4'), array([u'LDLPFC'],</pre>
      dtype='<U6'), array([u'CALC'],</pre>
      dtype='<U4'), array([u'LDLPFC'],</pre>
      dtype='<U6'), array([u'LDLPFC'],</pre>
      dtype='<U6')]
```