Problem 1

E) Write out the equation for the line through the point $(x_0, y_0) \in \mathbb{R}^2$ with slope $a \in \mathbb{R}$ and compute the intersection of the line with the x-axis. Use this to derive the following iteration-methods: Newton-method, secant-method, and Regula Falsi.

H) First Programming Assignment

Write a function regulafalsi(f,a,b,tol), which finds the root of a function f in the interval [a,b] with the Regula Falsi. The iteration shall be repeated as long as the difference between two consecutive iteration values is greater than tol (see lecture slides). Then use your Regula-Falsi function to find, with ten digits accuracy, the smallest positive root of the function $f(x) = 1 + \cos(x) \cosh(x)$.

Hints:

- First, plot f to find a good initial value.
- The Matlab and Python command to find the absolute value is abs.
- In Matlab, to pass a function as input parameter to another function, write @ before the function name. For example: To find the fixpoint of $x = \cos(x)$ in the interval [1, 2] with accuracy 0.01 call your function with regulafalsi(@cos,1,2,0.01).

Problem 2 2 Points

- E) The equation $x = -2 \ln(x)$ has exactly one solution x_* . This solution lies in the interval (0,1). You can not find it using the fixpoint iteration-method $x_{k+1} = -2 \ln(x_k)$. (Why not?) Find an iteration-method which converges to x_* .
- H) Show that the function $g: \mathbb{R} \to \mathbb{R}$ with $g(x) = \frac{1}{2}x^2 12$ has exactly two fixpoints. Are they attracting or repelling fixpoints? Can you find them with the iteration-method $x_{k+1} = g(x_k)$?

Problem 3 6 Points

Let a > 0.

E) Show that the Heron-method

$$x_{k+1} = \frac{1}{2} \left(x_k + \frac{a}{x_k} \right), \quad x_0 > 0 \quad (*)$$

is the Newton-method to compute \sqrt{a} . Show, that this method has quadratic order of convergence.

H a) Show that the iteration-method

$$x_{k+1} = \frac{1}{n} \left((n-1) x_k + \frac{a}{x_k^{n-1}} \right), \quad x_0 > 0$$

is the Newton-method to compute $\sqrt[n]{a}$, assuming the function f(x) is given by $f(x) = x^n - a$.

H b) Show that the following iteration-method to compute \sqrt{a} has order of convergence 3.

$$x_{k+1} = \frac{1}{2} \left(x_k + \frac{a}{x_k} \right) - \frac{(x_k^2 - a)^2}{8 x_k^3}, \quad x_0 > 0.$$
 (**)

H c) Using the method (**), how many iterations are necessary to find the number $\sqrt{5}$ with 15 digits accuracy, if the initial value is $x_0 = 5$? How many iterations are necessary for the same problem, when the Newton-method (*) is used. (For the computations use Python, Matlab, or a calculator.)

Problem 4 2 Points

Write out the Newton-method to find the root of f and find the next iterated value $[x_1 \ y_1]^T$ after the start vector $[x_0 \ y_0]^T = [1 \ 1]^T$.

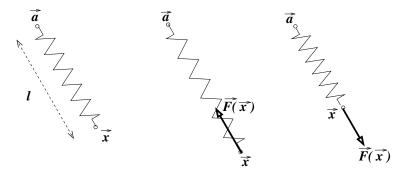
$$E) f(\begin{bmatrix} x \\ y \end{bmatrix}) = \begin{bmatrix} xy + x - y - 1 \\ xy^2 + 5 \end{bmatrix} H) f(\begin{bmatrix} x \\ y \end{bmatrix}) = \begin{bmatrix} x^3 + y - 2 \\ x + \frac{1}{y} \end{bmatrix}.$$

Second Programming Assignment

Consider a spring in \mathbb{R}^2 which is pivot-mounted at one of its endpoints $\vec{a} \in \mathbb{R}^2$. The spring constant is s > 0 and the relaxed length of the spring is $\ell > 0$. Let $\vec{F}(\vec{x})$ be the force the spring exerts on its other endpoint \vec{x} . According to Hooke's law we have

$$\vec{F}(\vec{x}) = -s(\|\vec{x} - \vec{a}\|_2 - \ell) \frac{\vec{x} - \vec{a}}{\|\vec{x} - \vec{a}\|_2} = s\left(\frac{\ell}{\|\vec{x} - \vec{a}\|_2} - 1\right) (\vec{x} - \vec{a}).$$

Explanation: The force vector $\vec{F}(\vec{x})$ points along the line between the endpoints of the spring, its absolute value is the spring constant times the difference between relaxed length and stretched length of the spring, i.e. $\|\vec{F}(\vec{x})\|_2 = s \|\vec{x} - \vec{a}\|_2 - \ell\|$. When the spring is stretched the force acts in the direction of \vec{a} . When the spring is compressed the force acts in the opposite direction, away from the point \vec{a} . See the sketch (left: relaxed spring, middle: stretched spring, right: compressed spring).



The Jacobi matrix of the force function \vec{F} is given by

$$\vec{F}'(\vec{x}) = s \left(\left(\frac{\ell}{\|\vec{x} - \vec{a}\|_2} - 1 \right) I - \ell \frac{(\vec{x} - \vec{a})(\vec{x} - \vec{a})^\top}{\|\vec{x} - \vec{a}\|_2^3} \right).$$

Notation: I is the identity matrix. $\vec{x} - \vec{a}$ is a column vector, so $(\vec{x} - \vec{a})^{\top}$ so is a row vector (transposed). The product $(\vec{x} - \vec{a})(\vec{x} - \vec{a})^{\top}$ (matrix multiplication) is a quadratic matrix.

Now, lets consider a mass m, whose center is at the position $\vec{x} \in \mathbb{R}^2$, which is attached to two springs with spring constants $s_1, s_2 > 0$ (see the Figure). The springs are fixed at the points \vec{a}_1 and \vec{a}_2 . The relaxed lengths of the springs are ℓ_1 and ℓ_2 . Three forces act on the mass: the spring forces

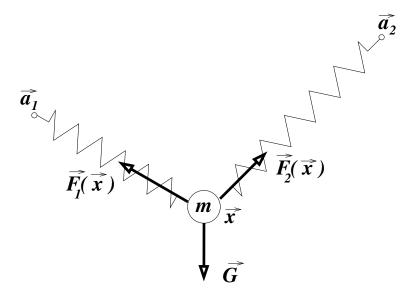
$$\vec{F}_k(\vec{x}) = -s_k (|\vec{x} - \vec{a}_k| - \ell_k) \frac{\vec{x} - \vec{a}_k}{|\vec{x} - \vec{a}_k|} = s_k \left(\frac{\ell_k}{|\vec{x} - \vec{a}_k|} - 1 \right) (\vec{x} - \vec{a}_k), \qquad k = 1, 2$$

and the gravitational force

$$\vec{G} = \begin{bmatrix} 0 \\ -g m \end{bmatrix}$$
, $g = 9.81 \, m/s^2$ (gravitational constant).

So the total force acting on the mass at the point \vec{x} is given by

$$\vec{F}_{total}(\vec{x}) = \vec{F}_1(\vec{x}) + \vec{F}_2(\vec{x}) + \vec{G}.$$



Task: Compute, using the Newton-method, the equilibrium position \vec{x} of the mass m, i.e. find the position vector \vec{x} which satisfies $\vec{F}_{total}(\vec{x}) = \vec{0}$ for the given data.

$$\vec{a}_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \qquad \vec{a}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \qquad s_1 = s_2 = 10, \qquad \ell_1 = \ell_1 = 2, \qquad m = 1.$$

As initial condition for the Newton-method, use $\vec{x}_0 = \begin{bmatrix} 0 \\ -4 \end{bmatrix}$ and (in a second run of your program) $\vec{x}_0 = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$. How can you explain that the results are different?