

# Title

D. Zack Garza

January 9, 2020

## Contents

1 Thursday January 9th

1

## 1 Thursday January 9th

**Recall:** For  $M^n$  a closed smooth manifold, consider a smooth map  $f : M^n \rightarrow \mathbb{R}$ .

**Definition:** A critical point  $p$  of  $f$  is *non-degenerate* iff  $\det(H := \frac{\partial^2 f}{\partial x_i \partial x_j}(p)) \neq 0$  in some coordinate system  $U$ .

**Lemma (The Morse Lemma):** For any non-degenerate critical point  $p$  there exists a coordinate system around  $p$  such that

$$f(x_1, \dots, x_n) = f(p) - x_1^2 - x_2^2 - \dots - x_\lambda^2 + x_{\lambda+1}^2 + \dots + x_n^2.$$

$\lambda$  is called the *index of  $f$  at  $p$* .

**Lemma:**  $\lambda$  is equal to the number of *negative* eigenvalues of  $H(p)$ .

*Proof:* A change of coordinates sends  $H(p) \rightarrow A^t H(p) A$ , which (exercise) has the same number of positive and negative values.

Exercise: show this assuming that  $A$  is invertible and not necessarily orthogonal.

This means that  $f$  can be written as the quadratic form

$$\begin{bmatrix} -2 & 0 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 & 0 \\ 0 & 0 & \ddots & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}.$$

*Proof of Morse Lemma:*

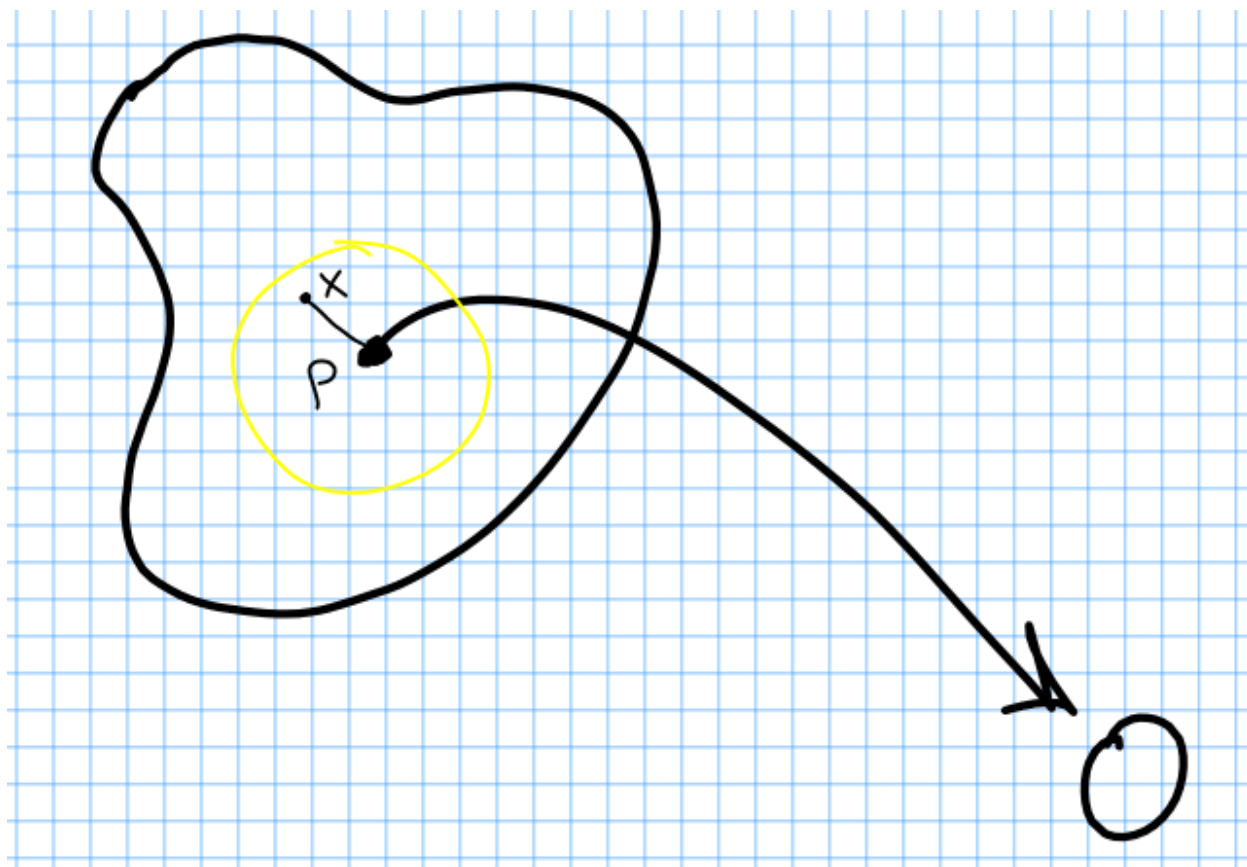
Suppose that we have a coordinate chart  $U$  around  $p$  such that  $p \mapsto 0 \in U$  and  $f(p) = 0$ .

**Step 1 – Claim:** There exists a coordinate system around  $p$  such that

$$f(x) = \sum_{i,j=1}^n x_i x_j h_{ij}(x),$$

where  $h_{ij}(x) = h_{ji}(x)$ .

*Proof:* Pick a convex neighborhood  $V$  of  $0 \in \mathbb{R}^n$ .



Restrict  $f$  to a path between  $x$  and  $0$ , and by the FTC compute

$$I = \int_0^1 \frac{df(tx_1, tx_2, \dots, tx_n)}{dt} dt = f(x_1, \dots, x_n) - f(0) = f(x_1, \dots, x_n).$$

since  $f(0) = 0$ .

We can compute this in a second way,

$$I = \int_0^1 \frac{\partial f}{\partial x_1} x_1 + \frac{\partial f}{\partial x_2} x_2 + \dots + \frac{\partial f}{\partial x_n} x_n dt \implies \sum_{i=1}^n x_i \int_0^1 \frac{\partial f}{\partial x_i} dt = f(x).$$