

Chapter 5 — Estimation

1. Distributions of Functions of RVs

- Two RVs are said to be **independent** if the realization of one of them does not change the probability distribution of the other, and vice versa. If two RVs are not independent, then they are **dependent**.
- Some rules of expectation and variance follow:
 - (a) $E(c) = c$.
 - (b) $E(c * X) = c * E(X)$.
 - (c) $E(X + c) = E(X) + c$.
 - (d) $E(X + Y) = E(X) + E(Y)$.
 - (e) $VAR(c) = 0$.
 - (f) $VAR(c * X) = c^2 VAR(X)$.
 - (g) $VAR(X + c) = VAR(X)$.
 - (h) If X and Y are independent, $VAR(X + Y) = VAR(X) + VAR(Y)$.
- A sample of size n from a population is called a **simple random sample** if every possible sample of size n is equally likely to be drawn.
- We say a sample is drawn **with replacement** if an element is replaced to the population before the next element is drawn. There is a chance the same element could be drawn more than once. Otherwise we say the sample is drawn **without replacement**, and every element can be drawn at most once.
- A collection of RVs X_1, X_2, \dots, X_n are said to be **independent and identically distributed**, or **iid**, if the following things are true:
 - They are all independent from one another. That is, the realization of any one of them does not change the probability distribution of any other one.
 - They all have exactly the same probability distribution.

2. Estimation

- Sample mean: $\hat{\mu} = \bar{X} = \frac{\sum_{i=1}^n X_i}{n}$

- Sample variance of X : $\hat{\sigma}^2 = S^2 = \frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n-1}$
- Sample standard deviation of X : $\hat{\sigma} = S = \sqrt{\frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n-1}}$
- The formula that describes how data from a sample would be used to compute a guess about a population parameter is called an **estimator**, or a **statistic**. The numerical value computed once the data is collected is called an **estimate**. An estimator is an RV, and an estimate is a realization of that RV.
- The **bias** in an estimator $\hat{\theta}$ is defined as:

$$bias(\hat{\theta}) = E(\hat{\theta}) - \theta.$$

If the the bias is equal to zero, the estimator $\hat{\theta}$ is called **unbiased** for θ . All other things being equal, smaller bias is better.

- The variance of an estimator $\hat{\theta}$ is defined as $VAR(\hat{\theta})$. All other things being equal, smaller variance is better. The square root of the variance is usually called the standard deviation or SD. However, when we are talking about estimating a parameter, we instead use the term **standard error** or **SE**, to remind us that this is the amount of error in estimation. Thus the square root of the variance of an estimator will be denoted $SE(\hat{\theta})$.
- The **mean squared error**, or **MSE**, of an estimator $\hat{\theta}$ is defined as:

$$MSE(\hat{\theta}) = VAR(\hat{\theta}) + bias(\hat{\theta})^2.$$

All other things being equal, smaller MSE is better.

- $E(\bar{X}) = E\left(\frac{X_1 + X_2 + \dots + X_n}{n}\right) = \frac{\mu + \mu + \dots + \mu}{n} = \mu.$
- $VAR(\bar{X}) = VAR\left(\frac{X_1 + X_2 + \dots + X_n}{n}\right) = \frac{\sigma^2 + \sigma^2 + \dots + \sigma^2}{n^2} = \frac{\sigma^2}{n}.$
- $SE(\bar{X}) = \sqrt{VAR(\bar{X})} = \frac{\sigma}{\sqrt{n}}.$
- Estimated standard error of \bar{X} : $\widehat{SE}(\bar{X}) = \frac{\hat{\sigma}}{\sqrt{n}} = \frac{S}{\sqrt{n}}.$

3. A **normal quantile-quantile plot** or **normal QQ plot** can be used to evaluate normality. If the data appears to be drawn from a normally distributed population, the points in the plot will usually fall on a roughly straight line.
4. The Central Limit Theorem can be stated as follows. Let X_1, X_2, \dots, X_n be a collection of iid RVs with $E(X_i) = \mu$ and $VAR(X_i) = \sigma^2$. For large enough n , the distribution of \bar{X} will be approximately normal with $E(\bar{X}) = \mu$ and $VAR(\bar{X}) = \frac{\sigma^2}{n}$. That is, $\bar{X} \sim N(\mu, \frac{\sigma^2}{n})$. The required size for n depends on the nature of the true distribution of X_i . The closer the distribution of X_i is to normal, the smaller n is required for the approximation to be good. Usually about $n = 30$ is sufficient.

5. Confidence Intervals

- The interpretation for a confidence interval constructed for a population parameter θ , is that if you had theoretically taken many samples from the population, and created a different interval for each sample, $100(1 - \alpha)\%$ of them would cover the true value of θ . This is usually shortened to saying we have $100(1 - \alpha)\%$ **confidence** that the interval covers θ .
- When using \bar{X} to estimate μ , if the X_i are normal and σ is known, or n is large enough for the CLT to work, then a $100(1 - \alpha)\%$ CI for μ is given by:

$$\bar{X} \pm z_{\alpha/2} \frac{\sigma}{\sqrt{n}}.$$

- When using \bar{X} to estimate μ , if the X_i are normal, σ is unknown, and the sample size is small, then a $100(1 - \alpha)\%$ CI for μ is given by:

$$\bar{X} \pm t_{(n-1, \alpha/2)} \frac{S}{\sqrt{n}}.$$

- The general form for a CI often looks like:

$$\text{estimate} \pm \text{multiplier} * \text{estimated SE(estimator)}$$

- When intending to create a $100(1 - \alpha)\%$ CI for μ , assuming normality and a large sample size, the n required to achieve a half-width of no larger than H is given by:

$$n = \frac{(z_{\alpha/2}^2)(\sigma^2)}{H^2}.$$

6. Bootstrap Methods

- When the sample does not look like it was drawn from a normal population, and the sample size is too small to use the CLT to approximate the sampling distribution of $t = \frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}}$, the **bootstrap** can be used to approximate the distribution of t . The steps are as follows:
 - (1) Compute the estimate of the sample mean from the data sampled, \bar{x} .
 - (2) Draw a simple random sample, with replacement, of size n , from the sample data. Call these observations $x_1^*, x_2^*, \dots, x_n^*$. Often this means that the same data point will be repeated twice in the resampling.
 - (3) Compute the mean and sd of the resampled data. Call these things \bar{x}^* and s^* .
 - (4) Compute the statistic $\hat{t} = \frac{\bar{x}^* - \bar{x}}{\frac{s^*}{\sqrt{n}}}$.
 - (5) Repeat steps 2-4 a large number of times, and compute \hat{t} from each one. This is an approximation to the sampling distribution of t .
- Using the bootstrap, a $100(1 - \alpha)\%$ CI for μ based on the approximate sampling distribution of t is given by:

$$(\bar{x} - \hat{t}_{(\alpha/2)} \frac{s}{\sqrt{n}}, \bar{x} - \hat{t}_{(1-\alpha/2)} \frac{s}{\sqrt{n}}),$$

where $\hat{t}_{(\alpha/2)}$ and $\hat{t}_{(1-\alpha/2)}$ are the $\alpha/2$ and $1 - \alpha/2$ critical values of the approximate sampling distribution.

7. Estimation of a Population Proportion

- If a sample can be considered a collection of iid RVs Y_i where the outcome of each is either zero or one, then we define the sample proportion:

$$\text{Sample proportion: } \hat{\pi} = P = \frac{\sum_{i=1}^n Y_i}{n}.$$

- $E(P) = \pi$, $VAR(P) = \frac{\pi(1-\pi)}{n}$, $SE(P) = \sqrt{\frac{\pi(1-\pi)}{n}}$.
- So long as $n\pi > 5$ and $n(1 - \pi) > 5$, the approximate distribution of P is:

$$P \sim N\left(\pi, \frac{\pi(1-\pi)}{n}\right).$$

- So long as $n\pi > 5$ and $n(1 - \pi) > 5$, an approximate $100(1 - \alpha)\%$ CI for π would be of the form:

$$P \pm z_{\alpha/2} \sqrt{\frac{P(1-P)}{n}}.$$