

Floer Talk

D. Zack Garza

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1 Background and Notation

From the text:

- $(W, \omega \in \Omega_2(W))$ is a (compact?) symplectic manifold
- $C^\infty(A, B)$ is the space of smooth maps with the C^∞ topology (idea: uniform convergence of a function and all derivatives on compact subsets)
- $C_{\text{Loc}}^\infty(A, B)$ is the space with the C^∞ uniform convergence topology on compact subsets of A
- $H \in C^\infty(W; \mathbb{R})$ a Hamiltonian with X_H its vector field.
- $H \in C^\infty(W \times \mathbb{R}; \mathbb{R})$ given by $H_t \in C^\infty(W; \mathbb{R})$ is a time-dependent Hamiltonian.
- The action functional is given by

$$\begin{aligned}\mathcal{A}_H : \mathcal{L}W &\longrightarrow \mathbb{R} \\ x &\mapsto - \int_{\mathbb{D}} u^* \omega + \int_0^1 H_t(x(t)) \, dt\end{aligned}$$

where $\mathcal{L}W$ is the contractible loop space of W , $u : \mathbb{D} \longrightarrow W$ is an extension of $x : S^1 \longrightarrow W$ to the disc with $u(\exp(2\pi it)) = x(t)$.

$$- \text{ Example: } W = \mathbb{R}^{2n} \implies \mathcal{A}_H(x) = \int_0^1 (H_t \, dt - p \, dq).$$

- Critical points of the action functional \mathcal{A}_H are given by orbits, i.e. contractible loops $x, y \in \mathcal{L}W$
- In general, x, y are two periodic orbits of H of period 1.

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- The Floer equation is given by

$$\frac{\partial u}{\partial s} + J(u) \frac{\partial u}{\partial t} + \text{grad } H_t(u) = 0.$$

This is a first-order perturbation of the Cauchy-Riemann equations, for which solutions would be J -holomorphic curves.

- Solutions are functions $u \in C^\infty(\mathbb{R} \times S^1; W) = C^\infty(\mathbb{R}; \mathcal{L}W)$
 - They correspond to “embedded cylinders” with sides u and contractible caps x, y regarded as loops in W .
 - They also correspond to paths in $\mathcal{L}W$ from $x \rightarrow y$ (precisely: trajectories of the vector field $-\text{grad} \mathcal{A}_H$)
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Fig. 6.5

Here $u(s) \in \mathcal{L}W$ is a loop with value at time t given by $u(s, t)$, and $\lim_{s \rightarrow -\infty} u_s(t) = x$, $\lim_{s \rightarrow \infty} u_s(t) = y$.

- The energy of a solution is $E(u) = \int_{\mathbb{R} \times S^1} |\partial_s u|^2 ds dt$.
- $\mathcal{M} = \{u \in C^\infty(\mathbb{R}; \mathcal{L}W) \mid E(u) < \infty\}$ (contractible solutions of finite energy), which is compact.
- $\mathcal{M}(x, y)$ is the space of solutions of the Floer equation connecting orbits x and y .
- $C_{\searrow}(x, y)$:

$$C_{\searrow}(x, y) := \{u \in C^\infty(\mathbb{R} \times S^1; W) \mid \lim_{s \rightarrow -\infty} u(s, t) = x(t), \lim_{s \rightarrow \infty} u(s, t) = y(t), \\ \left| \frac{\partial u}{\partial s}(s, t) \right| \leq K e^{-\delta|s|}, \quad \left| \frac{\partial u}{\partial t}(s, t) - X_H(u) \right| \leq K e^{-\delta|s|}\}$$

where $K, \delta > 0$ are constants depending on u . So

$$|\partial_s u(s, t)|, |\partial_t u(s, t) - X_H(u)| \sim e^{|s|}.$$

From the Appendices

- Relatively compact: has compact closure.
- Compact operator: the image of bounded sets are relatively compact.
- Index of an operator: $\dim \ker - \dim \text{coker}$.
- Fredholm operators: those for which the index makes sense, i.e. $\dim \ker < \infty, \dim \text{coker} < \infty$.
- Elliptic operators: generalize the Laplacian Δ , coefficients of highest order derivatives are positive, principal symbol is invertible (???)
- Locally integrable: integrable on every compact subset

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- Sobolev spaces: in dimension 1, define $\|u(t)\|_{s,p} = \sum_{i=0}^s \left\| \partial_t^i u(t) \right\|_{L^p}$ on $C^\infty(\bar{U})$, then take the completion and denote $W^{s,p}(\bar{U})$. Yields a distribution space, elements are functions with weak derivatives.
 - Distribution: $C_c^\infty(U)^\vee$, the dual of the space of smooth compactly supported functions on an open set $U \subset \mathbb{R}^n$.

2 Talk

Overview: Analyze the space $\mathcal{M}(x, y)$ of solutions to the Floer equation connecting two orbits x, y of H . Show $\mathcal{M}(x, y)$ is in fact a manifold of dimension $\mu(x) - \mu(y)$.

Strategy:

1. Describe $\mathcal{M}(x, y)$ as the zero set of a section of a vector bundle over the Banach manifold $\mathcal{P}(x, y)$.
2. Apply the Sard-Smale theorem: perturb H to make $\mathcal{M}(x, y)$ the inverse image of a regular value of some map.
3. Show that the tangent maps (?) are Fredholm operators of index $\mu(x) - \mu(y) = \dim \mathcal{M}(x, y)$.

Goals:

- 8.3: Overview and big picture
- 8.4: Formula for linearization of \mathcal{F} .

2.1 Review 8.2

What is \mathcal{F} ?

We started with the unadorned Floer map:

$$\begin{aligned} \mathcal{F} : \mathcal{C}^\infty(\mathbf{R} \times S^1; W) &\longrightarrow \mathcal{C}^\infty(\mathbf{R} \times S^1; TW) \\ u &\mapsto \frac{\partial u}{\partial s} + J \frac{\partial u}{\partial t} + \text{grad}_u(H_t) \end{aligned}$$

and promoted this to a map of Banach spaces

$$\begin{aligned} \mathcal{F} : \mathcal{P}^{1,p}(x, y) &\longrightarrow \mathcal{L}^p(x, y) \\ \mathcal{F}(u) &= \frac{\partial u}{\partial s} + J(u) \frac{\partial u}{\partial t} + \text{grad } H_t(u). \end{aligned}$$

What is the LHS? It is the space of maps

$$\begin{aligned} \mathcal{P}^{1,p}(x, y) &: ? \longrightarrow ? \\ (s, t) &\mapsto \exp_{w(s,t)} Y(s, t). \end{aligned}$$

where $Y \in W^{1,p}(w^*TW)$ and $w \in C_\infty^\infty(x, y)$.

2.2 8.3: The Space of Perturbations of H

Goal: given a fixed Hamiltonian $H \in C^\infty(W \times S^1; \mathbb{R})$, perturb it (without modifying the periodic orbits) so that $\mathcal{M}(x, y)$ are manifolds of the expected dimension.

Start by trying to construct a subspace $C_\varepsilon^\infty(H) \subset C^\infty(W \times S^1; \mathbb{R})$, the space of perturbations of H , and show it is dense.

Idea: define a norm $\|\cdot\|_\varepsilon$ on $C_\varepsilon^\infty(H)$ and take the subspace of finite-norm elements.

- Let $h(\mathbf{x}, t) \in C_\varepsilon^\infty(H)$ denote a perturbation of H .
- Fix $\varepsilon = \{\varepsilon_k \mid k \in \mathbb{Z}^{\geq 0}\} \subset \mathbb{R}^{>0}$ a sequence of real numbers, which we will choose carefully later.
- For a fixed $\mathbf{x} \in W, t \in \mathbb{R}$ and $k \in \mathbb{Z}^{\geq 0}$, define

$$\left| d^k h(\mathbf{x}, t) \right| = \max \left\{ d^\alpha h(\mathbf{x}, t) \mid |\alpha| = k \right\},$$

the maximum over all sets of multi-indices α of length k .

Note: I interpret this as

$$d^{\alpha_1, \alpha_2, \dots, \alpha_k} h = \frac{\partial^k h}{\partial x_{\alpha_1} \partial x_{\alpha_2} \cdots \partial x_{\alpha_k}},$$

the partial derivatives wrt the corresponding variables.

- Define a norm on C_ε^∞ :

$$\|h\|_\varepsilon = \sum_{k \geq 0} \varepsilon_k \sup_{(x, t) \in W \times S^1} \left| d^k h(x, t) \right|.$$

- Fix a covering $\{B_i\}$ of $W \times S^1$ such that $\bigcup_i B_i^\circ = W \times S^1$

Then

$$\|h\|_\varepsilon = \sum_{k \geq 0} \varepsilon_k \sup_{(x, t) \in W \times S^1} \sup_{i, z \in B(0, 1)} \left| d^k (h \circ \Psi_i^{-1})(z) \right|.$$

Where $\{\varepsilon_k\} \subset \mathbb{R}$ is chosen such that $C_\varepsilon^\infty \hookrightarrow C^\infty(W \times S^1)$ is dense for the C^∞ topology, and the $\Psi_i : B_i \rightarrow \overline{B(0, 1)}$ is a fixed finite sequence of diffeomorphisms where $\bigcup_i B_i^\circ = W \times S^1$.

Note that we'll only use density for the C^1 topology in our case.

Proposition 2.1.

Such a sequence $\{\varepsilon_k\}$ can be chosen.

Proof.

Show that $C^\infty(W \times S^1)$ is separable, yielding a sequence $(f_n) \subset C^\infty(W \times S^1)$ that is dense in

the C^1 topology, then

$$\varepsilon_n = \frac{1}{2^n \max_{k \leq n} \|f_k\|_{C^n(W \times S^1)}}$$

where the diffeomorphisms Ψ_i are used to compute these norms. ■

Go on to show that for $\|h\|_\varepsilon \ll 1$, the $\text{Per}(H_0 + h) = \text{Per}(H_0)$ and are nondegenerate.

2.3 8.4: Linearizing the Floer equation: The Differential of \mathcal{F}

Embed $TW \hookrightarrow \mathbb{R}^m \times \mathbb{R}^m$ to identify tangent vectors (such as Z_i , tangents to W along u or in a neighborhood B of u) with actual vectors in \mathbb{R}^m .

Why? Bypasses differentiating vector fields and the Levi-Cevita connection.

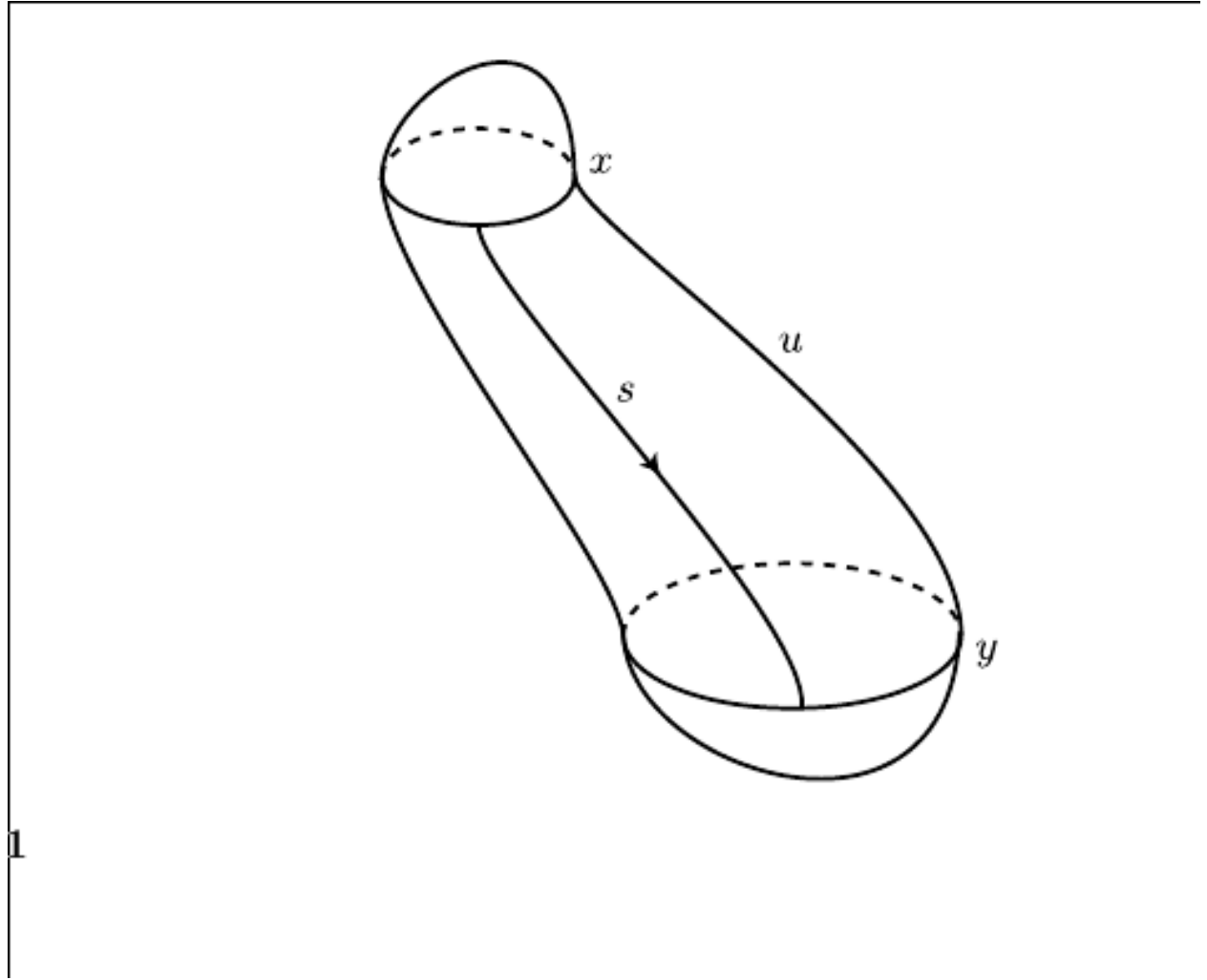
We can then identify $\text{im } \mathcal{F} = C^\infty(\mathbb{R} \times S^1; \mathbb{R}^m)$ or $L^p(\mathbb{R} \times S^1; W)$, and we seek to compute its differential $d\mathcal{F}$.

We've just replaced the target spaces here.

Recall that x, y are contractible loops in W that are nondegenerate critical points of the action functional \mathcal{A}_H (i.e. solutions to the Floer equation), and $C_{\searrow}(x, y)$ was the set of maps $u : \mathbb{R} \times S^1 \rightarrow W$ satisfying some conditions.

Fix a solution $u \in \mathcal{M}(x, y) \subset C_{\text{Loc}}^\infty(\mathbb{R} \times S^1; W)$.

We lift each map to $\tilde{u} : S^2 \rightarrow W$ in the following way: the loops x, y are contractible, so they bound discs. So we extend according to:



Recall assumption 6.22: every smooth map $w : S^2 \rightarrow W$ yields a symplectic trivialization of w^*TW (e.g. when $\pi_2(W) = 0$, so every map from S^2 extends to B^3).

Trivialize the symplectic fiber bundle \tilde{u}^*TW to obtain an orthonormal unitary frame $\{Z_i\}_{i=1}^{2n} \subset T_{u(s,t)}W$ depending smoothly on $(s, t) \in S^2$, where $\lim_{s \rightarrow \pm\infty} Z_i$ exists for each i . We also require that $\partial_s Z_i, \partial_s^2 Z_i, \partial_s \partial_t Z_i \xrightarrow{s \rightarrow \pm\infty} 0$ for each i .

This frame defines a chart about u of $\mathcal{P}^{1,p}(x, y)$ given by

$$\begin{aligned} \iota : W^{1,p}(\mathbb{R} \times S^1; \mathbb{R}^{2n}) &\rightarrow \mathcal{P}^{1,p}(x, y) \\ \mathbf{y} = (y_1, \dots, y_{2n}) &\mapsto \exp_u \left(\sum y_i Z_i \right). \end{aligned}$$

Since $(d\exp)_0 = \text{id}$, we have $(d\iota)_0(\mathbf{y}) = \sum_i y_i Z_i$.

We'll now consider and compute the differential of

$$\begin{aligned} \mathcal{F} : \mathcal{P}^{1,p}(x, y) &\xrightarrow{\mathcal{F}} L^p(\mathbb{R} \times S^1; TW) \rightarrow L^p(\mathbb{R} \times S^1; \mathbb{R}^m) \\ u &\mapsto \frac{\partial u}{\partial s} + J(u) \left(\frac{\partial u}{\partial t} - X_t(u) \right). \end{aligned}$$

Take the vector $Y(s, t) := (y_1(s, t), \dots) \in \mathbb{R}^{2n} \subset \mathbb{R}^m$, where we view Y as a vector in \mathbb{R}^m tangent to W , given by $Y = \sum y_i Z_i$.

We write

$$\mathcal{F}(u + Y) = \frac{\partial(u + Y)}{\partial s} + J(u + Y) \frac{\partial(u + Y)}{\partial t} - J(u + Y) X_t(u + Y)$$

and extract the part that is linear in Y :

$$(d\mathcal{F})_u(Y) = \frac{\partial Y}{\partial s} + (dJ)_u(Y) \frac{\partial u}{\partial t} + J(u) \frac{\partial Y}{\partial t} - (dJ)_u(Y) X_t - J(u) (dX_t)_u(Y).$$

Lemma 2.2 (Acting by Derivation).

For any $J \rightarrow \text{End}(\mathbb{R}^m)$ and $Y, v : ? \rightarrow \mathbb{R}^m$ we have

$$(dj)(Y) \cdot v = d(Jv)(Y) - Jdv(Y).$$

There is a proof.

For every such smooth map $u : \mathbb{R} \times S^1 \rightarrow W$, $(d\mathcal{F})_u(Y) = O_1 + O_0$ where O_i are differential operators of order i , and in fact O_1 can be chosen to be a Cauchy-Riemann operator. In this specific chart, we can in fact decompose $(d\mathcal{F})_u(Y) = \bar{\partial}Y + SY$ where $S : \mathbb{R} \times S^1 \rightarrow \text{End}(\mathbb{R}^n)$ is linear of order 0, and in fact we have

Proposition 2.3.

If u solves Floer's equation, then $(d\mathcal{F})_u = \bar{\partial} + S(s, t)$ where S is linear, tends to a symmetric operator as $s \rightarrow \pm\infty$, and $\lim \partial_t S = 0$ uniformly in t .

There is a very long computational proof.

Denote the order 0 part of $(d\mathcal{F})_u$ as $Y \mapsto S \cdot Y$ so $S : \mathbb{R} \times S^1 \rightarrow \text{End}(\mathbb{R}^m)$ and define $S^\pm := \lim_{s \rightarrow \pm\infty} S(s, \cdot)$.

Proposition 2.4.

The equation $\partial_t Y = J_0 S^\pm Y$ linearizes Hamilton's equation $\dot{z} = X_t(z)$ at $x = \lim_{s \rightarrow \pm\infty} u$ for S^+ and S^- respectively.

Proof: uses previous proposition.

Given a solution u , the product

$$\begin{aligned} u \cdot s : ? &\rightarrow ? \\ (\sigma, t) &\mapsto u(\sigma + s, t) \end{aligned}$$

is also a solution and $\mathcal{F}(u \cdot s) = 0$ for all s .

Punchline:

Thus $\frac{\partial u}{\partial s}$ is a solution of the linearized equation, since

$$0 = \frac{\partial}{\partial s} \mathcal{F}(u \cdot s) = (d\mathcal{F})_u \left(\frac{\partial u}{\partial s} \right).$$

Along any nonconstant solution connecting x and y , $\dim \ker(d\mathcal{F})_u \geq 1$.