# Section 8.6: The Solutions of the Floer Equation are "Somewhere Injective".

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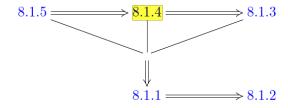
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#### 0.1 Outline

Two Goals:

- 1. Prove critical points are discrete and regular points are open/dense.
- 2. Prove the continuation principle that was used in Proposition 8.1.4

#### 0.2 Outline of Statements



- 8.1.5:  $(d\mathcal{F})_u$  is a Fredholm operator of index  $\mu(x) \mu(y)$ .
- 8.1.4:  $\Gamma: W^{1,p} \times C_{\varepsilon}^{\infty} \longrightarrow L^p$  has a continuous right-inverse and is surjective
- 8.1.3:  $\mathcal{Z}(x,y,J)$  is a Banach manifold
- 8.1.1: For  $h \in \mathcal{H}_{reg}$ ,  $H_0 + h$  is nondegenerate and  $(d\mathcal{F})_u$  is surjective for every  $u \in \mathcal{M}(H_0 + h, J)$ .
- 8.1.2: For  $h \in \mathcal{H}_{reg}$  and all contractible orbits x, y of  $H_0$ ,  $\mathcal{M}(x, y, H_0 + h)$  is a manifold of dimension  $\mu(x) \mu(y)$ .

#### 0.3 Notation

• The Floer equation and its linearization:

$$\mathcal{F}(u) = \frac{\partial u}{\partial s} + J \frac{\partial u}{\partial t} + \operatorname{grad}_{u}(H) = 0$$
$$(d\mathcal{F})_{u}(Y) = \frac{\partial Y}{\partial s} + J_{0} \frac{\partial Y}{\partial t} + S \cdot Y$$
$$Y \in u^{*}TW, \ S \in C^{\infty}(\mathbb{R} \times S^{1}; \operatorname{End}(\mathbb{R}^{2n})).$$

- z = s + it
- X is a vector field (time-dependent and periodic) on  $\mathbb{R}^{2n}$ , J an almost complex structure -X, J are smooth
- $u \in C^{\infty}(\mathbb{R} \times S^1; W)$  is a solution to the equation

$$\frac{\partial u}{\partial s} + J(t, u) \left( \frac{\partial u}{\partial t} - X(t, u) \right) = 0$$

• C(u) the set of critical points and R(u) the set of regular points of u:

$$(s_0, t_0) \in C(u) \subseteq \mathbb{R} \times S^1 \iff \frac{\partial u}{\partial s}(s_0, t_0) = 0$$
  
$$(s_0, t_0) \in R(u) \subset \mathbb{R} \times S^1 \iff (s_0, t_0) \notin C(u) \& s \neq s_0 \implies u(s_0, t_0) \neq u(s, t_0).$$

#### 0.4 Goal 1: Discrete Critical Points and Dense Regular Points

Goal 1: prove the following theorem

Theorem 0.1(8.5.4).

- 1. C(u) is discrete and 2.  $R(u) \hookrightarrow \mathbb{R} \times S^1$  is open and dense.

Outline of the proof:

• Prove 8.6.1 (direct, short) which transforms the equation

$$\frac{\partial u}{\partial s} + J(t, u) \left( \frac{\partial u}{\partial t} - X(t, u) \right) = 0 \text{ where } u \in C^{\infty}(\mathbb{R} \times S^1; W)$$

to a Cauchy-Riemann equation on  $\mathbb{R}^2$ :

$$\frac{\partial v}{\partial s} + J \frac{\partial v}{\partial t} = 0$$
 where  $v \in C^{\infty}(\mathbb{R}^2; W)$ 

- Produces a map v which reduces Theorem 8.5.4 to two statements
  - 8.6.2: C(v) (and thus C(u)) is discrete
    - \* Proved later using similarity principle.
  - 8.6.3 (Injectivity): If v is a smooth periodic solution of CR with  $\frac{\partial v}{\partial s} \neq 0$  then  $R(v) \hookrightarrow \mathbb{R}^2$ is open and dense.
- Prove 8.6.3 (Injectivity)

- Show open.
- Show dense
- Prove 8.6.8 (similarity principle)
- Use similarity principle to prove 8.6.1, yields theorem.



#### 0.5 8.6.1: Transform to Cauchy-Riemann

Proposition 0.2(8.6.1, Transform to CR-equation on R2).

If u is a solution to the following equation:

$$\frac{\partial u}{\partial s} + J(t, u) \left( \frac{\partial u}{\partial t} - X(t, u) \right) = 0.$$

Then there exists

- An almost complex structure  $J_1$
- A diffeomorphism  $\varphi$  on W?
- A map  $v \in C^{\infty}(\mathbb{R}^2; W)$

satisfying

$$\frac{\partial v}{\partial s} + J_1(v)\frac{\partial v}{\partial t} = 0$$

where

- 1.  $v(s, t + 1) = \varphi(v(s, t))$
- 2. C(u) = C(v), i.e. u, v have the same critical points
- 3. R(u) = R(v).

Proof

- Since  $W \times S^1$  is compact, the flow  $\psi_t$  of  $X_t$  is defined on all of W
  - We thus have a map  $\psi_t: W \longrightarrow W$  such that  $* \frac{\partial}{\partial t} \psi_t = X_t \circ \psi_t$

$$* \psi_0 = id$$

• Define the (important!) map

$$v(s,t) \coloneqq \left(\psi_t^{-1} \circ u\right)(s,t)$$

• We can then compute

$$\begin{aligned} \frac{\partial u}{\partial s} &= (d\psi_t) \left( \frac{\partial v}{\partial s} \right) \\ \frac{\partial u}{\partial t} &= (d\psi_t) \left( \frac{\partial v}{\partial t} \right) + X_t(u) \end{aligned}$$

.

- Attempt at explanation: rearrange, use chain rule, and known derivative of  $\psi_t$ :

$$u(s,t) = (\psi_t \circ v)(s,t) \implies \frac{\partial u}{\partial s} \qquad \qquad = \frac{\partial \psi_t}{\partial s}(v(s,t)) \cdot \frac{\partial v}{\partial s}(s,t)$$

$$\implies \frac{\partial u}{\partial t} \qquad \qquad = \frac{\partial \psi_t}{\partial t}(v(s,t)) \cdot \frac{\partial v}{\partial t}(s,t)$$

$$= (X_t \circ \psi_t)(v(s,t)) \cdot \frac{\partial v}{\partial t}(s,t).$$

• Continuing computations,

$$0 = \frac{\partial u}{\partial s} + J\left(\frac{\partial u}{\partial t} - X_t(u)\right) \qquad \text{since } u \text{ is a solution}$$

$$= \frac{\partial u}{\partial s} + J\frac{\partial u}{\partial t} - JX_t(u) \qquad \text{expanding terms}$$

$$= \left(\left(d\psi_t\right)\left(\frac{\partial v}{\partial s}\right)\right) + J\left(\left(d\psi_t\right)\left(\frac{\partial v}{\partial t}\right) + X_t(u)\right) - JX_t(u) \qquad \text{by substitution}$$

$$= \left(d\psi_t\right)\left(\frac{\partial v}{\partial s}\right) + J(u)\left(d\psi_t\right)\left(\frac{\partial v}{\partial t}\right) \qquad \text{cancelling}$$

$$= \left(d\psi_t\right)\left(\frac{\partial v}{\partial s} + \left(d\psi_t\right)^{-1}J(u)\left(d\psi_t\right)\left(\frac{\partial v}{\partial t}\right)\right) \qquad \text{collecting terms}$$

$$\coloneqq \left(d\psi_t\right)\left(\frac{\partial v}{\partial s} + \psi_t^*J(v)\right) \qquad \text{by definition.}$$

 $\bullet$  Conclude that v is a solution of

$$\frac{\partial v}{\partial s} + \psi_t^{\star} J(v) \frac{\partial v}{\partial t} = 0.$$

• Set  $\varphi \coloneqq \psi_1$  and  $J_1(v) \coloneqq \psi_1^* J(v)$  to obtain

$$\frac{\partial v}{\partial s} + J_1(v) \frac{\partial v}{\partial t} = 0$$

of which v is still a solution

• We can check directly that

$$v(s,t+1) := (\psi_t^{-1} \circ u)(s,t+1)$$

$$? = (\psi_1 \circ \psi_t^{-1} \circ u)(s,t)$$

$$= \psi_1(v(s,t))$$

$$:= \varphi(v(s,t)),$$

which verifies property 1.

Note: just a guess from me!

• Verifying that C(u) = C(v): not spelled out. Property of flow?

Lemma 8.6.2: The set of critical points of v above is discrete. Precisely: There exists a constant  $\delta > 0$  such that  $(dv)_z \neq 0$  for any  $0 << |z| < \delta$ .

Proof: Postponed to p.264.

Definition: Multiple points

Proposition 8.6.3: Injectivity result. Let v be a smooth 1-periodic (in t) solution of the CR equation, i.e.  $v(s,t+1) = \phi(v(s,t))$  for some smooth  $\phi$ ? and  $\frac{\partial v}{\partial s} \neq 0$ . Then  $R(v) \hookrightarrow \mathbb{R}^2$  is open and dense.

#### 0.6 Regular Points Are Open and Dense

Proof (BIG):

- Show R(v) is open (easy)
- Show R(v) is dense (delicate)

Long proof.

Lemma 8.6.4: For every r > 0 there exists a  $\delta > 0$  such that

$$|t - t_0|, |s - s_0| < \delta \implies \exists s' \in B_r(s_i) \text{ s.t. } v(s, t) = v(s', t).$$

Proof: short.

Lemma 8.6.5: Let  $v_1, v_2$  be two solutions of the CR-equation with  $X_t \equiv 0$  on  $B_{\varepsilon}(0), v_1(0,0) = v_2(0,0)$  such that  $(dv_1)_0, (dv_2)_0 \neq 0$ . Also suppose

$$\forall \varepsilon \; \exists \delta \; \text{s.t.}$$

$$\forall (s,t) \in B_{\delta}(0), \ \exists s' \in \mathbb{R} \begin{cases} (s',t) \in B_{\varepsilon}(0) \\ v_1(s,t) = v_2(s',t) \end{cases}.$$

Then

$$\forall z \in B_{\varepsilon}(0), \quad v_1(s,t) = v_2(s,t).$$

Take perturbed CR equation:

$$\frac{\partial Y}{\partial s} + J_0 \frac{\partial Y}{\partial t} + S \cdot Y = 0.$$

Fix  $S \in C^{\infty}(\mathbb{R}^2; \operatorname{End}(\mathbb{R}^{2n}))$ 

Lemma (Similarity Principle, used to prove continuation principle and 8.6.8): Let  $Y \in C^{\infty}(B_{\varepsilon}; \mathbb{C}^n)$  be a solution to the perturbed CR equation and let p > 2. Then there exists  $0 < \delta < \varepsilon$  and a map  $A \in W^{1,p}(B_{\delta}, \mathrm{GL}(\mathbb{R}^{2n}))$  and a holomorphic map  $\sigma : B_{\delta} \longrightarrow \mathbb{C}^n$  such that

$$\forall (s,t) \in B_{\delta} \quad Y(s,t) = A(s,t) \ \sigma(s+it) \quad \text{and} \quad J_0 A(s,t) = A(s,t) J_0.$$

Use continuation principle to finish proofs of many old theorems/lemmas.

Theorem (8.6.11, Essential property of  $\bar{\partial}$ ) For every p > 1, the following operator is surjective and Fredholm:

$$\bar{\partial}: W^{1,p}(S^2; \mathbb{C}^n) \longrightarrow L^p(\Lambda^{0,1}T^*S^2 \otimes \mathbb{C}^n).$$

Lead up to the proof of 8.1.5 in Section 8.7

## 1 Goal 2: Continuation Principle

Goal 2: prove a continuation principle:

#### Proposition 1.1(8.6.6, Continuation Principle).

On an open  $U \subset \mathbb{R}^2$ , let Y be a solution to the perturbed CR equation

$$\frac{\partial Y}{\partial s} + J_0 \frac{\partial Y}{\partial t} + S \cdot Y = 0$$

where  $J_0$  is the standard complex structure on  $\mathbb{R}^{2n}$  and  $S \in C^{\infty}(\mathbb{R}^2, \operatorname{End}(\mathbb{R}^{2n}))$ . Say that f has an *infinite-order zero* at  $z_0$  iff

$$\forall k \ge 0, \quad \sup_{|z-z_0| \le t} \frac{|f(z)|}{r^k} \stackrel{r \longrightarrow 0}{\longrightarrow} 0.$$

For f smooth, equivalently  $f^{(k)}(z_0) = 0$  for all k.

Then the set

$$C \coloneqq \left\{ (s,t) \in U \mid Y \text{ has an infinite order zero at } (s,t) \right\}$$

is clopen. In particular, if U is connected and Y=0 on some nonempty  $V\subset U$ , then  $Y\equiv 0$ .

#### Proposition 1.2(8.1.4,).

Define

$$\mathcal{Z}(x, y, J) := \{(u, H_0 + h) | h \in \mathcal{C}_{\varepsilon}^{\infty}(H_0) \text{ and } u \in \mathcal{M}(x, y, J, H)\}.$$

If  $(u, H_0 + h) \in \mathcal{Z}(x, y)$  then the following map admits a continuous right-inverse and is

surjective:

$$\Gamma: W^{1,p}\left(\mathbb{R} \times S^1; \mathbb{R}^{2n}\right) \times \mathcal{C}_{\varepsilon}^{\infty}\left(H_0\right) \longrightarrow L^p\left(\mathbb{R} \times S^1; \mathbb{R}^{2n}\right)$$
$$(Y,h) \longmapsto \left(d\mathcal{F}^{H_0+h}\right)_u(Y) + \operatorname{grad}_u h$$

where  $\mathcal{F}^{H_0+h}$  is the Floer operator corresponding to  $H_+h$ .

Used to show (via the implicit function theorem) that  $\mathcal{Z}(x,y,J)$  is a Banach manifold when  $x \neq y$ .