开源硬件总结

##第一天

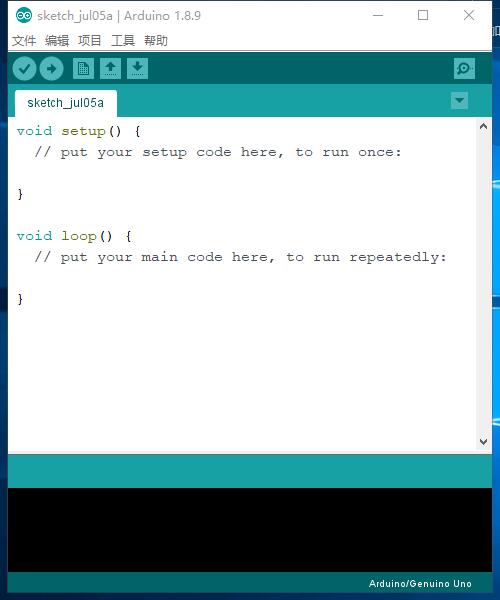
####学习内容

·为什么要学习开源硬件

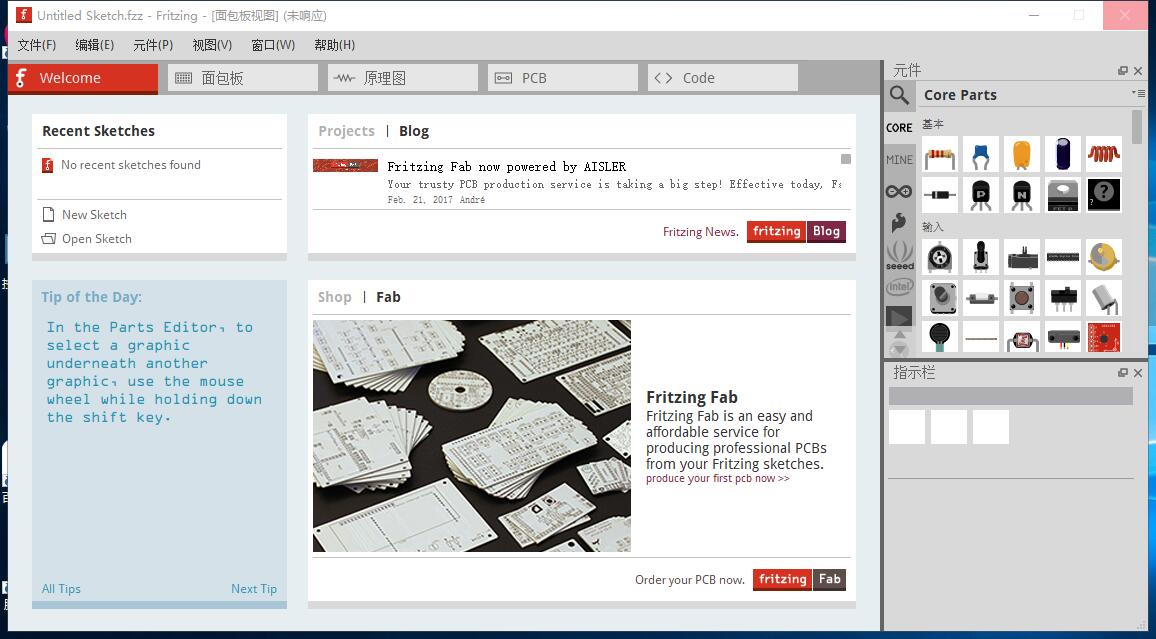
·如何学习开源硬件

·三个软件

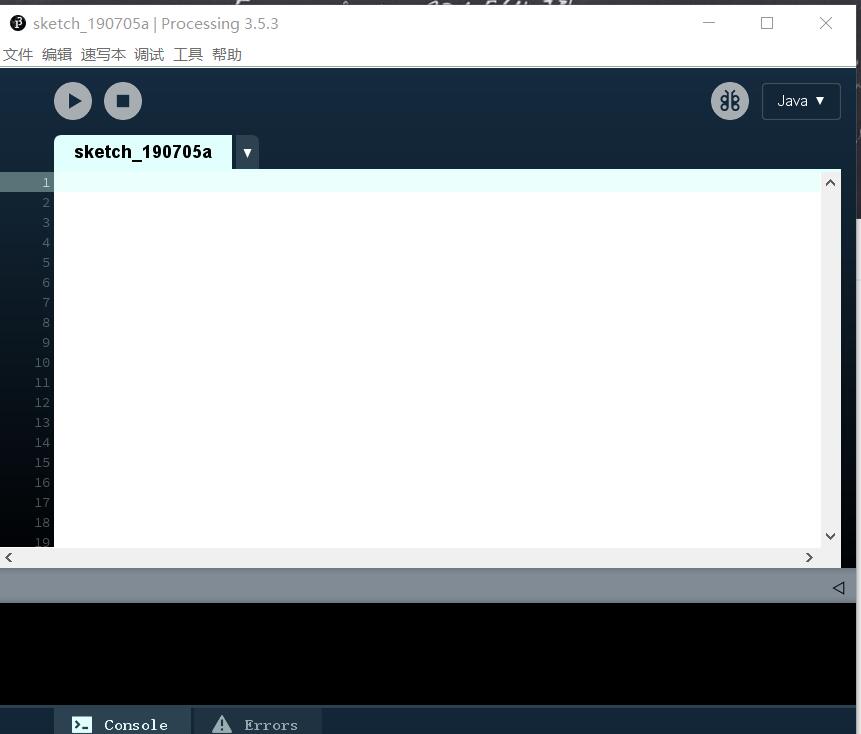
arduino



Fritzing



Processing



·几个常用网站

[arduino网址](https://arduino.cc)

[fritzing网址](https://fritzing.org)

[processing网址](https://processing.org)

##第二天

arduino编程

#include<Morse.h>

Morse morse(13);

//定义莫尔斯电码表

char MORSE[][4]={

{'.', '-', '\*', '\*'}, //A

{'-', '.', '.', '.'}, //B

{'-', '.', '-', '.'}, //C

{'-', '.', '.', '\*'}, //D

{'.', '\*', '\*', '\*'}, //E

{'.', '.', '-', '.'}, //F

{'-', '-', '.', '\*'}, //G

{'.', '.', '.', '.'}, //H

{'.', '.', '\*', '\*'}, //I

{'.', '-', '-', '-'}, //J

{'-', '.', '-', '\*'}, //K

{'.', '-', '.', '.'}, //L

{'-', '-', '\*', '\*'}, //M

{'-', '.', '\*', '\*'}, //N

{'-', '-', '-', '\*'}, //O

{'.', '-', '-', '.'}, //P

{'-', '-', '.', '-'}, //Q

{'.', '-', '.', '\*'}, //R

{'.', '.', '.', '\*'}, //S

{'-', '\*', '\*', '\*'}, //T

{'.', '.', '-', '\*'}, //U

{'.', '.', '.', '-'}, //V

{'.', '-', '-', '\*'}, //W

{'-', '.', '.', '-'}, //X

{'-', '.', '-', '-'}, //Y

{'-', '-', '.', '.'},//Z

};

void setup() {

Serial.begin(9600); // put your setup code here, to run once:

}

void loop() {

String str = "";

String morse\_s = "";

int i, t, temp = 0;

int n = 0;

while(Serial.available()>0){

temp = 1;

str += char(Serial.read());

delay(2);

n++;// put your main code here, to run repeatedly:

}

if (temp){

for (i=0;i<n;i++)

{

for(t=0;t<4;t++)

{

if(str[i]>=97 && str[i]<=122)

{

morse\_s +=char(MORSE[int(str[i]-97)][t]);

}

}

morse\_s +=' ';

}

Serial.println(morse\_s);

for (i=0;morse\_s[i]!='\0';i++)

{

if(morse\_s[i] =='.')morse.dot();

else if(morse\_s[i]=='-')morse.dash();

else if(morse\_s[i]==' ')morse.w\_space();

if(morse\_s[i] !=' ' && str[i] != '\*')morse.c\_space();

}

Serial.println("发送完毕");

delay(2);

}

}

##第三天

小车代码和电路图

void setup()

{

pinMode(0,OUTPUT);

pinMode(1,OUTPUT);

pinMode(2,OUTPUT);

pinMode(3,OUTPUT);

pinMode(4,OUTPUT);

pinMode(5,OUTPUT);

Serial.begin(9600);

}

byte income=0;

void loop()

{

if(Serial.available()>0)

{income=Serial.read();

income=income-'0';

if(income&0x1)

{

digitalWrite(1,HIGH);

}

else

{

digitalWrite(1,LOW);

}

if((income>>1)&0x1)

{

digitalWrite(2,HIGH);

}

else

{

digitalWrite(2,LOW);

}

if((income>>2)&0x1)

{

digitalWrite(3,HIGH);

}

else

{

digitalWrite(3,LOW);

}

if((income>>3)&0x1)

{

digitalWrite(4,HIGH);

}

else

{

digitalWrite(4,LOW);

}

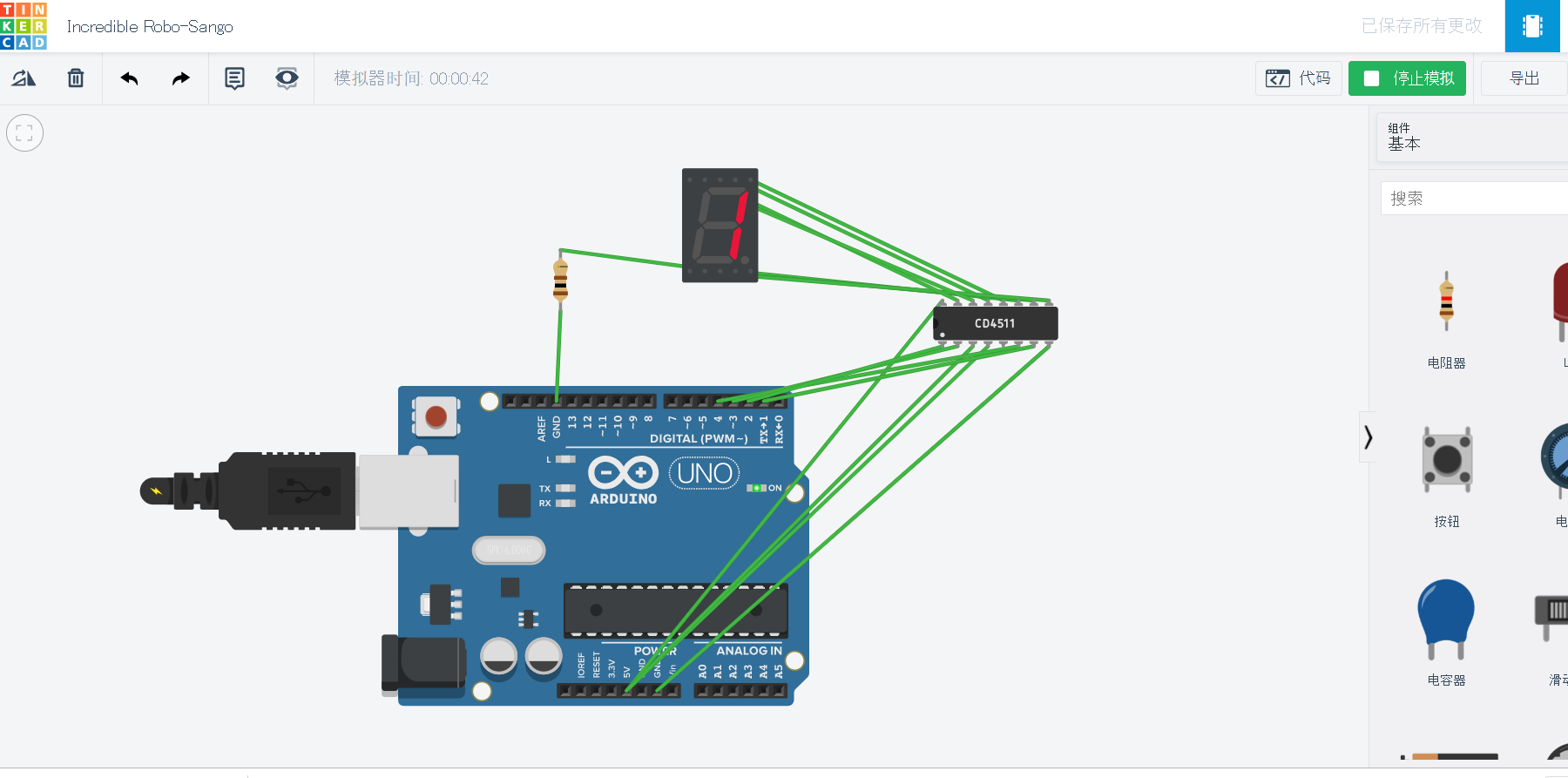
}

delay(10);

digitalWrite(0,HIGH);

delay(10);

}



##第四天

MORSE代码tinkercad可运行代码

int \_pin=13;

int \_dottime=250;

void dot()

{

digitalWrite(\_pin,HIGH);

delay(\_dottime);

digitalWrite(\_pin,LOW);

delay(\_dottime);

}

void dash()

{

digitalWrite(\_pin,HIGH);

delay(\_dottime\*4);

digitalWrite(\_pin,LOW);

delay(\_dottime);

}

void c\_space()

{

digitalWrite(\_pin,LOW);

delay(\_dottime\*3);

}

void w\_space()

{

digitalWrite(\_pin,LOW);

delay(\_dottime\*7);

}

char MORSE[][4] = {

{'.', '-', '\*', '\*'}, //A

{'-', '.', '.', '.'}, //B

{'-', '.', '-', '.'}, //C

{'-', '.', '.', '\*'}, //D

{'.', '\*', '\*', '\*'}, //E

{'.', '.', '-', '.'}, //F

{'-', '-', '.', '\*'}, //G

{'.', '.', '.', '.'}, //H

{'.', '.', '\*', '\*'}, //I

{'.', '-', '-', '-'}, //J

{'-', '.', '-', '\*'}, //K

{'.', '-', '.', '.'}, //L

{'-', '-', '\*', '\*'}, //M

{'-', '.', '\*', '\*'}, //N

{'-', '-', '-', '\*'}, //O

{'.', '-', '-', '.'}, //P

{'-', '-', '.', '-'}, //Q

{'.', '-', '.', '\*'}, //R

{'.', '.', '.', '\*'}, //S

{'-', '\*', '\*', '\*'}, //T

{'.', '.', '-', '\*'}, //U

{'.', '.', '.', '-'}, //V

{'.', '-', '-', '\*'}, //W

{'-', '.', '.', '-'}, //X

{'-', '.', '-', '-'}, //Y

{'-', '-', '.', '.'} //Z

};

void setup()

{ pinMode(\_pin,OUTPUT);

Serial.begin(9600);

}

void loop()

{

String str = "";

String morse\_s = "";

int i, t , temp = 0;

int n = 0;

while (Serial.available() > 0)

{

temp = 1;

str += char(Serial.read());

delay(2);

n++;

}

if (temp)

{

for (i = 0; i < n; i++)

{

for (t = 0; t < 4; t++)

{

if (str[i] >= 97 && str[i] <= 122)

{

morse\_s += char(MORSE[int(str[i] - 97)][t]);

}

}

morse\_s += ' ';

}

Serial.println(morse\_s);

for (i = 0; morse\_s[i]!='\0' ; i++)

{

if (morse\_s[i] == '.')dot();

else if (morse\_s[i] == '-')dash();

else if (morse\_s[i] == ' ')w\_space();

if (morse\_s[i] != ' ' && str[i] != '\*')c\_space();

}

Serial.println("发送完毕");

delay(2);

}

}

