

# Halide



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# What is Halide?

A Functional, Domain Specific Language (DSL) designed for Image Processing (but useful for many other things)

Developed at MIT and Google since 2012

- <http://halide-lang.org>
- Produces highly efficient, parallel, vectorized code
- Used extensively by Google Camera on Pixel phones, most Pixels have specialized Halide hardware (Pixel Visual/Neural Core).

Uses llvm, backends for:

- x86, ARMv7, ARMv8, CUDA, OpenGL Compute Shaders, OpenCL
- Windows, OSX, Linux, Android, iOS

# What Makes Halide Different?

- The most significant difference between Halide and other languages is the separation of the processing pipeline into an **Algorithm** and a **Schedule**.
- The **Algorithm** describes the inputs, outputs, and sequence of operations in the pipeline.  
The **Schedule** defines how the pipeline will be mapped onto a particular processing architecture.
- Modifying the schedule is guaranteed not to change the result. This allows you to get the algorithm working and then improve performance.

# Why Halide?

- Bounds inference
  - Halide can always work out the size of any intermediate buffers and iterate over them automatically.
- Automatic parallelization
  - Function evaluations can always be computed in parallel and there can never be undetectable race conditions.
- Multiple architectures
  - Use the same algorithm but a different schedule to support mobile, desktop and GPU programming.

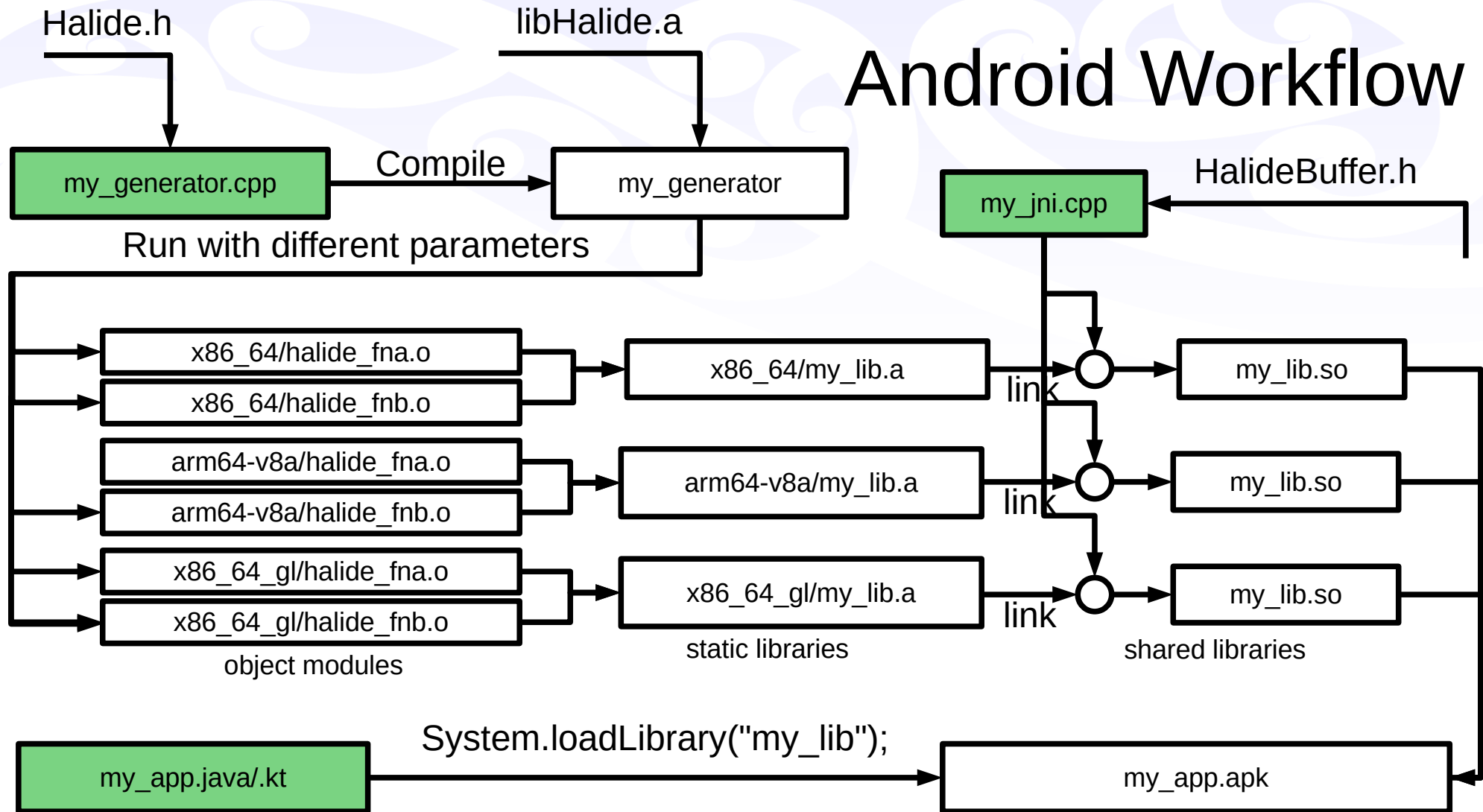
# How to write Halide code

- Halide is usually written as a C++ generator, the generator class contains a **generate()** method for the algorithm and a **schedule()** method for the schedule with inputs and outputs defined as member variables.
- This generator can produce object modules for any supported architecture and OS by running it with different parameters e.g.

```
./halide_generator -g halide_bitmap -o arm64-v8a target=arm-64-android -e o,h  
./halide_generator -g halide_vel_step -o x86_64 target=x86-64-android -e o,h  
./halide_generator -g halide_vel_step -o x86_64_gl target=x86-64-android-openglcompute -e o,h
```

- For Android you will also need some native jni “glue” to call the Halide code and manage Buffers.

# Android Workflow



# Parts of a Halide Algorithm

**Variables** – range is determined by bounds inference

```
Var x,y;
```

**Expressions**

```
Expr lum=77*red+150*green+29*blue;
```

**Functions**

```
Func sum_x;
```

```
sum_x(x,y)=sum(base(x * size + rTile, y))/size;
```

There lots of built in functions, e.g.

```
sum(), max(), clamp(), select(), mux(), lerp(), argmin()
```

**Reduction Domains** – iterate over a specified range

```
RDom rTile(0, size);
```

**Tuples** – simple data structure indexed with []

```
Tuple t={xmin,ymin};
```

# Limitations

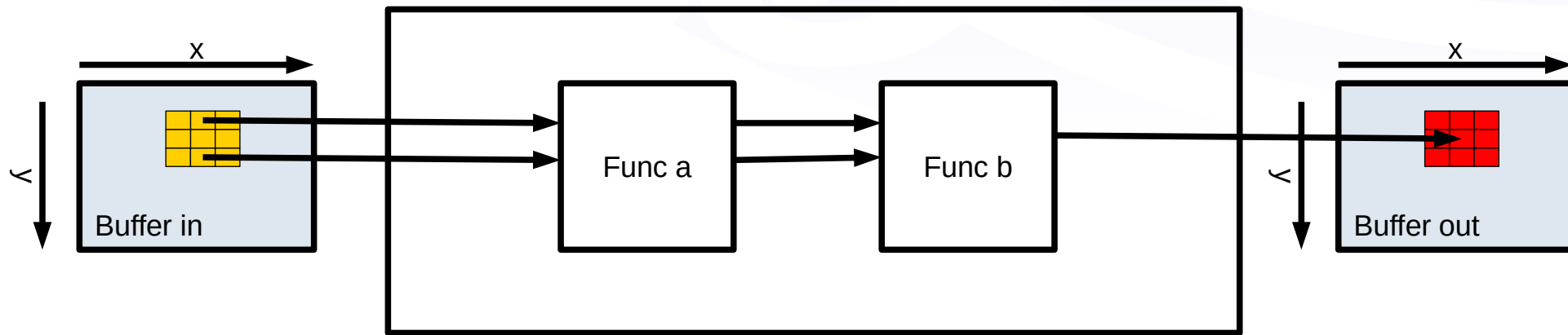
- Not a Turing complete language
  - You can only write functions that are guaranteed to terminate
  - No recursion
  - No loops (except over Var bounds or RDoms)
  - No **if** statements
- Use RDom for fixed size iteration
- Use select() or mux() instead of **if**
- Use C++ calling Halide for iteration until a condition is met



# Halide schedules

- The schedule specifies the order and manner in which the algorithm is computed using functions such as **parallel()**, **vectorize()**, **unroll()** and **reorder()**.
- The schedule can be used to specify when to compute the value of a function. **compute\_root()** will compute and store all values for a function, **compute\_at()** and **compute\_with()** allow a value to be computed inside a loop for computing another function.
- The default schedule is **compute\_inline()**, for all but the most trivial functions, this will not work well!

# Halide schedules

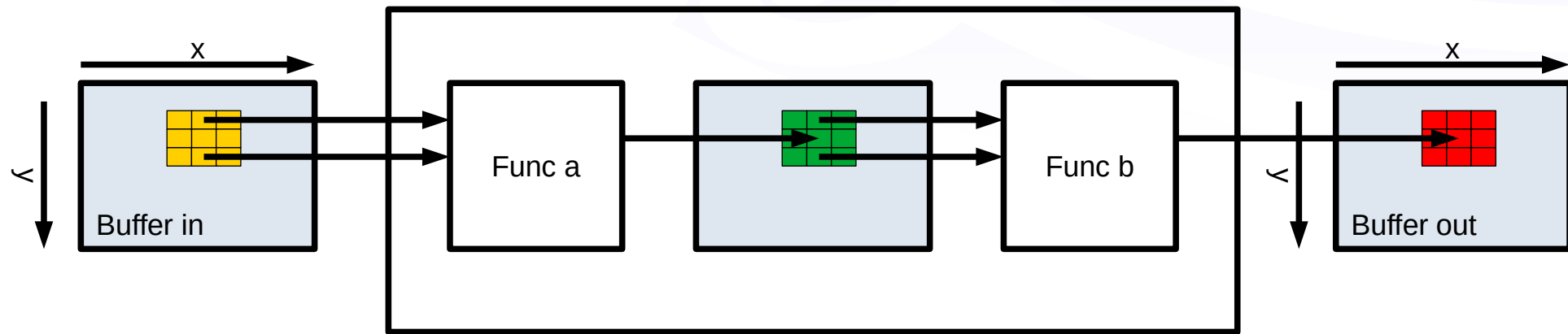


Consider two Functions, **a** and **b**

Each uses 2 pixels to get the value for each output pixel

There are many ways to compute **a** followed by **b**.

# Halide schedules

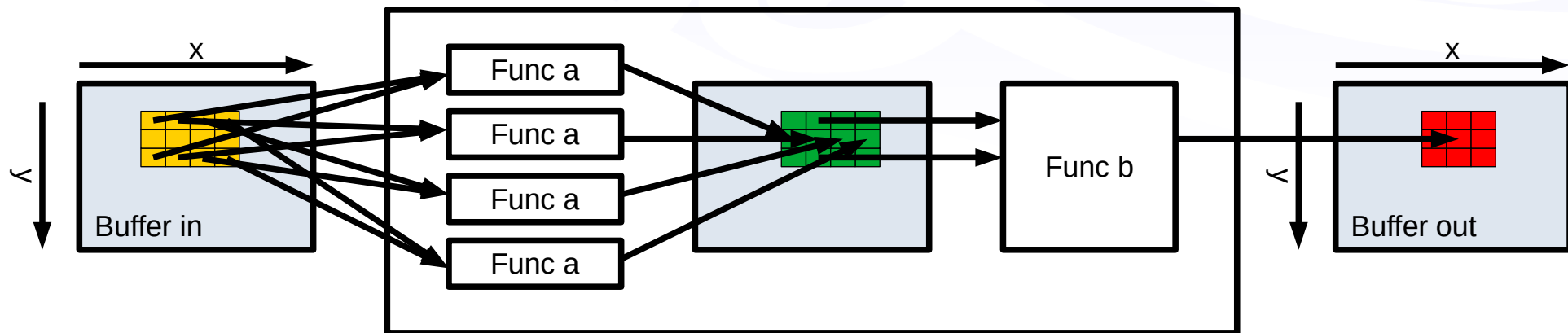


No  
parallelism

```
a.compute_root();  
b.compute_root();
```

Needs a  
new buffer.

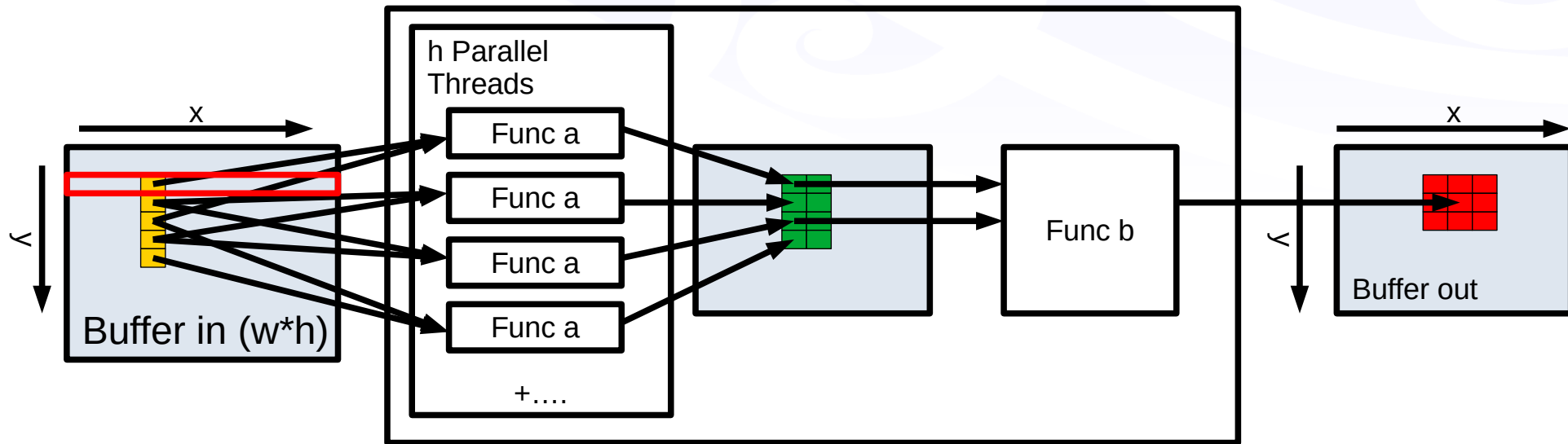
# Halide schedules



```
a.compute_root().vectorize(x,4);  
b.compute_root();
```

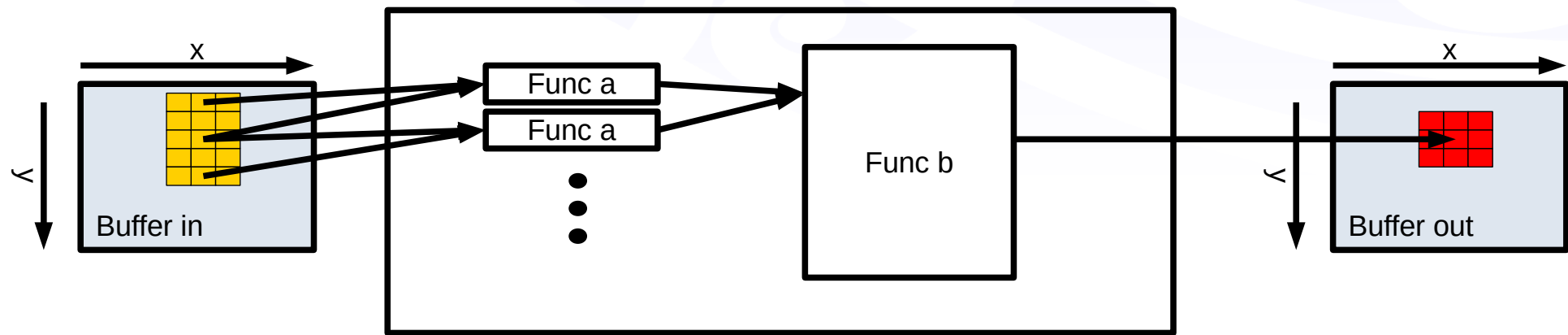
parallelism

# Halide schedules



```
a.compute_root().parallel(y);  
b.compute_root();
```

# Halide schedules

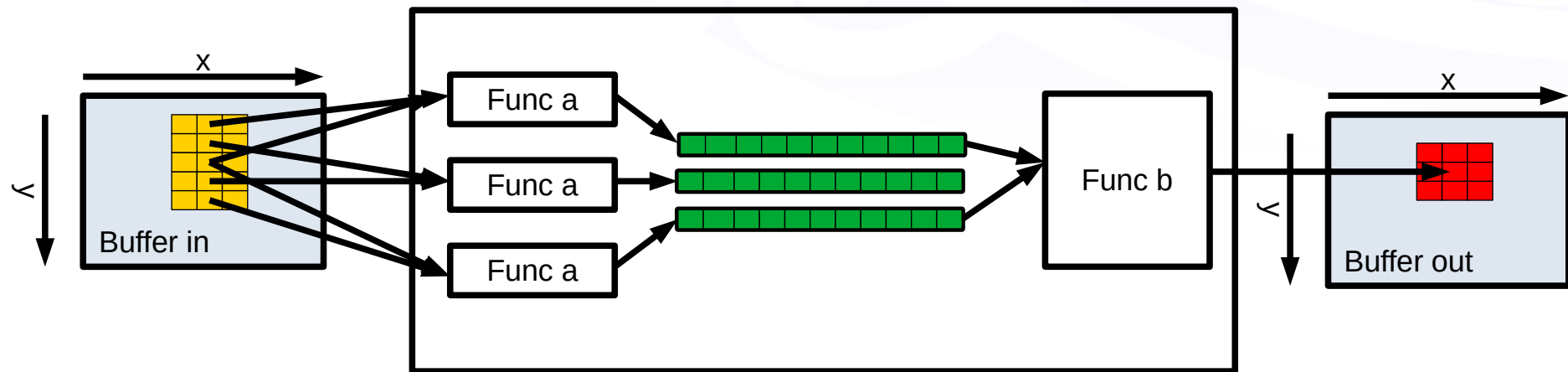


```
a.compute_inline();  
b.compute_root();
```

unnecessary because  
this is the default

Extra evaluations of **a**  
But no storage necessary

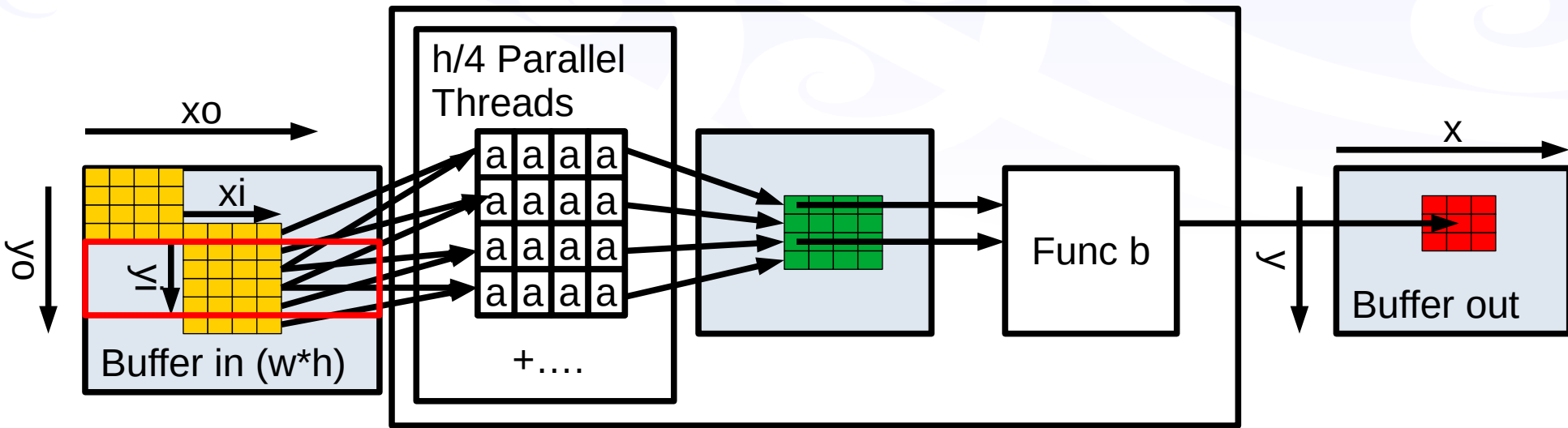
# Halide schedules



```
a.compute_at(b,y);  
b.compute_root();
```

Needs a 3 line buffer.

# Halide schedules



```
a.compute_root().tile(x, y, x0, y0, xi, yi, 4, 4)
    .parallel(y0).vectorize(xi);
b.compute_root();
```

Lots of parallelism!



# Example – Fluid Simulation Paper (GDC 2003)

## Real-Time Fluid Dynamics for Games

Jos Stam

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Email: [jstam@aw.sgi.com](mailto:jstam@aw.sgi.com),

Url: <http://www.dgp.toronto.edu/people/stam/reality/index.html>.

### Abstract

In this paper we present a simple and rapid implementation of a fluid dynamics solver for game engines. Our tools can greatly enhance games by providing realistic fluid-like effects such as swirling smoke past a moving character. The potential applications are endless. Our algorithms are based on the physical equations of fluid flow, namely the Navier-Stokes equations. These equations are notoriously hard to solve when strict physical accuracy is of prime importance. Our solvers on the other hand are geared towards visual quality. Our emphasis is on stability and speed, which means that our simulations can be advanced with arbitrary time steps. We also demonstrate that our solvers are easy to code by providing a complete C code implementation in this paper. Our algorithms run in real-time for reasonable grid sizes in both two and three dimensions on standard PC hardware, as demonstrated during the presentation of this paper at the conference.

# Real-Time Fluid Dynamics for Games

## – Jos Stam 2003

- Used by many games to display fire or smoke.
  - Solves the Navier-Stokes equations for incompressible fluids.
  - Contains a full C implementation of the algorithm.
  - Uses 3 x 2D arrays of floats - density(d), x-velocity(u), y-velocity(v)
- 3 main functions:
  - diffuse() - diffusion of density and velocity
  - advect() - change density and velocity
  - project() - make the velocity field obey the equations
- Called by dens\_step() and vel\_step()

# Android App

- <https://github.com/dzo/FluidSimulation>
  - MainActivity.java - Runs the simulation in BG thread
  - Simulation.java – Interface to the simulation
  - JavaSimulation.java – Implementation in Java
  - NativeSimulation.java – native declarations
  - SettingsActivity.java – Preference Settings
  - SimulationView.java – Custom View for drawing the simulation
  - jnisimulation.cpp – C Implementation and Halide glue
  - halide\_generator.cpp – Generator for Halide code

# C Implementation of advect()

```
void advect(float *d, float *d0, float *u, float *v, float dt) {
    int i, j, i0, j0, i1, j1;
    float x, y, s0, t0, s1, t1, dt0;

    dt0 = dt * NH;
    FOR_EACH_CELL
        x = i - dt0 * u[IX(i, j)];
        y = j - dt0 * v[IX(i, j)];
        if (x < 0.5f) x = 0.5f;
        if (x > NH + 0.5f) x = NH + 0.5f;
        i0 = (int) x;
        i1 = i0 + 1;
        if (y < 0.5f) y = 0.5f;
        if (y > NW + 0.5f) y = NW + 0.5f;
        j0 = (int) y;
        j1 = j0 + 1;
        s1 = x - i0;
        s0 = 1 - s1;
        t1 = y - j0;
        t0 = 1 - t1;
        d[IX(i, j)] = s0 * (t0 * d0[IX(i0, j0)] + t1 * d0[IX(i0, j1)]) +
                      s1 * (t0 * d0[IX(i1, j0)] + t1 * d0[IX(i1, j1)]);
    END_FOR
}
```

# Java Implementation of advect()

```
void advect(float[][] d, float[][] d0, float[][] u, float[][] v, float dt) {
    int i0, j0, i1, j1;
    float x, y, s0, t0, s1, t1, dth ;
    dth = dt * height;
    for (int i = 1; i <= height; i++) {
        for (int j = 1; j <= width; j++) {
            x = i - dth * u[i][j];
            y = j - dth * v[i][j];
            if (x < 0.5f) x = 0.5f;
            if (x > height + 0.5f) x = height + 0.5f;
            i0 = (int) x;
            i1 = i0 + 1;
            if (y < 0.5f) y = 0.5f;
            if (y > width + 0.5f) y = width + 0.5f;
            j0 = (int) y;
            j1 = j0 + 1;
            s1 = x - i0;
            s0 = 1 - s1;
            t1 = y - j0;
            t0 = 1 - t1;
            d[i][j] = s0 * (t0 * d0[i0][j0] + t1 * d0[i0][j1])
                    + s1 * (t0 * d0[i1][j0] + t1 * d0[i1][j1]);
        }
    }
}
```

# Halide Implementation of advect()

```
Func advect (Func d0, Func u, Func v, Expr dt, Expr w, Expr h) {  
    Func advected{"advected"};  
  
    Expr dt0 = dt*h;  
    Expr xx = clamp(x-dt0*v(x,y), 0.5f, w+0.5f);  
    Expr yy = clamp(y-dt0*u(x,y), 0.5f, h+0.5f);  
    Expr i0=cast<int>(xx);  
    Expr j0=cast<int>(yy);  
    Expr i1=i0+1;  
    Expr j1=j0+1;  
    Expr s1 = xx-i0;  
    Expr t1 = yy-j0;  
    advected(x,y) = lerp(lerp(d0(i0,j0),d0(i0,j1),t1),  
                        lerp(d0(i1,j0),d0(i1,j1),t1),s1);  
    return advected;  
}
```

# Halide VelStep Inputs, Outputs and Funcs

```
class VelStepGenerator : public
Halide::Generator<VelStepGenerator> {
public:
    Input <Buffer<float>> u{"u", 2};
    Input <Buffer<float>> v{"v", 2};
    Input <Buffer<float>> u0{"u0", 2};
    Input <Buffer<float>> v0{"v0", 2};
    Input<float> visc{"visc"};
    Input<float> dt{"dt"};
    Output<Buffer<float>> outputu{"outputu", 2};
    Output<Buffer<float>> outputv{"outputv", 2};

    Func uu{"uu"}, vv{"vv"}, diffU{"diffU"}, diffV{"diffV"};
    Func au0{"au0"}, av0{"av0"}, adU{"adU"}, adV{"adV"};
```

# Halide generate() for VelStep

```
void generate() {  
    Expr w = u.width() - 2;  
    Expr h = u.height() - 2;  
    uu(x,y) = u(x,y) + u0(x,y) * dt;  
    vv(x,y) = v(x,y) + v0(x,y) * dt;  
    diffU(x,y) = diffuse(u0, uu, visc, dt, w, h);  
    diffV(x,y) = diffuse(v0, vv, visc, dt, w, h);  
    project(diffU, diffV, au0, av0, w, h);  
    adU(x,y) = advect(au0, au0, av0, dt, w, h);  
    adV(x,y) = advect(av0, au0, av0, dt, w, h);  
    project(adU, adV, outputu, outputv, w, h);  
}
```



# Halide schedule() for VelStep

```
void schedule() {  
    if (auto_schedule) {  
        u.set_estimates({{0, 512},{0, 786}});  
        v.set_estimates({{0, 512},{0, 786}});  
        u0.set_estimates({{0, 512},{0, 786}});  
        v0.set_estimates({{0, 512},{0, 786}});  
        outputu.set_estimates({{0, 512},{0, 786}});  
        outputv.set_estimates({{0, 512},{0, 786}});  
        dt.set_estimate(0.1);  
        visc.set_estimate(0.00001);  
    } else {  
        good_schedule({uu, vv, au0, av0, adU, adV, outputu, outputv});  
        if(!gpu) {  
            adU.compute_with(adV, x);  
            uu.compute_with(vv, x);  
            au0.compute_with(av0, x);  
            outputu.compute_with(outputv, x);  
        }  
    }  
}
```

# good\_schedule()

```
void good_schedule(vector <Func> v) {  
    if(auto_sch)  
        return;  
    for(Func f:v) {  
        if (gpu)  
            f.compute_root().gpu_tile(x,y, xo,yo,xi, yi, 16,16);  
        else  
            f.compute_root().tile(x, y, xi, yi, 16, 16)  
                .parallel(y).vectorize(xi,16);  
    }  
}
```

# JNI code

```
JNIEXPORT void JNICALL
Java_com_example_martin_simulation_NativeSimulation_dens_1step(JNIEnv *env, jobject
thiz, jfloat diff, jfloat dt) {
    if(halide>1) {
        dens0_h.set_host_dirty();
        halide_dens_step(dens_h, dens0_h, u_h, v_h, diff, dt, dens_h);
    }
    else
        dens_step(width, height, dens, dens_prev, u, v, diff, dt);
}

JNIEXPORT void JNICALL
Java_com_example_martin_simulation_NativeSimulation_vel_1step(JNIEnv *env, jobject
thiz, jfloat visc, jfloat dt) {
    if(halide>1) {
        u0_h.set_host_dirty();
        v0_h.set_host_dirty();
        halide_vel_step(u_h, v_h, u0_h, v0_h, visc, dt, u_h, v_h);
    }
    else
        vel_step(width, height, u, v, u_prev, v_prev, visc, dt);
}
```

# Profiler – generate using -profile

halide\_vel\_step

total time: 688.737427 ms samples: 651 runs: 373 time/run: 1.846481 ms

average threads used: 6.978495

heap allocations: 312574 peak heap usage: 2986112 bytes

halide_malloc:	0.076ms	(4%)	threads:	10.074			
halide_free:	0.068ms	(3%)	threads:	9.625			
vv:	0.110ms	(5%)	threads:	3.200	peak:	589824	num: 373 avg: 589824
uu:	0.000ms	(0%)	threads:	0.000	peak:	589824	num: 373 avg: 589824
f2:	0.090ms	(4%)	threads:	4.718	peak:	595984	num: 373 avg: 595984
f1:	0.054ms	(2%)	threads:	10.157	peak:	335232	num: 9325 avg: 27936
f5:	0.127ms	(6%)	threads:	4.022	peak:	595984	num: 373 avg: 595984
f4:	0.045ms	(2%)	threads:	10.125	peak:	335232	num: 9325 avg: 27936
div:	0.116ms	(6%)	threads:	4.926	peak:	589824	num: 373 avg: 589824
fy:	0.139ms	(7%)	threads:	5.612	peak:	602176	num: 373 avg: 602176
fx:	0.082ms	(4%)	threads:	10.379	peak:	19008	num: 144724 avg: 1584
av0:	0.128ms	(6%)	threads:	6.088	peak:	595984	num: 373 avg: 595984
au0:	0.000ms	(0%)	threads:	0.000	peak:	595984	num: 373 avg: 595984
adV:	0.317ms	(17%)	threads:	8.437	peak:	595984	num: 373 avg: 595984
adU:	0.000ms	(0%)	threads:	0.000	peak:	595984	num: 373 avg: 595984
div\$1:	0.065ms	(3%)	threads:	3.869	peak:	589824	num: 373 avg: 589824
fy\$1:	0.213ms	(11%)	threads:	6.680	peak:	602176	num: 373 avg: 602176
fx\$1:	0.093ms	(5%)	threads:	10.696	peak:	19008	num: 144724 avg: 1584
outputu:	0.000ms	(0%)	threads:	0.000			
outputv:	0.116ms	(6%)	threads:	6.951			

# Makefile

```
include Makefile.inc
GENERATOR_SRC=$(HALIDE_SRC_PATH)/tools/GenGen.cpp
GENERATOR_OPTS_RT=-no_asserts-no_bounds_query
SCHEDULE=auto_schedule=false
EMIT=-e o,h,stmt
all: arm64-v8a/libnavierstokes_halide.a x86_64/libnavierstokes_halide.a \
x86_64_gl/libnavierstokes_halide.a arm64-v8a_gl/libnavierstokes_halide.a \
arm64-v8a_cl/libnavierstokes_halide.a \
define haliderules
$(1)/libnavierstokes_halide.a : $(1)/halide_dens_step.o $(1)/halide_vel_step.o \
$(1)/halide_bitmap.o
    ar r $(1)/libnavierstokes_halide.a $$^
$(1)/%.o: halide_generator
    ./$$< -g $$(*F) -o $(1) target=$(2)$(GENERATOR_OPTS_RT) $(EMIT) $(SCHEDULE)
endif
.SECONDARY: halide_generator
$(eval $(call haliderules,arm64-v8a,arm-64-android))
$(eval $(call haliderules,arm64-v8a_gl,arm-64-android-openglcompute))
$(eval $(call haliderules,arm64-v8a_cl,arm-64-android-opencl))
$(eval $(call haliderules,x86_64,x86-64-android))
$(eval $(call haliderules,x86_64_gl,x86-64-android-openglcompute))

%:: %.cpp
    $(CXX) $(CXXFLAGS) $< $(GENERATOR_SRC) -g $(LIB_HALIDE) -o $@ -lpthread \
        -fno-rtti -ldl -lz -lncurses -rdynamic -O3 $(LDFLAGS) $(LLVM_SHARED_LIBS)
```

# Demo

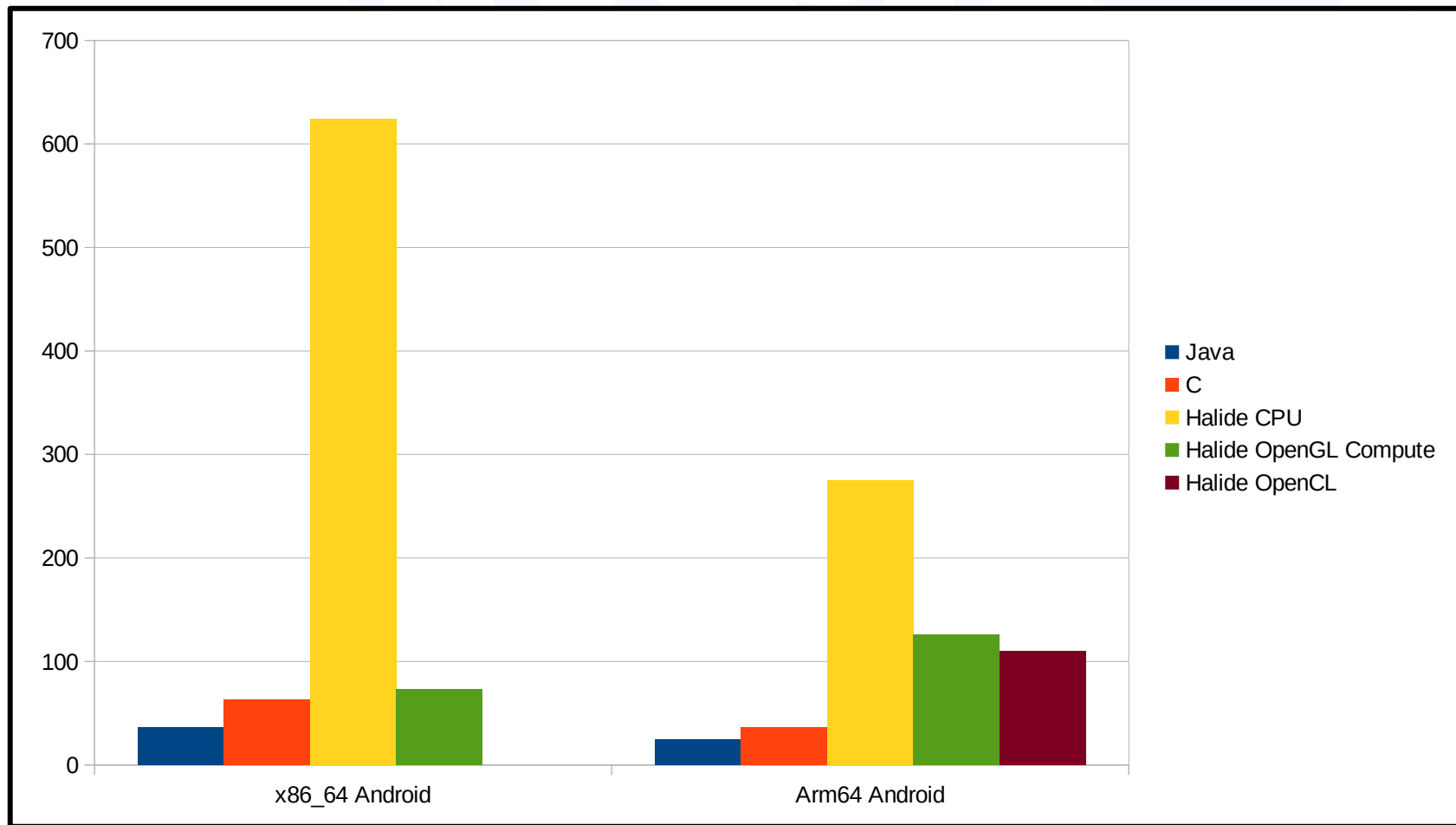
- Android Emulator on Linux
- 4 core (of 6) Ryzen 3600 4.2GHz
- 270x432 grid



# Android Performance

- x86\_64 (emulator - 4 core Ryzen 3600 4.2GHz) (270x432 grid)
  - Java: 36fps
  - C: 63fps
  - Halide CPU: 624fps (250fps with autoschedule)
  - Halide OpenGL: 73fps (not reliable)
- ARM64 (Snapdragon 870 – 8 core 1x3.2GHz, 3x2.4GHz, 4x1.8GHz) (270x547 grid)
  - Java 25fps
  - C: 36fps
  - Halide CPU: 275fps (125fps with autoschedule)
  - Halide OpenGL: 126fps
  - Halide OpenCL: 110fps (fluctuates a lot)

# Android Performance





# Desktop Performance

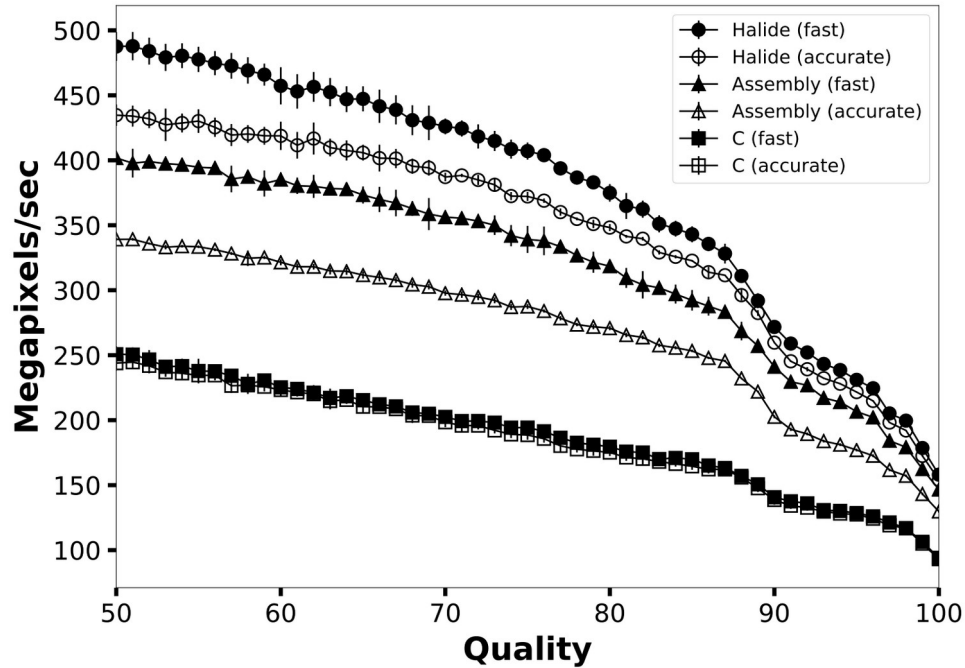
- 6 core (12 thread) Ryzen 3600 4.2GHz, 384x384 grid, GTX1650Super GPU
  - C 41fps
  - Halide CPU 466fps
  - Halide OpenGL Compute 1706fps
  - Halide OpenCL 788fps
  - Halide Cuda 2155fps

# Power Consumption (ARM64 Android)

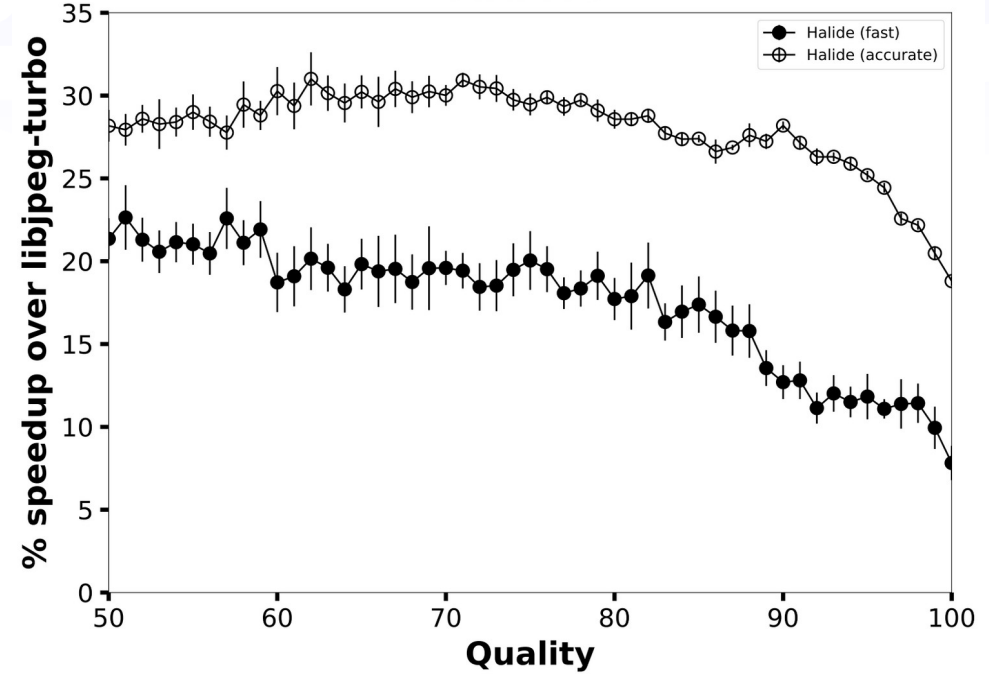
	Fps	Current Consumption	Fps multiple	Current multiple
Java	25fps	180mA	1.0	1.0
C	36fps	210mA	1.44	1.16
Halide CPU	275fps	780mA	11	4.33
Halide OpenGL	126fps	240mA	5.04	1.33
Halide OpenCL	110fps	300mA	4.4	1.66

# Another Example: JPEG Decoding

ARMv8



ARMv8



# Conclusions

- C++ is not significantly faster than Java/Kotlin with ART
- Halide can give you an order of magnitude performance increase over Java/C++
- Writing Halide is easy and fun!
- Halide CPU gives best mobile performance, but uses lots of power
- Halide with OpenGL gives good Performance and Power Consumption