

Title

Contents

1	Elementary Algebra	2
2	Abstract Algebra	2
3	Complex Numbers	3
4	Analysis	3
5	Combinatorics and Probability	3
6	Linear Algebra	3

1 | Elementary Algebra

- Looking at real roots:
 - Let p be number of sign changes in $f(x)$;
 - Let q be number of sign changes in $f(-x)$;
 - Let n be the degree of f .
 - Then p gives the maximum number of positive real roots, q gives the maximum number of negative real roots, and $n - p - q$ gives the *minimum* number of complex roots.
 - Rational Roots Theorem: If $p(x) = ax^n + \cdots + c$ and $r = \frac{p}{q}$ where $p(r) = 0$, then $p \mid c$ and $q \mid a$.

2 | Abstract Algebra

- Order p : One, Z_p
- Order p^2 : Two abelian groups, Z_{p^2}, Z_p^2
- Order p^3 :
 - 3 abelian $Z_{p^3}, Z_p \times Z_{p^2}, Z_p^3$,
 - 2 others $Z_p \rtimes Z_{p^2}$.

◇ The other is the quaternion group for $p = 2$ and a group of exponent p for $p > 2$.
- Order pq :
 - $p \mid q - 1$: Two groups, Z_{pq} and $Z_q \rtimes Z_p$
 - Else cyclic, Z_{pq}
- Every element in a permutation group is a product of disjoint cycles, and the order is the lcm of the order of the cycles.

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- The product ideal IJ is *not* just elements of the form ij , it is all sums of elements of this form! The product alone isn't enough.
 - The intersection of any number of ideals is also an ideal

3 | Complex Numbers

- $\lim_{z \rightarrow z_0} f(z) = x_0 + iy_0$ iff the component functions limit to x_0 and y_0 respectively. Moreover, both ways are equal!

4 | Analysis

- f injective implies f has a nonzero derivative (in neighborhoods)
- In \mathbb{R} , singletons are closed. This means any finite subset is closed, as a finite union of singleton sets! Good for counterexamples to continuity.
- Definition of topology: arbitrary unions and finite intersections of open sets are open. Equivalently, arbitrary intersections and finite unions of closed sets are closed.
- The best source of examples and counterexamples is the open/closed unit interval in \mathbb{R} . Always test against these first!
- Every Cauchy sequence converges in a complete metric space

5 | Combinatorics and Probability

- Counting non-isomorphic things: Pick a systematic way. Can descend my maximum vertex degree, or ascend by adding nodes/leaves.

6 | Linear Algebra

- An $m \times n$ matrix is a map from n -dimensional space to m -dimensional space. Number of *rows* tell you the dimension of the codomain, the number of *columns* tell you the dimension of the *domain*.
- The column space of A (i.e. linear combinations of the columns) are a basis for the *image* of A .
- The row space is a basis for the *coimage*, which is nullspace perp.
- Not enough pivots implies columns don't span the entire target domain
- The determinant of an RREF matrix is the product of the diagonals
- An $n \times n$ matrix P is diagonalizable iff its eigenspace is all of \mathbb{R}^n (i.e. there are n linearly independent eigenvectors, so they span the space.) Equivalently, if there is a basis of eigenvectors for the range of P

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- Projections decompose the range into the direct sum of its nullspace and nullspace perp.
 - The space of matrices is not an integral domain!
 - The transition matrix from a given basis $\mathcal{B} = b_i$ to the standard basis is given by just creating a matrix with each b_i being a column.
 - The transition matrix from the standard basis to \mathcal{B} is just the inverse of the above!
 - Inverting matrices quickly:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \quad \text{where } ad - bc \neq 0$$