

Gaussian Discriminant Analysis

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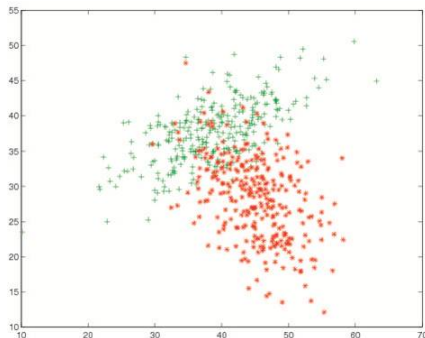
Generative vs Discriminative (Recap)

Two approaches to classification:

- **Discriminative approach:** estimate parameters of decision boundary/class separator directly from labeled examples.
 - ▶ Model $p(t|\mathbf{x})$ directly (logistic regression models)
 - ▶ Learn mappings from inputs to classes (linear/logistic regression, decision trees etc)
 - ▶ Tries to solve: How do I separate the classes?
- **Generative approach:** model the distribution of inputs characteristic of the class (Bayes classifier).
 - ▶ Model $p(\mathbf{x}|t)$
 - ▶ Apply Bayes Rule to derive $p(t|\mathbf{x})$.
 - ▶ Tries to solve: What does each class "look" like?

Classification: Diabetes Example

- Gaussian discriminant analysis (GDA) is a Bayes classifier for continuous-valued inputs.
- Observation per patient: White blood cell count & glucose value.



- $p(\mathbf{x} | t = k)$ for each class is shaped like an ellipse
 \implies we model each class as a multivariate Gaussian

Gaussian Discriminant Analysis

- **Gaussian Discriminant Analysis** in its general form assumes that $p(\mathbf{x}|t)$ is distributed according to a multivariate Gaussian distribution
- Multivariate Gaussian distribution:

$$p(\mathbf{x} | t = k) = \frac{1}{(2\pi)^{D/2} |\Sigma_k|^{1/2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^T \Sigma_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) \right]$$

where $|\Sigma_k|$ denotes the determinant of the matrix.

- Each class k has associated mean vector $\boldsymbol{\mu}_k$ and covariance matrix Σ_k
- How many parameters?
 - ▶ Each $\boldsymbol{\mu}_k$ has D parameters, for DK total.
 - ▶ Each Σ_k has $\mathcal{O}(D^2)$ parameters, for $\mathcal{O}(D^2 K)$

GDA: Learning

- Learn the parameters for each class using maximum likelihood
- For simplicity, assume binary classification

$$p(t | \phi) = \phi^t (1 - \phi)^{1-t}$$

- You can compute the ML estimates in closed form (ϕ and $\boldsymbol{\mu}_k$ are easy, $\boldsymbol{\Sigma}_k$ is tricky)

$$\phi = \frac{1}{N} \sum_{i=1}^N r_1^{(i)}$$

$$\boldsymbol{\mu}_k = \frac{\sum_{i=1}^N r_k^{(i)} \cdot \mathbf{x}^{(i)}}{\sum_{i=1}^N r_k^{(i)}}$$

$$\boldsymbol{\Sigma}_k = \frac{1}{\sum_{i=1}^N r_k^{(i)}} \sum_{i=1}^N r_k^{(i)} (\mathbf{x}^{(i)} - \boldsymbol{\mu}_k)(\mathbf{x}^{(i)} - \boldsymbol{\mu}_k)^\top$$

$$r_k^{(i)} = \mathbb{1}[t^{(i)} = k]$$

GDA Decision Boundary

- Recall: for Bayes classifiers, we compute the decision boundary with Bayes' Rule:

$$p(t | \mathbf{x}) = \frac{p(t) p(\mathbf{x} | t)}{\sum_{t'} p(t') p(\mathbf{x} | t')}$$

- Plug in the Gaussian $p(\mathbf{x} | t)$:

$$\begin{aligned} \log p(t_k | \mathbf{x}) &= \log p(\mathbf{x} | t_k) + \log p(t_k) - \log p(\mathbf{x}) \\ &= -\frac{D}{2} \log(2\pi) - \frac{1}{2} \log |\Sigma_k| - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^\top \Sigma_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) + \\ &\quad + \log p(t_k) - \log p(\mathbf{x}) \end{aligned}$$

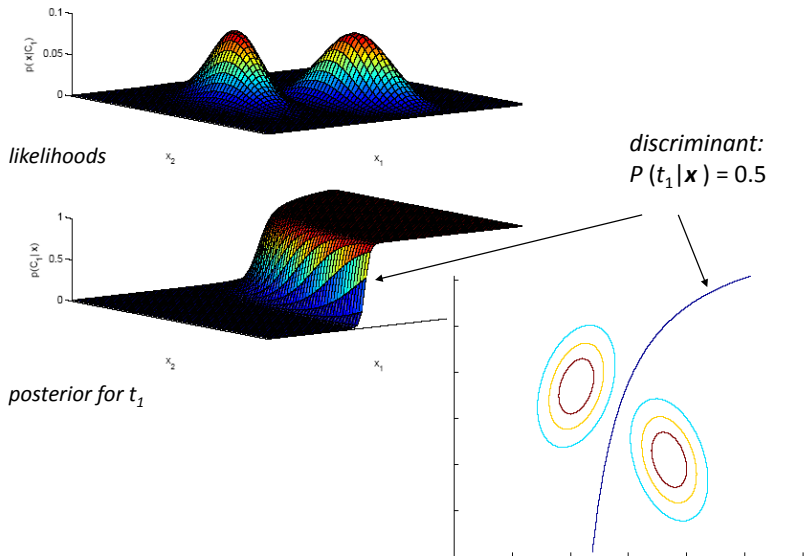
- Decision boundary:

$$(\mathbf{x} - \boldsymbol{\mu}_k)^\top \Sigma_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) = (\mathbf{x} - \boldsymbol{\mu}_\ell)^\top \Sigma_\ell^{-1} (\mathbf{x} - \boldsymbol{\mu}_\ell) + \text{Const}$$

What's the shape of the boundary?

- ▶ We have a quadratic function in \mathbf{x} , so the decision boundary is a conic section!

GDA Decision Boundary



GDA Decision Boundary

- Our equation for the decision boundary:

$$(\mathbf{x} - \boldsymbol{\mu}_k)^\top \boldsymbol{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) = (\mathbf{x} - \boldsymbol{\mu}_\ell)^\top \boldsymbol{\Sigma}_\ell^{-1} (\mathbf{x} - \boldsymbol{\mu}_\ell) + \text{Const}$$

- Expand the product and factor out constants (w.r.t. \mathbf{x}):

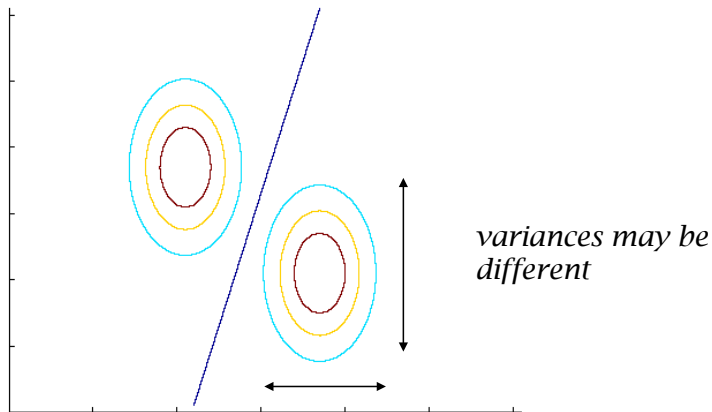
$$\mathbf{x}^\top \boldsymbol{\Sigma}_k^{-1} \mathbf{x} - 2\boldsymbol{\mu}_k^\top \boldsymbol{\Sigma}_k^{-1} \mathbf{x} = \mathbf{x}^\top \boldsymbol{\Sigma}_\ell^{-1} \mathbf{x} - 2\boldsymbol{\mu}_\ell^\top \boldsymbol{\Sigma}_\ell^{-1} \mathbf{x} + \text{Const}$$

- What if all classes share the same covariance $\boldsymbol{\Sigma}$?
 - ▶ We get a linear decision boundary!

$$-2\boldsymbol{\mu}_k^\top \boldsymbol{\Sigma}^{-1} \mathbf{x} = -2\boldsymbol{\mu}_\ell^\top \boldsymbol{\Sigma}^{-1} \mathbf{x} + \text{Const}$$

$$(\boldsymbol{\mu}_k - \boldsymbol{\mu}_\ell)^\top \boldsymbol{\Sigma}^{-1} \mathbf{x} = \text{Const}$$

GDA Decision Boundary: Shared Covariances



GDA vs Logistic Regression

- Binary classification: If you examine $p(t = 1 | \mathbf{x})$ under GDA and assume $\Sigma_0 = \Sigma_1 = \Sigma$, you will find that it looks like this:

$$p(t | \mathbf{x}, \phi, \mu_0, \mu_1, \Sigma) = \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x} - b)}$$

where (\mathbf{w}, b) are chosen based on $(\phi, \mu_0, \mu_1, \Sigma)$.

- Same model as logistic regression!

GDA vs Logistic Regression

When should we prefer GDA to logistic regression, and vice versa?

- GDA makes a stronger modeling assumption: assumes class-conditional data is multivariate Gaussian
 - ▶ If this is true, GDA is asymptotically efficient (best model in limit of large N)
 - ▶ If it's not true, the quality of the predictions might suffer.
- Many class-conditional distributions lead to logistic classifier.
 - ▶ When these distributions are non-Gaussian (i.e., almost always), LR usually beats GDA
- GDA can handle easily missing features (how do you do that with LR?)

Gaussian Naive Bayes

- What if \mathbf{x} is high-dimensional?
 - ▶ The Σ_k have $\mathcal{O}(D^2K)$ parameters, which can be a problem if D is large.
 - ▶ We already saw we can save some a factor of K by using a shared covariance for the classes.
 - ▶ Any other idea you can think of?
- **Naive Bayes:** Assumes features independent given the class

$$p(\mathbf{x} | t = k) = \prod_{j=1}^D p(x_j | t = k)$$

- Assuming likelihoods are Gaussian, how many parameters required for Naive Bayes classifier?
 - ▶ This is equivalent to assuming the x_j are uncorrelated, i.e. Σ is diagonal.
 - ▶ Hence, only D parameters for Σ !

Gaussian Naïve Bayes

- Gaussian Naïve Bayes classifier assumes that the likelihoods are Gaussian:

$$p(x_j | t = k) = \frac{1}{\sqrt{2\pi}\sigma_{jk}} \exp \left[\frac{-(x_j - \mu_{jk})^2}{2\sigma_{jk}^2} \right]$$

(this is just a 1-dim Gaussian, one for each input dimension)

- Model the same as GDA with diagonal covariance matrix
- Maximum likelihood estimate of parameters

$$\mu_{jk} = \frac{\sum_{i=1}^N r_k^{(i)} x_j^{(i)}}{\sum_{i=1}^N r_k^{(i)}}$$

$$\sigma_{jk}^2 = \frac{\sum_{i=1}^N r_k^{(i)} (x_j^{(i)} - \mu_{jk})^2}{\sum_{i=1}^N r_k^{(i)}}$$

$$r_k^{(i)} = \mathbb{1}[t^{(i)} = k]$$

Decision Boundary: Isotropic

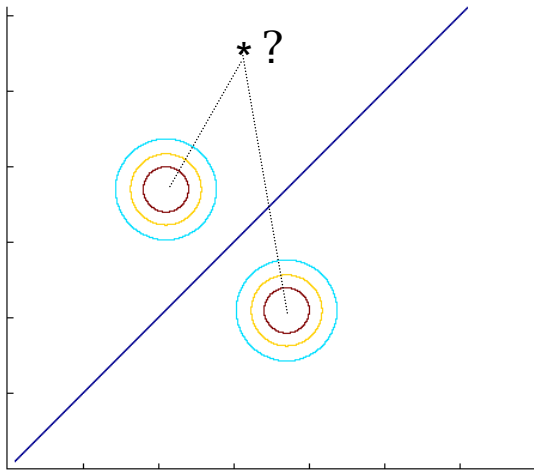
- We can go even further and assume the covariances are **spherical**, or **isotropic**.
- In this case: $\Sigma = \sigma^2 \mathbf{I}$ (just need one parameter!)
- Going back to the class posterior for GDA:

$$\begin{aligned}\log p(t_k | \mathbf{x}) &= \log p(\mathbf{x} | t_k) + \log p(t_k) - \log p(\mathbf{x}) \\ &= -\frac{D}{2} \log(2\pi) - \frac{1}{2} \log |\Sigma_k^{-1}| - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_k)^\top \Sigma_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) + \\ &\quad + \log p(t_k) - \log p(\mathbf{x})\end{aligned}$$

- Suppose for simplicity that $p(t)$ is uniform. Plugging in $\Sigma = \sigma^2 \mathbf{I}$ and simplifying a bit,

$$\begin{aligned}\log p(t_k | \mathbf{x}) - \log p(t_\ell | \mathbf{x}) &= -\frac{1}{2\sigma^2} [(\mathbf{x} - \boldsymbol{\mu}_k)^\top (\mathbf{x} - \boldsymbol{\mu}_k) - (\mathbf{x} - \boldsymbol{\mu}_\ell)^\top (\mathbf{x} - \boldsymbol{\mu}_\ell)] \\ &= -\frac{1}{2\sigma^2} [\|\mathbf{x} - \boldsymbol{\mu}_k\|^2 - \|\mathbf{x} - \boldsymbol{\mu}_\ell\|^2]\end{aligned}$$

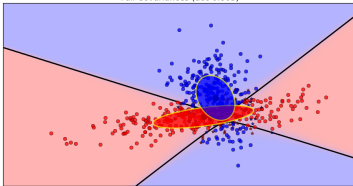
Decision Boundary: Isotropic



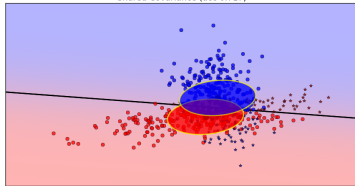
- The decision boundary bisects the class means!

Example

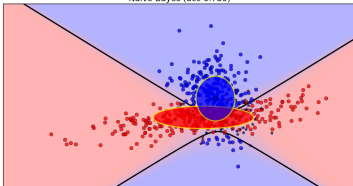
Full Covariances (acc 0.805)



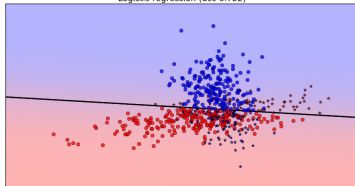
Shared Covariance (acc 0.717)



Naive Bayes (acc 0.780)



Logistic regression (acc 0.722)



Generative models - Recap

- GDA has quadratic (conic) decision boundary.
- With shared covariance, GDA is similar to logistic regression.
- Generative models:
 - ▶ Flexible models, easy to add/remove class.
 - ▶ Handle missing data naturally.
 - ▶ More “natural” way to think about things, but usually doesn’t work as well.
- Tries to solve a hard problem (model $p(\mathbf{x})$) in order to solve a easy problem (model $p(t | \mathbf{x})$).