

Forward Analysis of Depth-Bounded Processes

Thomas Wies **Damien Zufferey** Thomas A. Henzinger

IST Austria (Institute of Science and Technology Austria)

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From the LIFT web framework (using SCALA actors)

```
class DynamicBlogView extends CometActor {
  //...
  override def localSetup {
    //...
    (BlogCache.cache != AddBlogWatcher(this, this.blogid)) match {
      case BlogUpdate(entries) => this.blog = entries
    }
  }

  override def lowPriority : PartialFunction[Any, Unit] = {
    case BlogUpdate(entries : List[Entry]) => this.blog = entries; reRender(false)
  }
}

class BlogCache extends LiftActor {
  //...
  protected def messageHandler =
  {
    case AddBlogWatcher(me, id) =>
      val blog = cache.getOrElse(id, getEntries(id)).take(20)
      reply(BlogUpdate(blog))
      //...

    case AddEntry(e, id) =>
      cache += (id -> (e :: cache.getOrElse(id, getEntries(id))))
      sessions.getOrElse(id, Nil).foreach(_ ! BlogUpdate(cache.getOrElse(id, Nil)))

    case DeleteEntry(e, id) => //...
    case EditEntry(e, id) => //..
    case _ =>
  }
}
```

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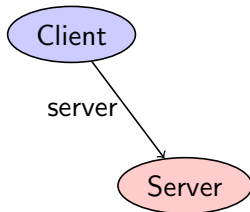
```
case DeleteEntry(e, id) => //...  
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```

```
  }  
}
```

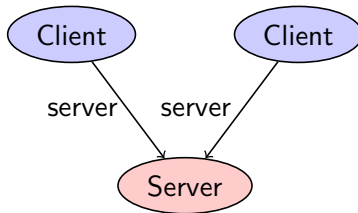
Motivation: Client-Server system (# of clients)



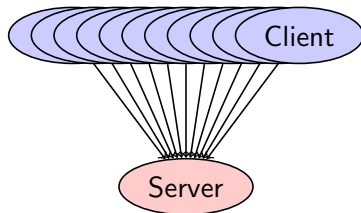
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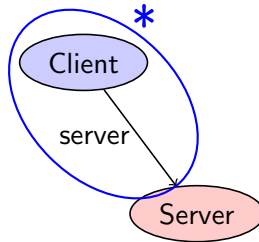
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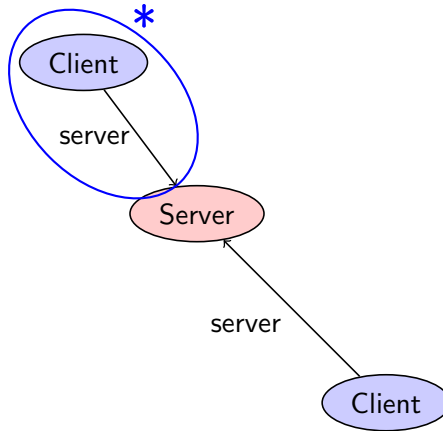
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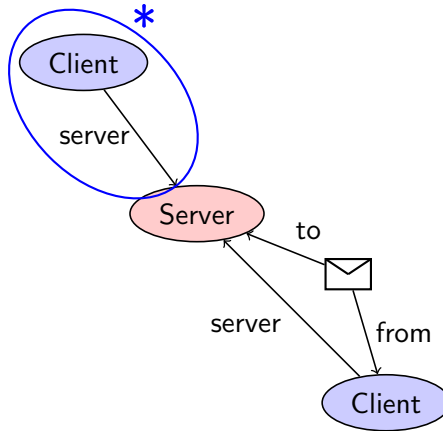
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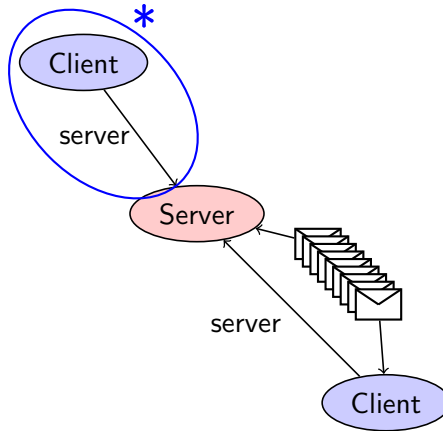
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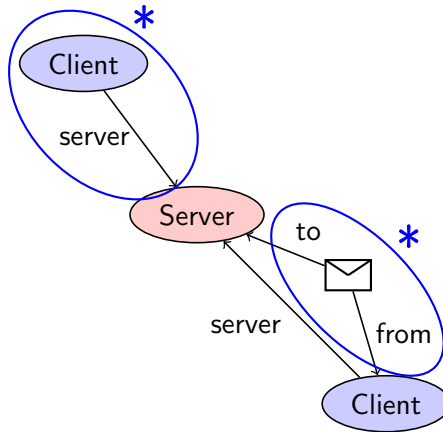
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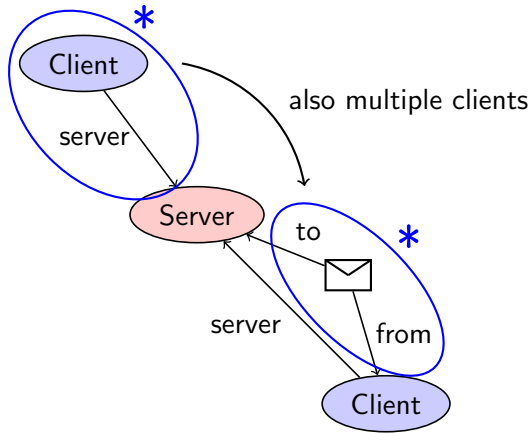
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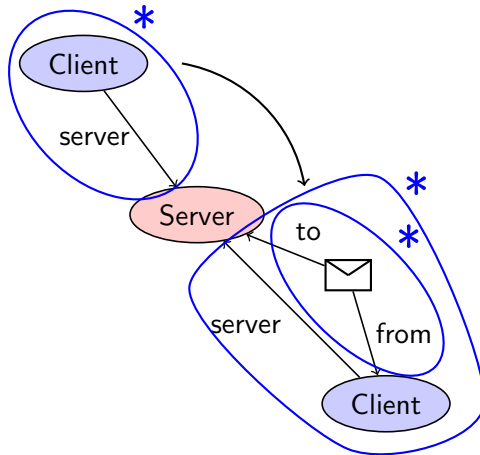
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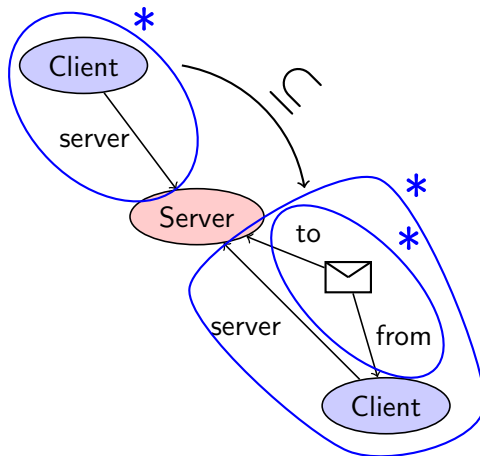
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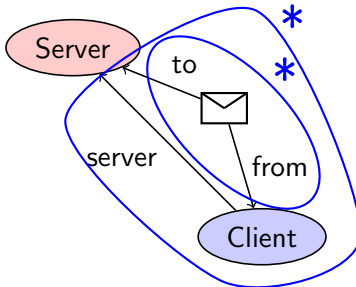
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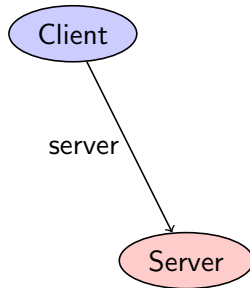
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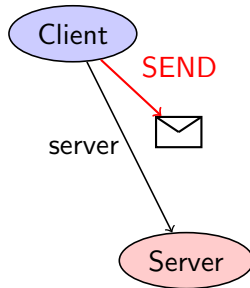
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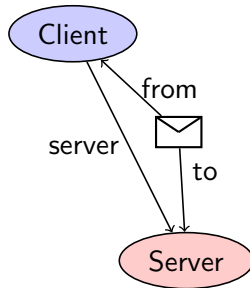
Motivation: Client-Server system (dynamic topology)



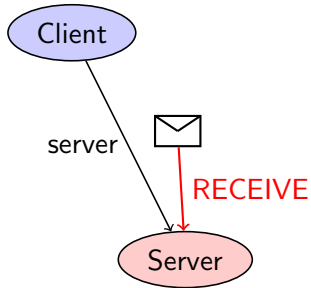
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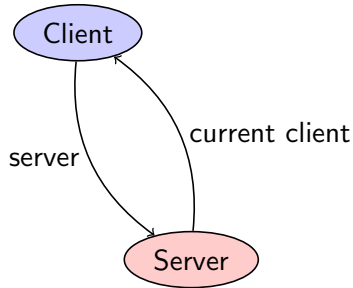
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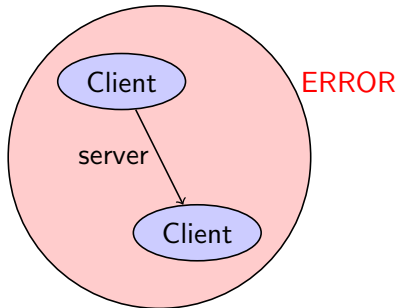
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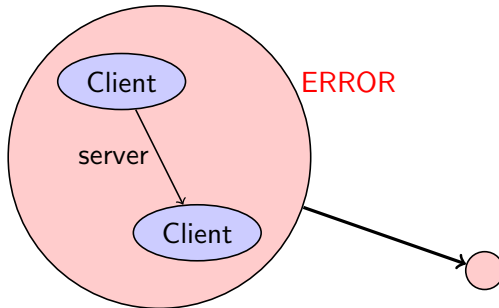
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Covering problem



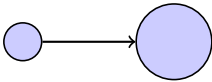
Covering problem



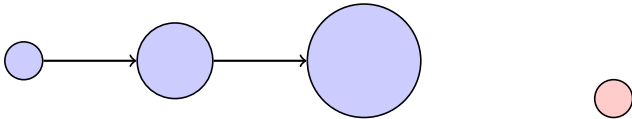
initial state



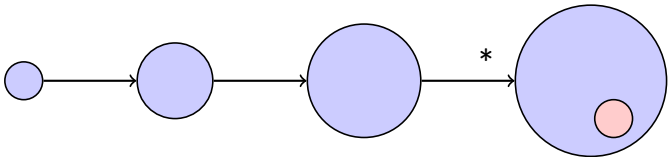
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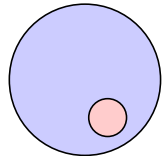
Covering problem



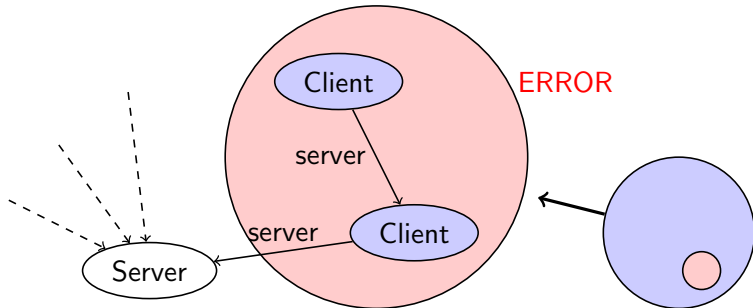
Covering problem



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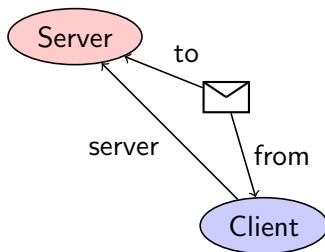
Covering problem



- π -calculus, depth-bounded systems
- WSTS
- Forward/Backward analysis
- ADL for depth-bounded systems

The π -calculus [Milner et al., 1992a, Milner et al., 1992b] is a process calculus that describes dynamic distributed computations in a message passing-setting.

$$(\nu x)(Server(x) \mid (\nu y)(Client(y, x) \mid Messages(x, y)))$$



The π -calculus is build around the notions of

Names : channels as first class values.

Threads : concurrent execution of parallel threads: $P \mid Q$.

i/o prefixes : sending/receiving messages.

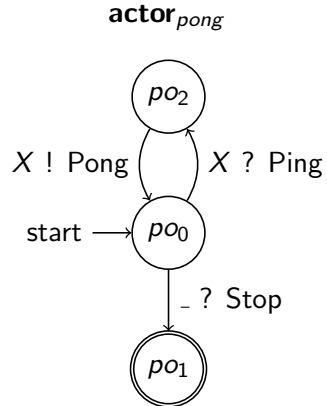
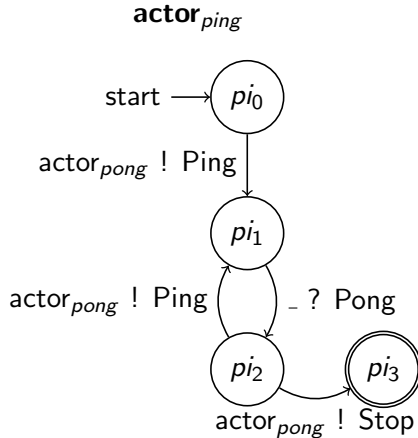
$P ::=$	$x(y).P$	(input prefix)
	$\bar{x}\langle y \rangle.P$	(output prefix)
	$\sum_i a_i(b_i).P_i$	(external choice)
	$P \mid P$	(parallel composition)
	$!P$	(replication)
	$(\nu x)P$	(name creation)
	0	(unit process)

Example (1): `scala/docs/examples/actors/pingpong.scala`

```
class Ping(count: Int, pong: Actor) extends Actor {  
  def act() {  
    var pingsLeft = count - 1  
    pong ! Ping  
    loop {  
      react {  
        case Pong =>  
          if (pingsLeft % 1000 == 0)  
            println("Ping: pong")  
          if (pingsLeft > 0) {  
            pong ! Ping  
            pingsLeft -= 1  
          } else {  
            println("Ping: stop")  
            pong ! Stop  
            exit()  
          }  
        }  
      }  
    }  
  }  
}
```

```
class Pong extends Actor {  
  def act() {  
    var pongCount = 0  
    loop {  
      react {  
        case Ping =>  
          if (pongCount % 1000 == 0)  
            println("Pong: ping "+pongCount)  
          sender ! Pong  
          pongCount += 1  
        case Stop =>  
          println("Pong: stop")  
          exit()  
        }  
      }  
    }  
  }  
}
```

Example (2): `scala/docs/examples/actors/pingpong.scala`



π -calculus: Example (1)

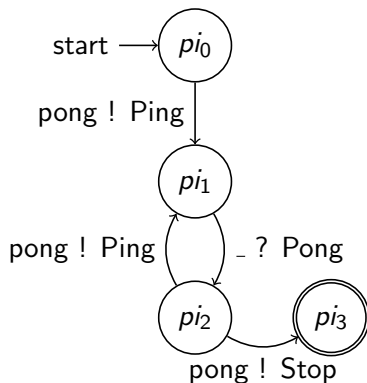
$$pi_0 = \overline{\text{pong}}_{Ping} \langle \text{ping}_{Pong} \rangle | pi_1$$

$$pi_1 = \text{ping}_{Pong}().pi_2$$

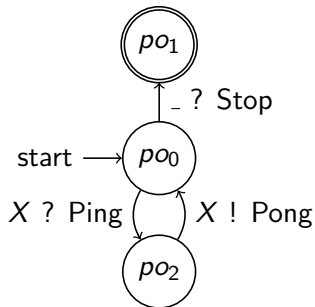
$$pi_2 = \overline{\text{pong}}_{Ping} \langle \text{ping}_{Pong} \rangle | pi_1$$

$$\oplus \overline{\text{pong}}_{Stop} \langle \rangle | pi_3$$

$$pi_3 = 0$$



$$\begin{aligned} po_0 &= \text{pong}_{\text{Stop}}().po_1 \\ &+ \text{pong}_{\text{Ping}}(X).po_2(X) \\ po_1 &= 0 \\ po_2(X) &= \overline{X}(\langle \rangle) | po_0 \end{aligned}$$



Evaluating a formula in π -calculus reduces to applying the rule:

$$\bar{a}\langle b \rangle.P \mid \sum_{i \in I} a_i(b_i).Q_i \rightarrow P \mid Q_x[b/b_x] \quad \text{where } a_x = a$$

What happens:

- channel a carries b ;
- b is sent through a and replace b_x in the continuation Q_x .

Evaluating a formula in π -calculus reduces to applying the rule:

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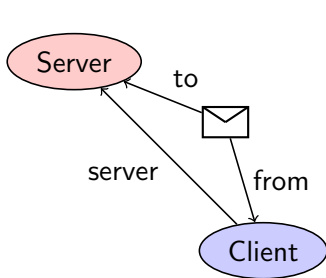
Client-Server: communication topology

$$(\nu x)(Server(x) \mid (\nu y)(Client(y, x) \mid Messages(x, y)))$$

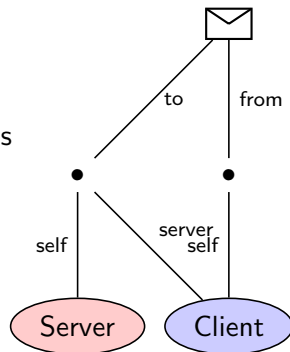
$Server(self) = self(sender) \dots$

$Client(self, server) = self() \dots$

$Messages(to, from) = \overline{to}(from)$

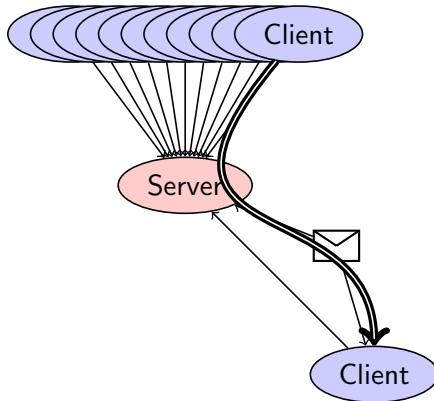


explicit names

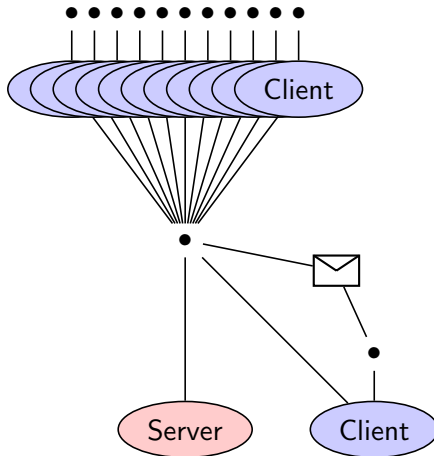


Depth-bounded systems: [Meyer, 2008] (1)

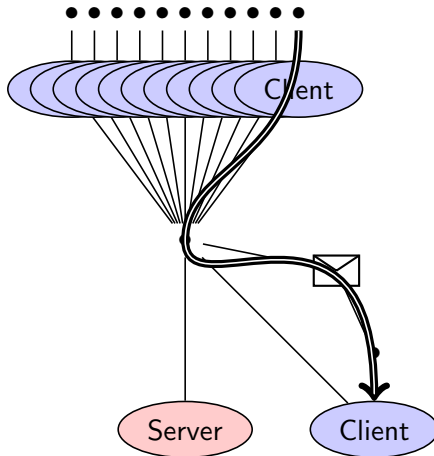
System with a bound on the longest acyclic path.
(Concretely: it is not possible to encode an infinite memory.)



Depth-bounded systems: [Meyer, 2008] (2)



Depth-bounded systems: [Meyer, 2008] (2)



Nesting of names:

$$\begin{aligned} nest_\nu((\nu x)P) &= 1 + nest_\nu(P), \\ nest_\nu(P_1 \mid P_2) &= \max \{ nest_\nu(P_1), nest_\nu(P_2) \}, \\ &\dots \end{aligned}$$

The Depth of a configuration:

$$depth(P) = \min \{ nest_\nu(Q) \mid Q \equiv P \}$$

A process \mathcal{P} is *depth-bounded* if:

$$\exists k \in \mathbb{N}, \forall P \in Reach(\mathcal{P}), \text{ depth}(P) \leq k$$

- Depth-bounded systems are well-structured transition systems [Meyer, 2008].
- Reachability is undecidable.
- Termination is decidable.
- Coverability is decidable for system of known depth.
- Coverability for any depth-bounded system was an open problem.

Our contribution:

Coverability is decidable for any depth-bounded system.

Well-structured transition system

A well-structured transition system (WSTS) is a transition system $\langle S, \rightarrow, \leq \rangle$ such that:

- \leq is a well-quasi-ordering (wqo),
i.e. well-founded + no infinite antichain.
- compatibility of \leq w.r.t. \rightarrow

$$\forall \begin{array}{c} t \xrightarrow{*} t' \\ s \longrightarrow s' \end{array} \quad \exists$$

for more detail see:

[Finkel and Schnoebelen, 2001, Abdulla et al., 1996]

A better-quasi-ordering is a wqo closed under the powerset construction.

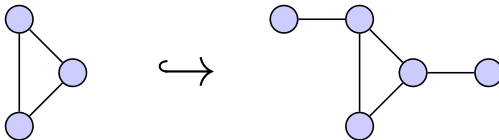
$\uparrow x = \{x' \in S \mid x \leq x'\}$ is an upward-closed set.

$\downarrow x = \{x' \in S \mid x' \leq x\}$ is an downward-closed set.

Depth bounded systems as WSTS

[Meyer, 2008] showed that depth-bounded processes are WSTS for

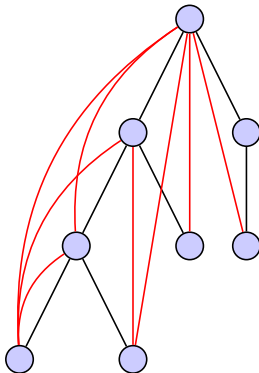
- their *reachable* configurations and
- the quasi-ordering \hookrightarrow induced by *subgraph isomorphism*.



[Meyer, 2008] showed that \hookrightarrow is a well-quasi-ordering on the reachable configurations.

We show that it is a better-quasi-ordering.

Closure of a tree



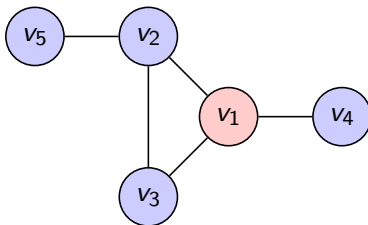
Add **edges** according to the transitive closure of the parent relation.

Every (undirected) graph is included in the closure of some tree.

Tree-Depth of a graph

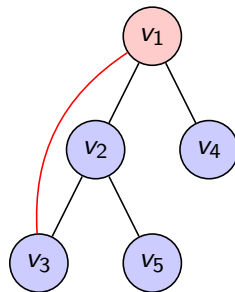
Tree-Depth

The tree-depth $\text{td}(G)$ of a graph G is the minimal height of all trees whose closure contains G .



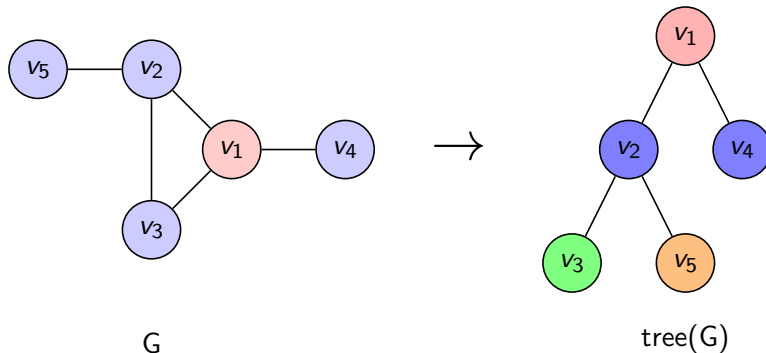
tree-depth = 2

\equiv



height = 2

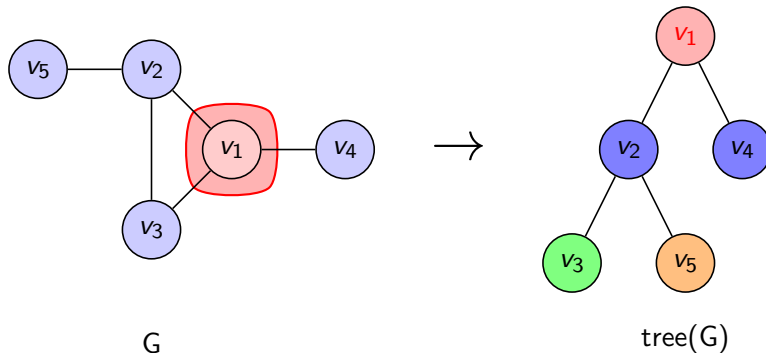
Tree encoding of depth bounded graph



The labels of $\text{tree}(G)$ are graphs.

The **number of labels** used in the encodings is **finite**.

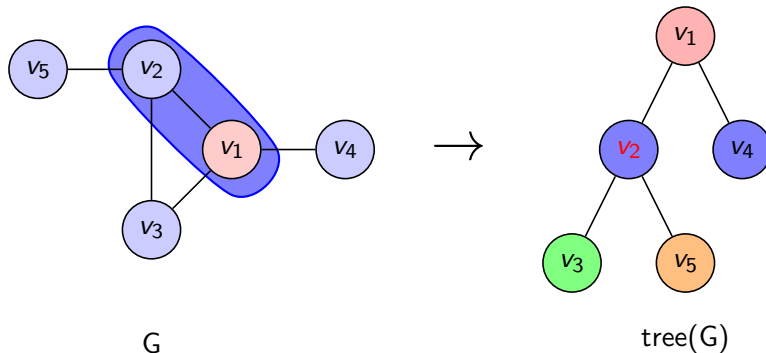
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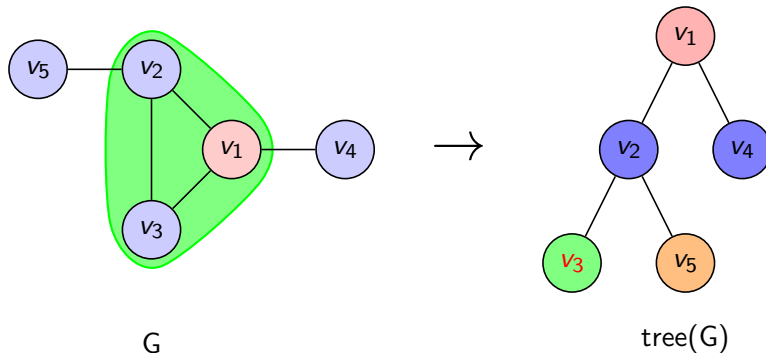
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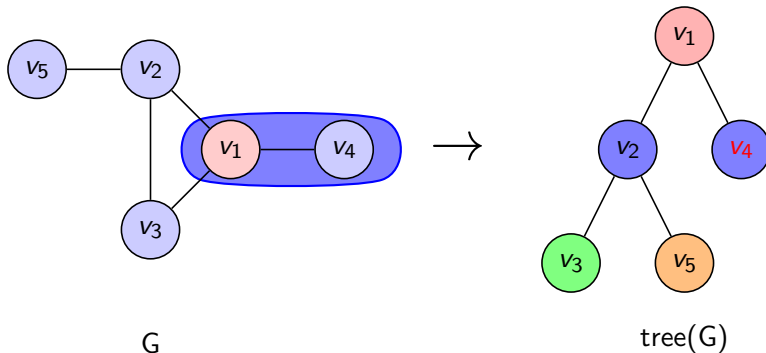
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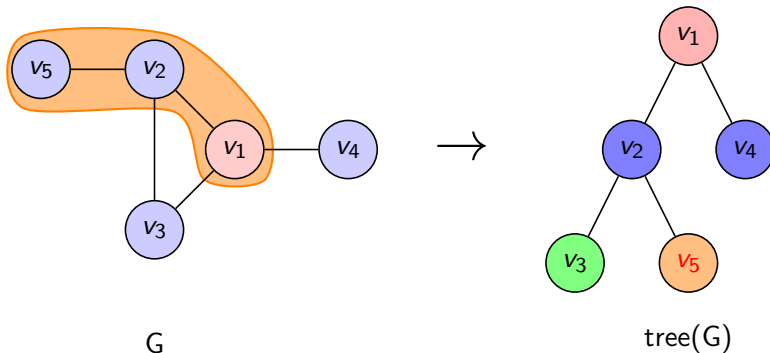
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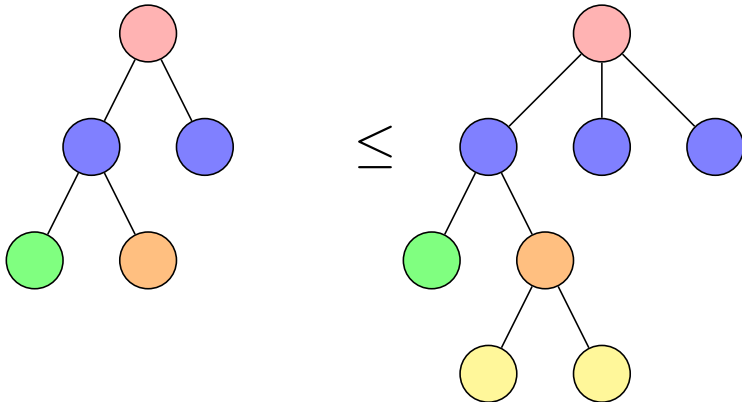
Tree encoding of depth bounded graph



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Homeomorphic tree embedding



We can show for all graphs G_1, G_2 :

$$\text{tree}(G_1) \leq \text{tree}(G_2) \text{ implies } G_1 \hookrightarrow G_2$$

Extension of Kruskal's tree theorem [Laver, 1971]

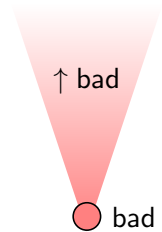
Homeomorphic tree embedding is a better-quasi-ordering on finite trees, where the labels are better-quasi-ordered.

Proposition

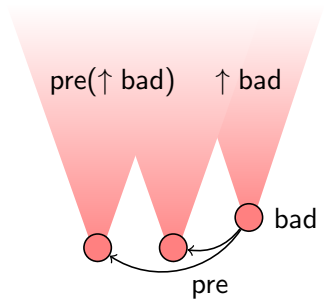
Labelled graphs of bounded tree-depth are better-quasi-ordered by the relation induced by subgraph isomorphisms.

⇒ Subgraph isomorphisms induce a better-quasi-ordering on the reachable configurations of a depth-bounded system.

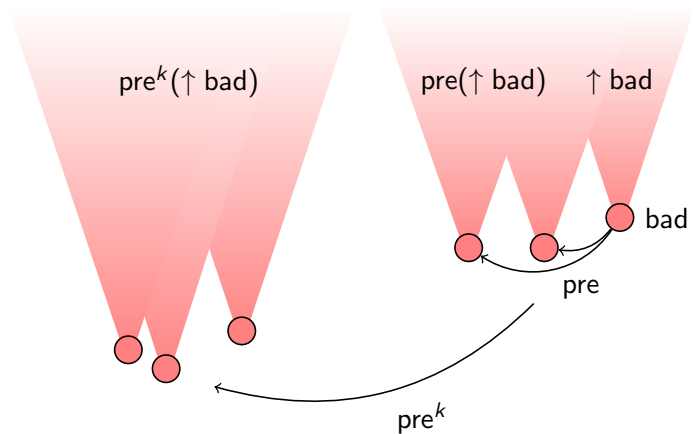
Backward analysis



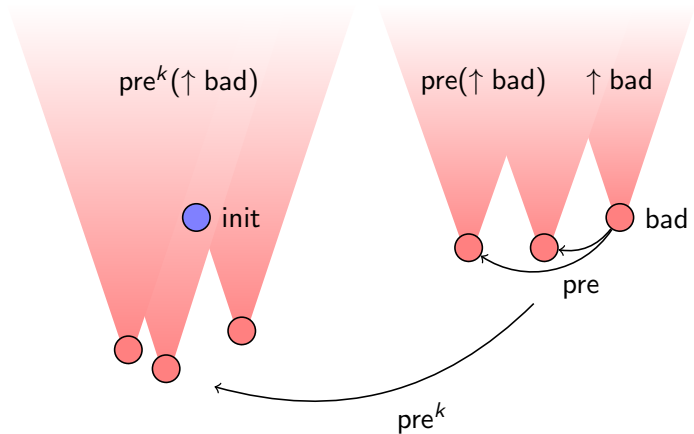
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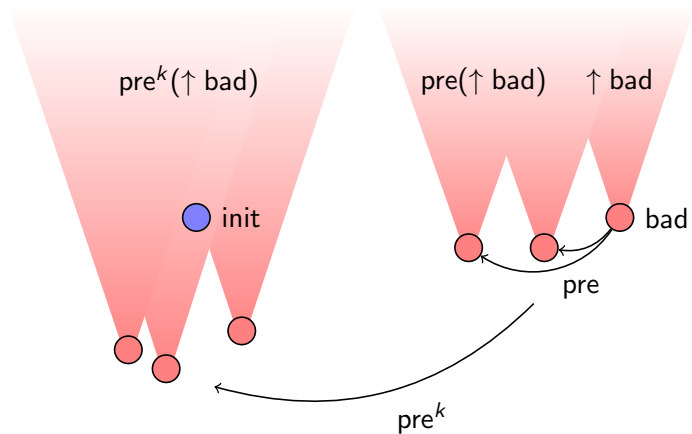


Backward analysis



Backward analysis





Termination

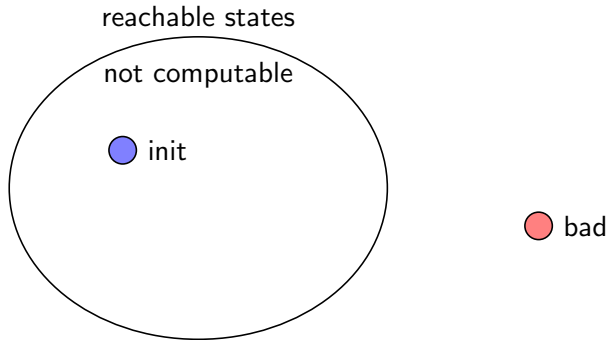
Let $I_n = \bigcup_{i=0}^n pre^i(\text{bad})$ then $I_0 \subseteq I_1 \subseteq \dots \subseteq I_n \subseteq I_{n+1} \dots$
This sequence stabilizes because a wqo has no infinite antichain.

- Backward analysis requires *pre* to be computable.
- The WSTS of a depth-bounded system is defined wrt. the *forward-reachable* configurations.
- *pre* generates unreachable configurations.
- The set of reachable configurations is not computable
- We need to know the depth to preserve the wqo.
- Backward algorithms for coverability works only with processes of *known depth*.

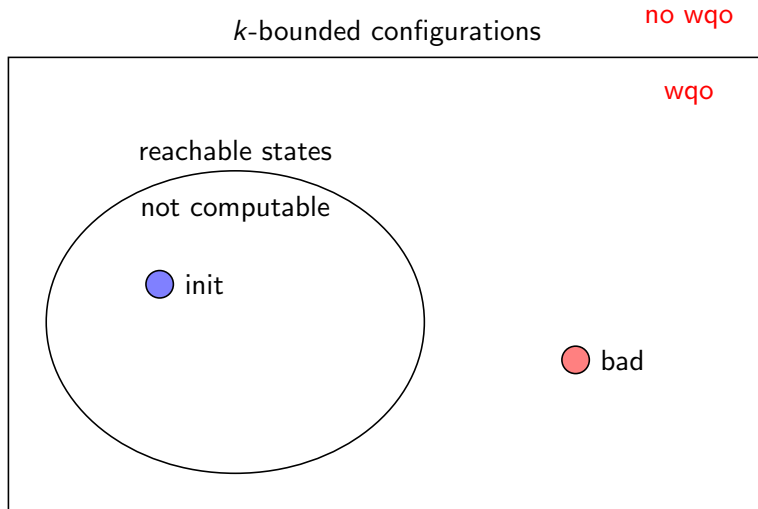
Analysis of depth-bounded systems: computing *pre*



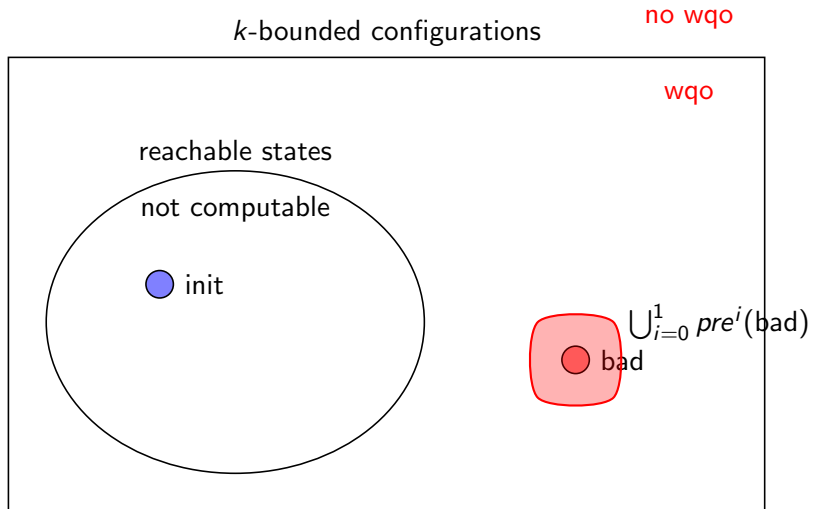
Analysis of depth-bounded systems: computing *pre*



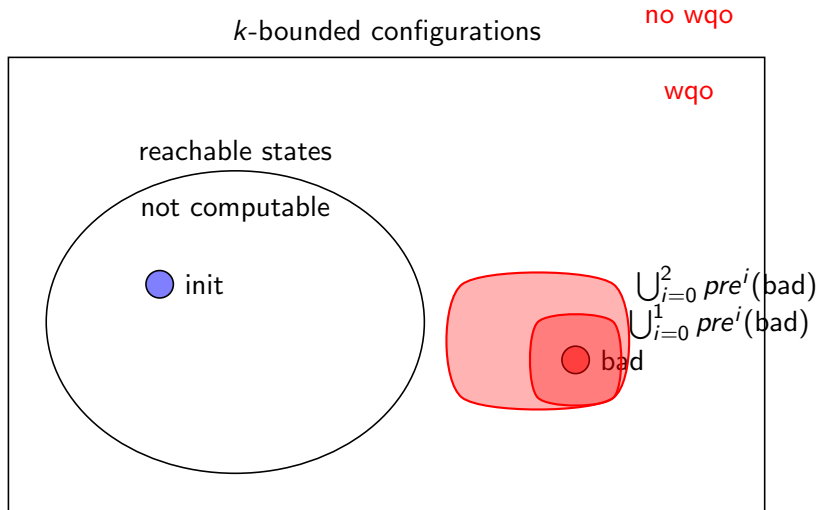
Analysis of depth-bounded systems: computing *pre*



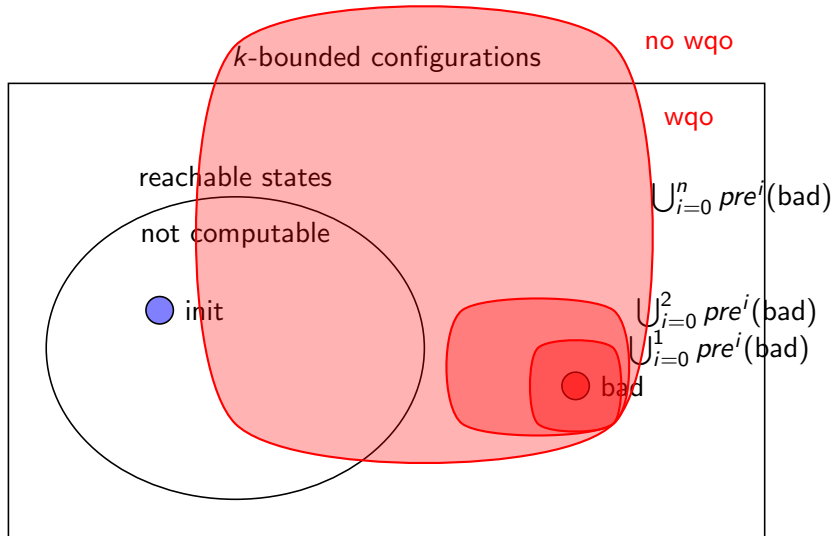
Analysis of depth-bounded systems: computing *pre*



Analysis of depth-bounded systems: computing *pre*



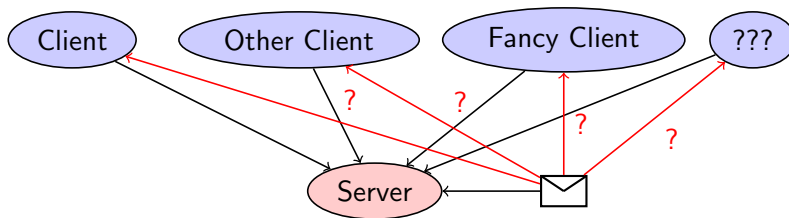
Analysis of depth-bounded systems: computing *pre*

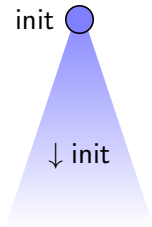


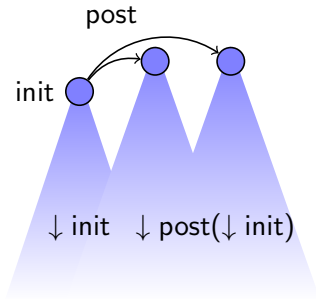
Backward analysis: aliasing problem

Backward analysis has to guess the exchanged names of each reduction step.

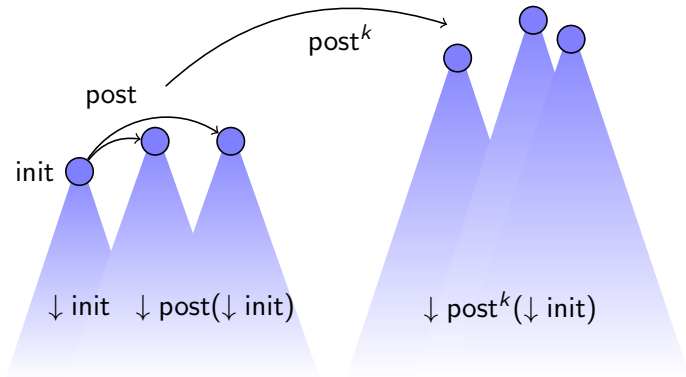
→ explosion in the nondeterminism.



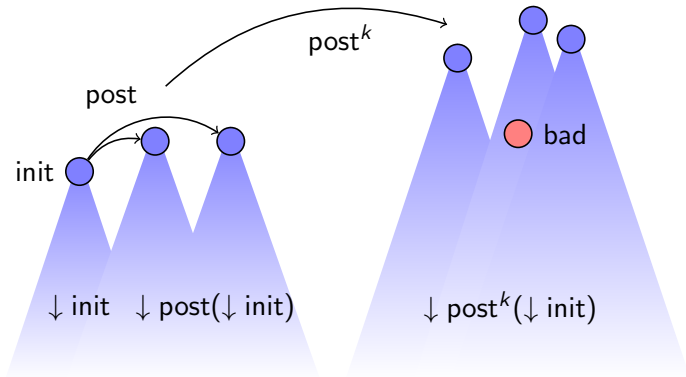




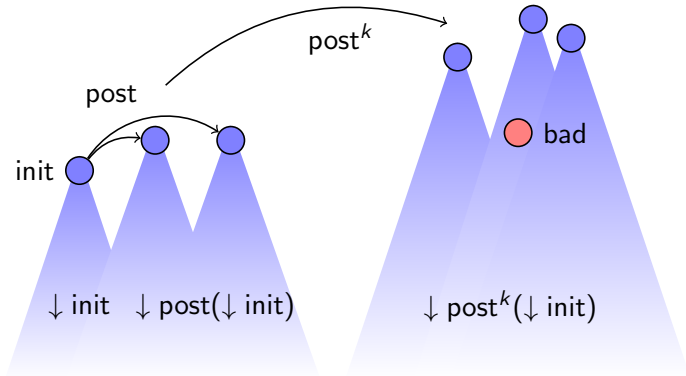
Forward analysis



Forward analysis



Forward analysis



Problem

How to represents downward-closed sets ?

- Forward algorithms terminate even if the *bound is not known*.
- The algorithm is an instance of the expand enlarge check algorithm [Geeraerts et al., 2006] that uses **adequate domain of limits** (ADL).
- [Finkel and Goubault-Larrecq, 2009b] provides a theoretical framework for the manipulation of downward-closed sets and the construction of ADL.
- We build such an ADL by extending configurations with '!'.

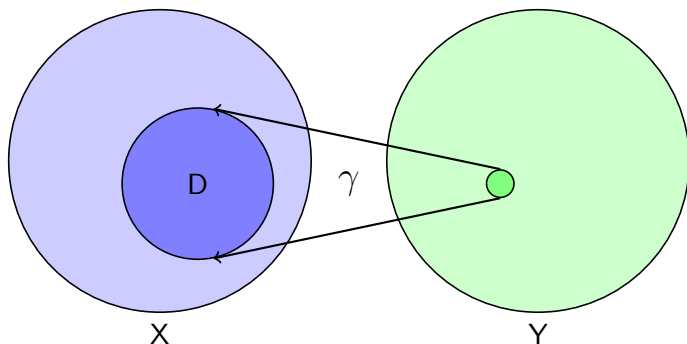
⇒ coverability is decidable for the entire class of depth-bounded systems.

Adequate Domain of Limit (1)

ADL: [Geeraerts et al., 2006]

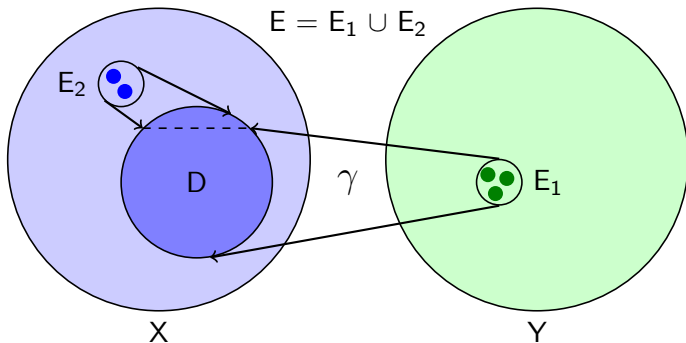
let Y an ADL for wqo set X :

For every $z \in X \cup Y$, $\gamma(z)$ is a downward-closed subset of X .

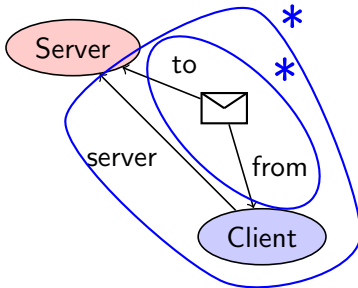


Adequate Domain of Limit (2)

Every downward-closed subset D of X is generated by a finite subset E of $Y \cup X$.



$$(\nu x)(Server(x) \mid !(\nu y)(Client(y, x) \mid !Messages(x, y)))$$



Limits configuration for depth-bounded systems

We use ' $!$ ' not as a recursion operator but as a mean to represent infinite sets of configurations.

$\mathcal{C}(PI, k)$ is the set of configurations.

$\mathcal{L}(PI, k)$ is the set of limit configurations.

Theorem

Let $k \in \mathbb{N}$ and let PI be a finite set of process identifiers. Then $(\mathcal{L}(PI, k), \sqsubseteq, \gamma)$ is a weak adequate domain of limits for the well-quasi-ordered set $(\mathcal{C}(PI, k), \leq)$.

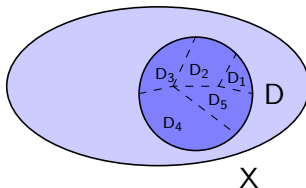
Corollary

Coverability is decidable for the entire class of depth-bounded systems.

Limits configuration for depth-bounded systems

Theorem [Finkel and Goubault-Larrecq, 2009b]

The downward-closed directed subsets of a wqo set X form an ADL for X .



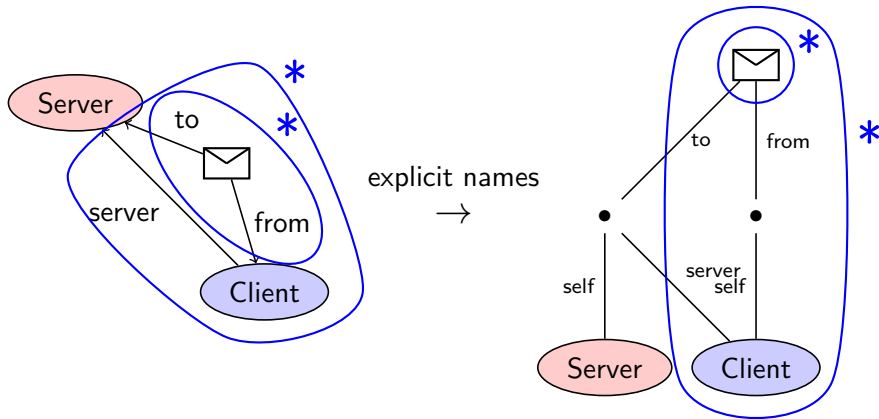
Proposition

The directed downward-closed sets of depth-bounded configurations are exactly the denotations of limit configurations.

We characterize the tree encodings of downward-closed sets of configurations in terms of the languages of *hedge automata*.

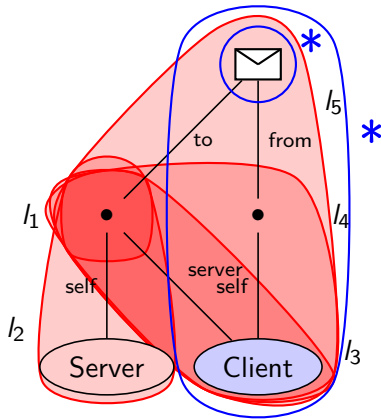
Regular language of unranked trees for Client-Server (1)

$$(\nu x)(Server(x) \mid !(\nu y)(Client(y, x) \mid Messages(x, y)))$$

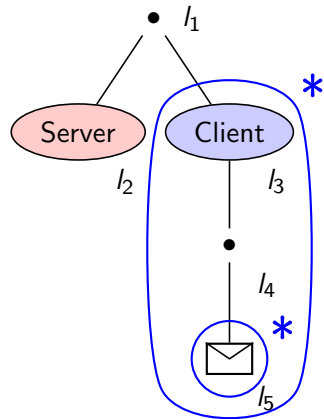


Regular language of unranked trees for Client-Server (2)

$$(\nu x)(Server(x) \mid !(\nu y)(Client(y, x) \mid !Messages(x, y)))$$

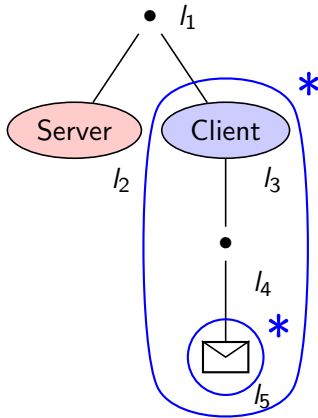


as tree
→



Regular language of unranked trees for Client-Server (3)

$$(\nu x)(Server(x) \mid !(\nu y)(Client(y, x) \mid !Messages(x, y)))$$



tree language
 \rightarrow

$$l_1(q_1 q_2^*) \rightarrow q_{final}$$

$$l_2(\epsilon) \rightarrow q_1$$

$$l_3(q_3) \rightarrow q_2$$

$$l_4(q_4^*) \rightarrow q_3$$

$$l_5(\epsilon) \rightarrow q_4$$

We started an implementation to compute (an over-approximation of) the cover using [Finkel and Goubault-Larrecq, 2009a].

Equations:

```
-----  
client1(A, B) = (A().(client1(A, B) |  
                      request1(B, A)))  
answer1(A) = (A<>.0)  
new1(A) = (A<>.0)  
request1(A, B) = (A<B>.0)  
server(A, B) = (A(C).(answer1(C) |  
                      server(A, B)) +  
                B().(ny D)  
                    (client1(D, A) |  
                     answer1(D) |  
                     new1(B) |  
                     server(A, B)))
```

Initial configuration:

```
-----  
(ny A, B)  
  (new1(A) |  
   server(B, A))
```

Computed cover:

```
(ny A, B)  
  (!((ny C)  
      (answer1(C) |  
       client1(C, B))) |  
   !((ny D)  
      (client1(D, B) |  
       request1(B, D))) |  
   new1(A) |  
   server(B, A))
```

Coverability is decidable for depth-bounded processes.

- We provide an ADL for depth-bounded processes;
- prepared the ground for a spectrum of forward algorithms for depth-bounded processes.

Questions ?



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