# Problem Set 1

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## **Contents**

1	Pro	Problem 3           1.1 Part 1																1															
	1.1	Part 1																			 									 			]
	1.2	Part 1																			 		•										]
2	Problem 4           2.1 Part 1																2																
	2.2	Part 2																			 		•			•	•	•		 •		•	4
3	Problem 5           3.1 Part 1																2																
	3.1	Part 1															 				 												4
	3.2	Part 2																			 											•	٠
4	Problem 6           4.1 Part 1																4																
	4.1	Part 1															 				 												4
	12	Part 2																															r

## 1 Problem 3

#### 1.1 Part 1

Note: Throughout this question, we will identify  $\{f: C^{\infty}(M) \to \mathbb{R}\} \cong C^{\infty}(M)^{\vee}$  as vector spaces.

Let M, N be smooth manifolds and  $f: M \to N$  be a fixed smooth map, and define a map

$$\phi: C^{\infty}(N) \times T_p M \to \mathbb{R}$$
$$(h, v) \mapsto v(h \circ f)$$

#### 1.2 Part 1

Using the derivation definition, we can identify this assignment as a map

$$\phi: C^{\infty}(N) \times C^{\infty}(M)^{\vee} \to \mathbb{R}$$
  
 $(h, g_v) \mapsto g_v(h \circ f)$ 

We'd like to show that this yields a well-defined element of  $T_pM = C^{\infty}(M)^{\vee}$ .

## 2 Problem 4

#### 2.1 Part 1

Let  $V = \mathbb{R}^n$  as a vector space, let g be a nonsingular matrix, and define a map

$$\phi: V \to V^{\vee}$$
$$v \mapsto (\phi_v: w \mapsto \langle v, qw \rangle)$$

The claim is that  $\phi$  is a natural isomorphism. It is clearly linear (following from the linearity of the inner product and matrix multiplication), so it remains to check that it is a bijection.

To see that  $\ker \phi = 0$ , so that only the zero gets sent to the zero map, we can suppose that  $x \in \ker \phi$ . Then  $\phi_x : w \to \langle x, gw \rangle$  is the zero map. But the inner product is nondegenerate by definition, i.e.  $\langle x, y \rangle = 0 \ \forall y \implies x = 0$ . So x could only have been the zero vector to begin with.

But dim  $V = \dim V^{\vee}$ , so any injective linear map will necessarily be surjective as well.

### 2.2 Part 2

Let  $g:TM\otimes TM\to\mathbb{R}$  be a metric, and consider the tangent space TM. By definition, the cotangent space  $T_p^*M=(T_pM)^\vee$ 

## 3 Problem 5

#### 3.1 Part 1

Let  $A \in Mat(n, n)$  be a positive definite  $n \times n$  matrix, so

$$\langle v, Av \rangle > 0 \quad \forall v \in \mathbb{R}^n,$$

and  $B \in Math(n, n)$  be positive semi-definite, so

$$\langle v, Bv \rangle > 0 \quad \forall v \in \mathbb{R}^n.$$

We'd like to show

$$\langle v, (A+B)v \rangle \ge 0 \quad \forall v \in \mathbb{R}^n,$$

which follows directly from

$$\langle v, (A+B)v \rangle = \langle v, Av \rangle + \langle v, Bv \rangle$$
  
>  $\langle v, Av \rangle + 0$   
 $\geq 0 + 0$   
= 0.

#### 3.2 Part 2

Let M be a smooth manifold with tangent bundle TM and a maximal smooth atlas  $\mathcal{A}$ . Choose a covering of M by charts  $\mathcal{C} = \{(U_i, \phi_i) \mid i \in I\} \subseteq \mathcal{A} \text{ such that } M \subseteq \bigcup_{i \in I} U_i.$  Then choose a partition of unity  $\{f_i\}_{i \in I}$  subordinate to  $\mathcal{C}$ , so for each i we have

$$f_i: M \to I$$

$$\forall p \in M, \quad \sum_{i \in I} f_i(p) = 1$$

In each copy of  $\phi_i(U_i) \cong \mathbb{R}^n$ , let  $g^i$  be the Euclidean metric given by the identity matrix, i.e.  $g^i_{jk} := \delta_{jk}$ . We then have

$$g^{i}: T\phi_{i}(U_{i}) \otimes T\phi_{i}(U_{i}) \to \mathbb{R}$$

$$(\partial x_{i}, \partial x_{j}) \mapsto \begin{cases} 1 & i = j \\ 0 & \text{otherwise} \end{cases}$$

which is defined for pairs of vectors in  $T\phi_i(U_i) \cong T\mathbb{R}^n = \operatorname{span}_{\mathbb{R}} \{\partial x_i\}_{i=1}^n$  on basis vectors as the Kronecker delta and extended linearly.

Note that each coordinate function  $\phi_i: U_i \to \mathbb{R}^n$  induces a map  $\tilde{\phi}_i: TU_i \to T\mathbb{R}^n$ .

Let  $G^i$  be the pullback of  $g^i$  along these induced maps  $\tilde{\phi}_i$ , so

$$G^{i}: TU_{i} \otimes TU_{i} \to \mathbb{R}$$
$$G^{i}(x,y) := \left(\left(\tilde{\phi}_{i}\right)^{*} g^{i}\right)(x,y) := g^{i}(\tilde{\phi}_{i}(x), \tilde{\phi}_{i}(y))$$

Then, for a point  $p \in M$ , define the following map:

$$g_p: T_pM \otimes T_pM \to \mathbb{R}$$
  
 $(x,y) \mapsto \sum_{i \in I} f_i(p)G^i(x,y).$ 

The claim is that  $g_p$  defines a metric on M, and thus the family  $\{g_p \mid p \in M\}$  yields a tensor field and thus a Riemannian metric on M. If we define the map

$$g: M \to (TM \otimes TM)^{\vee}$$
$$p \mapsto g_p$$

then g can be expressed as

$$g = \sum_{i \in I} f_i G^i.$$

We can check that this is positive definite by considering  $x \in T_pM$  and computing

$$g(x,x) := g_p(x,x)$$

$$= \sum_{i \in I} f_i(p) \ G^i(v,v)$$

$$= \sum_{i \in I} f_i(p) \ g^i(\tilde{\phi}_i(x), \tilde{\phi}_i(y)),$$

where each term is positive semi-definite, and at least one term is positive definite because  $\sum_i f_i(p)$  must equal 1. By part 1, this means that the entire expression is positive definite, so g is a metric.

## 4 Problem 6

#### 4.1 Part 1

Let  $M = S^2$  as a smooth manifold, and consider a vector field on M,

$$X: M \to TM$$

We want to show that there is a point  $p \in M$  such that X(p) = 0.

Every vector field on a compact manifold without boundary is complete, and since  $S^2$  is compact with  $\partial S^2 = \emptyset$ , X is necessarily a complete vector field.

Thus every integral curve of X exists for all time, yielding a well-defined flow

$$\phi: M \times \mathbb{R} \to M$$

given by solving the initial value problems

$$\frac{\partial}{\partial s}\phi_s(p)\Big|_{s=t} = X(\phi_t(p)),$$

$$\phi_0(p) = p$$

at every point  $p \in M$ .

This yields a one-parameter family

$$\phi_t: M \to M \in \mathrm{Diff}(M,M).$$

In particular,  $\phi_0 = \mathrm{id}_M$ , and  $\phi_1 \in \mathrm{Diff}(M, M)$ . Moreover  $\phi_0$  is homotopic to  $\phi_1$  via the homotopy

$$H: M \times I \to M$$
  
 $(p,t) \mapsto \phi_t(p).$ 

We can now apply the Lefschetz fixed-point theorem to  $\phi_0$  and  $\phi_1$ . For an arbitrary map  $f: M \to M$ , we have

$$\Lambda(f) = \sum_{k} \operatorname{Tr} \left( f_* \Big|_{H_k(X;\mathbb{Q})} \right).$$

where  $f_*: H_*(X; \mathbb{Q}) \to H_*(X; \mathbb{Q})$  is the induced map on homology, and

 $\Lambda(f) \neq 0 \iff f$  has at least one fixed point.

In particular, we have

$$\begin{split} \Lambda(\mathrm{id}_M) &= \sum_k \mathrm{Tr}(\mathrm{id}_{H_k(X;\mathbb{Q})}) \\ &= \sum_k \dim H_k(X;\mathbb{Q}) \\ &= \chi(M), \end{split}$$

the Euler characteristic of M.

Since homotopic maps induce equal maps on homology, we also have  $\Lambda(\phi_1) = \chi(M)$ . Since

$$H_k(S^2) = \begin{cases} \mathbb{Z} & k = 0, 2\\ 0 & \text{otherwise} \end{cases}$$

we have  $\chi(S^2) = 2 \neq 0$ , and thus  $\phi_1$  has a fixed point  $p_0$ , thus  $\frac{\partial}{\partial t}\phi_t(p_0)\Big|_{t=1}$  so

$$\phi_t(p) = p$$

$$\Rightarrow \frac{\partial}{\partial t} \phi_t(p) = \frac{\partial}{\partial t} p = 0 \qquad \text{by differentiating wrt } t$$

$$\Rightarrow \frac{\partial}{\partial t} \phi_t(p) \Big|_{t=1} = 0 \Big|_{t=0} = 0 \qquad \text{by evaluating at } t = 0$$

$$\Rightarrow X(\phi_1(p_0)) := \frac{\partial}{\partial t} \phi_t(p) \Big|_{t=1} = 0 \qquad \text{by definition of } \phi_1$$

so  $X(\phi_1(p_0)) = 0$ , which shows that  $p_0$  is a zero of X. So X has at least one zero, as desired.  $\square$ 

#### 4.2 Part 2

The trivial bundle

$$\mathbb{R}^2 \longrightarrow S^2 \times \mathbb{R}^2$$

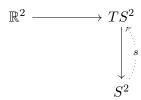
$$\downarrow^{r}$$

$$S^2$$

has a nowhere vanishing section, namely

$$s: S^2 \to S^2 \times \mathbb{R}^2$$
  
 $\mathbf{x} \to (\mathbf{x}, [1, 1])$ 

which is the identity on the  $S^2$  component and assigns the constant vector [1,1] to every point. However, as part 1 shows, the bundle



can not have a nowhere vanishing section.  $\qed$