

Software needed

Installing the whole package of available utilities: IDE, compiler etc is a relatively complex process. There are many installation methods/sources. The sequence of steps below is one of the variants that allow a complete installation.

1. Install STM32 utilities

1.1 **Install STM32 CubeMX** CubeMX - automatic initialization code generator

Install from here: <https://www.st.com/en/development-tools/stm32cubemx.html>

It may be necessary to create an ST account for download. This package will be needed to make changes to the software, not to compile and load the initial test software already provided.

1.2 **STM32 Cube CLT installation** - this package contains, among other things, the main GNU C/C++ compiler (called "Gcc toolchain", gcc-arm-eabi variant for ARM "Embedded Application Binary Interface" processors) and other components.

Install from here: <https://www.st.com/en/development-tools/stm32cubeclt.html>

1.3 **Install Make for Windows**: is the utility that allows working with makefiles generated by STM32CubeMX. This package is generic, not just for STM32, so install it directly from source (GNU):

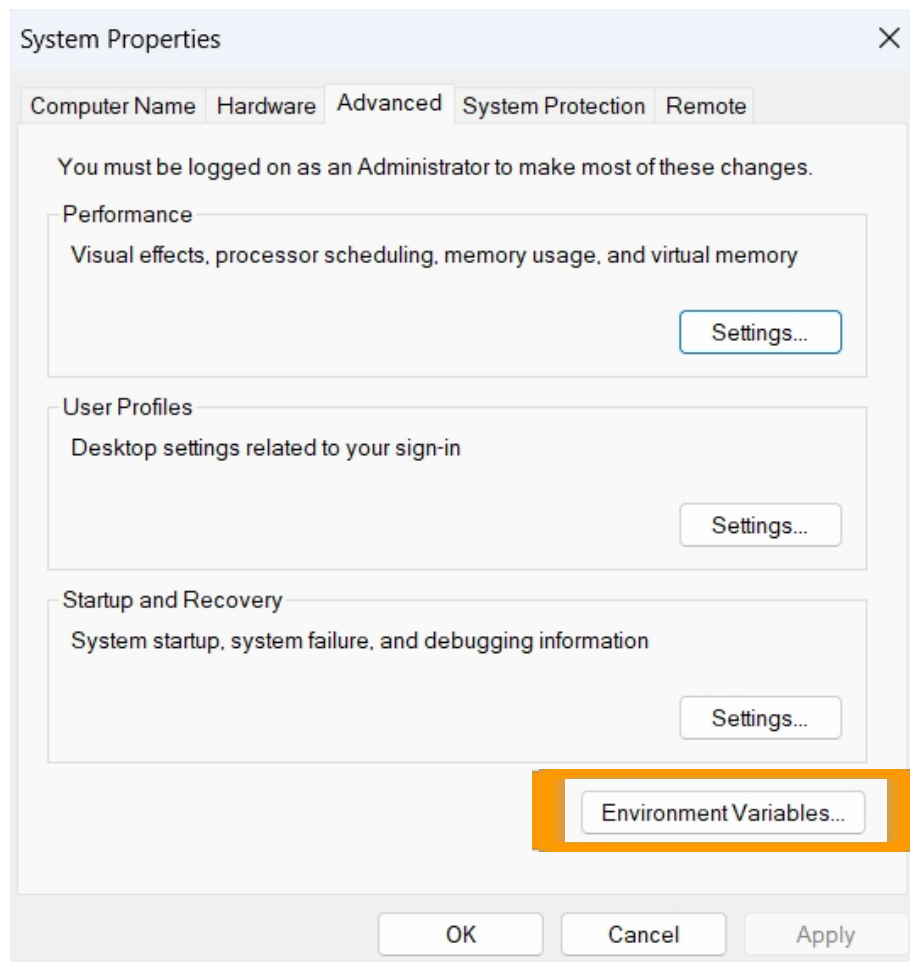
<https://gnuwin32.sourceforge.net/packages/make.htm>

from here download the "Binaries" and "Dependencies" packages.

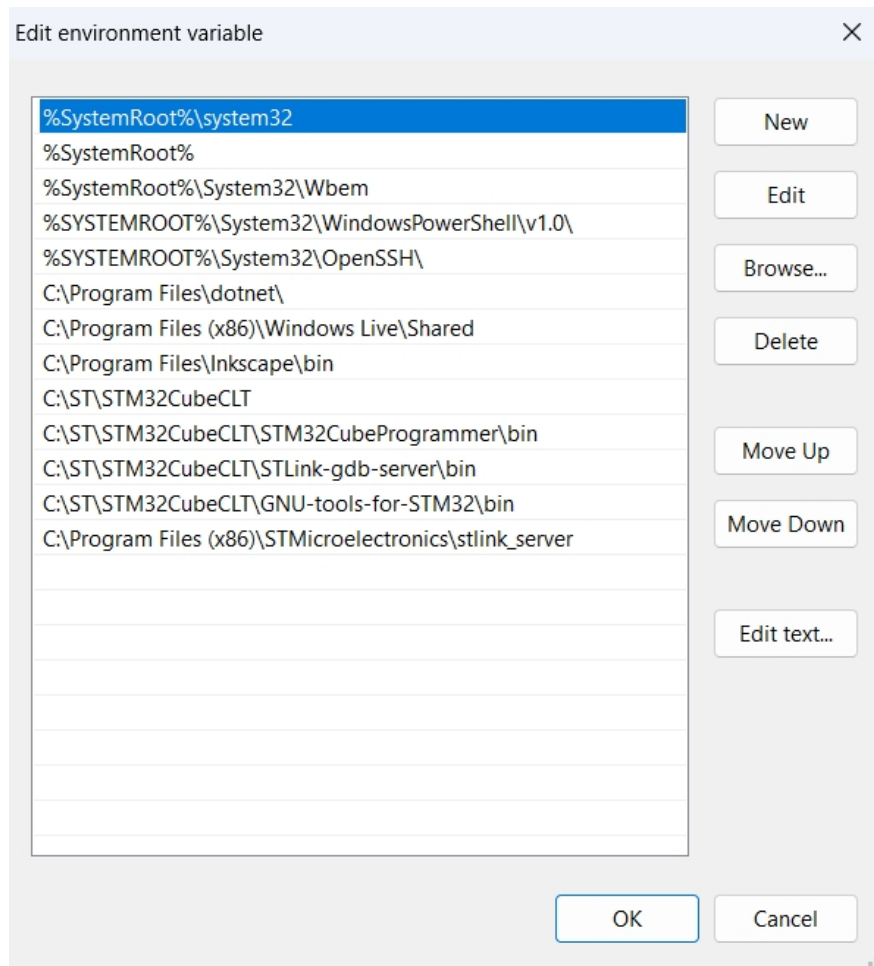
Unpack both archives in **the same** folder of your choice, created in advance. For example, C:\\ST\\make-3.81 (or whatever specific version was downloaded). Note that some of the archive folders are common, but the files are not the same.

1.3.1 **Set PATH under Windows to include Make:**

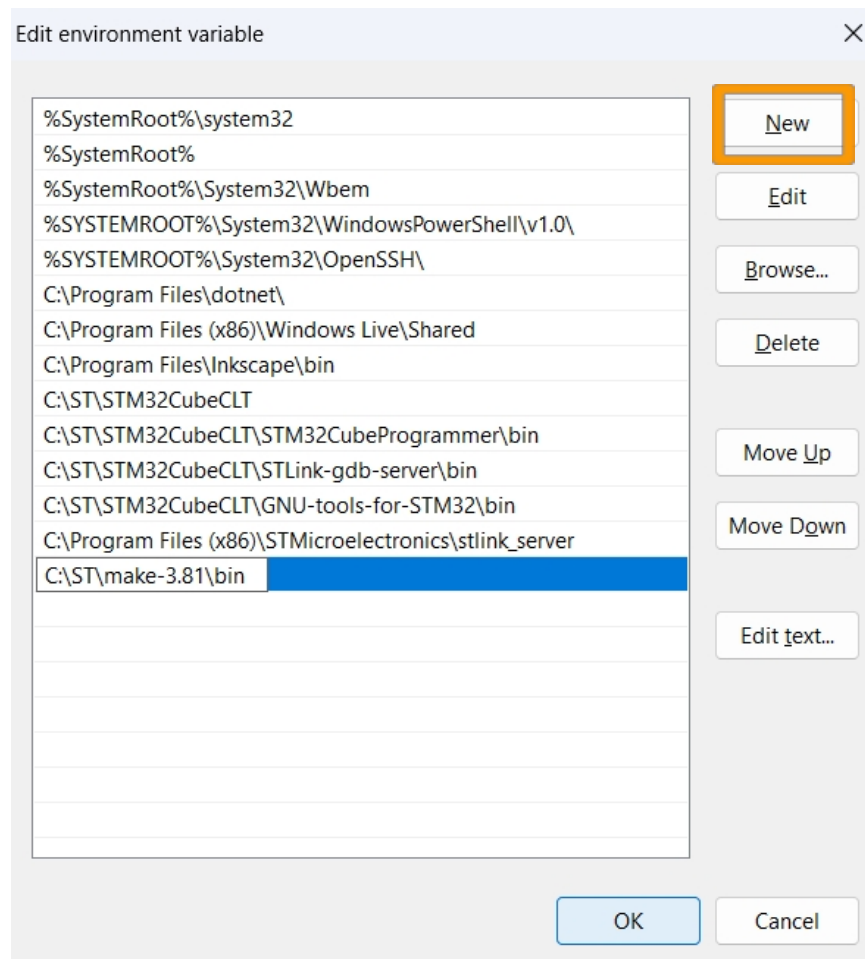
search for "System Properties" in Windows:



Select "Environment Variables" then "System variables" (note, not "user") and select Path→ Edit



Press the "New" button to add a new line in Path; manually add the "bin" folder from the folder where the 2 Make archives were unpacked:




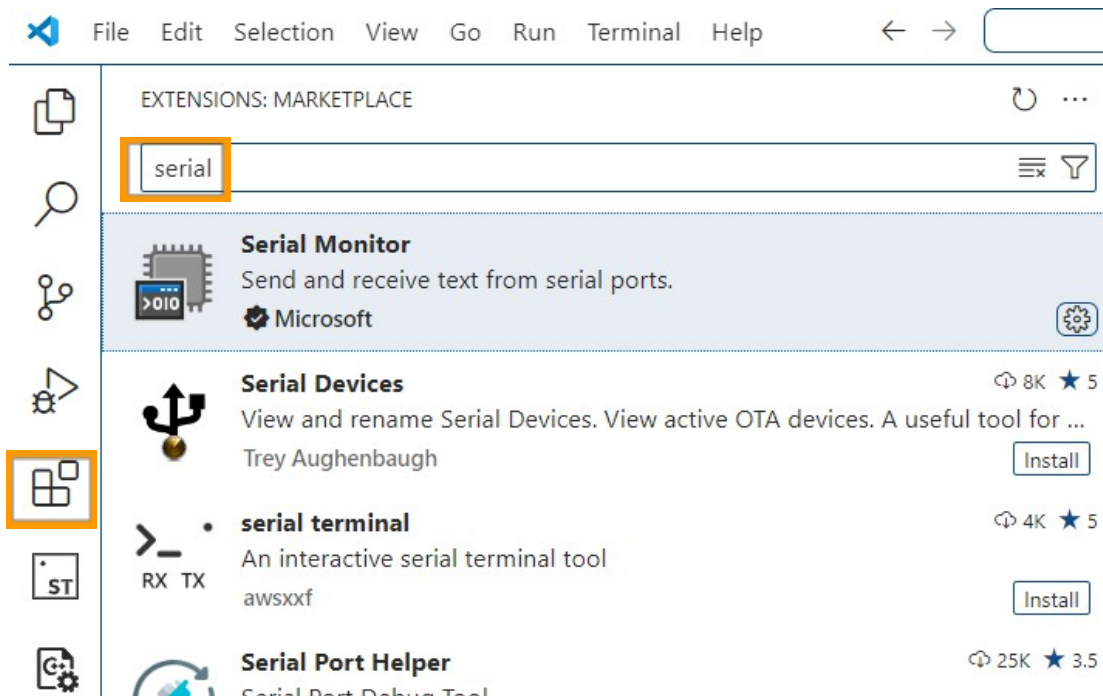
2. Install Visual Studio Code (VS Code).

This is the IDE for writing code and calling the compiler and other tools. Install from here:
<https://code.visualstudio.com/download>

2.1 Install VS Code extension: serial terminal

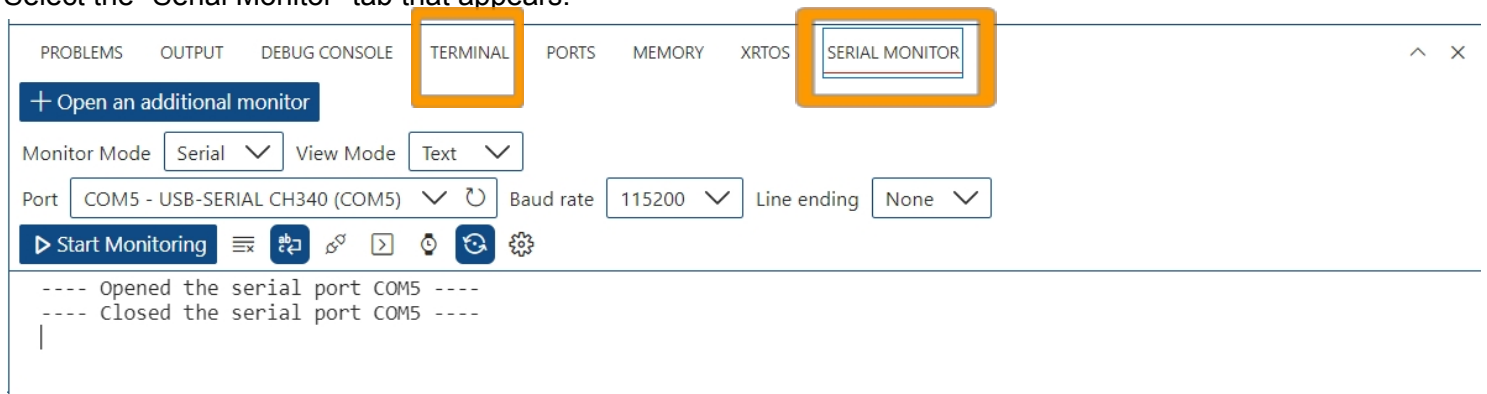
Purpose: To install and test a serial terminal (*serial monitor*). Start VS Code installed above. Press

button  (Extensions manager), type "Serial" in the text box, several variants will appear. Select "Serial Monitor" (Microsoft) and press the *Install* button. After installation, the installed extensions no longer show the *Install* button but the "cogwheel" for settings.



Note that in VS Code, there is not only *Serial Monitor*, but also a command line called "Terminal". If the window with the 2 tabs "Terminal" and "Serial Monitor" doesn't appear as below, on the right of the screen, bottom half, the command CTRL-J (Toggle Panel) makes it appear/disappear.

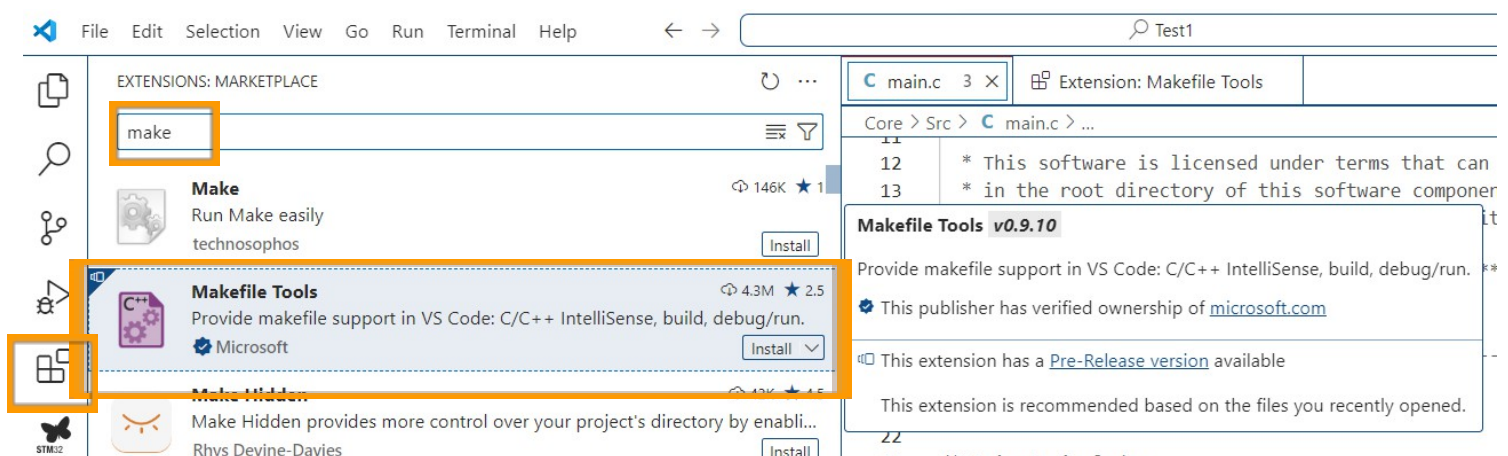
Select the "Serial Monitor" tab that appears:



Check the available ports with nothing connected to the PC. Connect a TTL-USB adapter. Check the available serial ports again, noting what has newly appeared (example on the figure: COM5, the figure may vary). If it does not appear, there is a problem with the Windows driver, search the Internet for "CH340 Windows driver" and install it manually.

2.2 You can also install the following VSCode extensions by going to the extensions button  and typing the first few letters, e.g. "make" in the search box:

1. Makefile Tools (Microsoft)

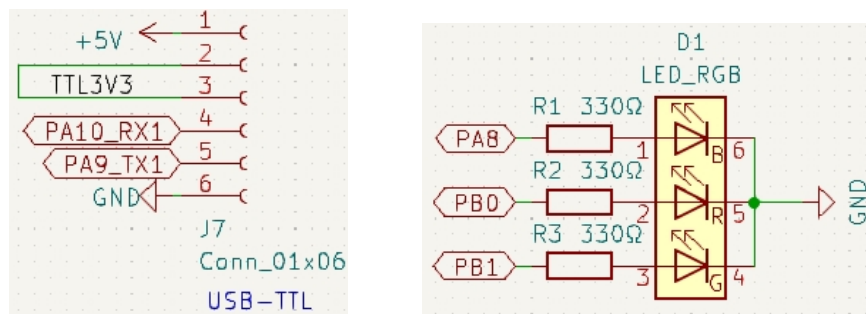


2. C/C++ Intellisense, debugging, and code browsing (Microsoft) - this will install a few more tools
3. STM32-for-VSCode (Bureau Moeilijke Moeilijke Dingen)
4. CSK Terminal - *optional but recommended* - another serial terminal that allows continuous transmission of characters without pressing ENTER after each character; useful to visualize serial characters on the oscilloscope without using SINGLE SWEEP mode

3. Loading test software into the processor

The STM32F103 processor contains a *bootloader* in the ROM that allows loading using the internal serial port UART1 (pins PA9, PA10). These pins are available at connector J7 to which a USB-TTL adapter set to 3.3V will be connected. A *bootloader* is a super-minimal operating system variant that only allows user software to be loaded into the processor. It can only communicate with a PC program (sometimes called a *PC-loader*) specially written according to a protocol compatible between the 2.

Important note: in the figure below, pins 2,3 of the J7 are shorted to each other, which is equivalent to setting the jumper to position "3V3" when using the TTL-USB adapter separately. This is because all signals from the STM32 chip are at 3.3V and can be destroyed if it receives 5V on a pin! The 5V voltage is only used for the input of a stabilizer which produces 3.3V for all components on the board.



There is also a tricolor LED on the board consisting of 3 R,G,B LEDs connected to PB0, PB1, PA8. These 3 LEDs can be used to signal program operation. When ROM *bootloader* is active, the LEDs are off. When the user program is active, the LEDs will blink as defined in the program. This way we know who is running: *the bootloader* or the user program.

3.1 Installing serial bootloader program (STM32Flash) on PC

Download from here: https://github.com/rogerclarkmelbourne/Arduino_STM32/tree/master

(note that these tools are not Arduino specific, but can be used in the Arduino environment, hence the name). select the **<> Code** button on the page and from there "download ZIP"

master 15 Branches 2 Tags

Go to file Code

stevstrong Rename hid-flash to hid_flash

- .github/workflows Using ln -s instead of
- STM32F1 fix BOARD_NR_PWM
- STM32F4 Update wirish_digital
- drivers fixed problem in last
- tools Rename hid-flash to

Clone

Which remote URL should I use?

HTTPS GitHub CLI

https://github.com/rogerclarkmelbourne/Arduino_

Clone using the web URL.

Open with GitHub Desktop

Download ZIP

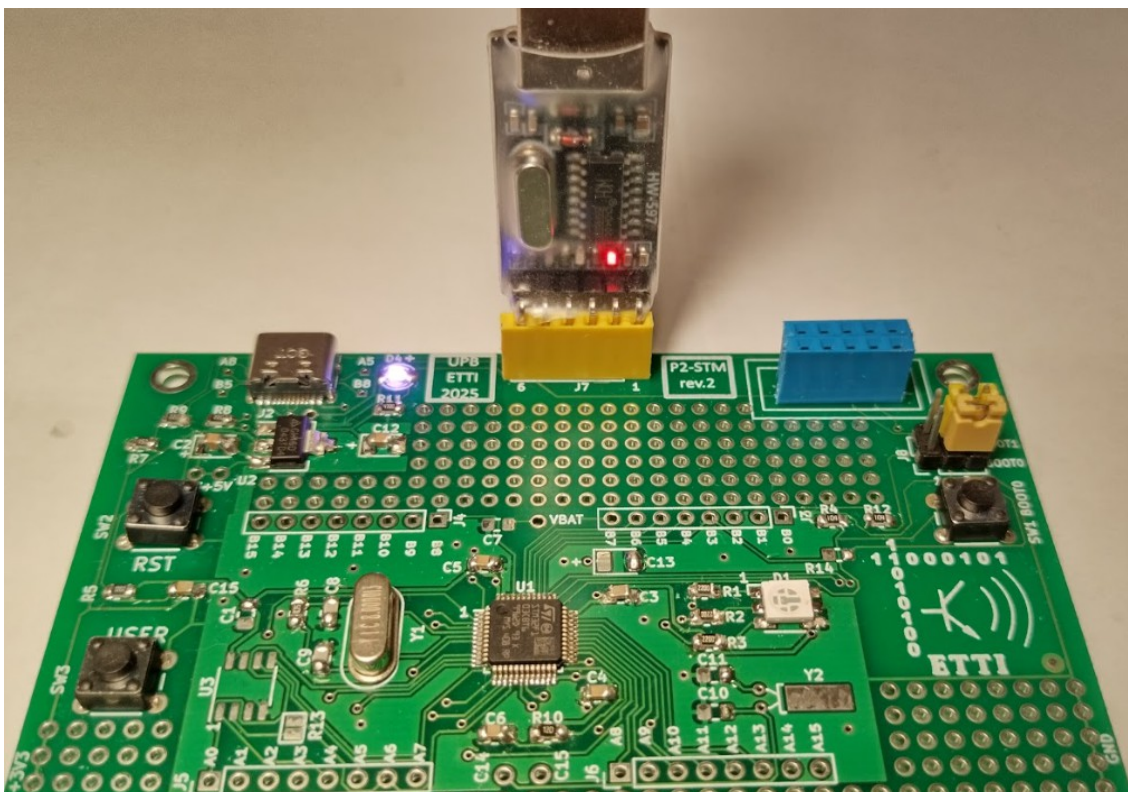
Extract from the tools archive→ win→ stm32flash.exe into a working folder, e.g. c:\project2 . This is the PC program that communicates with the bootloader on the microcontroller for loading a user program.

3.2 Loading the test software using the serial port (with USB-TTL serial adapter)

Download the ready compiled STM32F103 test software in binary format from here: <http://ham.elcom.pub.ro/proiect2/STM32/Test1.bin> . Copy the .bin file into the same folder as the executable stm32flash.exe, e.g. c:\project2

Connect the USB-TTL adapter to the board. **Attention!** Make sure that pin 1 of J7 on the board is connected to the "5V" pin of the adapter! *Do not connect the adapter backwards*, beware that the J7 does not have a key to allow single orientation.

Backwards connection may cause the board to fail, since the adapter also supplies power to the board.



From the Windows Device Manager under Ports: COM and LPT check for a USB-Serial CH340 port and its port number, e.g. COM5.

- Set jumpers BOOT0, BOOT1 to 0 (right).
- keep SW1 - BOOT0 button pressed down
- short press the RST (Reset) button and release. At this moment, the processor starts after reset and finds BOOT0=1 (because of the button) so the execution of the software will be done from the "system memory" where the bootloader is located
- release button SW1 - BOOT0
- on the PC, open a *Command Prompt*, switch to the folder that contains both the executable and the file .bin (for example: `cd c:\project2`), then run: (change the COM port number as necessary)

```
stm32flash.exe -b 115200 -w test1.bin COM5
```

wait for programming to finish with the message *Wrote address xxxxx (100%) Done*

- press briefly Reset; at this reset, the processor starts, it does not find BOOT0 pressed so the program execution is done from Flash, where the recently loaded user program is.

Alternatively, you can not use the BOOT0 button at all, but set the BOOT0 jumper to 1, press briefly and release Reset, then set the BOOT0 jumper to 0 and execute the program command. As you can see from the schematic, the SW1 - BOOT0 button is in parallel with the respective jumper - use one or the other according to preference.

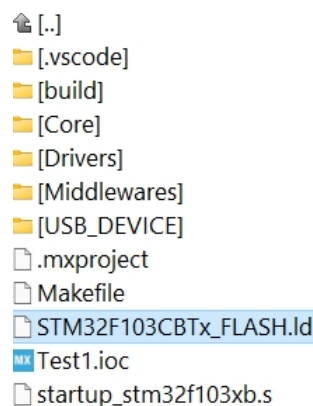
After loading the test software watch for the RGB LED to blink in succession. This indicates successful programming and operation of the test software. Also, on the UART1 port (connector J7), any X character received at 9600bps will return X+1, pressing ? will read the version number and the button will change the blink rate.

4. Recompiling the test software

This step verifies that *the* toolchain is correctly installed and allows the creation of the Text1.bin binary from the source files.

Download the test software source archive - the test1.zip file - from <http://ham.elcom.pub.ro/proiect2/STM32>.

Unzip it into any folder, it will unpack the following directory structure into a folder named for example Test1:



```
[..]  
[.vscode]  
[build]  
[Core]  
[Drivers]  
[Middlewares]  
[USB_DEVICE]  
.mxproject  
Makefile  
STM32F103CBTx_FLASH.ld  
Test1.ioc  
startup_stm32f103xb.s
```

The Test1.ioc file is the project for STM32CubeMX. The source code generated by this utility (to which I added the specific lines) is in **Core\Src** (the sources themselves) and **Core\Inc** (the #include files). The compilation and linking process will produce the executables Test1.bin, Test1.elf, Test1.hex in the **build**. All represent standard formats for several uC families. The .elf extension stands for "Executable and Linkable Format", the .hex extension is "Intel Hex" and .bin is a binary variant. All 3 formats are equivalent, but will



use one or the other depending on what the uploading software you are using supports (in our examples we use .bin). Watch the date and time of the file after you recompile to make sure it is the one produced at that time. Compiling (and linking) is done using the **make** utility which reads and applies the instructions in the Makefile. To recompile, go to the folder containing the Makefile and, making sure you set the PATH for "Make" correctly in step 1.3, issue the command:

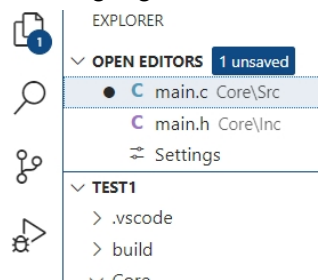
```
make all
```

If successful, messages of the following type will appear to confirm the executables produced:

```
arm-none-eabi-size build/Test1.elf
  text    date    bss    dec    hex filename
 24660    480    6632   31772   7c1c build/Test1.elf
arm-none-eabi-objcopy -O ihex build/Test1.elf build/Test1.hex
arm-none-eabi-objcopy -O binary -S build/Test1.elf build/Test1.bin
```

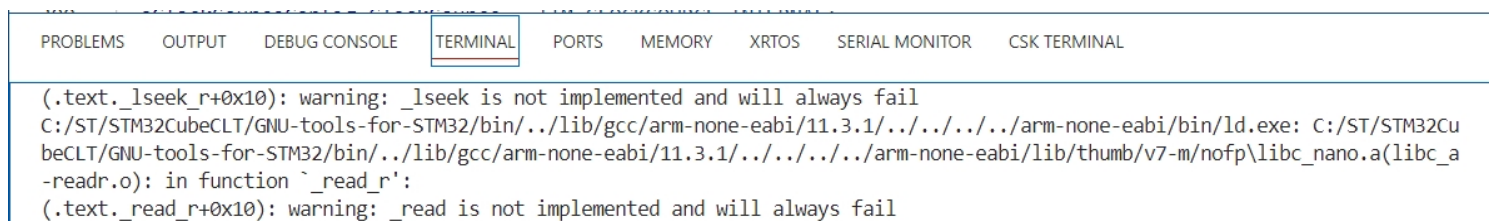
By now you have recompiled the test code already provided. *Arm-None-EABI* refers to the GCC compiler variant used, for the ARM family of microcontrollers (GCC also exists for Intel X86, etc). For code changes, open the code in the **Visual Studio Code** IDE installed in step 1. Select File→ Open Folder and select the folder where you unzipped the Test1 archive (where the Makefile is located). To view and

edit the files use the  tool in the left sidebar. For extensions select the  . If you make any changes in the code, this will be highlighted in file explorer:



Warning. Save all files in bulk using File → Save All (**CTRL K S**) For recompilation:

- Either run **make all** as above from the already opened folder in Command Prompt
- either use the Terminal included in VS Code: if it does not appear, press CTRL+J, then select Terminal (not to be confused with the *serial terminal* called *Serial Monitor*, they are separate tabs in the figure below). From the Terminal you can issue the same commands: **make all**, etc. Also there you see warnings and error messages.



The **make** command will produce nothing if it detects that the source files have not changed since the last make.