



EECS 490 – Lecture 24

Advanced Metaprogramming

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Announcements

- ▶ HW5 due tonight at 8pm
- ▶ Project 5 due Tue 12/12 at 8pm

Templates and Function Overloading

- Function templates can be specialized, but functions can also be overloaded, so overloading a function template with a non-template function is more common
- C++ prefers a non-template over a template instantiation if the parameter types are equally compatible with the arguments

```
template <class T>
string to_string(const T &item) {
    std::ostringstream oss;
    return (oss << item).str();
}

string to_string(bool item) {
    return item ? "true" : "false";
}
```

```
to_string(3.14)
-> "3.14"
to_string(true)
-> "true"
```

SFINAE

- A key to function templates is that *substitution failure is not an error (SFINAE)*
- This means that it is not an error if a function template fails to instantiate due to the types and expressions in the header being incompatible with the argument
- Instead, the template is removed from consideration

```
template <class T>
auto to_string(const T &item) ->
    decltype(std::to_string(item)) {
    return std::to_string(item);
}
```

Requires compatible
std::to_string()

This template fails to
instantiate, but the
previous one succeeds

```
to_string(Complex{ 3, 3.14 })
-> "(3,3.14i)"
to_string(3.14)
-> error: call is ambiguous
```

Both templates
are viable

Causing a Substitution Failure

- Sometimes we need to cause a substitution failure
- Common tool:

```
template <bool B, class T> struct enable_if {  
    typedef T type;  
};
```

```
template <class T> struct enable_if<false, T> {  
};
```

- Example:

```
template <int N> struct factorial {  
    static const typename  
        enable_if<N >= 0, long long>::type value =  
        N * factorial<N - 1>::value;  
};
```

This doesn't
exist if $N < 0$,
resulting in an
error

Overloading and Variadic Arguments

- We can use the fact that variadic arguments have lowest priority in overload resolution to prefer one overload over another:

```
template <class T>
auto to_string_helper(const T &item, int ignored)
    -> decltype(std::to_string(item)) {
    return std::to_string(item);
}
```

This overload
is preferred if
it is viable

```
template <class T>
string to_string_helper(const T &item, ...) {
    std::ostringstream oss;
    oss << item;
    return oss.str();
}
```

Variadic
arguments

```
template <class T>
string to_string(const T &item) {
    return to_string_helper(item, 0);
}
```

Dummy int
argument

Variadic Templates

- C++11 introduced support for templates that take a variable number of arguments
- Allows definition of variadic classes and functions that are type safe
- Example:

Accepts one
type argument

Parameter pack
accepts zero or more
type arguments

```
template <class First, class... Rest>
struct tuple {
    static const int size = 1 + sizeof...(Rest);
    // more code here
};
```

Size of
parameter pack

Empty
parameter
pack

```
tuple<int> t1;
tuple<double, char, int> t2;
```

Parameter
pack contains
char and int

Pattern Expansion

- An ellipsis to the right of a pattern that contains the name of a parameter pack is expanded into a comma-separated list

```
using first_type = First;  
using rest_type = tuple<Rest...>;
```

```
first_type first;  
rest_type rest;
```

If Rest contains char
and int, expanded
to tuple<char, int>

Recursive data
representation

Tuple Definition

```
template <class First, class... Rest>
struct tuple {
    static const int size = 1 + sizeof...(Rest);
    using first_type = First;
    using rest_type = tuple<Rest...>;
    first_type first;
    rest_type rest;
    tuple(First f, Rest... r) :
        first(f), rest(r...) {}
};
```

Expands to multiple
parameters

Base
case


```
template <class First>
struct tuple<First> {
    static const int size = 1;
    using first_type = First;
    first_type first;
    tuple(First f) : first(f) {}
};
```

Constructing a Tuple

- We can write a function template to construct a tuple and then use it with argument deduction

```
template <class... Types>
tuple<Types...> make_tuple(Types... items) {
    return tuple<Types...>(items...);
}
```

```
tuple<int> t1 = make_tuple(3);
tuple<double, char, int> t2 =
    make_tuple(4.9, 'c', 3);
```



Argument
types
deduced

Representing a Tuple Element

- We define a struct to represent a tuple element:

```
template <int Index, class Tuple>
struct tuple_element {
    using rest_type =
        tuple_element<Index - 1,
                      typename Tuple::rest_type>;
    using type = typename rest_type::type;
    type &item;
    tuple_element(Tuple &t) :
        item(rest_type(t.rest).item) {}
};
```

```
template <class Tuple>
struct tuple_element<0, Tuple> {
    using type = typename Tuple::first_type;
    type &item;
    tuple_element(Tuple &t) : item(t.first) {}
};
```

Obtaining a Tuple Element

- We can then define a function template to obtain an item from a tuple:

Alias
template

```
template <int Index, class... Types>  
tuple_element_t<Index, tuple<Types...>> &  
get(tuple<Types...> &t) {  
    return tuple_element<Index,  
                           tuple<Types...>>(t).item;  
}
```

```
tuple<double, char, int> t2 = make_tuple(4.9, 'c', 3);  
cout << get<0>(t2) << endl;  
cout << get<1>(t2) << endl;  
cout << get<2>(t2) << endl;  
get<0>(t2)++;  
get<1>(t2)++;  
get<2>(t2)++;  
cout << get<0>(t2) << endl;  
cout << get<1>(t2) << endl;  
cout << get<2>(t2) << endl;
```

```
4.9  
c  
3  
5.9  
d  
4
```

Multidimensional Arrays

- We can use metaprogramming to implement a multidimensional array abstraction in C++
- *Point*: a multidimensional index, represented by a sequence of integers

```
point<3> p = pt(3, -4, 5);
```

- *Domain*: a range of indices, represented by a lower-bound and an upper-bound point

```
rectdomain<3> rd{ pt(3, -4, 5), pt(5, -2, 8) };
```

- *Array*: constructed over a domain, indexed with a point

```
ndarray<double, 3> A(rd);  
A[p] = 3.14;
```

Points

- We can implement a point as follows:

Data
representation

```
template <int N> struct point {  
    int coords[N];  
    int &operator[](int i) {  
        return coords[i];  
    }  
    const int &operator[](int i) const {  
        return coords[i];  
    }  
};
```

Function to
construct a
point

```
template <class... Is>  
point<sizeof...(Is)> pt(Is... is) {  
    return point<sizeof...(Is)>{{ is... }};  
}
```

Inner initializer list
is for initializing
coords array

Point Operations

- Point operations have a common structure:

```
template <int N>
point<N> operator+(const point<N> &a,
                   const point<N> &b) {
    point<N> result;
    for (int i = 0; i < N; i++)
        result[i] = a[i] + b[i];
    return result;
}
```

```
template <int N>
bool operator==(const point<N> &a,
                const point<N> &b) {
    bool result = true;
    for (int i = 0; i < N; i++)
        result = result && (a[i] == b[i]);
    return result;
}
```

Generalized Macro

- General structure:

```
#define POINT_OP(op, rettype, header, action) \
    template <int N>                          \
    rettype operator op(const point<N> &a,    \
                        const point<N> &b) {   \
        header;                               \
        for (int i = 0; i < N; i++)          \
            action;                           \
        return result;                        \
    }
```

- Arithmetic structure:

```
#define POINT_ARITH_OP(op) \
    POINT_OP(op, point<N>, point<N> result, \
             result[i] = a[i] op b[i])
```


Implementing Operations

- We can implement the operations as follows:

```
POINT_ARITH_OP(+);  
POINT_ARITH_OP(-);  
POINT_ARITH_OP(*);  
POINT_ARITH_OP(/);
```

```
#define POINT_COMP_OP(op, start, combiner)      \  
    POINT_OP(op, bool, bool result = start,    \  
              result = result combiner         \  
              (a[i] op b[i]), result)
```

```
POINT_COMP_OP(==, true, &&);  
POINT_COMP_OP(!=, false, ||);  
POINT_COMP_OP(<, true, &&);  
POINT_COMP_OP(<=, true, &&);  
POINT_COMP_OP(>, true, &&);  
POINT_COMP_OP(>=, true, &&);
```

Rectangular Domains

► Interface:

```
template <int N>
struct rectdomain {
    point<N> lwb;
    point<N> upb;

    int size() const;

    struct iterator;

    iterator begin() const;

    iterator end() const;
};
```

Exclusive
upper bound



```
rectdomain<3> rd{ pt(1, 2, 3),
                  pt(3, 4, 5) };
for (auto p : rd)
    cout << p << endl;
```

```
(1,2,3)
(1,2,4)
(1,3,3)
(1,3,4)
(2,2,3)
(2,2,4)
(2,3,3)
(2,3,4)
```

Array Interface

```

template <class T, int N>
struct ndarray {
private:
    rectdomain<N> domain;
    int sizes[N];
    T *data;

    int indexof(const point<N> &index) const;

public:
    ndarray(const rectdomain<N> &dom);
    ndarray(const ndarray &rhs);
    ndarray &operator=(const ndarray &rhs);
    ~ndarray();

    T &operator[](const point<N> &index);
    const T &operator[](const point<N> &index) const;
};

```

Dimensionality

Element type

Translates
multidimensional
to linear index

Linear data
representation

The Big 3

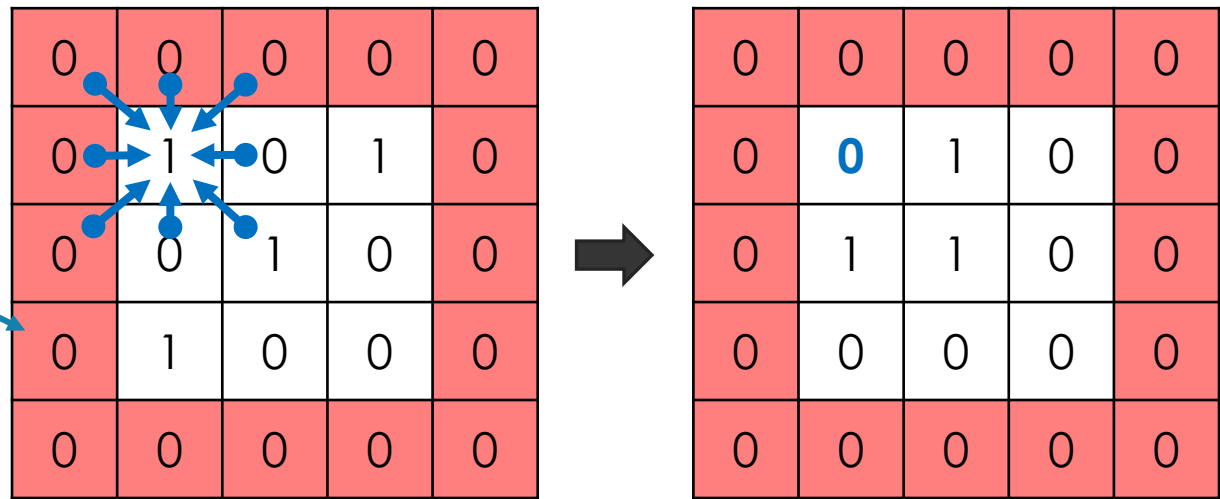
20

- ▶ We'll start again in five minutes.

Stencil

- A *stencil* is an iterative computation that updates grid points according to the previous value of neighboring points
- In the *Jacobi* method, the updates are *out of place*, so that new values are recorded in a different grid than old values

Ghost cells
at boundary



Stencil Data Structures

- Domains and arrays for 3D heat equation:

```
point<3> start = pt(0, 0, 0);  
point<3> end = pt(xdim, ydim, zdim);
```

Domain with
ghost cells

```
rectdomain<3> domain{ start + pt(-1, -1, -1),  
                      end + pt(1, 1, 1) };  
rectdomain<3> interior{ start, end };
```

```
ndarray<double, 3> gridA(domain);  
ndarray<double, 3> gridB(domain);
```

Include ghost
cells in array

Stencil Loop

- A single timestep:

```
for (auto p : interior) {  
    gridB[p] =  
        gridA[p + pt( 0, 0, 1)] +  
        gridA[p + pt( 0, 0, -1)] +  
        gridA[p + pt( 0, 1, 0)] +  
        gridA[p + pt( 0, -1, 0)] +  
        gridA[p + pt( 1, 0, 0)] +  
        gridA[p + pt(-1, 0, 0)] +  
        WEIGHT * gridA[p];  
}
```

- Problem: this is very slow on some compilers, including GCC

Nested Iteration

- Some compilers can do powerful analysis on nested loops, optimizing the iteration order to take advantage of the memory hierarchy
- This loop is 5x faster in GCC:

```
for (p[0] = interior.lwb[0];  
     p[0] < interior.upb[0]; p[0]++) {  
    for (p[1] = interior.lwb[1];  
         p[1] < interior.upb[1]; p[1]++) {  
        for (p[2] = interior.lwb[2];  
             p[2] < interior.upb[2]; p[2]++) {  
            gridB[p] = ...;  
        }  
    }  
}
```


Implementing Nested Iteration

Dimensions remaining

- Template metaprogramming to generate nested loops:

```
template <int N> struct rdloop {
    template <class F, class... Is>
    static void loop(const F &func, const int *lwb,
                    const int *upb, Is... is) {
        for (int i = *lwb; i < *upb; i++)
            rdloop<N-1>::loop(func, lwb+1, upb+1, is..., i);
    }
};
```

```
template <> struct rdloop<1> {
    template <class F, class... Is>
    static void loop(const F &func, const int *lwb,
                    const int *upb, Is... is) {
        for (int i = *lwb; i < *upb; i++)
            func(pt(is..., i));
    }
};
```

Functor object

Index bounds

Call functor with a point using computed indices

Indices computed so far

Custom Loop

- Loop abstraction:

Point variable

Domain

```
foreach (p, interior) {  
    gridB[p] =  
        gridA[p + pt( 0, 0, 1)] +  
        gridA[p + pt( 0, 0, -1)] +  
        gridA[p + pt( 0, 1, 0)] +  
        gridA[p + pt( 0, -1, 0)] +  
        gridA[p + pt( 1, 0, 0)] +  
        gridA[p + pt(-1, 0, 0)] +  
        WEIGHT * gridA[p];  
};
```

**Looks like body
of lambda
function**

Loop Macro

- Macro for foreach:

```
#define foreach(p, dom) \
    for (auto _iter = (dom).iter(); \
         !_iter.done; \
         _iter.done = true) \
        _iter = [&](const decltype((dom).lwb) &p)
```

Dummy loop
header to
introduce
iterator object

Iterator object
overloads assignment
operator to take
functor

Capture
locals by
reference

Deduce
point type
from domain

Point variable
is lambda
parameter

Fast Iterator

► Implementation:

```
struct fast_iter {  
    const rectdomain &domain;  
    bool done;  
  
    fast_iter(const rectdomain &dom)  
        : domain(dom), done(false) {}  
  
    template <class F>  
    fast_iter &operator=(const F &func) {  
        rdloop<N>::loop(func, domain.lwb.coords,  
                        domain.upb.coords);  
        return *this;  
    }  
};
```

For dummy
loop header

Use nested
loop generator

Assignment
operator
takes functor

This matches the performance of nested loops on GCC 6.

12/3/17