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# Graph Convolutional Neural Networks

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Lukasz Maziarka



# Convolutional Neural Networks

# Convolution operation

0	0	0	0	0	0	...
0	156	155	156	158	158	...
0	153	154	157	159	159	...
0	149	151	155	158	159	...
0	146	146	149	153	158	...
0	145	143	143	148	158	...
...	...	...	...	...	...	...

Input Channel #1 (Red)

0	0	0	0	0	0	...
0	167	166	167	169	169	...
0	164	165	168	170	170	...
0	160	162	166	169	170	...
0	156	156	159	163	168	...
0	155	153	153	158	168	...
...	...	...	...	...	...	...

Input Channel #2 (Green)

0	0	0	0	0	0	...
0	163	162	163	165	165	...
0	160	161	164	166	166	...
0	156	158	162	165	166	...
0	155	155	158	162	167	...
0	154	152	152	157	167	...
...	...	...	...	...	...	...

Input Channel #3 (Blue)

-1	-1	1
0	1	-1
0	1	1

Kernel Channel #1

1	0	0
1	-1	-1
1	0	-1

Kernel Channel #2

0	1	1
0	1	0
1	-1	1

Kernel Channel #3

308

+

-498

+

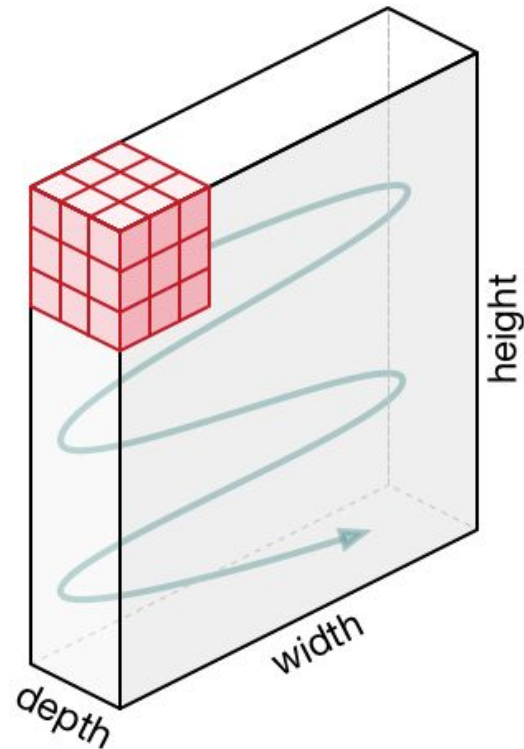
164

+ 1 = -25

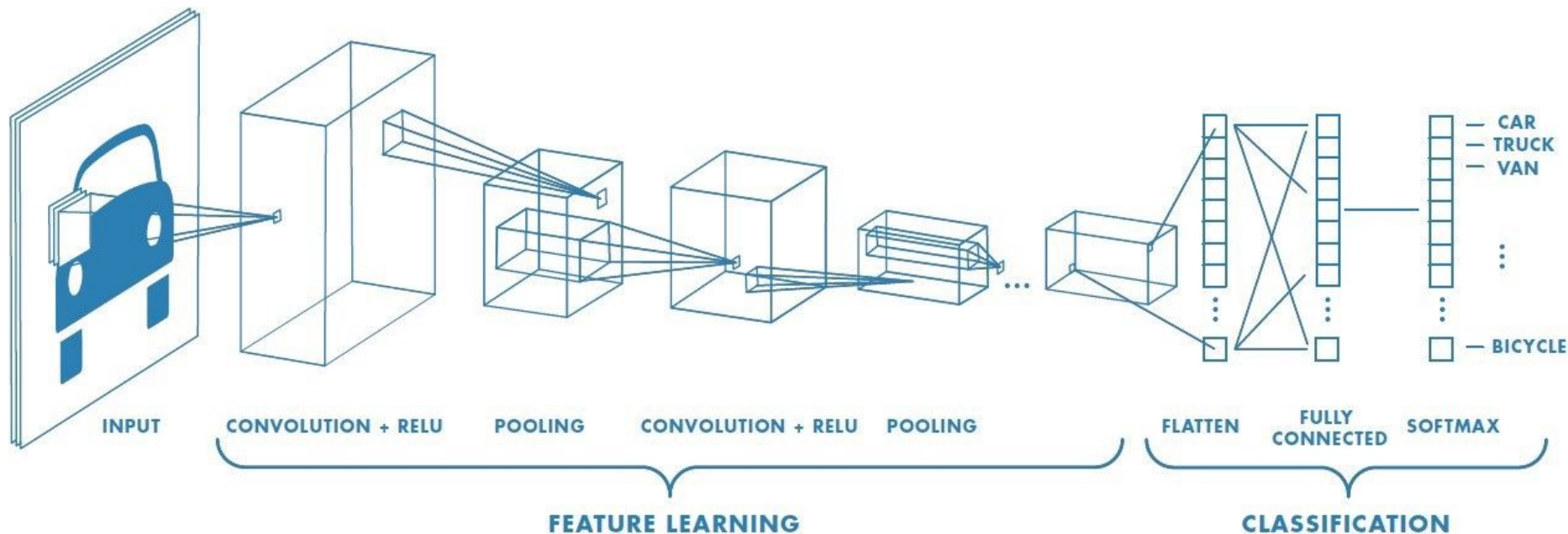
Bias = 1

Output

-25			...
			...
			...
			...
...	...	...	...



# Convolutional Neural Network



# Convolutional Neural Network

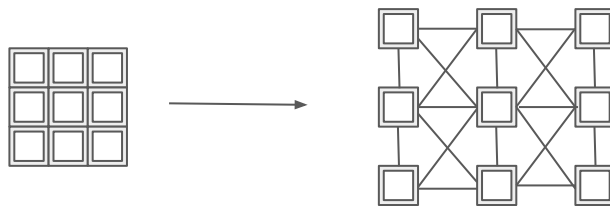
## Pros of trainable convolutional filters & weight sharing

- Custom filters (representation suitable for the given dataset)
- Equivariance for affine transform
- Much less parameters to train
  - faster training
  - less training data needed
  - less prone to overfitting
- CNNs were inspired by how the visual cortex in a human brain works. It can detect simple patterns in small receptive fields

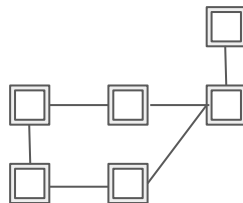


# Graph Convolutional Neural Networks

# Graph Convolution



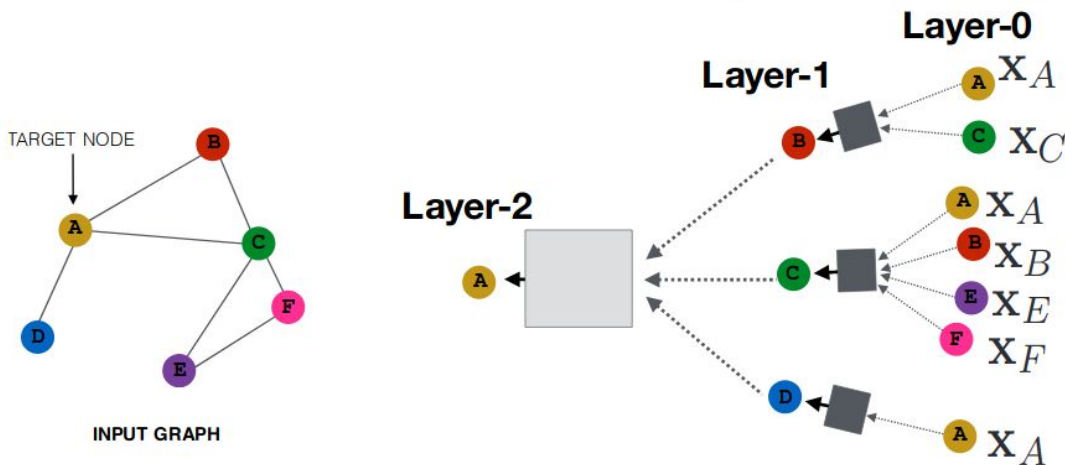
Images can be represented as a graph



However usually graphs do not have such nice structure

## Neighborhood Aggregation

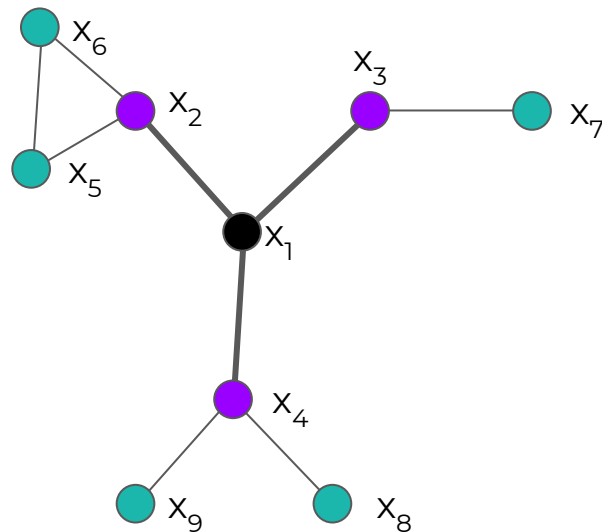
- Nodes have embeddings at each layer.
- Model can be arbitrary depth.
- “layer-0” embedding of node  $u$  is its input feature, i.e.  $x_u$ .





# Graph Convolutional Layer

Learning new nodes representation



Calculating new node vectors

$$h_i^{(k)} = ReLU(W^{(k)}x_i)$$

$$x_i^{(k+1)} = \frac{1}{|j : (i, j) \in E|} \sum_{j: (i, j) \in E} h_j^{(k)}$$

Calculating graph representation

$$x_{graph} = \frac{1}{|V|} \sum_{v \in V} x_v^{(N)}$$

## 1. Message passing phase

$$m_v^{t+1} = \sum_{w \in N(v)} M_t(h_v^t, h_w^t, e_{vw})$$

$$h_v^{t+1} = U_t(h_v^t, m_v^{t+1})$$

## 2. Readout phase

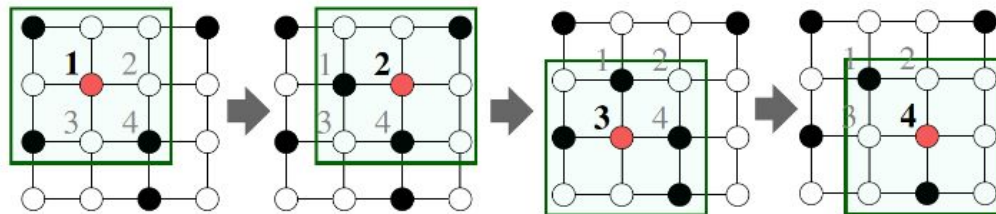
$$\hat{y} = R(\{h_v^T \mid v \in G\}).$$

The message functions  $\mathbf{M}_t$ , vertex update functions  $\mathbf{U}_t$  and readout function  $\mathbf{R}$  are all learned differentiable functions (Neural networks).

$\mathbf{R}$  operates on the set of node states and must be invariant to permutations of the node states in order for the MPNN to be invariant to graph isomorphism.

## Neighborhood “Convolutions”

- Neighborhood aggregation can be viewed as a center-surround filter.



- Mathematically related to spectral graph convolutions (see [Bronstein et al., 2017](#))

# Input atom representations

Indices	Description
0 – 10	Atomic identity as a one-hot vector of B, N, C, O, F, P, S, Cl, Br, I, other
11 – 16	Number of heavy neighbors as one-hot vector of 0, 1, 2, 3, 4, 5
17 – 21	Number of hydrogen atoms as one-hot vector of 0, 1, 2, 3, 4
22	Formal charge
23	Is in a ring
24	Is aromatic

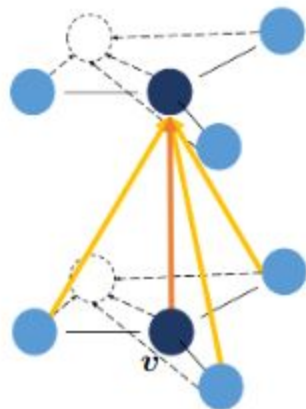


# Possible extensions

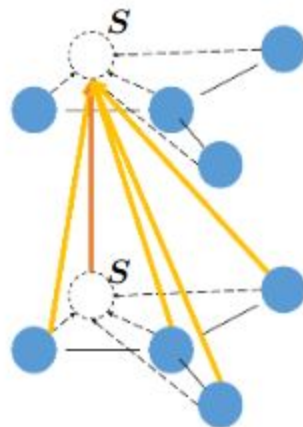
# Add edge features

Indices	Description
0-3	Bond order as one-hot vector of 1, 1.5, 2, 3
4	Is aromatic
5	Is conjugated
6	Is in a ring
7	Placeholder, is a bond

# Super node

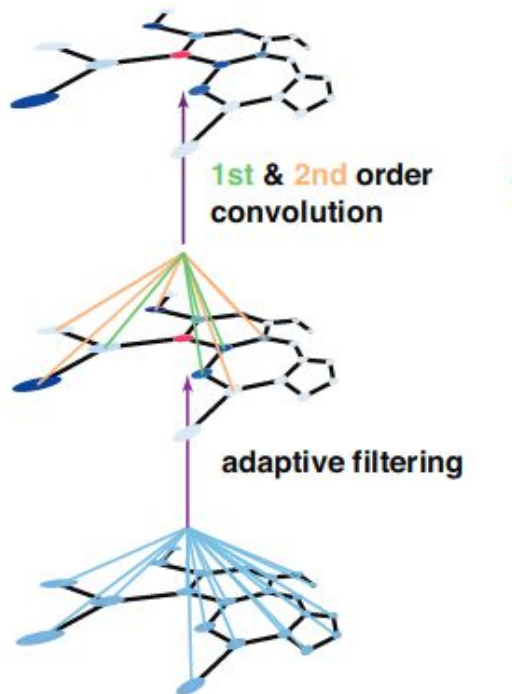


GraphConv



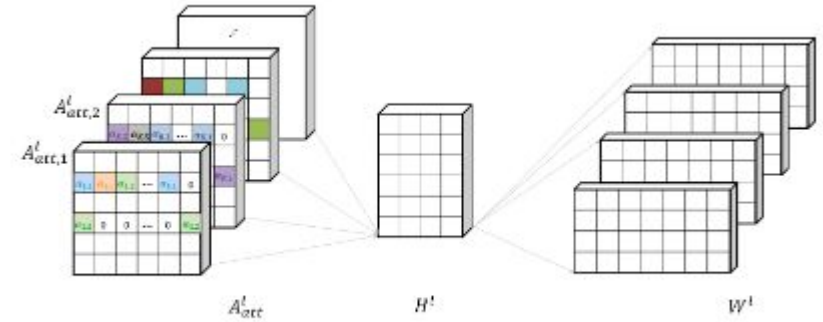
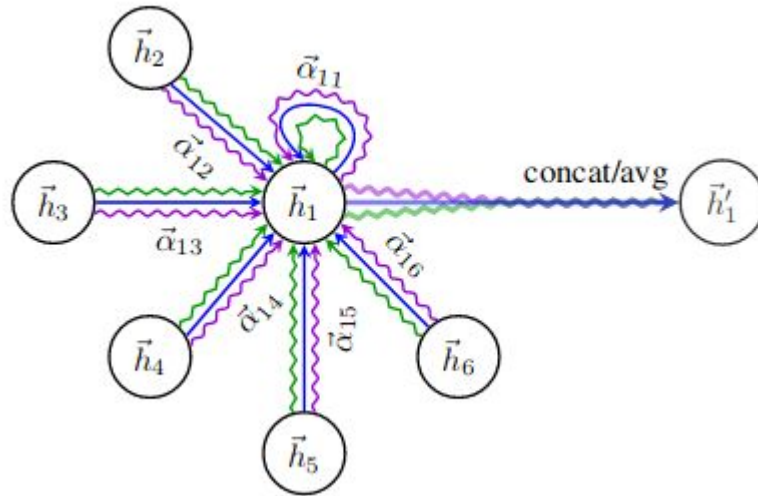
GraphConv(Super Node)

# Add higher order convolutions





# Add attention



$$\alpha_{ij} = \frac{\exp \left( \text{LeakyReLU} \left( \vec{a}^T [\mathbf{W} \vec{h}_i \| \mathbf{W} \vec{h}_j] \right) \right)}{\sum_{k \in \mathcal{N}_i} \exp \left( \text{LeakyReLU} \left( \vec{a}^T [\mathbf{W} \vec{h}_i \| \mathbf{W} \vec{h}_k] \right) \right)}$$

# Self attention & distances

## Molecule Transformer

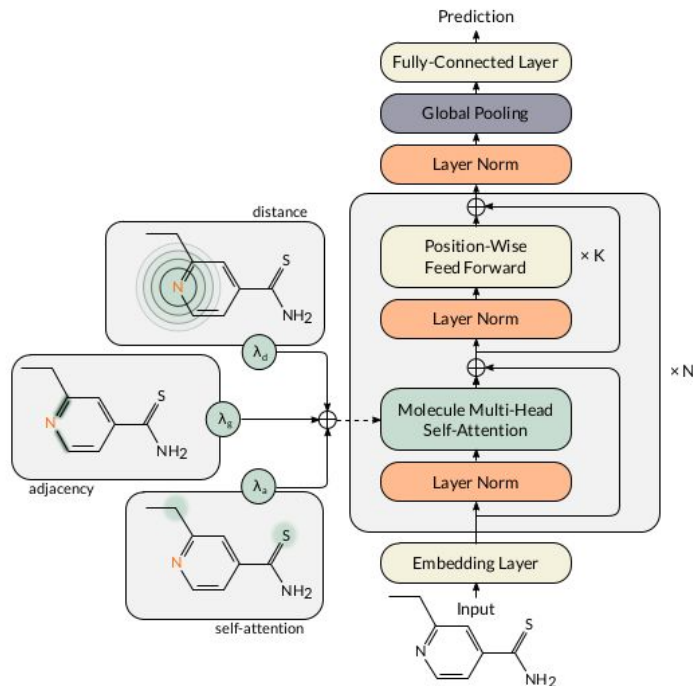


Figure 1: Molecule Transformer architecture. In the first layer we embed each atom using one-hot encoding and atomic features. The main innovation is the Molecule Multi-Head Self-Attention block that augments the self-attention module with distance, and graph structure of the molecule.



# PyTorch Geometric

PyTorch Geometric (PyG) is a geometric deep learning extension library for PyTorch.

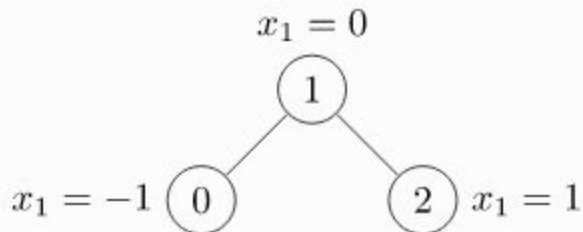
- [Github](#)
  - [Documentation](#)
  - [Tutorial](#)
  - [Paper](#)
-

# Representing Graphs

```
import torch
from torch_geometric.data import Data

edge_index = torch.tensor([[0, 1, 1, 2],
                           [1, 0, 2, 1]], dtype=torch.long)
x = torch.tensor([[-1], [0], [1]], dtype=torch.float)

data = Data(x=x, edge_index=edge_index)
>>> Data(edge_index=[2, 4], x=[3, 1])
```



# Working with data

- Merging them into batches
- Create Datasets
- Create Data Loaders
- Making Data Transformations

# Many included datasets

For both graph and node classification

- KarateClub
- TUDataset
- Planetoid
- CoraFull
- Coauthor
- Amazon
- PPI
- Reddit
- QM7b
- QM9
- Entities
- GEDDataset
- MNISTSuperpixels
- FAUST
- PascalVOCKeypoints
- DynamicFAUST
- ShapeNet
- ModelNet
- CoMa
- SHREC2016
- TOSCA
- PCPNetDataset
- S3DIS
- GeometricShapes
- BitcoinOTC
- ICEWS18
- GDELT
- DBP15K
- WILLOWObjectClass
- PascalPF

# Creating Message Passing Networks

“MessagePassing” is a base class in Torch Geometric

```
class MessagePassing(aggr='add', flow='source_to_target', node_dim=0) [source]
```

Base class for creating message passing layers

$$\mathbf{x}'_i = \gamma_{\Theta} \left( \mathbf{x}_i, \square_{j \in \mathcal{N}(i)} \phi_{\Theta} (\mathbf{x}_i, \mathbf{x}_j, \mathbf{e}_{i,j}) \right),$$

where  $\square$  denotes a differentiable, permutation invariant function, e.g., sum, mean or max, and  $\gamma_{\Theta}$  and  $\phi_{\Theta}$  denote differentiable functions such as MLPs. See [here](#) for the accompanying tutorial.

Parameters:

- **aggr** (*string, optional*) – The aggregation scheme to use ( "add", "mean" or "max" ). (default: "add" )
- **flow** (*string, optional*) – The flow direction of message passing ( "source\_to\_target" or "target\_to\_source" ). (default: "source\_to\_target" )
- **node\_dim** (*int, optional*) – The axis along which to propagate. (default: 0 )



# Creating Message Passing Networks

## Implementing GCN layer

$$\mathbf{x}_i^{(k)} = \sum_{j \in \mathcal{N}(i) \cup \{i\}} \frac{1}{\sqrt{\deg(i)} \cdot \sqrt{\deg(j)}} \cdot (\Theta \cdot \mathbf{x}_j^{(k-1)})$$

```
class GCNConv(MessagePassing):
    def __init__(self, in_channels, out_channels):
        super(GCNConv, self).__init__(aggr='add') # "Add" aggregation.
        self.lin = torch.nn.Linear(in_channels, out_channels)

    def forward(self, x, edge_index):
        # x has shape [N, in_channels]
        # edge_index has shape [2, E]

        # Step 1: Add self-loops to the adjacency matrix.
        edge_index, _ = add_self_loops(edge_index, num_nodes=x.size(0))

        # Step 2: Linearly transform node feature matrix.
        x = self.lin(x)

        # Step 3-5: Start propagating messages.
        return self.propagate(edge_index, size=(x.size(0), x.size(0)), x=x)

    def message(self, x_j, edge_index, size):
        # x_j has shape [E, out_channels]

        # Step 3: Normalize node features.
        row, col = edge_index
        deg = degree(row, size[0], dtype=x_j.dtype)
        deg_inv_sqrt = deg.pow(-0.5)
        norm = deg_inv_sqrt[row] * deg_inv_sqrt[col]

        return norm.view(-1, 1) * x_j

    def update(self, aggr_out):
        # aggr_out has shape [N, out_channels]

        # Step 5: Return new node embeddings.
        return aggr_out
```

# And many more implemented layers!

- **SplineConv** from Fey *et al.*: [SplineCNN: Fast Geometric Deep Learning with Continuous B-Spline Kernels](#) (CVPR 2018)
- **GCNConv** from Kipf and Welling: [Semi-Supervised Classification with Graph Convolutional Networks](#) (ICLR 2017)
- **ChebConv** from Defferrard *et al.*: [Convolutional Neural Networks on Graphs with Fast Localized Spectral Filtering](#) (NIPS 2016)
- **NNConv** from Gilmer *et al.*: [Neural Message Passing for Quantum Chemistry](#) (ICML 2017)
- **CGConv** from Xie and Grossman: [Crystal Graph Convolutional Neural Networks for an Accurate and Interpretable Prediction of Material Properties](#) (Physical Review Letters 120, 2018)
- **ECConv** from Simonovsky and Komodakis: [Edge-Conditioned Convolution on Graphs](#) (CVPR 2017)
- **GATConv** from Veličković *et al.*: [Graph Attention Networks](#) (ICLR 2018)
- **SAGEConv** from Hamilton *et al.*: [Inductive Representation Learning on Large Graphs](#) (NIPS 2017)
- **GraphConv** from, e.g., Morris *et al.*: [Weisfeiler and Leman Go Neural: Higher-order Graph Neural Networks](#) (AAAI 2019)
- **GatedGraphConv** from Li *et al.*: [Gated Graph Sequence Neural Networks](#) (ICLR 2016)
- **GINConv** from Xu *et al.*: [How Powerful are Graph Neural Networks?](#) (ICLR 2019)
- **ARMAConv** from Bianchi *et al.*: [Graph Neural Networks with Convolutional ARMA Filters](#) (CoRR 2019)
- **SGConv** from Wu *et al.*: [Simplifying Graph Convolutional Networks](#) (CoRR 2019)
- **APNP** from Klicpera *et al.*: [Predict then Propagate: Graph Neural Networks meet Personalized PageRank](#) (ICLR 2019)
- **AGNNConv** from Thekumparampil *et al.*: [Attention-based Graph Neural Network for Semi-Supervised Learning](#) (CoRR 2017)
- **TAGConv** from Du *et al.*: [Topology Adaptive Graph Convolutional Networks](#) (CoRR 2017)
- **RGCNConv** from Schlichtkrull *et al.*: [Modeling Relational Data with Graph Convolutional Networks](#) (ESWC 2018)
- **SignedConv** from Derr *et al.*: [Signed Graph Convolutional Network](#) (ICDM 2018)
- **DNAConv** from Fey: [Just Jump: Dynamic Neighborhood Aggregation in Graph Neural Networks](#) (ICLR-W 2019)
- **EdgeConv** from Wang *et al.*: [Dynamic Graph CNN for Learning on Point Clouds](#) (CoRR, 2018)
- **PointConv** (including [Iterative Farthest Point Sampling](#), dynamic graph generation based on [nearest neighbor](#) or [maximum distance](#), and [k-NN interpolation](#) for upsampling) from Qi *et al.*: [PointNet: Deep Learning on Point Sets for 3D Classification and Segmentation](#) (CVPR 2017) and [PointNet++: Deep Hierarchical Feature Learning on Point Sets in a Metric Space](#) (NIPS 2017)
- **XConv** from Li *et al.*: [PointCNN: Convolution On X-Transformed Points](#) (official implementation) (NeurIPS 2018)
- **PPFConv** from Deng *et al.*: [PPFNet: Global Context Aware Local Features for Robust 3D Point Matching](#) (CVPR 2018)
- **GMMConv** from Monti *et al.*: [Geometric Deep Learning on Graphs and Manifolds using Mixture Model CNNs](#) (CVPR 2017)
- **FeaStConv** from Verma *et al.*: [FeaStNet: Feature-Steered Graph Convolutions for 3D Shape Analysis](#) (CVPR 2018)
- **HypergraphConv** from Bai *et al.*: [Hypergraph Convolution and Hypergraph Attention](#) (CoRR 2019)
- A **MetaLayer** for building any kind of graph network similar to the [TensorFlow Graph Nets library](#) from Battaglia *et al.*: [Relational Inductive Biases, Deep Learning, and Graph Networks](#) (CoRR 2018)
- **GlobalAttention** from Li *et al.*: [Gated Graph Sequence Neural Networks](#) (ICLR 2016)
- **Set2Set** from Vinyals *et al.*: [Order Matters: Sequence to Sequence for Sets](#) (ICLR 2016)
- **Sort Pool** from Zhang *et al.*: [An End-to-End Deep Learning Architecture for Graph Classification](#) (AAAI 2018)
- **Dense Differentiable Pooling** from Ying *et al.*: [Hierarchical Graph Representation Learning with Differentiable Pooling](#) (NeurIPS 2018)
- **Graclus Pooling** from Dhillon *et al.*: [Weighted Graph Cuts without Eigenvectors: A Multilevel Approach](#) (PAMI 2007)
- **Voxel Grid Pooling** from, e.g., Simonovsky and Komodakis: [Dynamic Edge-Conditioned Filters in Convolutional Neural Networks on Graphs](#) (CVPR 2017)
- **Top-K Pooling** from Gao and Ji: [Graph U-Nets](#) (ICML 2019), Cangea *et al.*: [Towards Sparse Hierarchical Graph Classifiers](#) (NeurIPS-W 2018) and Knyazev *et al.*: [Understanding Attention and Generalization in Graph Neural Networks](#) (ICLR-W 2019)
- **SAG Pooling** from Lee *et al.*: [Self-Attention Graph Pooling](#) (ICML 2019) and Knyazev *et al.*: [Understanding Attention and Generalization in Graph Neural Networks](#) (ICLR-W 2019)
- **Edge Pooling** from Diehl *et al.*: [Towards Graph Pooling by Edge Contraction](#) (ICML-W 2019) and Diehl: [Edge Contraction Pooling for Graph Neural Networks](#) (CoRR 2019)
- **Local Degree Profile** from Cai and Wang: [A Simple yet Effective Baseline for Non-attribute Graph Classification](#) (CoRR 2018)
- **Jumping Knowledge** from Xu *et al.*: [Representation Learning on Graphs with Jumping Knowledge Networks](#) (ICML 2018)
- **Node2Vec** from Grover and Leskovec: [node2vec: Scalable Feature Learning for Networks](#) (KDD 2016)
- **Deep Graph Infomax** from Veličković *et al.*: [Deep Graph Infomax](#) (ICLR 2019)
- All variants of **Graph Auto-Encoders** from Kipf and Welling: [Variational Graph Auto-Encoders](#) (NIPS-W 2016) and Pan *et al.*: [Adversarially Regularized Graph Autoencoder for Graph Embedding](#) (IJCAI 2018)
- **RENet** from Jin *et al.*: [Recurrent Event Network for Reasoning over Temporal Knowledge Graphs](#) (ICLR-W 2019)
- **GraphUNet** from Gao and Ji: [Graph U-Nets](#) (ICML 2019)
- **NeighborSampler** from Hamilton *et al.*: [Inductive Representation Learning on Large Graphs](#) (NIPS 2017)

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**Thank You!**

