# **Appendix**

P -values, Z -scores and funnel plots

We assume an *indicator* Y with a *target*  $\theta_0$  which specifies the desired expectation, so that  $\text{Exp}(Y|\theta_0) = \theta_0$ . The target is assumed known and measured without error.

For each observation y we calculate a standard P-value

$$p_i = P(Y > y_i \mid \theta_0, \rho_i),$$

where  $\rho_i$  is a measure of measurement precision such as the sample size. For discrete Binomial and Poisson distributions  $p_i$  could be calculated more precisely as

$$p_i = P(Y > y_i | \theta_0, \rho_i) + \frac{1}{2}P(Y = y_i | \theta_0, \rho_i).$$

These P-values are then used to test the hypothesis that the trust is 'on-target', *i.e.*  $Exp(Y) = \theta_0$ .

For indicators with suspected over-dispersion, sample sizes will generally be large enough so that the indicator can be reported as  $y_i$  and  $s_i$  = estimated standard error of  $y_i$ , although a log-transformation may be adopted for small samples. The general definition of a Z-statistic is

$$z_i = \frac{y_i - \theta_0}{s_{0i}},\tag{1}$$

where  $s_{0i}=$  standard error of  $y_i$  given the trust is on target: hence  $s_{0i}=\sqrt{\mathrm{Var}(\mathbf{Y}\,|\,\boldsymbol{\theta}_0,\rho_i)}$ . It is important to note that  $s_{0i}$  may not necessarily be the same as the reported  $s_i$ , and hence some care is required in calculating the Z-scores. For example, if  $y_i$  is an observed proportion between 0 and 1, then

$$s_i = \sqrt{\frac{y_i(1 - y_i)}{n_i}},$$

where  $n_i$  is the 'effective' sample size.  $s_i^0$  can then be estimated to be

$$s_{0i} = \sqrt{\frac{\theta_0 (1 - \theta_0)}{n_i}}.$$

The difference between these two standard errors explains why the caterpillar plots and the funnel plots can give slightly different classifications - the correct hypothesis tests are based on the funnel plots.

Funnel plots simply indicate values of Y that would reject the null hypothesis of  $\theta_0$  using the appropriate P-value. For normal approximations, funnel plot limits  $\theta_0 \pm z_p s_0$  are defined as a function of standard errors  $s_0$ , where  $z_p$  is the appropriate standard normal deviate.

### Interval target

Suppose a target interval  $(\theta_0^L, \theta_0^H)$  is assumed as the Lowest and Highest acceptable rate: these might not necessarily be symmetric about the average, and thought should be given as to what is meant by both 'poor' and 'good' performance. Then for observations within this target, no P-value can be calculated, while for observations above the target interval,  $\theta_0^H$  is used as the target, and similarly for below the interval. The funnel is therefore drawn at  $\theta_0^L - z_p s_0, \theta_0^H + z_p s_0$ .

# Over-dispersion model

Following the standard approach of generalised linear modelling [13] we shall introduce an over-dispersion factor  $\phi$  that will inflate the null variance, so that

$$\operatorname{Var}(Y \mid \theta_0, \rho, \phi) = \phi \operatorname{Var}_0(Y \mid \theta_0, \rho).$$

Suppose we have a sample of I units that we shall assume (for the present) all to be on-target.  $\phi$  may be estimated as follows:

$$\hat{\phi} = \frac{1}{I} \sum_{i} z_i^2, \tag{2}$$

where  $z_i$  is the standardised Pearson residual defined in (1).  $I\hat{\phi}$  is a standard test of heterogeneity, and is distributed as a  $\chi^2_{I-1}$  distribution under the null hypothesis that all are hitting an (estimated) target. Over-dispersion might only be assumed if  $\hat{\phi}$  is 'significantly' greater than 1, although it would be more appropriate to avoid such a preliminary significance test to avoid a discontinuity in its use. The current control limits in the funnel plot can then be inflated by a factor  $\sqrt{\hat{\phi}}$  around  $\theta_0$ . For example, based on the approximate normal control limits, over-dispersed control limits can then be plotted as

$$\theta_0 \pm z_p \sqrt{\hat{\phi}} s_0, \tag{3}$$

equivalent to creating a 'modified' Z -score  $z_i/\sqrt{\hat{\phi}}$  and comparing to standard normal deviates.

Robust 'winsorised' Z -scores can be used in estimating  $\phi$  - see below.

#### Random-effects model

This assumes that  $\text{Exp}(Y_i) = \theta_i$ , and that for 'on-target' trusts  $\theta_i$  is distributed with mean  $\theta_0$  and standard deviation  $\tau$ .  $\tau$  can be estimated using a standard 'method of moments' [14]

$$\hat{\tau}^2 = \frac{I\hat{\phi} - (I - 1)}{\sum_i w_i - \sum_k w_i^2 / \sum_i w_i}$$
 (4)

where  $w_i = 1/s_i^2$ , and  $\hat{\phi}$  is the estimate of heterogeneity: if  $\hat{\phi} < (I-1)/I$ , then  $\hat{\tau}^2$  is set to 0 and complete homogeneity is assumed. Otherwise the adjusted Z-scores are given by

$$z_i^D = \frac{y_i - \theta_0}{\sqrt{s_0^2 + \tau^2}},$$

and the funnel plot boundaries are given by

$$\theta_0 \pm z_p \sqrt{s_0^2 + \tau^2} : \tag{5}$$

a more refined procedure would base  $s_0^2$  on the estimated rate under the random-effects model.

## Winsorising z -scores

Winsorising consists of shrinking in the extreme Z-scores to some selected percentile.

- 1. Rank cases according to their naive *Z* -scores.
- 2. Identify  $Z_q$  and  $Z_{1-q}$ , the 100q% most extreme top and bottom naive Z-scores, where q might, for example, be 0.1.
- 3. Set the lowest 100q% of Z-scores to  $Z_q$ , and the highest 100q% of Z-scores to  $Z_{1-q}$ . These are the Winsorised statistics.

This retains the same number of Z-scores but discounts the influence of outliers. An alternative would be 'trimming', in which the extremes are discarded entirely. In theory an adjustment can be made to allow for this Winsorisation [9], but this is not carried out here.