# Synchronous Shared Memory Parallel Examples

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### **Examples**

- Data parallel prefix sum and OpenMP example
- Task parallel prefix sum and OpenMP example
- Simple heat distribution problem with OpenMP
- Iterative solver with OpenMP
- Simple heat distribution problem with HPF
- Iterative solver with HPF
- Gaussian Elimination with HPF



### **Dataparallel Prefix Sum**

Dataparallel forall: concurrent write and read, but read always fetches old value: forall has "copy-in-copy-out" semantics (viz. CRCW PRAM model)



### **OpenMP Prefix Sum v1**

*Note: use bitshift to compute*  $2^{j} = 1 << j$ 



### **Task Parallel Prefix Sum**

```
for each processor 0 \leq p < n
private j
{
  for (j = 1; j < n; j = 2*j)
    {
    if (p >= j)
        x[p] = x[p] + x[p-j];
    barrier
  }
}
```

Task/thread-parallel: best to parallelize outer loops



### **OpenMP Prefix Sum v2**

```
#pragma omp parallel shared(n,x) private(j,tid) num_threads(n)
{
   tid = omp_get_thread_num();
   for (j = 1; j < n; j = 2*j)
    {
      if (tid >= j)
         x[tid] = x[tid] + x[tid - j];
      #pragma omp barrier
   }
}
```

Uses n threads!
But what if n is large?



### **OpenMP Prefix Sum v3**

```
#pragma omp parallel shared(n,nthr,x,z) private(i,j,tid,work,lo,hi)
  #pragma omp single
                                           Note: assumes nthreads = 2^k
   nthr = omp get num threads();
  tid = omp get thread num();
  work = (n + nthr-1) / nthr;
  lo = work * tid;
 hi = lo + work;
  if (hi > n)
   hi = n;
  for (i = lo+1; i < hi; i++)
                                             Local prefix sum over x
   x[i] = x[i] + x[i-1];
  z[tid] = x[hi-1];
                                            z = local prefix sum x[hi]
  #pragma omp barrier
  for (j = 1; j < nthr; j = 2*j)
    if (tid >= j)
      z[tid] = z[tid] + z[tid - j];
                                            Global prefix sum over z
    #pragma omp barrier
  for (i = lo; i < hi; i++)
                                             Update local prefix sum x
    x[i] = x[i] + z[tid] - x[hi-1];
```



### Dataparallel Heat Distribution Problem

$$h_{i,j} = \frac{h_{i-1,j} + h_{i+1,j} + h_{i,j-1} + h_{i,j+1}}{4}$$

```
for (iter = 0; iter < limit; iter++)
  forall (i = 0; i < n; i++)
  forall (j = 0; j < n; j++)
    h[i][j] = 0.25*(h[i-1][j]+h[i+1][j]+h[i][j-1]+h[i][j+1]);</pre>
```

Dataparallel = synchronous

Corresponds to Jacobi iteration



### OpenMP Heat Distribution Problem



# Dataparallel Heat Distribution Red-black Ordering

```
for (iter = 0; iter < limit; iter++)
{
  forall (i = 0; i < n; i++)
    forall (j = 0; j < n; j++)
      if ((i+j) % 2 != 0)
        h[i][j] = 0.25*(h[i-1][j]+h[i+1][j]+h[i][j-1]+h[i][j+1]);
  forall (i = 0; i < n; i++)
    forall (j = 0; j < n; j++)
    if ((i+j) % 2 == 0)
      h[i][j] = 0.25*(h[i-1][j]+h[i+1][j]+h[i][j-1]+h[i][j+1]);
}</pre>
```

#### Dataparallel = synchronous



# OpenMP Heat Distribution Red-black Ordering

```
#pragma omp parallel shared(h,limit,n) private(iter,i,j)
{
    for (iter = 0; iter < limit; iter++)
    {
        #pragma omp for
        for (i = 0; i < n; i++)
            for (j = 0; j < n; j++)
            if ((i+j) % 2 != 0)
                h[i][j] = 0.25*(h[i-1][j]+h[i+1][j]+h[i][j-1]+h[i][j+1]);
    #pragma omp for
    for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
            if ((i+j) % 2 == 0)
                h[i][j] = 0.25*(h[i-1][j]+h[i+1][j]+h[i][j-1]+h[i][j+1]);
    }
}</pre>
```



### **Iterative Solver**

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

Jacobi iteration 
$$x_i^k = rac{1}{a_{i,i}} \left[ b_i - \sum_{j 
eq i} a_{i,j} x_j^{k-1} 
ight]$$

$$\sqrt{\sum_{i=0}^{n-1} (x_i^k - x_i^{k-1})^2} < \epsilon \qquad \left| \sum_{j=0}^{n-1} a_{i,j} x_j^k - b_i \right| < \epsilon \qquad \forall i = 0, \dots, n-1$$

Pacheco

Bertsekas and Tsitsiklis



### **Iterative Solver: Jacobi Method**

```
for (i = 0; i < n; i++)
  x[i] = b[i];
for (iter = 0; iter < limit; iter++)</pre>
  for (i = 0; i < n; i++)
    sum = -a[i][i] * x[i];
    for (j = 0; j < n; j++)
      sum = sum + a[i][j] * x[j];
    new x[i] = (b[i] - sum) / a[i][i];
  for (i = 0; i < n; i++)
    x[i] = new x[i];
```

Note: stopping criterium omitted



### Dataparallel Iterative Solver: Jacobi Method

```
for (i = 0; i < n; i++)
    x[i] = b[i];

for (iter = 0; iter < limit; iter++)
{
    forall (i = 0; i < n; i++)
        sum[i] = -a[i][i] * x[i];
    for (j = 0; j < n; j++)
        forall (i = 0; i < n; i++)
        sum[i] = sum[i] + a[i][j] * x[j];
    forall (i = 0; i < n; i++)
        x[i] = (b[i] - sum[i]) / a[i][i];
}</pre>
```

#### Dataparallel = synchronous (lock-step)

Note: stopping criterium omitted



### Task Parallel Iterative Solver: Jacobi Method

```
for each processor 0 \leq p < n
private iter, sum, j
{
    x[p] = b[p];
    for (iter = 0; iter < limit; iter++)
    {
        sum = -a[p][p] * x[p];
        for (j = 0; j < n; j++)
            sum = sum + a[p][j] * x[j];
        barrier
        x[p] = (b[p] - sum) / a[p][p];
    }
}</pre>
```



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# Iterative Solver: Jacobi Method in OpenMP

```
#pragma omp parallel shared(a,b,x,new x,n) private(iter,i,j,sum)
 #pragma omp for
 for (i = 0; i < n; i++)
   x[i] = b[i];
 for (iter = 0; iter < limit; iter++)</pre>
  {
    #pragma omp for
    for (i = 0; i < n; i++)
      sum = -a[i][i] * x[i];
      for (j = 0; j < n; j++)
        sum = sum + a[i][j] * x[j];
      new x[i] = (b[i] - sum) / a[i][i];
    #pragma omp for
    for (i = 0; i < n; i++)
      x[i] = new x[i];
```

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# OpenMP Iterative Solver Checking for Convergence

```
#pragma omp parallel shared(a,b,x,new x,n,notdone) ...
  for (iter = 0; iter < limit; iter++)</pre>
  {
     #pragma omp for reduce(||:notdone) private(sum,i,j)
     for (i = 0; i < n; i++)
    \{ sum = 0;
       for (j = 0; j < n; j++)
         sum = sum + a[i][j] * x[j];
       if (fabs(sum - b[i]) >= tolerance)
         notdone = 1;
                                                   \left| \sum_{i=0}^{n-1} a_{i,j} x_j^k - b_i \right| < \epsilon \qquad \forall i = 0, \dots, n-1
    if (notdone == 0) break;
                                                        Bertsekas and Tsitsiklis
```



### OpenMP Iterative Solver Gauss-Seidel Relaxation

```
#pragma omp parallel shared(a,b,x,n,nt) private(iter,i,j,sum,tid,work,lo,hi,loc x)
  #pragma omp single
                                        for (iter = 0; iter < limit; iter++)</pre>
   nt = omp get num threads();
  tid = omp get thread num();
                                          #pragma omp barrier
 work = (n + nt-1) / nt;
                                          for (i = lo; i < hi; i++)
 lo = work * tid;
 hi = lo + work;
                                            sum = -a[i][i] * x[i];
  if (hi > n)
                                           for (j = 0; j < n; j++)
   hi = n:
  for (i = lo; i < hi; i++)
                                             if (j >= lo && j < i)
   x[i] = b[i];
                                                sum = sum + a[i][j] * loc x[j-lo];
  #pragma omp flush(x) // need this?
                                              else
                                                sum = sum + a[i][j] * x[j];
  Departure from pure
                                            loc x[i-lo] = (b[i] - sum) / a[i][i];
  dataparallel model!
                                          #pragma omp barrier
                                          for (i = lo; i < hi; i++)
```

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x[i] = loc x[i-lo];

#pragma omp flush(x) // need this?



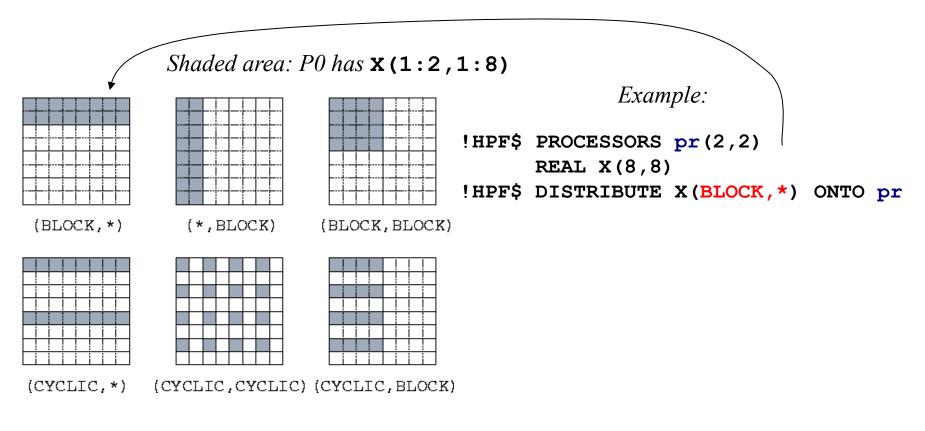
# Synchronous Computing with High-Performance Fortran

- High Performance Fortran (HPF) is an extension of Fortran 90 with constructs for parallel computing
  - □ Dataparallel FORALL
  - □ PURE (side-effect free functions)
  - □ Directives for recommended data distributions over processors
  - □ Library routines for parallel sum, prefix (scan), scattering, sorting, ...
- Uses the array syntax of Fortran 90 for as a dataparallel model of computation
  - Spreads the work of a single array computation over multiple processors
  - Allows efficient implementation on both SIMD and MIMD style architectures, shared memory and DSM
- But most users and vendors prefer OpenMP over HPF



#### **HPF**

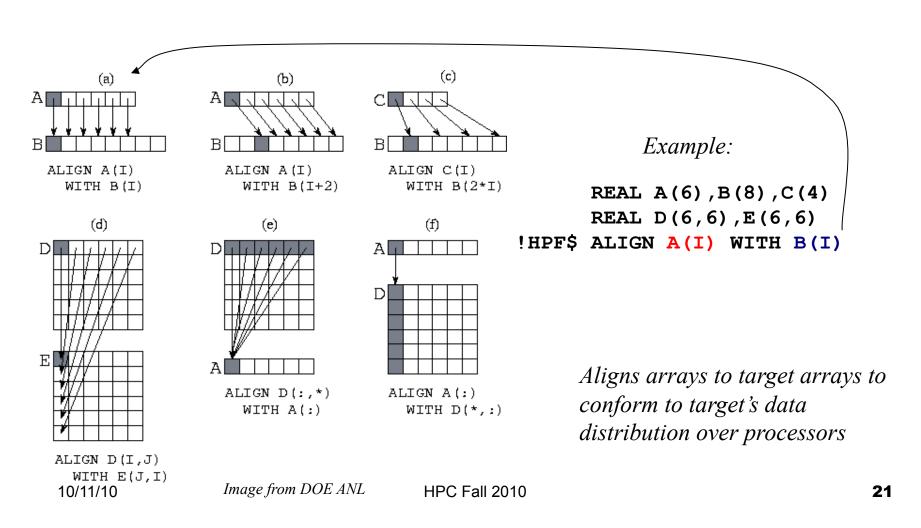
!HPF\$ PROCESSORS procname(dim1,...,dimN)
!HPF\$ DISTRIBUTE array1(dist),...,arrayM(dist) ONTO procname





### **HPF**

#### !HPF\$ ALIGN array WITH target





### **HPF Heat Distribution Problem**

$$h_{i,j} = \frac{h_{i-1,j} + h_{i+1,j} + h_{i,j-1} + h_{i,j+1}}{4}$$



# HPF Heat Distribution Problem Red-black Ordering

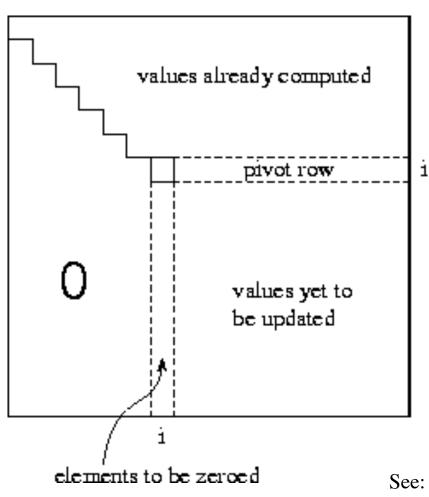
```
!HPF$ PROCESSORS pr(4)
    REAL h(100,100)
!HPF$ DISTRIBUTE h(BLOCK,*) ONTO pr
    ...
    FORALL (i=2:99, j=2:99, MOD(i+j,2).EQ.0)
        h(i,j) = 0.25*(h(i-1,j)+h(i+1,j)+h(i,j-1)+h(i,j+1))
    FORALL (i=2:99, j=2:99, MOD(i+j,2).EQ.1)
        h(i,j) = 0.25*(h(i-1,j)+h(i+1,j)+h(i,j-1)+h(i,j+1))
```



### HPF Iterative Solver: Jacobi Method



### **Gaussian Elimination**



 The original system of equations is reduced to an upper triangular form

$$Ux = y$$

where U is a matrix of size  $N \times N$  in which all elements below the diagonal are zero, and diagonal elements have the value 1

 Back substitution: the new system of equations is solved to obtain the values of x

See: http://www-unix.mcs.anl.gov/dbpp/text/node82.html

Image from DOE ANL



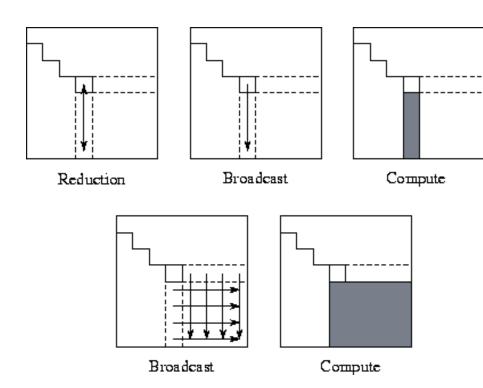
### **HPF Gaussian Elimination 1**

```
REAL A(n,n+1), X(n), Fac(n), Row(n+1)
      INTEGER indx(n), itmp(1), max indx, i, j, k
!HPF$ ALIGN Row(j) WITH A(1,j)
!HPF$ ALIGN X(i) WITH A(i,N+1)
!HPF$ DISTRIBUTE A(*,CYCLIC)
      indx = 0
     DO i = 1,n
        itmp = MAXLOC(ABS(A(:,i)), MASK=indx.EQ.0) ! Stage 1
       \max indx = itmp(1)
                                                     ! Stage 2
        indx(max indx) = i
        Fac = A(:,i) / A(max indx,i)
                                                     ! Stage 3+4
        Row = A(max indx,:)
        FORALL (j=1:n, k=i:n+1, indx(j).EQ.0)
                                                     ! Stage 5
          A(j,k) = A(j,k) - Fac(j)*Row(k)
      ENDDO
!
     Row exchange
      FORALL (j=1:n) A(indx(j),:) = A(j,:)
•
      Backsubstitution, uses B(:) stored in A(1:n,n+1)
     DO j = n, 1, -1
       X(j) = A(j,n+1) / A(j,j)
        A(1:j-1,n+1) = A(1:j-1,n+1) - A(1:j-1,j) *X(j)
     ENDDO
```



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### **HPF Gaussian Elimination 2**



- Computing the upper triangular form takes five stages:
  - 1. Reduction with MAXLOC
  - 2. Broadcast (copy) max\_indx
  - 3. Compute scale factors Fac
  - Broadcast scale factor Fac and pivot row value Row (k)
  - 5. Row update with **FORALL**

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