HOMEWORK 1

PROBLEMS RAISED IN LECTURES

Problem 1: For a free SDOF system with the EOM $\ddot{x} + 2\xi\omega_n\dot{x} + \omega_n^2x = 0$, if the damping ratio $\xi < 1$, the homogeneous solution (i.e., the transient response) can be expressed as the following complex form $x_h = e^{-\xi\omega_nt}(\alpha e^{i\omega_dt} + \beta e^{-i\omega_dt})$. Based on this, please derive the homogeneous solution in real form. If the damping ratio $\xi = 1$, we can just obtain one particular solution as $e^{-\omega_dt}$, please derive another particular solution so that the homogeneous solution can be constructed. (10 points)

Problem 2: For a SDOF system subjected to harmonic excitations, the EOM is $m\ddot{x} + c\dot{x} + kx = A_0 \sin \omega_f t$, the particular solution (i.e., the steady-state response) can be expressed as the following real form

$$x_{p} = \frac{A_{0}/k}{\sqrt{\left(1-\left(\frac{\omega_{f}}{\omega_{n}}\right)^{2}\right)^{2}+\left(2\xi\frac{\omega_{f}}{\omega_{n}}\right)^{2}}}sin(\omega_{f}t-\phi_{f}), \text{ where } \phi_{f} = arctan\left(\frac{2\xi\frac{\omega_{f}}{\omega_{n}}}{1-\left(\frac{\omega_{f}}{\omega_{n}}\right)^{2}}\right).$$

Based on this, please derive the particular solution in complex form if the excitation force is $A_0 e^{i\omega_f t}$. (7 points)

DERIVE EOM AND CALCULATE NATURAL FREQUENCY

Problem 3: A disk of mass m and radius R rolls without slip while restrained by a dashpot with coefficient of viscous damping c in parallel with a spring of stiffness k, as shown in figure. Derive the differential equation by the Newton's second law for the displacement x(t) of the disk mass center C and determine the viscous damping factor ζ and the frequency ω_n of undamped oscillation. (8 points)

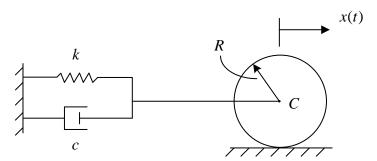


Figure: Rolling disk restrained by a spring and a dashpot

CALCULATE THE VALUE OF CRITICAL DAMPING

Problem 4: Derive the differential equation by the Newton's second law. Calculate the frequency of damped oscillation of the system shown in the following figure for the values m = 1750 kg, $c = 3500 N \cdot \text{s/m}$, $k = 7 \times 10^5 \text{N/m}$ a = 0.9m and b = 2m. Determine the value of the critical damping. (10 points)

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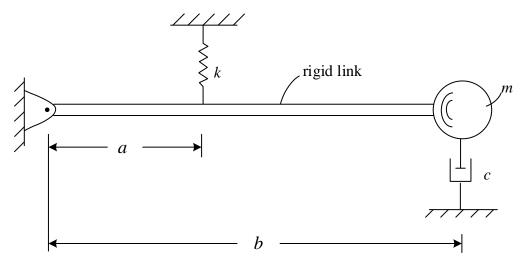
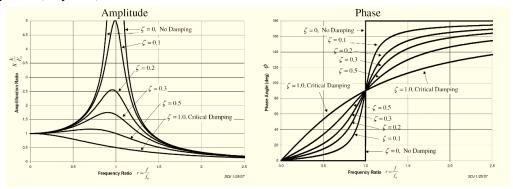


Figure: Mass supported by a spring and dashpot through a rigid bar

GENERATE FREQUENCY-RESPONSE DIAGRAM

Problem 5: Using Mathematica/MATLAB, please derive the steady-state response (i.e., the particular solution) of the following SDOF system $m\ddot{x} + c\dot{x} + kx = F_0 \sin(2\pi f_f t)$. Based on the response, please regenerate the following figures. In addition to the printed results, the Mathematica/Matlab code should be uploaded to the eLearning system. (10 points)



RESPONSE UNDER HARMONIC DISPLACEMENT EXCITATION

Problem 6: In practice, it's hard to apply a periodic force to a system. Consider the most fundamental of seismometers, which often measure the relative displacement directly using an optical transducer (e.g. a light beam deflected by a mirror on the mass). Now we will focus on another system that a vehicle traveling on a rough road. Let the vehicle velocity be uniform, v = const, and calculate the response z(t), as well as the force transmitted to the vehicle. (10 points)

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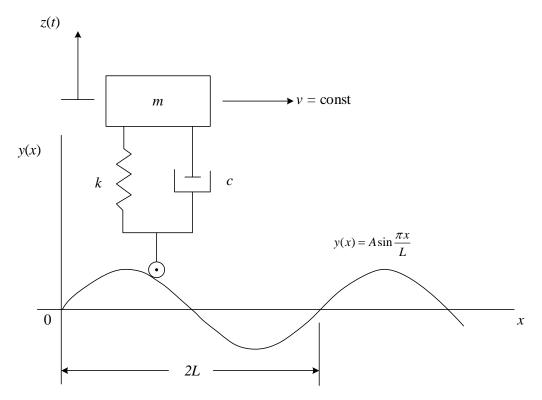


Figure: Vehicle traveling on a rough road

RESPONSE UNDER RANDOM PERIODIC EXCITATION VIA FOURIER ANALYSIS

Problem 7: Solve the differential equation

$$m\ddot{x}(t) + c\dot{x}(t) + kx(t) = f(t)$$

by means of a Fourier analysis, where f(t) is the periodic function shown in the following figure, m = 1 kg, c = 0.2 N·s/m, k = 10 N/m. Please use the function 'ode45' to generate and plot its response in MATLAB (15 points)

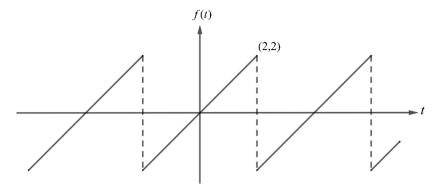


Figure: Periodic excitation

RESPONSE UNDER RANDOM NON-PERIODIC EXCITATION VIA SUPERPOSITION PRINCIPLE

Problem 8: Use the superposition principle to derive the response of the single-degree-of-

freedom system in Problem 10 but at the triangular pulse shown in. (15 points)

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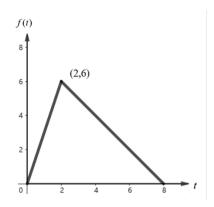


Figure: Fore in the form of a triangular pulse

RESPONSE UNDER RANDOM NON-PERIODIC EXCITATION VIA CONVOLUTION INTEGRAL

Problem 9: Derive the response of a viscously damped single-degree-of-freedom system to the force $F(t) = F_0(1 - e^{-\alpha t})u(t)$ by means of the convolution integral. The system parameters are: m = 12kg, $c = 24N \cdot \text{s/m}, k = 4800$ N/m. Use convolution integral to plot the response to a step function of magnitude $F_0 = 100$ N, $\alpha = 1$. Then, compare the result with the simulation using ode45 method. (15 points)

Hint: the impulse response of a viscously damped single-degree-of-freedom system is

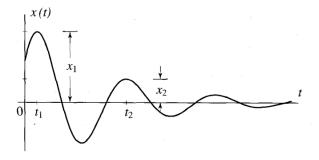
$$g(t) = \frac{1}{m\omega_d} e^{-\xi\omega_n t} \sin(\omega_d t)$$

ADDITIONAL PROBLEMS (INVERSE PROBLEM)

Additional Problem: Measurements of the response peak amplitudes of a vibrating single-degree-of-freedom system has yielded the values $x_1 = 14.88$, $x_2 = 12.99$, $x_3 = 11.49$, $x_4 = 10.56$, $x_5 = 9.16$, $x_6 = 7.85$, $x_7 = 7.04$ and $x_8 = 5.96$. Develop a least squares approach to determine the "best" viscous damping factor ζ . (10 points)

Hint: You can use some basic transformations like $z_i = ln(x_i)$ to minimize the sum of the squares of loss.

$$\frac{x_1}{x_2} = \frac{e^{-\zeta \omega_n t_1} \cos(\omega_d t_1 - \phi)}{e^{-\zeta \omega_n (t_1 + T)} \cos[\omega_d (t_1 + T) - \phi]} = \frac{e^{\zeta \omega_n T} \cos(\omega_d t_1 - \phi)}{\cos(\omega_d t_1 - \phi + 2\pi)}$$
$$= e^{\zeta \omega_n T} = e^{2\pi \zeta \omega_n / \omega_d} = e^{2\pi \zeta / \sqrt{1 - \zeta^2}}$$



ADDITIONAL PROBLEMS (INVERSE PROBLEM)

Additional Problem: Please read the "Reading Material 1", and solve the problems listed at the end (30 points)