# **Localizing Configurations in Highly-Configurable Systems**

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# **ABSTRACT**

The complexity of configurable systems has grown immensely, and it is only getting more complex. Such systems are a challenge for software testing and maintenance, because bugs and other defects can and do appear in any configuration. One common challenge for many development tasks is to identify the space of configurations that lead to a given defect or some other program behavior. We distill this challenge down to a simple question: given a program location in a source file, what are valid configurations that include the location? The key obstacle is scalability. When there are hundreds or thousands of configuration options, enumerating all combinations is exponential and infeasible. We provide a set of target programs of increasing difficulty and variations on the challenge question so that submitters of all experience levels can try out solutions. Our hope is to engage the community and stimulate new and interesting approaches to the problem of analyzing configurations.

#### CCS CONCEPTS

• Software and its engineering → Software configuration management and version control systems; Software testing and debugging;

# **KEYWORDS**

Configurations, Variability, Program Analysis, Testing

#### **ACM Reference Format:**

#### 1 INTRODUCTION

The complexity of configurable systems has grown immensely, and it is only getting more complex. This complexity creates a great challenge for software testing and maintenance. Critical, widely-used software, such as Linux, BusyBox, Firefox, and Apache, have

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SPLC'18, 10–14 September, 2018, Gothenburg, Sweden © 2018 Association for Computing Machinery. ACM ISBN 978-x-xxxx-xxxx-x/YY/MM...\$15.00 https://doi.org/10.1145/nnnnnnn.nnnnnnnn

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millions or billions of configurations. While bugs can and do appear in any configuration [1], there are simply too many configurations to test them all separately. With the proliferation of Internet-of-things devices, maintenance and testing of all configurations are even more essential, given the variety of devices using different configurations of the same software.

All development and maintenance tasks are impeded by highly configurable software. Testing, localizing and repairing bugs, security auditing, finding code smells and dead code, just to name a few, must apply to all configurations of a system. One simple distillation of these challenges is to *identify interesting configurations*: Given some point of interest in a program, what is the space of the configurations reaching that point of interest? A point of interest can be a particular line, file, program slice, bug, or some subset of program behavior. The ability to answer this question enables a developer to pinpoint relevant configurations when confronted with a defect or when undertaking a maintenance task. For example, real-world bugs in Linux can be caused by modifications to some configurations of the source code that introduces bugs in others [1]. Identifying the configurations reaching the bug location will localize the source of these *variability bugs*.

Localizing configurations remains an open problem for several reasons. The major challenge is *scalability*. For instance, Linux has over 14,000 configuration options. There are more combinations of these options than the estimated number of atoms in the universe<sup>1</sup> by many, many orders of magnitude. Further complicating this issues is that not all combinations are valid configurations. For instance, x86 platform options should be restricted when compiling for an arm processor, and reasoning about these constraints is computationally expensive.

Another important difficulty is that many systems often rely on *third-party software* where the source code is unavailable. For Internet-of-things devices, it may not be possible to obtain source code or operating system details to analyze their configurations. Furthermore, in systems with multiple, heterogeneous devices, it is difficult to combine the configurations of each device into a cohesive model

Even when source code is available, *build systems tend to be ad-hoc*. Each piece of software can implement its own build rules and configuration options may not be explicitly documented. Configurability can be implemented in many ways, sometimes using custom solutions. For C systems, Makefiles and the preprocessor

<sup>&</sup>lt;sup>1</sup>https://www.wolframalpha.com/input/?i=estimated+number+of+atoms+in+the+

are common options. These tools have difficult semantics, impeding analysis, making a general solution to localizing configurations difficult to realize.

#### 2 THE CHALLENGE

**The challenge:** given a specific program location in the source code, can you apply automatic analysis techniques to find concrete configurations that include the program location in question?

A program location is a source file name and a line number. A concrete configuration is a valid combination of configuration options that can be used to build the target system. Since many configurations may cover the intended program location, an ideal answer would be a compact characterization that captures some or all configurations covering that location. This characterization may be expressed as a logical formula that we can use to extract valid, concrete configurations reaching the program location.

A naive solution to this challenge is to enumerate all possible combinations of configuration options. Configuring and building the system for each combination enables a search for those that contain the target program location. This approach is not practical, even for small configurable systems, because it is exponential in the number of configuration options. The axTLS web server contains only 94 configuration options, but requires enumerating 2<sup>94</sup> configurations, an unrealistic proposition.

There are two categories of analysis techniques for solving this challenge:

- Static approaches summarize configuration behavior by analyzing the program source code, including its build system.
- Dynamic approaches run the program using a sample of configurations, obtain execution traces, and use the traces to build model describing the configuration behavior.

Note that a purely static might not be feasible because the system might contain third-party library or compiled code. Similarly, a purely dynamic technique might not provide a precise model describing the configuration space. Thus, we hypothesize a working solution may have to combine static and dynamic approaches, particularly for very large systems.

A valid solution for a program P is one that, given a program location l, returns a set of configurations  $C_{P(l)}$ . C represents the combinations of configuration options that, when used to configure and build the target system, includes the program location l.

We will use the following precision and recall metrics to measure the quality of the solution, assuming C represents the actual set of configurations that reaches l.

$$Precision = \frac{|C_{P(I)} \cap C|}{|C_{P(I)}|}$$
 
$$Recall = \frac{|C_{P(I)} \cap C|}{|C|}$$

Note that a successful solution does not need to be sound or complete. The challenge is met if the concrete configurations in the solution achieves reasonable precision and recall. An acceptable solution should at least do better than randomly choosing a configuration for a given program location.

Given the ad-hoc nature of real-world build system implementations, repurposing the solution program for new systems may be tedious. Therefore the solution only needs to work on at least one of the target systems of the submitter's choice. To enable a wide audience to tackle the challenge, we provide a range of difficulty levels with target systems of increasing complexity. Submissions may also choose to find configurations that reach a source file only instead of a program location, but are encouraged to work towards the latter. For simplicity, solutions may focus on Boolean configuration options, assuming some manual settings for non-Boolean options. Specific instructions for obtaining source code for each system are available in the accompanying repository for this challenge: https://github.com/paulgazz/splc18challengecase.

Easy The variability bug database collected by Abal et al. [1] provides a set of very small C programs derived from real-world bugs or other defects. Typically, these C programs only depend on a handful of configuration options. There are so few configurations in fact that the naive solution is feasible, but submitted solutions should not rely solely on naive exhaustive enumeration. This dataset may also be useful as a proof-of-concept for solution approaches other than the naive one.

**Medium** The axTLS web server is a relatively small configurable system<sup>2</sup>. Even so it has enough configuration options, 94, to make exhaustive search infeasible.

**Hard** The BusyBox toolkit<sup>3</sup> provides a single executable containing common GNU utilities. It is frequently used in embedded systems such as routers to provide a rich operating system with a small footprint. It has over a thousand configuration options.

**Ultimate** The Linux kernel source code<sup>4</sup> is arguably the most complex, configurable open-source project; it contains over 14,000 configuration options.

#### 3 EXISTING TOOLS

Several existing tools analyze configurations in build systems and source code and may be useful as inspiration or included components of a solution. We have provided links to these tools in our repository.

Kmax [14] collects build system configurations for Kbuild-style Makefiles of the kind used in Linux and BusyBox. It uses static analysis to derive a Boolean expression of configuration options. KBuildMiner [4] also produces Boolean expressions for source files built with Kbuild Makefiles. It uses a heuristic parsing technique that tradeoffs precision for speed. Makex takes a similar parsing approach [22]. KconfigReader [16] converts constraints on configuration options described in the Kbuild build system into Boolean expressions. Dietrich et al. describe GOLEM [10] that uses a dynamic approach to build system analysis, trying one or more configuration variables at a time to see which C files are enabled. GOLEM was compared to other tools including KBuildMiner and Makex to evaluate coverage [11]. All above techniques consider only the build system, and do not inspect configurations within source files.

<sup>&</sup>lt;sup>2</sup>http://axtls.sourceforge.net/

<sup>&</sup>lt;sup>3</sup>https://busybox.net/

<sup>4</sup>https://www.kernel.org/

Several static approaches exist to deal with preprocessor configurations within C source files. New parsing algorithms deal explicitly with configuration options [13, 15, 17]

The iTree tool [30] uses dynamic analysis and machine learning to construct an "iteraction tree" and from the tree constructs configurations achieving high coverage. The iGen tool [23] dynamically infers *interactions*—logical formulae describing how configuration settings map to code coverage. The tool employs an iterative algorithm that runs the system, captures coverage data; processes data to infer interactions; and then generates new configurations to further refine interactions in the next iteration. The self-adaptive REFRACT [31] architecture monitors software for bugs and generates configuration guards to avoid the observed bugs. REFRACT works by monitoring a running program (e.g., Firefox), and when the program encounters a bug, REFRACT analyzes configurations occured during the buggy run to creates good configurations that do not exhibit the bug and also constructs guards for the program to avoid similar buggy behaviors.

#### 4 RELATED WORK

There are several threads of related work.

Interaction discovery. Reisner et al. [27] developed the symbolic executor, Otter, and used it to fully explore the configuration space of a software system and extract interactions in conjunctive form. Symbolic execution, however, has scalability limitations and it is language specific. Consequently, several authors from the same group start using dynamic analyses and producing the aforementioned tools iTree and iGen that run much faster than Otter.

Lillack et al. describe a system that uses static analysis to derive a configuration map of source code [18]. Zhang and Ernst describe a tool that combines dynamic and static analysis to help users reconfigure a system undergoing software evolution [38]. Ouellet et al. describe static techniques to localize configurations of source code in avionics systems [26]. Several sampling approaches have been studied for exploring configuration spaces to find optimal configurations [20, 25, 29].

Feature interactions and presence conditions. Thüm et al [34] classified the feature interactions and presence conditions problems in software product line research. Since then, there have been multiple attempts addressing these problems. Apel et al. [3] studied the number of feature interactions in a system and their effects, including bug triggering, power consumption, etc. Lillack et al. [19] use (language-specific) taint analysis to find interactions in Android applications. Nadi et al [21] and von Rhein et al. [28] presented tools that work with presence conditions that are already provided. Czarnecki and Pietroszek [8] check for well-formedness errors in UML featured-based model templates using an SAT solver.

Combinatorial interaction testing. Many researchers have explored combinatorial interaction testing (CIT) [6, 24, 32, 36], a family of techniques for testing a program under a systematically generated set of configurations. One particularly popular approach is called t-way covering arrays, which, given an coverage  $strength\ t$ , generates a set of configurations containing all t-way combinations of option settings at least once. Over last 30 years, many studies

have focused on improving the speed, quality and flexibility of covering arrays [5, 7, 9, 12, 35, 37].

Build system analysis. As discussed in Section 3, several existing tools deal specifically with analyzing configurations in build systems [4, 14, 16, 22]. In addition, Tamrawi et al. [33] developed SYMake, a symbolic Makefile evaluator. SYMake generates a symbolic dependency graph from Makefiles for use in identifying code smells and in refactoring. Adams et al. [2] describe MAKAO, a visualization tool for Makefile dependencies. It extracts a concrete dependency graph for a single configuration.

### 5 PROPOSED CASE REVIEWERS

We recommend the following case reviewers who have the expertise required to evaluate submitted solutions:

- Paul Gazzillo (paul@pgazz.com). Research scholar at Stevens Institute of Technology.
- Ugur Koc (ukoc@cs.umd.edu). Ph.D. student at University of Maryland.
- ThanhVu H. Nguyen (tnguyen@cse.unl.edu). Assistant professor at University of Nebraska-Lincoln.
- Shiyi Wei (swei@utdallas.edu). Assistant professor at the University of Texas at Dallas.
- Jeho Oh (jeho.oh@utexas.edu). Ph.D. student at the University of Texas at Austin.

# **ACKNOWLEDGMENTS**

We would like to thank Julia Lawall for bringing up this challenge problem and providing concrete instances of it for the Linux source code.

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