

# Problem Set 1

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## 1 Problem 3

### 1.1 Part 1

Let  $M, N$  be smooth manifolds and  $f : M \rightarrow N$  be a fixed smooth map, and define a map

$$\begin{aligned}\phi : C^\infty(N) \times T_p M &\rightarrow \mathbb{R} \\ (h, v) &\mapsto v(h \circ f)\end{aligned}$$

### 1.2 Part 1

Using the derivation definition, we can identify this assignment as a map

$$\begin{aligned}\phi : C^\infty(N) \times C^\infty(M)^\vee &\rightarrow \mathbb{R} \\ (h, g_v) &\mapsto g_v(h \circ f)\end{aligned}$$

We'd like to show that this yields a well-defined element of  $T_p M = C^\infty(M)^\vee$ .

## 2 Problem 4

### 2.1 Part 1

Let  $V = \mathbb{R}^n$  as a vector space, let  $g$  be a nonsingular matrix, and define a map

$$\begin{aligned}\phi : V &\rightarrow V^\vee \\ v &\mapsto (\phi_v : w \mapsto \langle v, gw \rangle)\end{aligned}$$

The claim is that  $\phi$  is a natural isomorphism. It is clearly linear (following from the linearity of the inner product and matrix multiplication), so it remains to check that it is a bijection.

To see that  $\ker \phi = 0$ , so that only the zero gets sent to the zero map, we can suppose that  $x \in \ker \phi$ . Then  $\phi_x : w \rightarrow \langle x, gw \rangle$  is the zero map. But the inner product is nondegenerate by definition, i.e.  $\langle x, y \rangle = 0 \ \forall y \implies x = 0$ . So  $x$  could only have been the zero vector to begin with.

But  $\dim V = \dim V^\vee$ , so any injective linear map will necessarily be surjective as well.

### 2.2 Part 2

Let  $g : TM \otimes TM \rightarrow \mathbb{R}$  be a metric, and consider the tangent space  $TM$ . By definition, the cotangent space  $T_p^*M = (T_p M)^\vee$

## 3 Problem 5

### 3.1 Part 1

Let  $A \in \text{Mat}(n, n)$  be a positive definite  $n \times n$  matrix, so

$$\langle v, Av \rangle > 0 \quad \forall v \in \mathbb{R}^n,$$

and  $B \in \text{Mat}(n, n)$  be positive semi-definite, so

$$\langle v, Bv \rangle \geq 0 \quad \forall v \in \mathbb{R}^n.$$

We'd like to show

$$\langle v, (A + B)v \rangle \geq 0 \quad \forall v \in \mathbb{R}^n,$$

which follows directly from

$$\begin{aligned}\langle v, (A + B)v \rangle &= \langle v, Av \rangle + \langle v, Bv \rangle \\ &> \langle v, Av \rangle + 0 \\ &\geq 0 + 0 \\ &= 0.\end{aligned}$$

### 3.2 Part 2

Let  $M$  be a smooth manifold with tangent bundle  $TM$  and a maximal smooth atlas  $\mathcal{A}$ . Choose a covering of  $M$  by charts  $\mathcal{C} = \{(U_i, \phi_i) \mid i \in I\} \subseteq \mathcal{A}$  such that  $M \subseteq \bigcup_{i \in I} U_i$ . Then choose a partition of unity  $\{f_i\}_{i \in I}$  subordinate to  $\mathcal{C}$ , so for each  $i$  we have

$$\begin{aligned} f_i &: M \rightarrow \mathbb{R} \\ \forall p \in M, \quad \sum_{i \in I} f_i(p) &= 1 \end{aligned}$$

In each copy of  $\phi_i(U_i) \cong \mathbb{R}^n$ , let  $g^i$  be the Euclidean metric given by the identity matrix, i.e.  $g_{jk}^i := \delta_{jk}$ . We then have

$$\begin{aligned} g^i &: T\phi_i(U_i) \otimes T\phi_i(U_i) \rightarrow \mathbb{R} \\ (\partial x_i, \partial x_j) &\mapsto \begin{cases} 1 & i = j \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

which is defined for pairs of vectors in  $T\phi_i(U_i) \cong T\mathbb{R}^n = \text{span}_{\mathbb{R}} \{\partial x_i\}_{i=1}^n$  on basis vectors as the Kronecker delta and extended linearly.

Note that each coordinate function  $\phi_i : U_i \rightarrow \mathbb{R}^n$  induces a map  $\tilde{\phi}_i : TU_i \rightarrow T\mathbb{R}^n$ .

Let  $G^i$  be the pullback of  $g^i$  along these induced maps  $\tilde{\phi}_i$ , so

$$\begin{aligned} G^i &: TU_i \otimes TU_i \rightarrow \mathbb{R} \\ G^i(x, y) &:= \left( (\tilde{\phi}_i)^* g^i \right)(x, y) := g^i(\tilde{\phi}_i(x), \tilde{\phi}_i(y)) \end{aligned}$$

Then, for a point  $p \in M$ , define the following map:

$$\begin{aligned} g_p &: T_p M \otimes T_p M \rightarrow \mathbb{R} \\ (x, y) &\mapsto \sum_{i \in I} f_i(p) G^i(x, y). \end{aligned}$$

The claim is that  $g_p$  defines a metric on  $M$ , and thus the family  $\{g_p \mid p \in M\}$  yields a tensor field and thus a Riemannian metric on  $M$ . If we define the map

$$\begin{aligned} g &: M \rightarrow (TM \otimes TM)^\vee \\ p &\mapsto g_p \end{aligned}$$

then  $g$  can be expressed as

$$g = \sum_{i \in I} f_i G^i.$$

We can check that this is positive definite by considering  $x \in T_p M$  and computing

$$\begin{aligned} g(x, x) &:= g_p(x, x) \\ &= \sum_{i \in I} f_i(p) G^i(x, x) \\ &= \sum_{i \in I} f_i(p) g^i(\tilde{\phi}_i(x), \tilde{\phi}_i(x)), \end{aligned}$$

where each term is positive semi-definite, and *at least one term* is positive definite because  $\sum_i f_i(p)$  must equal 1. By part 1, this means that the entire expression is positive definite, so  $g$  is a metric.  $\square$

## 4 Problem 6

### 4.1 Part 1

Let  $M = S^2$  as a smooth manifold, and consider a vector field on  $M$ ,

$$X : M \rightarrow TM$$

We want to show that there is a point  $p \in M$  such that  $X(p) = 0$ .

Every vector field on a compact manifold without boundary is complete, and since  $S^2$  is compact with  $\partial S^2 = \emptyset$ ,  $X$  is necessarily a complete vector field.

Thus every integral curve of  $X$  exists for all time, yielding a well-defined flow

$$\phi : M \times \mathbb{R} \rightarrow M$$

given by solving the initial value problems

$$\begin{aligned} \frac{\partial}{\partial s} \phi_s(p) \Big|_{s=t} &= X(\phi_t(p)), \\ \phi_0(p) &= p \end{aligned}$$

at every point  $p \in M$ .

This yields a one-parameter family

$$\phi_t : M \rightarrow M \in \text{Diff}(M, M).$$

In particular,  $\phi_0 = \text{id}_M$ , and  $\phi_1 \in \text{Diff}(M, M)$ . Moreover  $\phi_0$  is homotopic to  $\phi_1$  via the homotopy

$$\begin{aligned} H : M \times I &\rightarrow M \\ (p, t) &\mapsto \phi_t(p). \end{aligned}$$

We can now apply the Lefschetz fixed-point theorem to  $\phi_0$  and  $\phi_1$ . For an arbitrary map  $f : M \rightarrow M$ , we have

$$\Lambda(f) = \sum_k \text{Tr} \left( f_* \Big|_{H_k(X; \mathbb{Q})} \right).$$

where  $f_* : H_*(X; \mathbb{Q}) \rightarrow H_*(X; \mathbb{Q})$  is the induced map on homology, and

$$\Lambda(f) \neq 0 \iff f \text{ has at least one fixed point.}$$

In particular, we have

$$\begin{aligned}\Lambda(\text{id}_M) &= \sum_k \text{Tr}(\text{id}_{H_k(X; \mathbb{Q})}) \\ &= \sum_k \dim H_k(X; \mathbb{Q}) \\ &= \chi(M),\end{aligned}$$

the Euler characteristic of  $M$ .

Since homotopic maps induce equal maps on homology, we also have  $\Lambda(\phi_1) = \chi(M)$ .

Since

$$H_k(S^2) = \begin{cases} \mathbb{Z} & k = 0, 2 \\ 0 & \text{otherwise} \end{cases}$$

we have  $\chi(S^2) = 2 \neq 0$ , and thus  $\phi_1$  has a fixed point  $p_0$ , thus

$\left. \frac{\partial}{\partial t} \phi_t(p_0) \right|_{t=1}$  so

$$\begin{aligned}\phi_t(p) &= p \\ \implies \frac{\partial}{\partial t} \phi_t(p) &= \frac{\partial}{\partial t} p = 0 && \text{by differentiating wrt } t \\ \implies \left. \frac{\partial}{\partial t} \phi_t(p) \right|_{t=1} &= 0 \Big|_{t=0} = 0 && \text{by evaluating at } t = 0 \\ \implies X(\phi_1(p_0)) &:= \left. \frac{\partial}{\partial t} \phi_t(p) \right|_{t=1} = 0 && \text{by definition of } \phi_1\end{aligned}$$

so  $X(\phi_1(p_0)) = 0$ , which shows that  $p_0$  is a zero of  $X$ . So  $X$  has at least one zero, as desired.  $\square$

## 4.2 Part 2

The trivial bundle

$$\begin{array}{ccc} \mathbb{R}^2 & \longrightarrow & S^2 \times \mathbb{R}^2 \\ & & \downarrow \scriptstyle s \\ & & S^2 \end{array}$$

has a nowhere vanishing section, namely

$$\begin{aligned}s : S^2 &\rightarrow S^2 \times \mathbb{R}^2 \\ \mathbf{x} &\rightarrow (\mathbf{x}, [1, 1])\end{aligned}$$

which is the identity on the  $S^2$  component and assigns the constant vector  $[1, 1]$  to every point.

However, as part 1 shows, the bundle

$$\begin{array}{ccc}
 \mathbb{R}^2 & \longrightarrow & TS^2 \\
 & & \downarrow s \\
 & & S^2
 \end{array}$$

can *not* have a nowhere vanishing section.  $\square$