Title

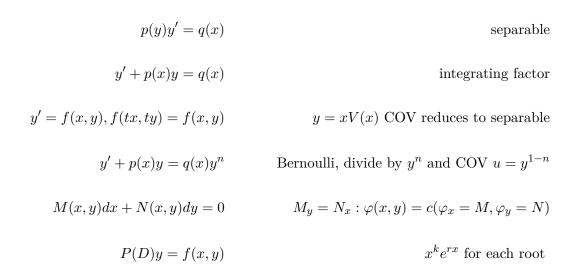
D. Zack Garza

Contents

l	Ordi	inary Differential Equations	2
	1.1	Techniques Overview	2
	1.2	Types of Equations	3
	1.3	Linear Homogeneous	3
	1.4	Linear Inhomogeneous	4
		1.4.1 Undetermined Coefficients	4
		1.4.2 Variation of Parameters	5
		1.4.3 Reduction of Order	5
	1.5	Systems of Differential Equations	5
	1.6	Laplace Transforms	5

1 Ordinary Differential Equations

1.1 Techniques Overview



Where e^{zx} yields $e^{ax} \cos bx$, $e^{ax} \sin bx$

1.2 Types of Equations

Contents 2

• Separable equations:

$$p(y)\frac{dy}{dx} - q(x) = 0 \implies \int p(y)dy = \int q(x)dx + C$$

$$\frac{dy}{dx} = f(x)g(y) \implies \int \frac{1}{g(y)}dy = \int f(x)dx + C$$

- Population growth:

$$\frac{dP}{dt} = kP \implies P = P_0 e^{kt}$$

- Logistic growth:
 - \diamondsuit General form: $\frac{dP}{dt} = (B(t) D(t))P(t)$
 - \diamondsuit Assume birth rate is constant $B(t) = B_0$ and death rate is proportional to instantaneous population $D(t) = D_0 P(t)$. Then let $r = B_0, C = B_0/D_0$ be the carrying capacity:

$$\frac{dP}{dt} = r\left(1 - \frac{P}{C}\right)P \implies P(t) = \frac{P_0}{\frac{P_0}{C} + e^{-rt}(1 - \frac{P_0}{C})}$$

• First order linear:

$$\frac{dy}{dx} + p(x)y = q(x) \implies I(x) = e^{\int p(x)dx}, \qquad y(x) = \frac{1}{I(x)} \left(\int q(x)I(x)dx + C \right)$$

- Exact:
 - $M(x,y)dx + N(x,y)dy = 0 \text{ is exact } \iff \exists \varphi : \frac{\partial \varphi}{\partial x} = M(x,y), \ \frac{\partial \varphi}{\partial y} = N(x,y)$ $\iff \frac{\partial M}{\partial y} = \frac{\partial N}{x}$
 - General solution:

$$\varphi(x,y) = \int_{-\infty}^{x} M(s,y)ds + \int_{-\infty}^{y} N(x,t)dt - \int_{-\infty}^{y} \frac{\partial}{\partial t} \left(\int_{-\infty}^{x} M(s,t)ds \right) dt$$

(where $\int_{-\infty}^{x} f(t)dt$ means take the antiderivative of f and consider it a function of x)

- Cauchy Euler: #todo
- Bernoulli: todo

1.3 Linear Homogeneous

General form:

$$y^{(n)} + c_{n-1}y^{(n-1)} + \dots + c_2y'' + cy' + cy = 0$$
$$p(D)y = \prod (D - r_i)^{m_i}y = 0$$

where p is a polynomial in the differential operator D with roots r_i :

• Real roots: contribute m_i solutions of the form

$$e^{rx}, xe^{rx}, \cdots, x^{m_i-1}e^{rx}$$

• Complex conjugate roots: for r = a + bi, contribute $2m_i$ solutions of the form

$$e^{(a\pm bi)x}, xe^{(a\pm bi)x}, \cdots, x^{m_i-1}e^{(a\pm bi)x}$$

= $e^{ax}\cos(bx), e^{ax}\sin(bx), xe^{ax}\cos(bx), xe^{ax}\sin(bx), \cdots,$

Example: by cases, second order equation of the form

$$ay'' + by' + cy = 0$$

- Two distinct roots: $c_1e^{r_1x} + c_2e^{r_2x}$ - One real root: $c_1e^{rx} + c_2xe^{rx}$ - Complex conjugates $\alpha \pm i\beta$: $e^{\alpha x}(c_1\cos\beta x + c_2\sin\beta x)$

1.4 Linear Inhomogeneous

General form:

$$y^{(n)} + c_{n-1}y^{(n-1)} + \dots + c_2y'' + cy' + cy = F(x)$$
$$p(D)y = \prod (D - r_i)^{m_i} y = 0$$

Then solutions are of the form $y_c + y_p$, where y_c is the solution to the associated homogeneous system and y_p is a particular solution.

Methods of obtaining particular solutions

1.4.1 Undetermined Coefficients

- Find an operator p(D) the annihilates F(x) (so q(D)F = 0)
- Find solution of q(D)p(D) = 0, subtract of known solutions from homogeneous part to obtain the form of the trial solution $A_0 f(x)$, where A_0 is the undetermined coefficient
- Substitute trial solution into original equation to determine A_0

Useful Annihilators:

$$\begin{split} F(x) &= p(x): & D^{\deg(p)+1} \\ F(x) &= p(x)e^{ax}: & (D-a)^{\deg(p)+1} \\ F(x) &= \cos(ax) + \sin(ax): & D^2 + a^2 \\ F(x) &= e^{ax}(a_0\cos(bx) + b_0\sin(bx)): & (D-z)(D-\overline{z}) = D^2 - 2aD + a^2 + b^2 \\ F(x) &= p(x)e^{ax}\cos(bx) + p(x)e^{ax}\cos(bx): & ((D-z)(D-\overline{z}))^{\max(\deg(p),\deg(q))+1} \end{split}$$

1.4.2 Variation of Parameters

todo

1.4.3 Reduction of Order

todo

1.5 Systems of Differential Equations

General form:

$$\frac{\partial \mathbf{x}(t)}{\partial t} = A\mathbf{x}(t) + \mathbf{b}(t) \iff \mathbf{x}'(t) = A\mathbf{x}(t) + \mathbf{b}(t)$$

General solution to homogeneous equation:

$$c_1\mathbf{x_1}(t) + c_2\mathbf{x_2}(t) + \dots + c_n\mathbf{x_n}(t) = \mathbf{X}(t)\mathbf{c}$$

If A is a matrix of constants: $\mathbf{x}(t) = e^{\lambda_i t} \mathbf{v}_i$ is a solution for each eigenvalue/eigenvector pair $(\lambda_i, \mathbf{v}_i)$ - If A is defective, you'll need generalized eigenvectors.

Inhomogeneous Equation: particular solutions given by

$$\mathbf{x}_p(t) = \mathbf{X}(t) \int_0^t \mathbf{X}^{-1}(s) \mathbf{b}(s) \ ds$$

1.6 Laplace Transforms

Definitions:

$$\begin{split} H_a(t) &:= \left\{ \begin{array}{l} 0, & 0 \leq t < a \\ 1, & t \geq a \end{array} \right. \\ \delta(t) &: \int_{\mathbb{R}} \delta(t-a) f(t) \ dt = f(a), \quad \int_{\mathbb{R}} \delta(t-a) \ dt = 1 \\ & (f * g)(t) = \int_0^t f(t-s) g(s) \ ds \\ & L[f(t)] = L[f] = \int_0^\infty e^{-st} f(t) dt = F(s). \end{split}$$

Useful property: for $a \leq b$, $H_a(t) - H_b(t) = \mathbb{1}[[a, b]]$.

$$t^{n}, n \in \mathbb{N} \iff n! \frac{1}{s^{n+1}}, s > 0$$

$$t^{-\frac{1}{2}} \iff \sqrt{\pi}s^{-\frac{1}{2}} s > 0$$

$$e^{at} \iff \frac{1}{s-a}, s > a$$

$$\cos(bt) \iff \frac{s}{s^{2}+b^{2}}, s > 0$$

$$\sin(bt) \iff \frac{b}{s^{2}+b^{2}}, s > 0$$

$$\delta(t-a) \iff e^{-as}$$

$$H_{a}(t) \iff s^{-1}e^{-as}$$

$$e^{at}f(t) \iff f(s-a)$$

$$H_{a}(t)f(t-a) \iff e^{-as}F(s)$$

$$f'(t) \iff sL(f)-f(0)$$

$$f''(t) \iff s^{2}L(f)-sf(0)-f'(0)$$

$$f^{(n)}(t) \iff s^{n}L(f)-\sum_{i=0}^{n-1}s^{n-1-i}f^{(i)}(0)$$

$$f(t)g(t) \iff F(s)*G(s)$$

• For f periodic with period T, $L(f) = \frac{1}{1 + e^{-sT}} \int_0^T e^{-st} f(t) dt$

$$p(y)y'=q(x)$$
 separable $y'+p(x)y=q(x)$ integrating factor $y'=f(x,y), f(tx,ty)=f(x,y)$ $y=xV(x)$ COV reduces to separable $y'+p(x)y=q(x)y^n$ Bernoulli, divide by y^n and COV $u=y^{1-n}$ $M(x,y)dx+N(x,y)dy=0$ $M_y=N_x: \varphi(x,y)=c(\varphi_x=M,\varphi_y=N)$ $P(D)y=f(x,y)$

1.6 Laplace Transforms