# **Complex Analysis Qualifying Exam Notes**

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## Tuesday 18<sup>th</sup> August, 2020

## Contents

1	Useful Techniques	2
2	Definitions	2
3	Theorems         3.1 Basics          3.2 Holomorphic and Entire Functions          3.2.1 Key Theorems          3.2.2 Others	4 4 4 5
	3.3 Series and Analytic Functions	6 7
4	Residues	7
5	Conformal Maps 5.1 Plane to Disc	9 9 10
6	Schwarz Reflection	10
7	7.1 Singularities	10 10 10
8	Linear Fractional Transformations	11
9	9.0.1 Fundamental Theorem of Algebra: Argument Principle	12 12 12 12 13
10		<b>13</b>

## 1 Useful Techniques

Showing a function is constant:

- Write f = u + iv and use Cauchy-Riemann to show  $u_x, u_y = 0$ , etc.
- Show that f is entire and bounded.

Showing a function is zero: Show f is entire, bounded, and  $\lim_{z \to \infty} f(z) = 0$ .

Things to know well:

- Estimates for derivatives, mean value theorem
- Cauchy's Theorem
- Cauchy's Integral Formula
- Cauchy's Inequality
- Morera's Theorem
- The Schwarz Reflection Principle
- Maximum Modulus Principle
- The Schwarz Lemma
- Liouville's Theorem
- Casorati-Weierstrass Theorem
- Rouché's Theorem
- Properties of linear fractional transformations
- Automorphisms of  $\mathbb{D}$ ,  $\mathbb{C}$ ,  $\mathbb{CP}^1$ .

Computing Arguments: Arg(z/w) = Arg(z) - Arg(w).

#### 2 Definitions

Definition 2.0.1 (Analytic).

A function  $f: \Omega \longrightarrow \mathbb{C}$  is analytic at  $z_0 \in \Omega$  iff there exists a power series  $g(z) = \sum a_n (z - z_0)^n$  with radius of convergence R > 0 and a neighborhood  $U \ni z_0$  such that f(z) = g(z) on U.

**Definition 2.0.2** (Holomorphic).

A function  $f: \mathbb{C} \longrightarrow \mathbb{C}$  is holomorphic at  $z_0$  if the following limit converges:

$$\lim_{h \to 0} \frac{1}{h} (f(z_0 + h) - f(z_0)) := f'(z_0).$$

Examples:

- $f(z) = \frac{1}{z}$  is holomorphic on  $\mathbb{C} \setminus \{0\}$ .
- $f(z) = \bar{z}$  is not holomorphic, since  $\frac{\bar{h}}{h}$  does not converge (but is real differentiable).

#### Definition 2.0.3 (Entire).

A function that is holomorphic on  $\mathbb{C}$  is said to be *entire*.

#### **Definition 2.0.4** (Meromorphic).

A function  $f:\Omega\longrightarrow\mathbb{C}$  is meromorphic iff there exists a sequence  $\{z_n\}$  such that

- $\{z_n\}$  has no limit points in  $\Omega$ .
- f is holomorphic in  $\Omega \setminus \{z_n\}$ .
- f has poles at the points  $\{z_n\}$ .

If f is either holomorphic or has a pole at  $z = \infty$  is said to be meromorphic on  $\mathbb{CP}^1$ .

#### Definition 2.0.5 (Harmonic).

A real function of two variables u(x,y) is harmonic iff its Laplacian vanishes:

$$\Delta u := \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) u = 0.$$

#### Definition 2.0.6 (Cauchy-Riemann Equations).

$$u_x = v_y$$
 and  $u_y = -v_x$   
 $\frac{\partial u}{\partial r} = \frac{1}{r} \frac{\partial v}{\partial \theta}$  and  $\frac{\partial v}{\partial r} = -\frac{1}{r} \frac{\partial u}{\partial \theta}$ 

#### **Definition 2.0.7** (Principal Part and Residue).

In a Laurent series  $f(z) := \sum_{n \in \mathbb{Z}} c_n (z - z_0)^n$ , the principal part of f at  $z_0$  consists of terms with negative degree:

$$P_f(z) := \sum_{n=1}^{\infty} c_{-n} (z - z_0)^{-n}.$$

The residue of f at  $z_0$  is the coefficient  $c_{-1}$ .

#### **Definition 2.0.8** (Removable Singularities).

If  $z_0$  is a singularity of f and there exists a g such that f(z) = g(z) for all z in some deleted neighborhood  $U \setminus \{z_0\}$ , then  $z_0$  is a removable singularity of f.

#### Definition 2.0.9 (Pole Terminology).

A pole  $z_0$  of a meromorphic function f(z) is a zero of  $g(z) := \frac{1}{f(z)}$ . If there exists an n such that

$$\lim_{z \to z_0} (z - z_0)^n f(z)$$

is holomorphic and nonzero in a neighborhood of  $z_0$ , then the minimal such n is the *order* of the pole. A pole of order 1 is said to be a *simple pole*.

The pole  $z_0$  is isolated iff there exists a neighborhood of  $z_0$  containing no other poles of f.

Definition 2.0.10 (Essential Singularity).

A singularity  $z_0$  is essential iff it is neither removable nor a pole.

Equivalently, a Laurent series expansion about  $z_0$  has a principal part with infinitely many terms.

### 3 Theorems

#### 3.1 Basics

Theorem 3.1 (Green's Theorem).

If  $\Omega \subseteq \mathbb{C}$  is bounded with  $\partial\Omega$  piecewise smooth and  $f,g \in C^1(\overline{\Omega})$ , then

$$\int_{\partial\Omega} f \, dx + g \, dy = \iint_{\Omega} \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA.$$

Theorem 3.2(Summation by Parts).

Define the forward difference operator  $\Delta f_k = f_{k+1} - f_k$ , then

$$\sum_{k=m}^{n} f_k \Delta g_k + \sum_{k=m}^{n-1} g_{k+1} \Delta f_k = f_n g_{n+1} - f_m g_m$$

Note: compare to  $\int_a^b f \, dg + \int_a^b g \, df = f(b)g(b) - f(a)g(a)$ .

#### 3.2 Holomorphic and Entire Functions

#### 3.2.1 Key Theorems

Theorem 3.3 (Cauchy's Theorem ).

If f is holomorphic on  $\Omega$ , then

$$\int_{\partial\Omega} f(z) \, dz = 0.$$

Slogan: closed path integrals of holomorphic functions vanish.

Theorem 3.4 (Morera's Theorem ).

If f is continuous on a domain  $\Omega$  and  $\int_T f = 0$  for every triangle  $T \subset \Omega$ , then f is holomorphic.

Slogan: if every integral along a triangle vanishes, implies holomorphic.

Theorem 3.5(Liouville's Theorem ).

If f is entire and bounded, f is constant.

#### Theorem 3.6 (Cauchy Integral Formula).

Suppose f is holomorphic on  $\Omega$ , then

$$f(z) = \frac{1}{2\pi i} \oint_{\partial \Omega} \frac{f(\xi)}{\xi - z} d\xi$$

and

$$\frac{\partial^n f}{\partial z^n}(z) = \frac{n!}{2\pi i} \int_{\partial \Omega} \frac{f(\xi)}{(\xi - z)^{n+1}} d\xi.$$

#### 3.2.2 Others

#### Theorem 3.7 (Holomorphic functions have harmonic components).

If f(z) = u(x, y) + iv(x, y), then u, v are harmonic.

#### Theorem 3.8 (Holomorphic functions are continuous.).

f is holomorphic at  $z_0$  iff there exists an  $a \in \mathbb{C}$  such that

$$f(z_0 + h) - f(z_0) - ah = h\psi(h), \quad \psi(h) \stackrel{h \longrightarrow 0}{\longrightarrow} 0.$$

In this case,  $a = f'(z_0)$ .

#### Proposition 3.9 (Cauchy-Riemann implies holomorphic).

If f = u + iv with  $u, v \in C^1(\mathbb{R})$  satisfying the Cauchy-Riemann equations on  $\Omega$ , then f is holomorphic on  $\Omega$  and  $f'(z) = \frac{\partial f}{\partial z} = \frac{1}{2} \left( \frac{\partial}{\partial x} + \frac{1}{i} \frac{\partial}{\partial y} \right) f$ .

#### Proposition 3.10 (Polar Cauchy-Riemann equations).

$$\frac{\partial u}{\partial r} = \frac{1}{r} \frac{\partial v}{\partial \theta}$$
 and  $\frac{1}{r} \frac{\partial u}{\partial \theta} = -\frac{\partial v}{\partial r}$ 

Proof.

#### Concepts Used:

- See walkthrough here.
- See problem set 1.
- Take derivative along two paths, along a ray with constant angle  $\theta_0$  and along a circular arc of constant radius  $r_0$ .
- Then equate real and imaginary parts.

#### Theorem 3.11 (Open Mapping).

Any holomorphic non-constant map is an open map.

#### 3.3 Series and Analytic Functions

#### Proposition 3.12 (Power Series are Smooth).

Any power series is smooth and its derivatives can be obtained using term-by-term differentiation.

### Proposition 3.13 (Uniform Convergence of Series).

A series of functions  $\sum_{n=1}^{\infty} f_n(x)$  converges uniformly iff

$$\lim_{n \to \infty} \left\| \sum_{k \ge n} f_k \right\|_{\infty} = 0.$$

### Theorem 3.14 (Weierstrass M-Test).

If  $\{f_n\}$  with  $f_n: \Omega \longrightarrow \mathbb{C}$  and there exists a sequence  $\{M_n\}$  with  $\|f_n\|_{\infty} \leq M_n$  and  $\sum_{n \in \mathbb{N}} M_n < \infty$ ,

then  $f(x) := \sum_{n \in \mathbb{N}} f_n(x)$  converges absolutely and uniformly on  $\Omega$ .

Moreover, if the  $f_n$  are continuous, by the uniform limit theorem, f is again continuous.

## Proposition 3.15 (Exponential is uniformly convergent in discs).

 $f(z) = e^z$  is uniformly convergent in any disc in  $\mathbb{C}$ .

#### Proof.

Apply the estimate

$$|e^z| \le \sum \frac{|z|^n}{n!} = e^{|z|}.$$

Now by the M-test,

$$|z| \le R < \infty \implies \left| \sum \frac{z^n}{n!} \right| \le e^R < \infty.$$

### Proposition 3.16 (Checking radius of convergence).

For a power series  $f(z) = \sum a_n z^n$ , define R by

$$\frac{1}{R} := \limsup |a_n|^{\frac{1}{n}}.$$

Then f converges absolutely on |z| < R and diverges on |z| > R.

THEOREMS

6

#### Theorem 3.17 (Maximum Modulus ).

If f is holomorphic and nonconstant on an open region  $\Omega$ , then |f| can not attain a maximum on  $\Omega$ .

If  $\Omega$  is bounded and f is continuous on  $\overline{\Omega}$ , then  $\max |f|$  occurs on  $\partial\Omega$ .

Conversely, if f attains a local maximum at  $z_0 \in \Omega$ , then f is constant on  $\Omega$ .

#### 3.4 Others

#### Theorem 3.18 (Casorati-Weierstrass).

If f is holomorphic on  $\Omega \setminus \{z_0\}$  where  $z_0$  is an essential singularity, then for every  $V \subset \Omega \setminus \{z_0\}$ , f(V) is dense in  $\mathbb{C}$ .

The image of a disc punctured at an essential singularity is dense in  $\mathbb{C}$ .

#### Theorem 3.19 (Little Picard).

Todo

Theorem 3.20 (Continuation Principle / Identity Theorem).

If f is holomorphic on a bounded connected domain  $\Omega$  and there exists a sequence  $\{z_i\}$  with a limit point in  $\Omega$  such that  $f(z_i) = 0$ , then  $f \equiv 0$  on  $\Omega$ .

Two functions agreeing on a set with a limit point are equal on a domain.

#### Corollary 3.21.

The ring of holomorphic functions on a domain in  $\mathbb{C}$  has no zero divisors.

Find the proof!

Proof.

4 Residues

#### Theorem 4.1 (Cauchy's Inequality).

For  $z_o \in D_R(z_0) \subset \Omega$ , we have

$$\left| f^{(n)}(z_0) \right| \le \frac{n!}{2\pi} \int_0^{2\pi} \frac{\|f\|_{\infty}}{R^{n+1}} R \, d\theta = \frac{n! \|f\|_{\infty}}{R^n},$$

where  $||f||_{\infty} := \sup_{z \in C_R} |f(z)|$ .

Slogan: the *n*th Taylor coefficient of an analytic function is at most  $\sup_{|z|=R} |f|/R^n$ .

771

Proof.

- Given  $z_0 \in \Omega$ , pick the largest disc  $D_R(z_0) \subset \Omega$  and let  $C_R = \partial D_R$ .
- Then apply the integral formula.

Theorem 4.2 (The Residue Theorem).

If f is holomorphic on an open set  $\Omega$  containing a curve  $\gamma$  and its interior  $\gamma^{\circ}$ , except for finitely many poles  $\{z_k\}_{k=1}^N \subset \gamma^{\circ}$ . Then

$$\int_{\gamma} f(z) dz = 2\pi i \sum_{k=1}^{N} \operatorname{Res}_{z_k} f.$$

Proposition 4.3 (For simple poles).

If  $z_0$  is a simple pole of f, then

$$\operatorname{Res}_{z_0} f = \lim_{z \to z_0} (z - z_0) f(z).$$

Example: Let  $f(z) = \frac{1}{1+z^2}$ , then  $Res(i, f) = \frac{1}{2i}$ .

Proposition 4.4(For higher order poles).

If f has a pole  $z_0$  of order n, then

$$\operatorname{Res}_{z=z_0} f = \lim_{z \to z_0} \frac{1}{(n-1)!} \left(\frac{\partial}{\partial z}\right)^{n-1} (z-z_0)^n f(z).$$

## 5 Conformal Maps

Notation:

- $S \coloneqq \left\{ x + iy \mid x \in \mathbb{R}, \ 0 < y < \pi \right\}.$   $\mathbb{D}$  the disc
- If the upper half plane
- $X_{\frac{1}{2}}$ : a "half" version of X.

Theorem 5.1 (Classification of Conformal Maps).

There are 8 major types of conformal maps:

Type/Domains	Formula
Translation/Dilation/Rotation	$z\mapsto e^{i heta}(cz+h)$
Sectors to sectors	$z \mapsto z^n \\ 1+z$
$\mathbb{D}_{\frac{1}{2}} \longrightarrow \mathbb{H}_{\frac{1}{2}}$ , the first quadrant	$z\mapsto rac{1+z}{1-z}$
$\mathbb{H} \longrightarrow S$	$z \mapsto \log(z)$

$$\begin{array}{c} \mathbb{D}_{\frac{1}{2}} \longrightarrow S_{\frac{1}{2}} & z \mapsto \log(z) \\ S_{\frac{1}{2}} \longrightarrow \mathbb{D}_{\frac{1}{2}} & z \mapsto e^{iz} \\ \mathbb{D}_{\frac{1}{2}} \longrightarrow \mathbb{H} & z \mapsto \frac{1}{2} \left(z + \frac{1}{z}\right) \\ S_{\frac{1}{2}} \longrightarrow \mathbb{H} & z \mapsto \sin(z) \end{array}$$

Conformal maps  $\mathbb{D} \longrightarrow \mathbb{D}$  have the form

$$g(z) = \lambda \frac{1-a}{1-\bar{a}z}, \quad |a| < 1, \quad |\lambda| = 1.$$

#### 5.1 Plane to Disc

$$\varphi : \mathbb{H} \longrightarrow \mathbb{D}$$

$$\varphi(z) = \frac{z - i}{z + i} \qquad f^{-1}(z) = i \left(\frac{1 + w}{1 - w}\right).$$

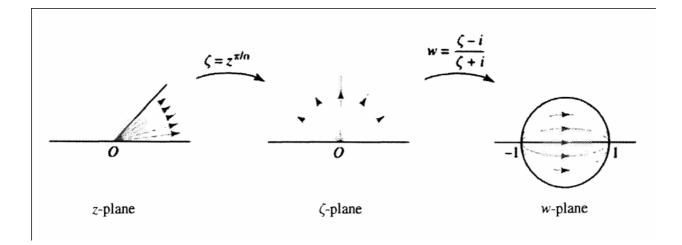
#### 5.2 Sector to Disc

For  $S_{\alpha} := \{z \in \mathbb{C} \mid 0 < \arg(z) < \alpha\}$  an open sector for  $\alpha$  some angle, first map the sector to the half-plane:

$$g: S_{\alpha} \longrightarrow \mathbb{H}$$
$$g(z) = z^{\frac{\pi}{\alpha}}.$$

Then compose with a map  $\mathbb{H} \longrightarrow \mathbb{D}$ :

$$f: S_{\alpha} \longrightarrow \mathbb{D}$$
 
$$f(z) = (\varphi \circ g)(z) = \frac{z^{\frac{\pi}{\alpha}} - i}{z^{\frac{\pi}{\alpha}} + i}.$$



#### 5.3 Strip to Disc

- Map to horizontal strip by rotation  $z \mapsto \lambda z$ .
- Map horizontal strip to sector by  $z \mapsto e^z$
- Map sector to  $\mathbb{H}$  by  $z \mapsto z^{\frac{\pi}{\alpha}}$ .
- Map  $\mathbb{H} \longrightarrow \mathbb{D}$ .

#### Theorem 5.2 (Riemann Mapping).

If  $\Omega$  is simply connected, nonempty, and not  $\mathbb{C}$ , then for every  $z_0 \in \Omega$  there exists a unique conformal map  $F: \Omega \longrightarrow \mathbb{D}$  such that  $F(z_0) = 0$  and  $F'(z_0) > 0$ .

Thus any two such sets  $\Omega_1, \Omega_2$  are conformally equivalent.

#### 6 Schwarz Reflection

#### Theorem 6.1(Schwarz Reflection).

If f is continuous and holomorphic on  $\mathbb{H}^+$  and real-valued on  $\mathbb{R}$ , then the extension defined by  $F(z) = \overline{f(\overline{z})}$  for  $z \in \mathbb{H}^-$  is a well-defined holomorphic function on  $\mathbb{C}$ .

#### Remark 1.

 $\mathbb{H}^+, \mathbb{H}^-$  can be replaced with any region symmetric about a line segment  $L \subseteq \mathbb{R}$ .

#### 7 Zeros and Poles

#### 7.1 Singularities

#### Theorem 7.1 (Riemann's Removable Singularity Theorem).

If f is holomorphic on  $\Omega$  except possibly at  $z_0$  and f is bounded on  $\Omega \setminus \{z_0\}$ , then  $z_0$  is a removable singularity.

#### 7.2 Counting Zeros

#### Theorem 7.2 (Argument Principle).

For f meromorphic in  $\gamma^{\circ}$ , if f has no poles and is nonvanishing on  $\gamma$  then

$$\Delta_{\gamma} \arg f(z) = \int_{\gamma} \frac{f'(z)}{f(z)} dz = 2\pi (Z_f - P_f),$$

where  $Z_f$  and  $P_f$  are the number of zeros and poles respectively enclosed by  $\gamma$ , counted with multiplicity.

#### Theorem 7.3 (Rouché's Theorem).

If f, g are analytic on a domain  $\Omega$  with finitely many zeros in  $\Omega$  and  $\gamma \subset \Omega$  is a closed curve surrounding each point exactly once, where |g| < |f| on  $\gamma$ , then f and f + g have the same number of zeros.

Alternatively:

Suppose f = g + h with  $g \neq 0, \infty$  on  $\gamma$  with |g| > |h| on  $\gamma$ . Then

$$\Delta_{\gamma} \arg(f) = \Delta_{\gamma} \arg(h)$$
 and  $Z_f - P_f = Z_g - P_g$ .

**Example 7.1.** • Take  $P(z) = z^4 + 6z + 3$ .

- On |z| < 2:
  - Set  $f(z) = z^4$  and g(z) = 6z + 3, then  $|g(z)| \le 6|z| + 3 = 15 < 16 = |f(z)|$ .
  - So P has 4 zeros here.
- On |z| < 1:
  - Set f(z) = 6z and  $g(z) = z^4 + 3$ .
  - Check  $|g(z)| \le |z|^4 + 3 = 4 < 6 = |f(z)|$ .
  - So P has 1 zero here.

**Example 7.2.** • Claim: the equation  $\alpha z e^z = 1$  where  $|\alpha| > e$  has exactly one solution in  $\mathbb{D}$ .

- Set  $f(z) = \alpha z$  and  $g(z) = e^{-z}$ .
- Estimate at |z| = 1 we have  $|g| = |e^{-z}| = e^{-\Re(z)} \le e^1 < |\alpha| = |f(z)|$
- f has one zero at  $z_0 = 0$ , thus so does f + g.

## 8 Linear Fractional Transformations

**Definition 8.0.1** (Linear Fractional Transformation).

A map of the following form is a linear fractional transformation:

$$T(z) = \frac{az+b}{cz+d},$$

where the denominator is assumed to not be a multiple of the numerator.

These have inverses given by

$$T^{-1}(w) = \frac{dw - b}{-cw + a}.$$

Theorem 8.1 (Cayley Transform).

The fractional linear transformation given by  $F(z) = \frac{i-z}{i+z}$  maps  $\mathbb{D} \longrightarrow \mathbb{H}$  with inverse

$$G(w) = i\frac{1-w}{1+w}.$$

Theorem 8.2 (Schwarz Lemma ).

If  $f: \mathbb{D} \longrightarrow \mathbb{D}$  is holomorphic with f(0) = 0, then

- 1.  $|f(z)| \le |z|$  for all  $z \in \mathbb{D}$
- 2.  $|f'(0)| \leq 1$ .

Moreover, if  $|f(z_0)| = |z_0|$  for any  $z_0 \in \mathbb{D}$  or |f'(0)| = 1, then f is a rotation

## 9 Appendix: Proofs of the Fundamental Theorem of Algebra

#### 9.0.1 Fundamental Theorem of Algebra: Argument Principle

- Let  $P(z) = a_n z^n + \cdots + a_0$  and g(z) = P'(z)/P(z), note P is holomorphic
- Since lim <sub>|z|→∞</sub> P(z) = ∞, there exist an R > 0 such that P has no roots in {|z| ≥ R}.
  Apply the argument principle:

$$N(0) = \frac{1}{2\pi i} \oint_{|\xi|=R} g(\xi) d\xi.$$

- Check that  $\lim_{|z\longrightarrow\infty|}zg(z)=n,$  so g has a simple pole at  $\infty$
- Then g has a Laurent series  $\frac{n}{z} + \frac{c_2}{z^2} + \cdots$  Integrate term-by-term to get N(0) = n.

#### 9.0.2 Fundamental Theorem of Algebra: Rouche's Theorem

- Let  $P(z) = a_n z^n + \cdots + a_0$
- Set  $f(z) = a_n z^n$  and  $g(z) = P(z) f(z) = a_{n-1} z^{n-1} + \dots + a_0$ , so f + g = P. Choose  $R > \max\left(\frac{|a_{n-1}| + \dots + |a_0|}{|a_n|}, 1\right)$ , then

$$\begin{split} |g(z)| &\coloneqq |a_{n-1}z^{n-1} + \dots + a_1z + a_0| \\ &\le |a_{n-1}z^{n-1}| + \dots + |a_1z| + |a_0| \quad \text{by the triangle inequality} \\ &= |a_{n-1}| \cdot |z^{n-1}| + \dots + |a_1| \cdot |z| + |a_0| \\ &= |a_{n-1}| \cdot R^{n-1} + \dots + |a_1|R + |a_0| \\ &\le |a_{n-1}| \cdot R^{n-1} + |a_{n-2}| \cdot R^{n-1} + \dots + |a_1| \cdot R^{n-1} + |a_0| \cdot R^{n-1} \quad \text{since } R > 1 \implies R^{a+b} \ge R^a \\ &= R^{n-1} \left( |a_{n-1}| + |a_{n-2}| + \dots + |a_1| + |a_0| \right) \\ &\le R^{n-1} \left( |a_n| \cdot R \right) \quad \text{by choice of } R \\ &= R^n |a_n| \\ &= |a_n z^n| \\ &\coloneqq |f(z)| \end{split}$$

• Then  $a_n z^n$  has n zeros in |z| < R, so f + g also has n zeros.

#### 9.0.3 Fundamental Theorem of Algebra: Liouville's Theorem

- Suppose p is nonconstant and has no roots, then  $\frac{1}{n}$  is entire
- Write  $g(z) := \frac{p(z)}{z^n} = a_n \left( \frac{a_{n-1}}{z} + \dots + \frac{a_0}{z^n} \right)$
- Outside a disc
  - Note  $\lim_{z \to \infty} = 0$  for the parenthesized terms, so there exists an R large enough such that  $|g(z)| \ge \frac{1}{2} |a_n|$

– Then 
$$|p(z)| \ge \frac{R^n}{2} |a_n|$$
 implies  $\frac{1}{p}$  is bounded in  $|z| > R$ 

- Inside a disc:
  - p is continuous with no roots so p is bounded below on |z| < R.
  - -p is continuous on a compact set and thus achieves a min A
  - Set  $B = \min(A, \frac{R^n}{2} |a_n|)$ , then  $p \ge B$  on |z| < R.
- Thus p is bounded below everywhere and thus  $\frac{1}{n}$  is bounded above everywhere, thus bounded.
- Thus  $\frac{1}{n}$  is constant, forcing p to be constant.

#### 9.0.4 Fundamental Theorem of Algebra: Open Mapping Theorem

- p induces a continuous map  $\mathbb{CP}^1 \longrightarrow \mathbb{CP}^1$
- The continuous image of compact space is compact;
- Since the codomain is Hausdorff space, the image is closed.
- p is holomorphic and non-constant, so by the Open Mapping Theorem, the image is open.
- Thus the image is clopen in  $\mathbb{CP}^1$ .
- The image is nonempty, since  $p(1) = \sum a_i \in \mathbb{C}$
- $\mathbb{CP}^1$  is connected
- But the only nonempty clopen subset of a connected space is the entire space.
- So p is surjective, and  $p^{-1}(0)$  is nonempty.
- So p has a root.

## 10 Appendix

$$dz = dx + i dy$$

$$d\bar{z} = dx - i dy$$

$$f_z = f_x = i^{-1} f_y$$

$$\int_0^{2\pi} e^{i\ell x} dx = \begin{cases} 2\pi & (\ell = 0) \\ 0 & (\ell \neq 0) \end{cases}.$$

#### 10.1 Misc Prerequisites

Standard forms of conic sections:

- Circle:  $x^2 + y^2 = r^2$  Ellipse:  $\left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 = 1$
- Hyperbola:  $\left(\frac{x}{a}\right)^2 \left(\frac{y}{b}\right)^2 = 1$ 
  - Rectangular Hyperbola:  $xy = \frac{c^2}{2}$ .
- Parabola:  $-4ax + y^2 = 0$ .

Mnemonic: Write  $f(x,y) = Ax^2 + Bxy + Cy^2 + \cdots$ , then consider the discriminant  $\Delta =$ 

- $\Delta < 0 \iff \text{ellipse}$  $-\Delta < 0$  and  $A = C, B = 0 \iff \text{circle}$
- $\Delta = 0 \iff \text{parabola}$
- $\Delta > 0 \iff \text{hyperbola}$

#### Completing the square:

$$x^{2} - bx = (x - s)^{2} - s^{2}$$
 where  $s = \frac{b}{2}$   
 $x^{2} + bx = (x + s)^{2} - s^{2}$  where  $s = \frac{b}{2}$ .

#### **Useful Properties**

- $\Re(z) = \frac{1}{2}(z + \bar{z}) \text{ and } \Im(z) = \frac{1}{2i}(z \bar{z}).$   $z\bar{z} = |z|^2$

• Exponential forms of cosine and sine:  

$$-\cos(\theta) = \frac{1}{2} \left( e^{i\theta} + e^{-i\theta} \right)$$

$$-\sin(\theta) = \frac{1}{2i} \left( e^{i\theta} - e^{-i\theta} \right).$$

#### **Useful Series**

$$\sum_{k=1}^{n} k = \frac{n(n+1)}{2}$$

$$\sum_{k=1}^{n} k^{2} = \frac{n(n+1)(2n+1)}{6}$$

$$\sum_{k=1}^{n} k^{3} = \frac{n^{2}(n+1)^{2}}{4}$$

$$\log(z) = \sum_{j=0}^{\infty} (-1)^{j} \frac{(z-a)^{j}}{j} \frac{\partial}{\partial z} \sum_{j=0}^{\infty} a_{j} z^{j}$$

$$= \sum_{j=0}^{\infty} a_{j+1} z^{j}$$

The sum of the interior angles of an *n*-gon is  $(n-2)\pi$ , where each angle is  $\frac{n-2}{\pi}\pi$ .

#### **Basics**

- Show that  $\frac{1}{z}\sum_{k=1}^{\infty}\frac{z^k}{k}$  converges on  $S^1\setminus\{1\}$  using summation by parts.
- Show that any power series is continuous on its domain of convergence.
- Show that a uniform limit of continuous functions is continuous.

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- Show that if f is holomorphic on  $\mathbb{D}$  then f has a power series expansion that converges uniformly on every compact  $K \subset \mathbb{D}$ .
- Show that any holomorphic function f can be uniformly approximated by polynomials.
- Show that if f is holomorphic on a connected region  $\Omega$  and  $f' \equiv 0$  on  $\Omega$ , then f is constant on  $\Omega$ .
- Show that if |f| = 0 on  $\partial \Omega$  then either f is constant or f has a zero in  $\Omega$ .
- Show that if  $\{f_n\}$  is a sequence of holomorphic functions converging uniformly to a function f on every compact subset of  $\Omega$ , then f is holomorphic on  $\Omega$  and  $\{f'_n\}$  converges uniformly to f' on every such compact subset.
- Show that if each  $f_n$  is holomorphic on  $\Omega$  and  $F := \sum f_n$  converges uniformly on every compact subset of  $\Omega$ , then F is holomorphic.
- Show that if f is once complex differentiable at each point of  $\Omega$ , then f is holomorphic.