# Dyuman Aditya

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#### EDUCATION

#### Ecole Centrale de Nantes

Nantes, France

MSc in Advanced Robotics

 $September\ 2025$ 

• M1: Artificial Intelligence, Control Theory, Signal Processing, Advanced Programming, Modelling & Design of Manipulators

#### Sri Aurobindo International Centre of Education

Pondicherry, India

BSc in Computer Science, Best Student Award

October 2022

• Computer Science, Mathematics, Mathematical Statistics, Physics, Numerical Analysis, English Literature, Tamil

#### Sri Aurobindo International Centre of Education

Pondicherry, India

Higher Secondary

Oct. 2019

• Computer Basics, Mathematics, Physics, Chemistry, English, French, Tamil, Sanskrit, Violin, Woodworking

## **PUBLICATIONS**

- Mukherji, K., Parkar, D., Pokala, L., **Aditya, Dyuman**, Shakarian, P. "Scalable Semantic Non-Markovian Simulation Proxy for Reinforcement Learning". Manuscript in preparation
- Aditya, Dyuman, Mukherji, K., Balasubramanian, S., Chaudhary, A., Shakarian, P. (2023). "PyReason: Software for Open World Temporal Logic". In AAAI Spring Symposium. (link)
- Aditya, Dyuman (2019). "Sanskrit and Computers A Future Together?". Mother India, 63-79. (link)

### EXPERIENCE

#### Research Assistant at Arizona State University

Mar. 2022 - Present

Prof. Paulo Shakarian's lab

Tempe, Arizona USA

- $\bullet$  Developed an implementation for  $\underline{\text{PyReason}}$  an explainable inference software supporting annotated, real-valued, graph-based, and temporal logic
- Accelerated PyReason using the python numba library, making it scalable
- Ran experiments on PyReason with large network graphs
- First Authored a manuscript presenting PyReason and experimental results published at AAAI-MAKE 2023

## Research Assistant at University of Maryland

June. 2023 - Present

ARLIS

College Park, Maryland USA

Developed a method to evaluate operational workflows due to added AI technology using PyReason as a simulator
of the workflow

## Research Intern at Carnegie Mellon University

Jun. 2022 - Nov. 2022

Prof. Min Xu's lab

 $Pittsburgh,\ Pennsylvania\ USA$ 

- Evaluated performance for algorithms that find the position and orientation of particles on biomedical images
- Started making improvements to the computer vision algorithms

## Robotics & Machine Learning Research Intern

Jul. 2020 - Aug. 2022

 $Telekinesis\ AI$ 

Darmstadt, Germany

#### Research

- Built a PyTorch Reinforcement Learning toolbox with 4 state-of-the-art algorithms from scratch and conducted experiments on OpenAI Gym
- Built custom reinforcement learning environments in Pybullet Drilling and Bin-picking. Conducted experiments on these using the reinforcement learning toolkit
- Developed a real-time, single object 6D object pose estimation pipeline and conducted experiments on the YCB dataset

## Industrial

• Developed a package to enable real-time motion control from external PCs

- Assisted in porting a large-scale legacy robotic application from Python to C++
- Designed and manufactured a hand-mounted device to track the orientation of the operator's hand
- Developed a networking package for TCP/IP and UDP communications between software components and industrial robots
- Developed a 3D Unity environment to display robots and integrated it into the main Telekinesis software

## PATENTS AND PATENT APPLICATIONS

Controlling Industrial Machines by Tracking Movements of their Operators (link)Patent Pending

Inventors: Pal, S., Chakraborty, K., Aditya, Dyuman, Datta, A., Peters, J.

Application number: EP21192932.8 Application date: 24 August 2021

#### Online Certificates

## Deep Learning Specialization - with Andrew Ng

Jun. 2020 - Oct. 2020

Coursera (verification link)

## Honours & Awards

Sri Aurobindo International Centre of Education

- Graduated with the The best student award: 2022. Awarded to the best student in the graduating class
- 9 Time Recipient of the Prize for Academic Excellence: 2011, 2014, 2015, 2016, 2017, 2019, 2020, 2021, 2022

#### **PROJECTS**

## File Manager (link)

Jan. 2021 - Apr. 2021

Developed a file manager with advanced functions that runs in a Linux terminal

Animatronic Hand Jan. 2019 - Oct. 2019

Designed and 3D printed an Animatronic hand that imitates an operator wearing a glove. Built a novel flex sensor using cheap potentiometers to measure finger movement. Presented in the annual school Science Fair

#### Low-Cost 3D Printer (link)

Jan. 2018 - Dec. 2018

Designed, prototyped and built a high-resolution, low-cost 3D printer from scratch, with a novel screw based motion system. The project has received over 110K views on instructables.com (Won 2nd prize). Presented in the annual school Science Fair

#### Extra-Curricular Activities

#### Teaching & Mentoring

Sri Aurobindo International Centre of Education

- Mentored freshmen in Mathematics (2022)
- Gave talks to high school students about my research and AI in general (2021-2022)
- Helped organize the annual science fair and mentored junior students (2019)
- Formed the "Science Group": a group of students interested in science and discussed breakthroughs and research papers in physics, chemistry, math and technology (2018)

#### Physical Education

Gymnastics, Athletics, Aquatic Sports, Games (Football, Basketball, Volleyball, Hockey)

Combative Sports and Running (2 time winner of the Annual Road Race).

## SKILLS

Languages: English, French, Sanskrit, Tamil

Programming Languages: Python, C, C++, Matlab, Bash

Computer & Software Skills: Autodesk Fusion 360, Git, Linux, OpenAI Gym, IATEX

Libraries & Frameworks: PyTorch, Keras, OpenCV, ROS, Numpy, Eigen, Matplotlib, Pandas, Pybullet, PCL, Numba Soft Skills: Logical Reasoning, Written Communication, Verbal Communication, Time Management, Discipline, Eye for Detail, Self-motivation, Teamwork