

## SNE 10 (RNN)

### 5. Uczenie głębokie (Deep learning) – Dalszy ciąg

#### 5.3 Recurrent Neural Network (RNN)

Rekurencyjne sieci neuronowe

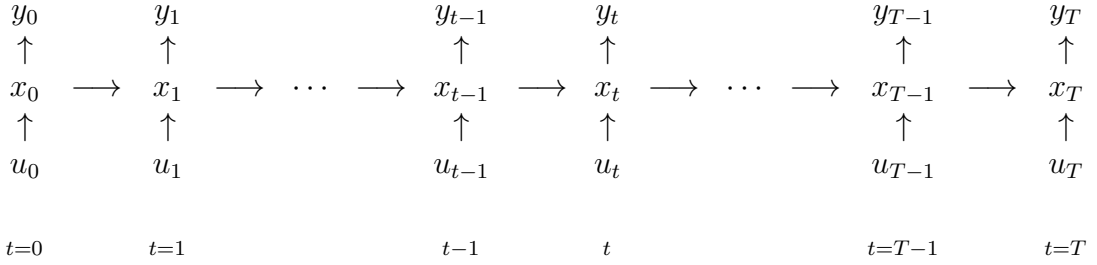
Static NN

$$x = f(u), \quad y = g(x)$$

$$\begin{array}{c} y \\ \uparrow \\ x \\ \uparrow \\ u \end{array}$$

Dynamic NN (Neural automaton, Neural Turing machine)  $\supset$  RNN

$$x_t = f(x_{t-1}, u_t), \quad y_t = g(x_t) \quad (1 \leq t \leq T)$$



( $u_t = F(x_t)$  Feedback, Sprzężenie zwrotne)

#### Sformułowanie RNN

Sygnały wejściowe (input)

Rozważamy  $U$  jako zero-wa warstwa  $X^{(0)}$ .

$$U = X^{(0)} = \prod_{t=0}^T U_t = \prod_{t=0}^T X_t^{(0)}$$

$$U_t = X_t^{(0)} = \{u_t(1), \dots, u_t(P)\} = \{x_t^{(0)}(1), \dots, x_t^{(0)}(P)\}$$

$$u_t(p) = x_t^{(0)}(p) = (u_{t;1}(p), \dots, u_{t;i_0}(p), \dots, u_{t;m}(p)) = (x_{t;1}^{(0)}(p), \dots, x_{t;i_0}^{(0)}(p), \dots, x_{t;n_0}^{(0)}(p)) \in \{0, 1\}^m \subset \mathbb{R}^m$$

$$(1 \leq p \leq P; n_0 = m)$$

Sygnały wyjściowe (output)

Rozważamy  $Y$  jako  $(R+1)$ -ta warstwa  $X^{(R+1)}$ .

$$Y = X^{(R+1)} = \prod_{t=0}^T Y_t = \prod_{t=0}^T X_t^{(R+1)}$$

$$Y_t = X_t^{(R+1)} = \{y_t(1), \dots, y_t(P)\} = \{x_t^{(R+1)}(1), \dots, x_t^{(R+1)}(P)\}$$

$$y_t(p) = x_t^{(R+1)}(p) = (y_{t;1}(p), \dots, y_{t;i_{R+1}}(p), \dots, y_{t;\ell}(p)) = (x_{t;1}^{(R+1)}(p), \dots, x_{t;i_{R+1}}^{(R+1)}(p), \dots, x_{t;n_{R+1}}^{(R+1)}(p)) \in \mathbb{R}^\ell$$

$$(1 \leq p \leq P; n_{R+1} = \ell)$$

Sygnały nauczyciela

$$Z = \prod_{t=0}^T Z_t$$

$$Z_t = \{z_t(1), \dots, z_t(P)\}$$

$$z_t(p) = (z_{t;1}(p), \dots, z_{t;i_{R+1}}(p), \dots, z_{t;\ell}(p)) \in \mathbb{R}^\ell$$

$$(1 \leq p \leq P)$$

Warstwy środkowe  $X$

$$X = \prod_{t=0}^T X_t$$

$X_t$  składa się z kilk warstw.

$$X_t = \prod_{r=1}^R X_t^{(r)}$$

$$X_t^{(r)} = \{x_t^{(r)}(1), \dots, x_t^{(r)}(P)\}$$

$$x_t^{(r)}(p) = (x_{t;1}^{(r)}(p), \dots, x_{t;i_r}^{(r)}(p), \dots, x_{t;n_r}^{(r)}(p))$$

$$(1 \leq p \leq P)$$

Wówczas dla  $t = 0$  przekształcenie

$$x_t^{(r)} \rightarrow x_t^{(r+1)}$$

w

$$x_t^{(0)} = u_t \rightarrow x_t^{(1)} \rightarrow \dots \rightarrow x_t^{(r)} \rightarrow x_t^{(r+1)} \rightarrow \dots \rightarrow x_t^{(R)} \rightarrow x_t^{(R+1)} = y_t$$

można wyrazić wzorem

$$x_{t;i_{r+1}}^{(r+1)}(p) = f\left(\sum_{i_r=1}^{n_r} w_{i_{r+1},i_r}^{(r)} x_{t;i_r}^{(r)}(p)\right)$$

$$(0 \leq r \leq R, 1 \leq p \leq P).$$

Natomiast dla  $1 \leq t \leq T$  przekształcenie

$$\begin{array}{ccc} & x_{t-1}^{(r+1)} & \\ & \downarrow & \\ x_t^{(r)} & \rightarrow & x_t^{(r+1)} \end{array}$$

w

$$\begin{array}{ccccccc} & x_{t-1}^{(1)} & & x_{t-1}^{(r)} & & x_{t-1}^{(r+1)} & & x_{t-1}^{(R)} \\ & \downarrow & & \downarrow & & \downarrow & & \downarrow \\ x_t^{(0)} = u_t & \rightarrow & x_t^{(1)} & \rightarrow & \dots & \rightarrow & x_t^{(r)} & \rightarrow & x_t^{(r+1)} & \rightarrow & \dots & \rightarrow & x_t^{(R)} & \rightarrow & x_t^{(R+1)} = y_t \end{array}$$

można wyrazić wzorem

$$x_{t;i_{r+1}}^{(r+1)}(p) = f\left(\sum_{i_r=1}^{n_r} w_{i_{r+1},i_r}^{(r)} x_{t;i_r}^{(r)}(p) + \sum_{i'_{r+1}=1}^{n_{r+1}} w_{i_{r+1},i'_{r+1}}^{(r+1)} x_{t-1;i'_{r+1}}^{(r+1)}(p)\right) \quad (i_{r+1} = 1, \dots, n_{r+1})$$

$(0 \leq r \leq R, 1 \leq p \leq P)$ .

## Cel RNN

Niech

$$E_t = \frac{1}{2} \sum_{p=1}^P \sum_{i=1}^{\ell} (y_{t;i}(p) - z_{t;i}(p))^2 \quad (0 \leq t \leq T).$$

Celem RNN jest minimalizacja błędu

$$E = E(w_{i_{r+1}, i_r}^{(r)}; r = 0, \dots, R, i_r = 1, \dots, n_r, i_{r+1} = 1, \dots, n_{r+1};$$

$$w_{i_{r+1}, i_{r+1}}^{(r+1)}; r = 0, \dots, R-1, i_{r+1} = 1, \dots, n_{r+1}, i_{r+1}' = 1, \dots, n_{r+1}) := \sum_{t=0}^T E_t$$

za pomocą metody gradientu.

### (1a) Gradienty $t = 0$

$(0 \leq r \leq R)$

$$\begin{aligned} & \frac{\partial E_t}{\partial w_{i_{r+1}, i_r}^{(r)}} \\ = & \sum_{p=1}^P \sum_{i_{R+1}=1}^{n_{R+1}} \sum_{i_R=1}^{n_R} \sum_{i_{R-1}=1}^{n_{R-1}} \dots \sum_{i_{r+2}=1}^{n_{r+2}} \frac{\partial E_t}{\partial x_{t; i_{R+1}}^{(R+1)}(p)} \frac{\partial x_{t; i_{R+1}}^{(R+1)}(p)}{\partial x_{t; i_R}^{(R)}(p)} \frac{\partial x_{t; i_R}^{(R)}(p)}{\partial x_{t; i_{R-1}}^{(R-1)}(p)} \dots \frac{\partial x_{t; i_{r+3}}^{(r+3)}(p)}{\partial x_{t; i_{r+2}}^{(r+2)}(p)} \frac{\partial x_{t; i_{r+2}}^{(r+2)}(p)}{\partial x_{t; i_{r+1}}^{(r+1)}(p)} \frac{\partial x_{t; i_{r+1}}^{(r+1)}(p)}{\partial w_{i_{r+1}, i_r}^{(r)}}. \end{aligned}$$

Szczegółowe wyrazy powyżej możemy obliczyć następująco:

$$\frac{\partial E_t}{\partial x_{t; i_{R+1}}^{(R+1)}(p)} = \frac{\partial E_t}{\partial y_{t; i_{R+1}}(p)} = y_{t; i_{R+1}}(p) - z_{t; i_{R+1}}(p),$$

$$\frac{\partial x_{t; i_{\alpha+1}}^{(\alpha+1)}(p)}{\partial x_{t; i_{\alpha}}^{(\alpha)}(p)} = f' \left( \sum_{i_{\beta}=1}^{n_{\alpha}} w_{i_{\alpha+1}, i_{\beta}}^{(\alpha)} x_{t; i_{\beta}}^{(\alpha)}(p) \right) w_{i_{\alpha+1}, i_{\alpha}}^{(\alpha)} \quad (\alpha = r+1, \dots, R),$$

$$\frac{\partial x_{t; i_{r+1}}^{(r+1)}(p)}{\partial w_{i_{r+1}, i_r}^{(r)}} = f' \left( \sum_{i_{\alpha}=1}^{n_r} w_{i_{r+1}, i_{\alpha}}^{(r)} x_{t; i_{\alpha}}^{(r)}(p) \right) x_{t; i_r}^{(r)}(p).$$

$(t = 0)$

### (1b) Gradienty $1 \leq t \leq T$

$(0 \leq r \leq R)$

$$\begin{aligned} & \frac{\partial E_t}{\partial w_{i_{r+1}, i_r}^{(r)}} \\ = & \sum_{p=1}^P \sum_{i_{R+1}=1}^{n_{R+1}} \sum_{i_R=1}^{n_R} \sum_{i_{R-1}=1}^{n_{R-1}} \dots \sum_{i_{r+2}=1}^{n_{r+2}} \frac{\partial E_t}{\partial x_{t; i_{R+1}}^{(R+1)}(p)} \frac{\partial x_{t; i_{R+1}}^{(R+1)}(p)}{\partial x_{t; i_R}^{(R)}(p)} \frac{\partial x_{t; i_R}^{(R)}(p)}{\partial x_{t; i_{R-1}}^{(R-1)}(p)} \dots \frac{\partial x_{t; i_{r+3}}^{(r+3)}(p)}{\partial x_{t; i_{r+2}}^{(r+2)}(p)} \frac{\partial x_{t; i_{r+2}}^{(r+2)}(p)}{\partial x_{t; i_{r+1}}^{(r+1)}(p)} \frac{\partial x_{t; i_{r+1}}^{(r+1)}(p)}{\partial w_{i_{r+1}, i_r}^{(r)}}. \end{aligned}$$

Szczegółowe wyrazy powyżej możemy obliczyć następująco:

$$\frac{\partial E_t}{\partial x_{t; i_{R+1}}^{(R+1)}(p)} = \frac{\partial E_t}{\partial y_{t; i_{R+1}}(p)} = y_{t; i_{R+1}}(p) - z_{t; i_{R+1}}(p),$$

$$\frac{\partial x_{t;i_{\alpha+1}}^{(\alpha+1)}(p)}{\partial x_{t;i_{\alpha}}^{(\alpha)}(p)} = f'(\sum_{i_{\beta}=1}^{n_{\alpha}} w_{i_{\alpha+1},i_{\beta}}^{(\alpha)} x_{t;i_{\beta}}^{(\alpha)}(p) + \sum_{i'_{\alpha+1}=1}^{n_{\alpha+1}} w_{i_{\alpha+1},i'_{\alpha+1}}^{(\alpha+1)} x_{t-1;i'_{\alpha+1}}^{(\alpha+1)}(p))) w_{i_{\alpha+1},i_{\alpha}}^{(\alpha)} \quad (\alpha = r+1, \dots, R),$$

$$\frac{\partial x_{t;i_{r+1}}^{(r+1)}(p)}{\partial w_{i_{r+1},i_r}^{(r)}} = f'(\sum_{i_{\alpha}=1}^{n_r} w_{i_{r+1},i_{\alpha}}^{(r)} x_{t;i_{\alpha}}^{(r)}(p) + \sum_{i'_{r+1}=1}^{n_{r+1}} w_{i_{r+1},i'_{r+1}}^{(r+1)} x_{t-1;i'_{r+1}}^{(r+1)}(p))) x_{t;i_r}^{(r)}(p).$$

$$(1 \leq t \leq T)$$

**(2) Gradienty (recurrent part)**  $1 \leq t \leq T$   
 $(0 \leq r \leq R-1)$

$$\frac{\partial E_t}{\partial w_{i_{r+1},i'_{r+1}}^{(r+1)}}$$

$$= \sum_{p=1}^P \sum_{i_{R+1}=1}^{n_{R+1}} \sum_{i_R=1}^{n_R} \sum_{i_{R-1}=1}^{n_{R-1}} \dots \sum_{i_{r+2}=1}^{n_{r+2}} \frac{\partial E_t}{\partial x_{t;i_{R+1}}^{(R+1)}(p)} \frac{\partial x_{t;i_{R+1}}^{(R+1)}(p)}{\partial x_{t;i_R}^{(R)}(p)} \frac{\partial x_{t;i_R}^{(R)}(p)}{\partial x_{t;i_{R-1}}^{(R-1)}(p)} \dots \frac{\partial x_{t;i_{r+3}}^{(r+3)}(p)}{\partial x_{t;i_{r+2}}^{(r+2)}(p)} \frac{\partial x_{t;i_{r+2}}^{(r+2)}(p)}{\partial x_{t;i_{r+1}}^{(r+1)}(p)} \frac{\partial x_{t;i_{r+1}}^{(r+1)}(p)}{\partial w_{t;i_{r+1},i'_{r+1}}^{(r+1)}}$$

$$(1 \leq t \leq T)$$

Szczegółowe wyrazy powyżej możemy obliczyć następująco:

$$\frac{\partial E_t}{\partial x_{t;i_{R+1}}^{(R+1)}(p)} = \frac{\partial E_t}{\partial y_{t;i_{R+1}}(p)} = y_{t;i_{R+1}}(p) - z_{t;i_{R+1}}(p),$$

$$\frac{\partial x_{t;i_{\alpha+1}}^{(\alpha+1)}(p)}{\partial x_{t;i_{\alpha}}^{(\alpha)}(p)} = f'(\sum_{i_{\beta}=1}^{n_{\alpha}} w_{i_{\alpha+1},i_{\beta}}^{(\alpha)} x_{t;i_{\beta}}^{(\alpha)}(p) + \sum_{i'_{\alpha+1}=1}^{n_{\alpha+1}} w_{i_{\alpha+1},i'_{\alpha+1}}^{(\alpha+1)} x_{t-1;i'_{\alpha+1}}^{(\alpha+1)}(p))) w_{i_{\alpha+1},i_{\alpha}}^{(\alpha)} \quad (\alpha = r+1, \dots, R),$$

$$\frac{\partial x_{t;i_{r+1}}^{(r+1)}(p)}{\partial w_{i_{r+1},i'_{r+1}}^{(r+1)}} = f'(\sum_{i_r=1}^{n_r} w_{i_{r+1},i_r}^{(r)} x_{t;i_r}^{(r)}(p) + \sum_{j'_{r+1}=1}^{n_{r+1}} w_{i_{r+1},j'_{r+1}}^{(r+1)} x_{t-1;j'_{r+1}}^{(r+1)}(p))) x_{t-1;i'_{r+1}}^{(r+1)}(p) \quad (i_{r+1} = 1, \dots, n_{r+1})$$

$$(1 \leq t \leq T)$$

Szkic algorytmu

$$E = E(w_{i_{r+1},i_r}^{(r)}; r = 0, \dots, R, i_r = 1, \dots, n_r, i_{r+1} = 1, \dots, n_{r+1}; ;$$

$$w_{i_{r+1},i'_{r+1}}^{(r+1)}; r = 0, \dots, R-1, i_{r+1} = 1, \dots, n_{r+1}, i'_{r+1} = 1, \dots, n_{r+1}) \rightarrow \text{Minimum lokalne}$$

za pomocą metody gradientu wygląda następująco.

**Algorytm**

$$w_{i_{r+1},i_r}^{(r)\text{new}} = w_{i_{r+1},i_r}^{(r)\text{old}} - c \frac{\partial E}{\partial w_{i_{r+1},i_r}^{(r)}}(w_{i_{r+1},i_r}^{(r)\text{old}}; r = 0, \dots, R, i_r = 1, \dots, n_r, i_{r+1} = 1, \dots, n_{r+1}; ;$$

$$w_{i_{r+1},i'_{r+1}}^{(r+1)\text{old}}; r = 0, \dots, R-1, i_{r+1} = 1, \dots, n_{r+1}, i'_{r+1} = 1, \dots, n_{r+1})$$

$$w_{i_{r+1},i'_{r+1}}^{(r+1)\text{new}} = w_{i_{r+1},i'_{r+1}}^{(r+1)\text{old}} - c \frac{\partial E}{\partial w_{i_{r+1},i'_{r+1}}^{(r+1)}}(w_{i_{r+1},i'_{r+1}}^{(r+1)\text{old}}; r = 0, \dots, R, i_r = 1, \dots, n_r, i_{r+1} = 1, \dots, n_{r+1}; ;$$

$$w_{i_{r+1}, i'_{r+1}}'^{(r+1)\text{old}}; r = 0, \dots, R-1, i_{r+1} = 1, \dots, n_{r+1}, i'_{r+1} = 1, \dots, n_{r+1})$$

### **Dodatek.** NETtalk

Learning, Then Talking (*The New York Times*, 16.08.1988)

Terrence Joseph Sejnowski (1947–) computational neuroscience

Institute for Neural Computation, University of California at San Diego (UCSD)

PhD in physics from Princeton University in 1978 with John Hopfield

co-invented the Boltzmann machine with Geoffrey Hinton

NETtalk był znanym zastosowaniem propagacji wstecznej w dziedzinie przetwarzania języka naturalnego (NLP=Natural Language Processing). Mimo tego, że nie używa się z RNNu (RNNu nie było w 80tych latach!), myślę, że można rozważać NETtalk jako pionierski prototyp RNNu dla NLP.

$$u \in \{0, 1\}^m \mapsto x \in \mathbb{R}^n \mapsto y \in \{0, 1\}^\ell$$

$$m = (26 + 3) \times 7 = 203, n = 80 \sim 120, \ell = 26$$

### Przykład

$$u = \_\_ \underline{\text{table}} \mapsto y = ([\text{ei}], \text{accent}, \dots)$$

$$u = \underline{\text{table}} \_\_\_ \mapsto y = ([\text{non}], \text{no accent}, \dots)$$