Homotopy Groups of Spheres

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Introduction

Spheres

Homotopy Groups of Spheres

Graduate Student Seminar

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Outline

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- Homotopy as a means of classification somewhere between homeomorphism and cobordism
- Comparison to homology
- Higher homotopy groups of spheres exist
- Homotopy groups of spheres govern gluing of CW complexes
- CW complexes fully capture that homotopy category of spaces
- There are concrete topological constructions of many important algebraic operations at the level of spaces (quotients, tensor products)
- Relation to framed cobordism?
- "Measuring stick" for current tools, similar to special values of L-functions
- Serre's computation

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Homotopies of paths:



– Regard paths γ in X and homotopies of paths H as morphisms

$$\gamma \in \mathsf{hom}_{\mathsf{Top}}(I, X)$$
 $H \in \mathsf{hom}_{\mathsf{Top}}(I \times I, X).$

- Yields an equivalence relation: write

$$\gamma_0 \sim \gamma_1 \iff \exists H \text{ with } H(0) = \gamma_0, H(1) = \gamma(1)$$

- Write $[\gamma]$ to denote a homotopy class of paths.

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– Why care about path homotopies? Historically: contour integrals in $\ensuremath{\mathbb{C}}$



– By the residue theorem, for a meromorphic function f with simple poles $P = \{p_i\}$ we know that

$$\oint_{\gamma} f(z) \ dz \text{ is determined by } [\gamma] \in \pi_1(\mathbb{C} \setminus P)$$

Definitions

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Generalize to a homotopy of morphisms:

$$f, g \in \mathsf{hom}_{\mathsf{Top}}(X, Y) \quad f \sim g \iff \exists F \in \mathsf{hom}_{\mathsf{Top}}(X \times I, Y)$$

- such that F(0) = f, F(1) = g.
- This yields an equivalence relation on morphisms, homotopy classes of maps

$$[X, Y] := \mathsf{hom}_{\mathsf{Top}}(X, Y) / \sim$$

Definition of homotopy equivalence:

$$X \sim Y \iff \exists \begin{cases} f \in \mathsf{hom}(X,Y) \\ g \in \mathsf{hom}(Y,X) \end{cases}$$
 such that $\begin{cases} f \circ g \sim \mathsf{id}_Y \\ g \circ f \sim \mathsf{id}_X \end{cases}$

Similarly write

$$[X] = \{ Y \in \mathsf{Top} \mid Y \sim X \}.$$

The Fundamental Group

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IIItroductioi

- $-\pi_1(X)$ is the group of homotopy classes of loops:
- Can recover this definition by finding a (co)representing object:

$$\pi_1(X) = [S^1, X]$$



Higher Homotopy Groups

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Can now generalize to define

$$\pi_k(X) := [S^k, X]$$



Fun side note: this kind of definition generalizes to AG, see Motivic Homotopy Theory – the (co)representing objects look \mathbb{A}^1 or \mathbb{P}^1 .

Classification

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- Holy grail: understand the topological category completely
 - I.e. have a well-understood geometric model one space of each homeomorphism type



Also have the derived category DTop, its interplay with hoTop is the subject of e.g. the Poincare conjecture(s).

- Any representative from a green box: a homotopy type.

Example: Homotopy Equivalence is Useful

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Proposition: Let B be a CW complex; then isomorphism classes of \mathbb{R}^1 -bundles over B are given by $H^1(X, \mathbb{Z}/2\mathbb{Z})$.

- Use the fact that for any fixed group G, the functor

$$h_G(\,\cdot\,):\mathsf{hoTop^{op}}\longrightarrow\mathsf{Set}$$

$$X\mapsto\{G\mathsf{-bundles\ over\ }X\}$$

is representable by a space called BG (Brown's representability theorem).

- I.e., let $Bun_G(X) = \{G-bundles/B\} / \sim$, there is an isomorphism

$$\operatorname{Bun}_G(X) \cong [X, BG]$$

- In general, identify $G = \operatorname{Aut}(F)$ the automorphism group of the fibers - for vector bundles of rank n, take $G = GL(n, \mathbb{R})$.

Example: Homotopy Equivalence is Useful

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Introduction Spheres Note that for a poset of spaces (M_i, \hookrightarrow) , the space $M^{\infty} := \varinjlim M_i$. These are infinite dimensional "Hilbert manifolds".

Proof:

$$\mathsf{Bun}_{\mathbb{R}^1}(X) = [X, B\mathrm{GL}(1, \mathbb{R})]$$

$$= [X, \mathsf{Gr}(1, \mathbb{R}^{\infty})]$$

$$= [X, \mathbb{RP}^{\infty}]$$

$$= [X, K(\mathbb{Z}/2\mathbb{Z}, 1)]$$

$$= H^1(X; \mathbb{Z}/2\mathbb{Z})$$

Work being swept under the rug: identifying the homotopy type of the representing object.

Example: Homotopy Equivalence is Useful

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Introduction Spheres **Corollary:** There are 2 distinct line bundles over $X = S^1$ (the cylinder and the mobius strip), since $H^1(S^1; \mathbb{Z}/2\mathbb{Z}) \cong \mathbb{Z}/2\mathbb{Z}$.

Corollary: A Riemann surface Σ_g satisfies $H^1(\Sigma_g; \mathbb{Z}/2\mathbb{Z}) = (\mathbb{Z}/2\mathbb{Z})^{2g}$ and thus there are 2^{2g} distinct real line bundles over it.



Example: Higher Homotopy Groups are Useful

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- Application: computing $\pi_1(SO(n,\mathbb{R})$ (rigid rotations in \mathbb{R}^n).
- The fibration

$$SO(n, \mathbb{R}) \longrightarrow SO(n+1, \mathbb{R}) \longrightarrow S^n$$

yields a LES in homotopy:

$$\cdots \longrightarrow \pi_2(SO(n,\mathbb{R})) \longrightarrow \pi_2(SO(n,\mathbb{R})) \longrightarrow \pi_2(S^n)$$

$$\pi_1(SO(n,\mathbb{R})) \longrightarrow \pi_1(SO(n,\mathbb{R})) \longrightarrow \pi_1(S^n)$$

Uses of Higher Homotopy

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Introduction Spheres Knowing $\pi_k S^n$, this reduces to

$$\cdots 0 \longrightarrow \pi_2(SO(n,\mathbb{R})) \longrightarrow \pi_2(SO(n,\mathbb{R})) \longrightarrow 0$$

$$\pi_1(SO(n,\mathbb{R})) \longrightarrow \pi_1(SO(n,\mathbb{R})) \longrightarrow 0$$

- Thus $\pi_1(SO(3,\mathbb{R})) \cong \pi_1(SO(4,\mathbb{R})) \cong \cdots$ and it suffices to compute $\pi_1(SO(3,\mathbb{R}))$ (stabilization)
- Use the fact that "accidental" homeomorphism in low dimension SO(3, \mathbb{R}) $\cong_{\mathsf{Top}} \mathbb{RP}^3$, and algebraic topology I yields $\pi_1 \mathbb{RP}^3 \cong \mathbb{Z}/2\mathbb{Z}$.

Can also use the fact that $SU(2,\mathbb{R}) \longrightarrow SO(3,\mathbb{R})$ is a double cover from the universal cover.

Uses of Higher Homotopy

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- Important consequence: SO(3, ℝ) is not simply connected!
- See "plate trick": non-contractible loop of rotations that squares to the identity.
- Robotics: paths in configuration spaces with singularities
- Computer graphics: smoothly interpolating between quaternions for rotated camera views



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Setup

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- Defining $\pi_k(X) = [S^k, X]$, the simplest objects to investigate: $X = S^n$
- Can consider the bigraded group $\pi_S := [S^k, S^n]$:



But Wait!

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The corresponding picture in homology is very easy:



Slogan: "conservation/duality of complexity"

History

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- 1895: Poincare, Analysis situs ("the analysis of position") in analogy to Euler Geometria situs in 1865 on the Kongisberg bridge problem
 - Studies spaces arising from gluing polygons, polyhedra, etc (surfaces!), first use of "algebraic invariant theory" for spaces by introducing π_1 and homology.
- 1920s: Rigorous proof of classification of surfaces (Klein, Möbius, Clifford, Dehn, Heegard)
 - Captured entirely by π_1 (equivalently, by genus and orientability).
- 1931: Hopf discovers a nontrivial (not homotopic to identity) map $S^3 \longrightarrow S^2$

History

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- 1932/1935: Cech (indep. Hurewicz) introduce higher homotopy groups, gives map relating $\pi_* \longrightarrow H_*$, shows $\pi_n X$ are **abelian** groups for $n \ge 2$.
 - Withdrew his paper because of this theorem!
- 1951: Serre uses spectral sequences to show that all groups $\pi_k S^n$ are torsion except,
 - k = n, since $\pi_n S^n = \mathbb{Z}$
 - $-k \equiv 3 \mod 4$, $n \equiv 0 \mod 2$, then $\mathbb{Z} \oplus T$
 - Tight bounds on where *p*-torsion can occur.
- 1953: Whitehead shows the homotopy groups of spheres split into stable and unstable ranges.

Today: We know $\pi_{n+k}S^n$ for

- $-k \le 64$ when $n \ge k + 2$ (stable range)
- $k \le 19$ when n < k + 2 (unstable range)
- We *only* have a complete list for S^0 and S^1 , and know *no* patterns beyond this!
 - Open for \sim 80 years.

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We'll fill out as much of this table as is easily known:



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This follows easily from CW approximation:

Any map $X \xrightarrow{f} Y$ between CW complexes is homotopic to a cellular map.

k < n: CW Complexes

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- Analogy from analysis: C^1 functions dense in L^2 .
 - If you're just computing homotopy groups, any space can be replaced with a weakly equivalent CW complex.





k < n: CW Complexes

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AT1 can show that spheres have a simple cell decomposition

$$S^k = e_0 \coprod_f e_k$$

Thus any map $f: S^k \longrightarrow S^n$ must send the k-skeleton of S^k to the k-skeleton of S^n , which is just a point:



$k \ge 1$, n = 1: Covering Space Theory

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Claim: $\pi_1 S^1 = \mathbb{Z}$ and $\pi_{\geq 2} S^1 = 0$. $\pi_k(S^n)$ n = 13 4 5 6 9 10

$k \ge 1$, n = 1: Covering Space Theory

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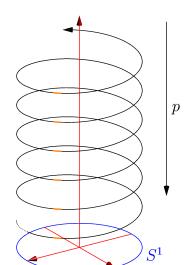
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– Use the fact that $\mathbb{Z} \longrightarrow \mathbb{R} \longrightarrow S^1$ is a covering space and $\mathbb{Z} \curvearrowright \mathbb{R}$ freely.

 \mathbb{R}



$k \ge 1$, n = 1: Covering Space Theory

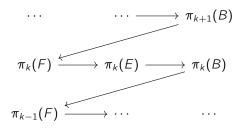
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Theorem: If $F \longrightarrow E \longrightarrow B$ is a *Serre Fibration* then there is a LES in homotopy



- If $\tilde{X} \longrightarrow X$ is a universal cover then $\pi_{\geq 2}(X) \cong \pi_{\geq 2}\tilde{X}$.
 - Proof coming up!

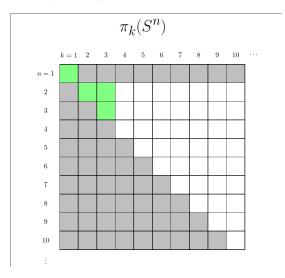
Misc: Serre Fibrations

Claim: $\pi_2 S^2 = \pi_3 S^2 = \pi_3 S^3 = \mathbb{Z}$.

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Misc: Serre Fibrations

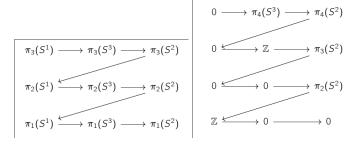
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Use the Hopf fibration:
$$S^1 \longrightarrow S^3 \longrightarrow S^2$$
 and the fact that $\pi_{\geq 2}S^1=0$:



Note that this works whenever the fiber is contractible (e.g. universal covers, fibers are discrete)

Hopf Fibration Visualizer

n = k: Stabilization

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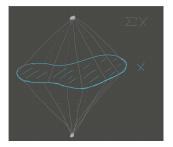
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– Theorem (1937, Freudenthal): For $k \gg 0$,

$$[\Sigma^k X, \Sigma^k Y] \cong [\Sigma^{k+1} X, \Sigma^{k+1} Y]$$

- Use the fact that $\Sigma S^k \cong S^{k+1}$, then in some stable range

$$\pi_{n+k}S^n \cong \pi_{n+k+1}S^{n+1}$$



Fun note: corresponds to "smash with a sphere"

n=k: Stabilization

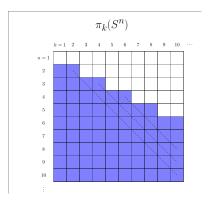
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Stable range:



n = k: Stabilization

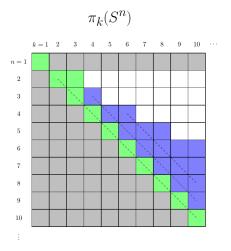
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We can thus suspend things we already know:



k = 4. n = 3

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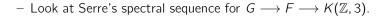
- Construct a map $S^3 \longrightarrow K(\mathbb{Z}_2)$ by "killing off homotopy" (identify K)
- Convert to a fibration and take the homotopy fiber to get $F \longrightarrow S^2 \longrightarrow \mathbb{CP}^{\infty}$
- By LES, $\pi_{>3}F \cong \pi_{>3}S^2$, by Hurewicz $\pi_3F \cong H_3F$, which we can compute
- Kill homotopy again and iterated homotopy fiber to get $G \longrightarrow F \longrightarrow K(\mathbb{Z},3)$
- By LES, $\pi > 4G \cong \pi_{>4}S^2$, by Hurewicz $\pi_4G \cong H_4G$.

k=4, n=3

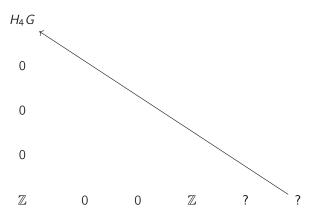
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k=4, n=3

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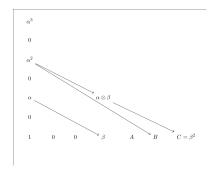
- Want target of arrow. Need to know
 - $-H^4F$, H^5F (total cohomology)
 - $-H^{5}K(\mathbb{Z},3)$ (source of arrow)
- Use Serre SS on $F \longrightarrow S^2 \longrightarrow K(\mathbb{Z},2)$ to deduce $H^5F = H^6F = \mathbb{Z}$
- Use Serre SS on $\Omega K(\mathbb{Z},3) \longrightarrow \{pt\} \longrightarrow K(\mathbb{Z},3)$:

k=4, n=3

Groups of Spheres

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Relevant quantity will be C term in SSS:



- Everything must go! Converges to homology of a point.
- Work out $d\alpha = \beta$ Work out $d(\alpha^2) = 2\alpha \otimes \beta$
- Work out $\beta^2 \neq 0$ Work outker($\alpha^2 \longrightarrow \alpha \otimes \beta$) = $2 \langle \alpha \otimes \beta \rangle$
- Conclude A = B = 0 and C ≅ Z/2Z.