Linearization and Transversality

D. Zack Garza

#### Review 8.2

Space of
Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F

# Linearization and Transversality

Sections 8.3 and 8.4

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Linearization and Transversality

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ection 8.3: The pace of Perturbations of

Linearizing the Floer Equation:
The Differential

Review 8.2

Linearization and

Section 8.3: The Space of Perturbations of

# Section 8.3: The Space of Perturbations of Н

### Goal

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Review 8.3

Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differentia of F **Goal**: Given a fixed Hamiltonian  $H \in C^{\infty}(W \times S^1; \mathbb{R})$ , perturb it (without modifying the periodic orbits) so that  $\mathcal{M}(x, y)$  are manifolds of the expected dimension.

### Goal

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Section 8.3: The Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F Start by trying to construct a subspace  $\mathcal{C}^{\infty}_{\mathbb{C}}(H) \subset \mathcal{C}^{\infty}(W \times S^1; \mathbb{R})$ , the space of perturbations of H depending on a certain sequence  $\varepsilon = \{\varepsilon_k\}$ , and show it is a dense subspace.



### Define an Absolute Value

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Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F Idea: similar to how you build  $L^2(\mathbb{R})$ , define a norm  $\|\cdot\|_{\varepsilon}$  on  $C_{\varepsilon}^{\infty}(H)$  and take the subspace of finite-norm elements.

- Let  $h(\mathbf{x}, t) \in C_{\varepsilon}^{\infty}(H)$  denote a perturbation of H.
- Fix  $\varepsilon = \left\{ \varepsilon_k \mid k \in \mathbb{Z}^{\geq 0} \right\} \subset \mathbb{R}^{>0}$  a sequence of real numbers, which we will choose carefully later.
- For a fixed  $\mathbf{x} \in W$ ,  $t \in \mathbb{R}$  and  $k \in \mathbb{Z}^{\geq 0}$ , define

$$|d^k h(\mathbf{x}, t)| = \max \{d^{\alpha} h(\mathbf{x}, t) \mid |\alpha| = k\},$$

the maximum over all sets of multi-indices  $\alpha$  of length k. Note: I interpret this as

$$d^{\alpha_1,\alpha_2,\cdots,\alpha_k}h=\frac{\partial^k h}{\partial x_{\alpha_1}\,\partial x_{\alpha_2}\cdots\partial x_{\alpha_k}},$$

the partial derivatives wrt the corresponding variables.

### Define a Norm

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Section 8.3: The Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F – Define a norm on  $C^{\infty}(W \times S^1; \mathbb{R})$ :

$$||h||_{U} = \sum_{k\geq 0} \varepsilon_k \sup_{(x,t)\in W\times S^1} |d^k h(x,t)|.$$

– Since  $W \times S^1$  is assumed compact (?), fix a finite covering  $\{B_i\}$  of  $W \times S^1$  such that

$$\bigcup_{i} B_{i}^{\circ} = W \times S^{1}.$$

Choose them in such a way we obtain charts

$$\Psi_i: B_i \longrightarrow \overline{B(0,1)} \subset \mathbb{R}^{2n+1}$$
 (?).

Obtain the computable form

$$||h||_{\cdot\cdot} = \sum_{k>0} \varepsilon_k \sup_{(x,t)\in W\times S^1} \sup_{i,z\in B(0,1)} |d^k(h\circ \Psi_i^{-1})(z)|.$$

# Define a Banach Space

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Review 8.3

Section 8.3: The Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F Define

$$C_{\varepsilon}^{\infty} = \left\{ h \in C^{\infty}(W \times S^{1}; \mathbb{R}) \mid \|h\|_{\varepsilon} < \infty \right\} \subset C^{\infty}(W \times S^{1}; \mathbb{R}),$$

which is a Banach space (normed and complete).

– Show that the sequence  $\{\varepsilon_k\}$  can be chosen so that  $C_{\varepsilon}^{\infty}$  is a dense subspace for the  $C^{\infty}$  topology, and in particular for the  $C^1$  topology.

#### **Theorem**

Such a sequence  $\{\varepsilon_k\}$  can be chosen.

#### Lemma

 $C^{\infty}(W \times S^1; \mathbb{R})$  with the  $C^1$  topology is separable as a topological space (contains a countable dense subset).

### Sketch Proof of Theorem

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#### Review 8.2

Section 8.3: The Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F

- By the lemma, produce a sequence  $\{f_n\} \subset C^{\infty}(W \times S^1; \mathbb{R})$  dense for the  $C^1$  topology.
- Using the norm on  $C^n(W \times S^1; \mathbb{R})$  for the  $f_n$ , define

$$\frac{1}{\varepsilon_n} = 2^n \max \left\{ \|f_k\| \ \middle| \ k \le n \right\} \implies \varepsilon_n \sup |d^n f_k(x,t)| \le 2^{-n}$$

which is summable.

Why does this imply density? I don't know.

### Modified Theorem

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Review 8

Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differentia of F The next proposition establishes a version of this theorem with compact support:

#### **Theorem**

For any  $(\mathbf{x}, t) \subset U \in W \times S^1$ ) there exists a  $V \subset U$  such that every  $h \in C^{\infty}(W \times S^1; \mathbb{R})$  can be approximated in the  $C^1$  topology by functions in  $C^{\infty}_{\epsilon}$  supported in U.

Then fix a time-dependent Hamiltonian  $H_0$  with nondegenerate periodic orbits and consider

$$\left\{h\in C_{\varepsilon}^{\infty}(H_0)\ \middle|\ h(x,t)=0 \text{ in some }U\supseteq \text{the 1-periodic orbits of }H_0\right\}$$

Then supp(h) is "far" from  $Per(H_0)$ , so

$$||h||_{\varepsilon} \ll 1 \implies \operatorname{Per}(H_0 + h) = \operatorname{Per}(H_0)$$

and are both nondegenerate.

Linearization and Transversality

Section 8.4: Linearizing the Floer Equation: The Differential

Section 8.4: Linearizing the Floer Equation: The Differential of F

### Goal

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Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F Choose  $m > n = \dim(W)$  and embed  $TW \hookrightarrow \mathbb{R}^m$  to identify tangent vectors (such as  $Z_i$ , tangents to W along u or in a neighborhood B of u) with actual vectors in  $\mathbb{R}^m$ .

Why? Bypasses differentiating vector fields and the Levi-Cevita connection.

We can then identify

im 
$$\mathcal{F} = C^{\infty}(\mathbb{R} \times S^1; \mathbb{R}^m)$$
 or  $L^p(\mathbb{R} \times S^1; W)$ ,

and we seek to compute its differential  $d\mathcal{F}$ .

We've just replaced the codomain here.

### **Definitions**

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Review 8.2

Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F

#### Recall that

- -x, y are contractible loops in W that are nondegenerate critical points of the action functional  $A_H$ ,
- $-u \in \mathcal{M}(x,y) \subset C^{\infty}_{loc}$  denotes a fixed solution to the Floer equation,
- $-C_{\searrow}(x,y)\subset \{u\in C^{\infty}(R\times S^1;W)\}$  is the set of smooth solutions  $u:\mathbb{R}\times S^1\longrightarrow W$  satisfying some conditions:

$$\lim_{s \to -\infty} u(s, t) = x(t), \quad \lim_{s \to \infty} u(s, t) = y(t)$$

and 
$$\left|\frac{\partial u}{\partial t}(s,t)\right|$$
,  $\left|\frac{\partial u}{\partial t}(s,t) - X_H(u)\right| \sim \exp(|s|)$ 

# Compactify to Sphere

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Review 8.2

Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F Fix a solution

$$u \in \mathcal{M}(x, y) \subset C^{\infty}_{loc}(\mathbb{R} \times S^1; W).$$

We lift each solution to a map

$$\tilde{u}:S^2\longrightarrow W$$

in the following way:

The loops x, y are contractible, so they bound discs. So we extend by pushing these discs out slightly:

# Lift to 2-Sphere

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Review 8.2

Section 8.3: Th Space of

Perturbations H

Section 8.4: Linearizing the Floer Equation: The Differential

$$u \in C^{\infty}(S^1 \times \mathbb{R}; W) \quad \mapsto \quad \tilde{u} \in C^{\infty}(S^2; W)$$



### Trivial the Pullback

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Review 8

Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F From earlier in the book, we have

#### Assumption (6.22):

For every  $w \in C^{\infty}(S^2, W)$  there exists a symplectic trivialization of the fiber bundle  $w^*TW$ , i.e.  $\langle c_1(TW), \pi_2(W) \rangle = 0$  where  $c_1$  denotes the first Chern class of the bundle TW.

Note: I don't know what this pairing is. The top Chern class is the Euler class (obstructs nowhere zero sections) and are defined inductively:

$$c_1(TW) = e(\Lambda^n(TW)) \in H^2(W; \mathbb{Z})$$

Assumption is satisfied when all maps  $S^2 \longrightarrow W$  lift to  $B^3 \iff \pi_2(W) = 0$ .

We have a pullback that is a symplectic fiber bundle:

$$\tilde{u}^* TW \xrightarrow{d\tilde{u}} TW 
\downarrow \qquad \downarrow \qquad \downarrow 
S^2 \xrightarrow{\tilde{u}} W$$

### Choose a Frame

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Review 8.

Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F – Using the assumption, trivialize the pullback  $\tilde{u}^*TW$  to obtain an orthonormal unitary frame

$$\{Z_i\}_{i=1}^{2n} \subset T_{u(s,t)}W$$

where

- The frame depends smoothly on  $(s, t) \in S^2$ ,
- $\lim_{s\to\infty} Z_i$  exists for each *i*.

$$\frac{\partial}{\partial s}$$
,  $\frac{\partial^2}{\partial s^2}$ ,  $\frac{\partial^2}{\partial s \ \partial t}$   $\sim Z_i \overset{s \longrightarrow \pm \infty}{\longrightarrow} 0$  for each  $i$ 

Claim: such trivializations exist, "using cylinders near the spherical caps in the figure".

### Define "Banach Manifold Charts"

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Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F Recall we had  $W^{1,p}(x,y)$  a completion of  $C^{\infty}$ 

$$\mathcal{M}(x,y) \subset C^{\infty}_{\searrow}(x,y) \subset \mathcal{P}^{1,p}(x,y) \underset{\mathsf{defn}}{\subset} \left\{ (s,t) \xrightarrow{\varphi} \exp_{w(s,t)} Y(s,t) \right\}.$$

where we restrict to

- $-Y\in W^{1,p}(w^*TW),$
- $w \in C^{\infty}_{\searrow}(x, y)$

Use the chosen frame  $\{Z_i\}$  to define a chart centered at u of  $\mathcal{P}^{1,p}(x,y)$  given by

$$\iota: W^{1,p}\left(\mathbb{R} \times S^1; \mathbb{R}^{2n}\right) \longrightarrow \mathcal{P}^{1,p}(x,y)$$
$$\mathbf{y} = (y_1, \dots, y_{2n}) \longmapsto \exp_u\left(\sum y_i Z_i\right).$$

- Note that the derivative at zero is  $\sum_{i=1}^{2n} y_i Z_i$ .

# Define the Floer Map in Charts

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Section 8.3: Th Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F Define and compute the differential of the composite map  $\tilde{\mathcal{F}}$  defined as follows:



– From now on, let  $\mathcal F$  denote  $\tilde{\mathcal F}$ .

# Add a Tangent

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Review 8.2

Section 8.3: Th Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F Take the vector

$$Y(s,t) := (y_1(s,t), \cdots) \in \mathbb{R}^{2n} \subset \mathbb{R}^m$$

- View Y as a vector in  $\mathbb{R}^m$  tangent to W, given by  $Y = \sum_{i=1}^{2n} y_i Z_i$ .
- Plug u+Y into the equation for  $\mathcal{F}$ , directly yielding

# Add a Tangent

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Review 8.2

Section 8.3: The Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F

$$\mathcal{F}(u) = \frac{\partial u}{\partial s} + J(u)\frac{\partial u}{\partial t} - J(u)X_t(u)$$

$$\mathcal{F}(u+Y) = \frac{\partial (u+Y)}{\partial s} + J(u+Y)\frac{\partial (u+Y)}{\partial t} - J(u+Y)X_t(u+Y)$$

### Extract Linear Part

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Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F Extract the part that is linear in Y and collect terms:

$$(d\mathcal{F})_{u}(Y)$$

$$= \frac{\partial Y}{\partial s} + (dJ)_{u}(Y)\frac{\partial u}{\partial t} + J(u)\frac{\partial Y}{\partial t} - (dJ)_{u}(Y)X_{t} - J(u)(dX_{t})_{u}(Y)$$

$$= \left(\frac{\partial Y}{\partial s} + J(u)\frac{\partial Y}{\partial t}\right)$$

$$+ \left((dJ)_{u}(Y)\frac{\partial u}{\partial t} - (dJ)_{u}(Y)X_{t} - J(u)(dX_{t})_{u}(Y)\right)$$

- This is a sum of two differential operators:
  - One of order 1, one of order 0 (Perspective 1)
  - The Cauchy-Riemann operator, and one of order zero (Perspective 2, not immediate from this form)

### Leibniz Rule

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Section 8.3: The Space of Perturbations of H

Section 8.4: Linearizing the Floer Equation: The Differential of F – Now compute in charts. Need a lemma:

#### Lemma (Leibniz Rule)

For any source space X and any maps

$$J: X \longrightarrow \operatorname{End}(\mathbb{R}^m)$$
$$Y : X \longrightarrow \mathbb{R}^m$$

we have

$$(dJ)(Y) \cdot v = d(Jv)(Y) - Jdv(Y).$$

### Sketch: Proof of Leibniz Rule

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Review 8.

Section 8.3: The Space of Perturbations of

Section 8.4: Linearizing the Floer Equation: The Differential of F Differentiate the map

$$J \cdot v : X \longrightarrow \mathbb{R}^m$$
$$x \mapsto J(x) \cdot v(x)$$

to obtain

$$J(x + Y)v(x + y)$$

$$= (J(x) + (dJ)_x(Y)) \cdot (v(x) + (dv)_x(Y)) + \cdots$$

$$= J(x) \cdot v(x) + J(x) \cdot (dv)_x(Y) + (dJ)_x(Y) \cdot v(x)$$

$$+ (dJ)_x(Y) \cdot (dv)_x(Y) + \cdots$$

$$\implies d(J \cdot v)_x(Y) = (dJ)_x(Y) \cdot v(x) + J(x) \cdot (dv)_x(Y).$$

Section 8.4: Linearizing the Floer Equation: The Differential of F Using the chart  $\iota$  defined by  $\{Z_i\}$  to write  $Y = \sum_{i=1}^{2n} y_i Z_i$  and thus

$$(d\mathcal{F})_u(Y) = O_0 + O_1$$

where  $O_0$  are order 0 terms ("they do not differentiate the  $y_i$ ") and the  $O_1$  are order 1 terms:

$$O_1 = \sum_{i=1}^{2n} \left( \frac{\partial y_i}{\partial s} Z_i + \frac{\partial y_i}{\partial t} J(u) Z_i \right)$$

$$O_0 = \sum_{i=1}^{2n} y_i \left( \frac{\partial Z_i}{\partial s} + J(u) \frac{\partial Z_i}{\partial t} + (dJ)_u(Z_i) \frac{\partial u}{\partial t} - J(u)(dX_t)_u Z_i - (dJ)_u(Z_i) X_t \right).$$