

Section 8.6: The Solutions of the Floer Equation are “Somewhere Injective”.

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Contents

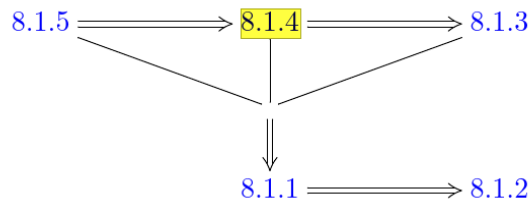
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0.1 Outline

Two Goals:

1. Prove critical points are discrete and regular points are open/dense.
2. Prove the continuation principle that was used in Proposition 8.1.4
3. Idea: A holomorphic function with all derivatives vanishing on a line is identically zero on \mathbb{C}

0.2 Outline of Statements



- 8.1.5: $(d\mathcal{F})_u$ is a Fredholm operator of index $\mu(x) - \mu(y)$.
- 8.1.4: $\Gamma : W^{1,p} \times C_\varepsilon^\infty \longrightarrow L^p$ has a continuous right-inverse and is surjective
- 8.1.3: $\mathcal{Z}(x, y, J)$ is a Banach manifold
- 8.1.1: For $h \in \mathcal{H}_{\text{reg}}$, $H_0 + h$ is nondegenerate and $(d\mathcal{F})_u$ is surjective for every $u \in \mathcal{M}(H_0 + h, J)$.

- 8.1.2: For $h \in \mathcal{H}_{\text{reg}}$ and all contractible orbits x, y of H_0 , $\mathcal{M}(x, y, H_0 + h)$ is a manifold of dimension $\mu(x) - \mu(y)$.

0.3 Notation

- The Floer equation and its linearization:

$$\begin{aligned}\mathcal{F}(u) &= \frac{\partial u}{\partial s} + J \frac{\partial u}{\partial t} + \text{grad}_u(H) = 0 \\ (d\mathcal{F})_u(Y) &= \frac{\partial Y}{\partial s} + J_0 \frac{\partial Y}{\partial t} + S \cdot Y \\ Y &\in u^*TW, \quad S \in C^\infty(\mathbb{R} \times S^1; \text{End}(\mathbb{R}^{2n})).\end{aligned}$$

- $z = s + it$
- X is a vector field (time-dependent and periodic) on \mathbb{R}^{2n} , J an almost complex structure
– X, J are smooth
- $u \in C^\infty(\mathbb{R} \times S^1; W)$ is a solution to the equation

$$\frac{\partial u}{\partial s} + J(t, u) \left(\frac{\partial u}{\partial t} - X(t, u) \right) = 0$$

- $C(u)$ the set of critical points and $R(u)$ the set of regular points of u :

$$\begin{aligned}(s_0, t_0) \in C(u) \subseteq \mathbb{R} \times S^1 &\iff \frac{\partial u}{\partial s}(s_0, t_0) = 0 \\ (s_0, t_0) \in R(u) \subset \mathbb{R} \times S^1 &\iff (s_0, t_0) \notin C(u) \ \& \ s \neq s_0 \implies u(s_0, t_0) \neq u(s, t_0).\end{aligned}$$

0.4 Goal 1: Discrete Critical Points and Dense Regular Points

Goal 1: prove the following theorem

Theorem 0.1(8.5.4).

1. $C(u)$ is discrete and
2. $R(u) \hookrightarrow \mathbb{R} \times S^1$ is open and dense.

Outline of the proof:

- Prove 8.6.1 (direct, short) which transforms the equation

$$\frac{\partial u}{\partial s} + J(t, u) \left(\frac{\partial u}{\partial t} - X(t, u) \right) = 0 \quad \text{where } u \in C^\infty(\mathbb{R} \times S^1; W)$$

to a Cauchy-Riemann equation on \mathbb{R}^2 :

$$\frac{\partial v}{\partial s} + J \frac{\partial v}{\partial t} = 0 \quad \text{where } v \in C^\infty(\mathbb{R}^2; W)$$

- Produces a map v which reduces Theorem 8.5.4 to two statements
 - 8.6.2: $C(v)$ (and thus $C(u)$) is discrete
 - * Proved later using similarity principle.

- 8.6.3 (Injectivity): If v is a smooth periodic solution of CR with $\frac{\partial v}{\partial s} \neq 0$ then $R(v) \hookrightarrow \mathbb{R}^2$ is open and dense.
- Prove 8.6.3 (Injectivity)
 - Show open.
 - Show dense
- Prove 8.6.8 (similarity principle)
- Use similarity principle to prove 8.6.1, yields theorem.

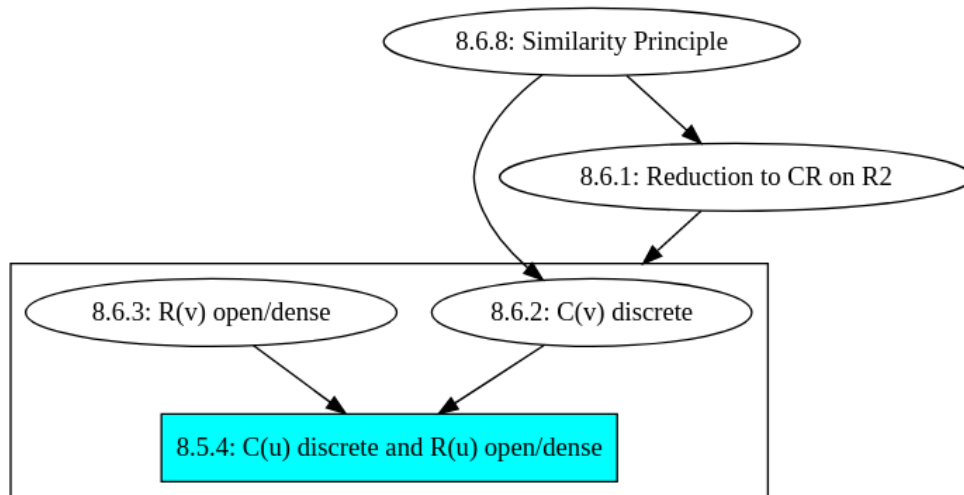
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open/dense" "8.6.3: R(v) open/dense ('Injectivity')" -> "8.5.4: C(u) discrete and R(u) open/dense"
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"8.1.2: Trajectories x->y Form a Manifold of the Right Dimension" [shape=box] "8.1.3: Z(x,y,J)
is a Banach Manifold" [shape=box] "8.1.4: Gamma is Surjective" [shape=box] "8.1.5: dF is
Fredholm" [shape=box] "8.5.4: Sard-Smale" -> "8.1.1: Nondegenerate Perturbations and Surjective
Differential"
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"8.1.1: Nondegenerate Perturbations and Surjective Differential" -> "8.1.2: Trajectories x->y Form a
Manifold of the Right Dimension" "8.1.3: Z(x,y,J) is a Banach Manifold" -> "8.1.1: Nondegenerate
Perturbations and Surjective Differential" "8.1.4: Gamma is Surjective" [shape=box] "8.1.4: Gamma
is Surjective" -> "8.1.3: Z(x,y,J) is a Banach Manifold" "8.1.5: dF is Fredholm" -> "8.1.4: Gamma
is Surjective" "8.6.5: Unique v Solutions in a Small Ball" -> "8.6.4: Failure of Injectivity" "8.6.4:
Failure of Injectivity" -> "8.6.3: R(v) open/dense ('Injectivity')"
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Reduction to CR on R2" -> "8.6.2: C(v) discrete" [lhead=cluster_1] "8.6.6: Continuation Principle"
-> "8.6.5: Unique v Solutions in a Small Ball" "8.6.6: Continuation Principle" -> "8.1.4: Gamma is
Surjective" "8.5.4: C(u) discrete and R(u) open/dense" -> "8.1.1: Nondegenerate Perturbations
and Surjective Differential" }
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0.5 8.6.1: Transform to Cauchy-Riemann

Proposition 0.2(8.6.1, Transform to CR-equation on R^2).

If u is a solution to the following equation:

$$\frac{\partial u}{\partial s} + J(t, u) \left(\frac{\partial u}{\partial t} - X(t, u) \right) = 0.$$

Then there exists

- An almost complex structure J_1
- A diffeomorphism φ on W ?
- A map $v \in C^\infty(\mathbb{R}^2; W)$

satisfying

$$\frac{\partial v}{\partial s} + J_1(v) \frac{\partial v}{\partial t} = 0$$

where

1. $v(s, t + 1) = \varphi(v(s, t))$
2. $C(u) = C(v)$, i.e. u, v have the same critical points
3. $R(u) = R(v)$.

Proof

- Since $W \times S^1$ is compact, the flow ψ_t of X_t is defined on all of W
 - We thus have a map $\psi_t : W \rightarrow W$ such that

$$\frac{\partial}{\partial t} \psi_t = X_t \circ \psi_t, \quad \psi_0 = \text{id}$$

- Define the (important!) map

$$v(s, t) := (\psi_t^{-1} \circ u)(s, t)$$

- We can then compute

$$\begin{aligned}\frac{\partial u}{\partial s} &= (d\psi_t)\left(\frac{\partial v}{\partial s}\right) \\ \frac{\partial u}{\partial t} &= (d\psi_t)\left(\frac{\partial v}{\partial t}\right) + X_t(u).\end{aligned}$$

- Attempt at explanation: rearrange, use chain rule, and known derivative of ψ_t :

$$u(s, t) = (\psi_t \circ v)(s, t) \implies \frac{\partial u}{\partial s}(s, t) = \frac{\partial \psi_t}{\partial s}(v(s, t)) \cdot \frac{\partial v}{\partial s}(s, t)$$

$$? \implies \frac{\partial u}{\partial s} = (d\psi_t) \cdot \left(\frac{\partial v}{\partial s}\right)$$

and

$$\begin{aligned}\frac{\partial u}{\partial t}(s, t) &= \frac{\partial \psi_t}{\partial t}(v(s, t)) \cdot \frac{\partial v}{\partial t}(s, t) \\ &= (X_t \circ \psi_t)(v(s, t)) \cdot \frac{\partial v}{\partial t}(s, t) \\ &= (X_t \circ \psi_t \circ v)(s, t) \cdot \frac{\partial v}{\partial t}(s, t) \\ &= X_t(u(s, t)) \cdot \frac{\partial v}{\partial t}(s, t) \\ &= X_t(u) \left(\frac{\partial v}{\partial t}\right) \dots ????.\end{aligned}$$

- Continuing computations,

$$\begin{aligned}0 &= \frac{\partial u}{\partial s} + J\left(\frac{\partial u}{\partial t} - X_t(u)\right) && \text{since } u \text{ is a solution} \\ &= \frac{\partial u}{\partial s} + J\frac{\partial u}{\partial t} - JX_t(u) && \text{expanding terms} \\ &= \left((d\psi_t)\left(\frac{\partial v}{\partial s}\right)\right) + J\left((d\psi_t)\left(\frac{\partial v}{\partial t}\right) + X_t(u)\right) - JX_t(u) && \text{by substitution} \\ &= (d\psi_t)\left(\frac{\partial v}{\partial s}\right) + J(u)(d\psi_t)\left(\frac{\partial v}{\partial t}\right) && \text{cancelling} \\ &= (d\psi_t)\left(\frac{\partial v}{\partial s} + (d\psi_t)^{-1}J(u)(d\psi_t)\left(\frac{\partial v}{\partial t}\right)\right) && \text{collecting terms} \\ &:= (d\psi_t)\left(\frac{\partial v}{\partial s} + \psi_t^*J(v)\right) && \text{by definition.}\end{aligned}$$

- Conclude that v is a solution of

$$\frac{\partial v}{\partial s} + \psi_t^*J(v)\frac{\partial v}{\partial t} = 0.$$

- Set $\varphi := \psi_1$ and $J_1(v) := \psi_1^*J(v)$ to obtain

$$\frac{\partial v}{\partial s} + J_1(v)\frac{\partial v}{\partial t} = 0$$

of which v is still a solution

- Attempt to check directly, using $\psi_{t+1} = \psi_t \circ \psi_1$:

$$\begin{aligned}
 v(s, t+1) &:= (\psi_t^{-1} \circ u)(s, t+1) \\
 &= (\psi_1 \circ \psi_t^{-1} \circ u)(s, t) \\
 &= \psi_1(v(s, t)) \\
 &:= \varphi(v(s, t)),
 \end{aligned}$$

which verifies property 1.

Note: just a guess from me!

- Recall definition of v :

$$v(s, t) := \psi_t^{-1}(u(s, t))$$

- Verifying that $C(v) = C(u)$: not spelled out. Property of flow?

- Need to check that

$$\frac{\partial u}{\partial s}(s_0, t_0) = 0 \implies \frac{\partial v}{\partial s}(s_0, t_0) = 0$$

where

$$\frac{\partial u}{\partial s} = (d\psi_t) \left(\frac{\partial v}{\partial s} \right)$$

- How: ?

- Verifying that $R(v) = R(u)$

- Need to check that for $(s_0, t_0) \notin C(u)$ and $s \neq s_0$ we have

$$u(s_0, t_0) \neq u(s, t_0) \implies v(s_0, t_0) \neq v(s, t_0)$$

- Follows directly:

$$\begin{aligned}
 v(s_0, t_0) \neq v(s, t_0) &\iff \psi_t^{-1}(u(s_0, t_0)) \neq \psi_t^{-1}(u(s, t_0)) \quad \text{by definition} \\
 &\iff (\psi_t \circ \psi_t^{-1})(u(s_0, t_0)) \neq (\psi_t \circ \psi_t^{-1})(u(s, t_0)) \quad \text{injectivity of } \psi_t \\
 &\iff u(s_0, t_0) \neq u(s, t_0).
 \end{aligned}$$

■

Lemma 8.6.2: The set of critical points of v above is discrete. Precisely: There exists a constant $\delta > 0$ such that $(dv)_z \neq 0$ for any $0 < |z| < \delta$.

Proof: Postponed to p.264.

Definition: Multiple points

Proposition 8.6.3: Injectivity result. Let v be a smooth 1-periodic (in t) solution of the CR equation, i.e. $v(s, t+1) = \phi(v(s, t))$ for some smooth ϕ ? and $\frac{\partial v}{\partial s} \neq 0$. Then $R(v) \hookrightarrow \mathbb{R}^2$ is open and dense.

0.6 Regular Points Are Open and Dense

Proof (BIG):

- Show $R(v)$ is open (easy)
- Show $R(v)$ is dense (delicate)

Long proof.

Lemma 8.6.4: For every $r > 0$ there exists a $\delta > 0$ such that

$$|t - t_0|, |s - s_0| < \delta \implies \exists s' \in B_r(s_j) \text{ s.t. } v(s, t) = v(s', t).$$

Proof: short.

Lemma 8.6.5: Let v_1, v_2 be two solutions of the CR-equation with $X_t \equiv 0$ on $B_\varepsilon(0)$, $v_1(0, 0) = v_2(0, 0)$ such that $(dv_1)_0, (dv_2)_0 \neq 0$. Also suppose

$$\forall \varepsilon \exists \delta \text{ s.t.}$$

$$\forall (s, t) \in B_\delta(0), \exists s' \in \mathbb{R} \begin{cases} (s', t) \in B_\varepsilon(0) \\ v_1(s, t) = v_2(s', t) \end{cases}.$$

Then

$$\forall z \in B_\varepsilon(0), \quad v_1(s, t) = v_2(s, t).$$

Take perturbed CR equation:

$$\frac{\partial Y}{\partial s} + J_0 \frac{\partial Y}{\partial t} + S \cdot Y = 0.$$

Fix $S \in C^\infty(\mathbb{R}^2; \text{End}(\mathbb{R}^{2n}))$

Lemma (Similarity Principle, used to prove continuation principle and 8.6.8): Let $Y \in C^\infty(B_\varepsilon; \mathbb{C}^n)$ be a solution to the perturbed CR equation and let $p > 2$. Then there exists $0 < \delta < \varepsilon$ and a map $A \in W^{1,p}(B_\delta, \text{GL}(\mathbb{R}^{2n}))$ and a holomorphic map $\sigma : B_\delta \rightarrow \mathbb{C}^n$ such that

$$\forall (s, t) \in B_\delta \quad Y(s, t) = A(s, t) \sigma(s + it) \quad \text{and} \quad J_0 A(s, t) = A(s, t) J_0.$$

Use continuation principle to finish proofs of many old theorems/lemmas.

Theorem (8.6.11, Essential property of $\bar{\partial}$) For every $p > 1$, the following operator is surjective and Fredholm:

$$\bar{\partial} : W^{1,p}(S^2; \mathbb{C}^n) \longrightarrow L^p(\Lambda^{0,1} T^* S^2 \otimes \mathbb{C}^n).$$

Lead up to the proof of 8.1.5 in Section 8.7

1 Goal 2: Continuation Principle

Goal 2: prove a continuation principle:

Proposition 1.1 (8.6.6, Continuation Principle).

On an open $U \subset \mathbb{R}^2$, let Y be a solution to the perturbed CR equation

$$\frac{\partial Y}{\partial s} + J_0 \frac{\partial Y}{\partial t} + S \cdot Y = 0$$

where J_0 is the standard complex structure on \mathbb{R}^{2n} and $S \in C^\infty(\mathbb{R}^2, \text{End}(\mathbb{R}^{2n}))$.

Say that f has an *infinite-order zero* at z_0 iff

$$\forall k \geq 0, \quad \sup_{|z-z_0| \leq t} \frac{|f(z)|}{r^k} \xrightarrow{r \rightarrow 0} 0.$$

For f smooth, equivalently $f^{(k)}(z_0) = 0$ for all k .

Then the set

$$C := \left\{ (s, t) \in U \mid Y \text{ has an infinite order zero at } (s, t) \right\}$$

is clopen. In particular, if U is connected and $Y = 0$ on some nonempty $V \subset U$, then $Y \equiv 0$.

Proposition 1.2 (8.1.4,).

Define

$$\mathcal{Z}(x, y, J) := \{ (u, H_0 + h) \mid h \in \mathcal{C}_\varepsilon^\infty(H_0) \text{ and } u \in \mathcal{M}(x, y, J, H) \}.$$

If $(u, H_0 + h) \in \mathcal{Z}(x, y)$ then the following map admits a continuous right-inverse and is surjective:

$$\begin{aligned} \Gamma : W^{1,p}(\mathbb{R} \times S^1; \mathbb{R}^{2n}) \times \mathcal{C}_\varepsilon^\infty(H_0) &\longrightarrow L^p(\mathbb{R} \times S^1; \mathbb{R}^{2n}) \\ (Y, h) &\longmapsto \left(d\mathcal{F}^{H_0+h} \right)_u(Y) + \text{grad}_u h \end{aligned}$$

where \mathcal{F}^{H_0+h} is the Floer operator corresponding to $H_0 + h$.

Used to show (via the implicit function theorem) that $\mathcal{Z}(x, y, J)$ is a Banach manifold when $x \neq y$.