



Neural Network Development for Predicting Instant Fuel Economy

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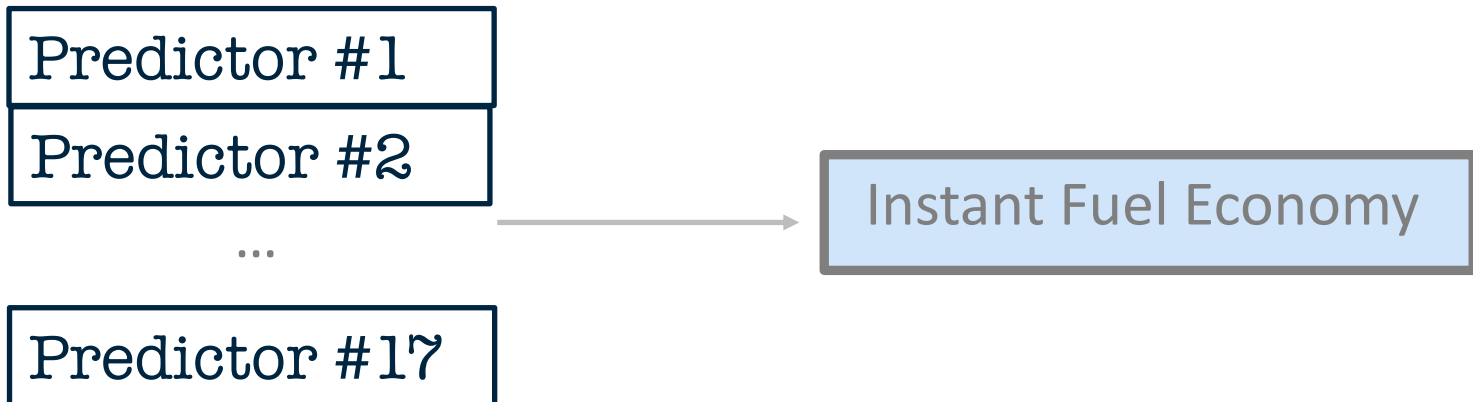
CS 229A: Applied Machine Learning
Spring 2019

Introduction

- Engine performance calculation is expensive with traditional techniques, and can take days to simulate with physics equations
- In this project, we aim to predict instant fuel economy within a reasonable range of the true instant fuel economy
- Predicting instant fuel economy with neural nets decreases computation time since it does not rely on physics equations to compute

Motivation

- Traditional physics-based model takes 400 hours to run, which is extremely expensive. [5] Ours takes 2 minutes to run.
- Current models unable to adapt to environment/driver variability.



- Baseline: Linear Regression with 7.51% accuracy

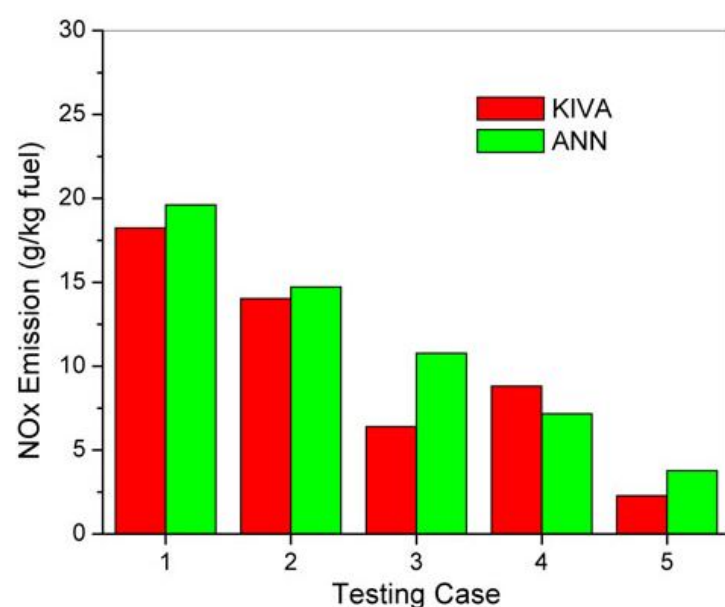


Fig. 1 KIVA vs. ANN

- Similar Performance but slower computational speed

Dataset

Input data:

- Car diagnostic data obtained via OBDLink LX tool from 2017 Mazda 3
- A total of 4,861 examples obtained from 2.05 hours of driving

Dataset



Fig. 2 Experimental Setup

Filtering:

- Redundant features removed such as Long term fuel trim 3, total fuel economy

Regional:

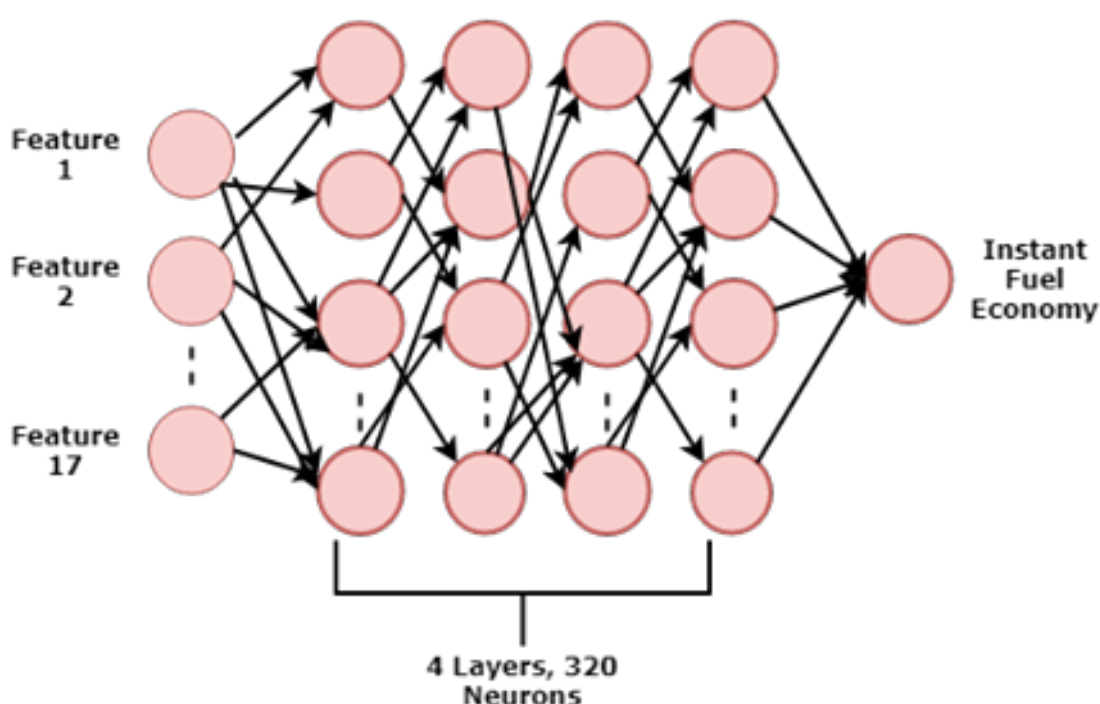
- Data was obtained on the highway and neighborhood streets

| | Absolute load value (%) | Absolute throttle position (%) | Ambient air temperature (F) | Barometric pressure (inHg) | Calculated load value (%) | Commanded fuel rail pressure A (inHg) | Engine coolant temperature (F) | Engine RPM (RPM) | Fuel level input (%) |
|---|-------------------------|--------------------------------|-----------------------------|----------------------------|---------------------------|---------------------------------------|--------------------------------|------------------|----------------------|
| 0 | 21.56863 | 9.411765 | 64.4 | 29.8254 | 15.29412 | 885.9030 | 183.2 | 1431.00 | 81.17647 |
| 1 | 19.60784 | 11.764710 | 59.0 | 29.8254 | 33.72549 | 933.1512 | 185.0 | 575.75 | 89.41177 |
| 2 | 41.56863 | 20.392160 | 59.0 | 29.8254 | 44.70588 | 1866.3020 | 183.2 | 1424.75 | 62.35294 |
| 3 | 25.09804 | 14.509800 | 64.4 | 29.8254 | 34.11765 | 1163.4860 | 186.8 | 1053.75 | 70.98039 |
| 4 | 79.21568 | 32.941180 | 59.0 | 29.8254 | 96.07843 | 2769.9230 | 185.0 | 1400.75 | 60.39216 |
| 5 | 11.37255 | 11.764710 | 71.6 | 29.5301 | 13.72549 | 885.9030 | 188.6 | 1221.50 | 92.94118 |
| 6 | 10.98039 | 12.156860 | 62.6 | 29.5301 | 12.94118 | 885.9030 | 181.4 | 1477.50 | 50.19608 |

Table 1. Raw Data

Models

- Baseline model: linear regression.
- Developed Model: Neural Network



$$error = \sum_i (y_i - \hat{y}_i)^2$$

Fig. 3 Graph of MSE over Epoch for NN Model D

Results

- 2917 samples in training sets, 972 samples in validation sets, and 972 samples in testing data sets
- As we increase our layers and neurons, the loss decreases.

| Experiments | Learning Rate | Epochs | Num of Layers | Num of Neurons | Accuracy (%) |
|-------------------|---------------|--------|---------------|-----------------|--------------|
| Linear Regression | n/a | n/a | n/a | n/a | 7.51 |
| NN Model A | 0.001 | 250 | 1 | 5 | 42.19 |
| NN Model B | 0.001 | 250 | 1 | 20 | 57.13 |
| NN Model C | 0.001 | 130 | 3 | 15,10,5 | 74.29 |
| NN Model D | 0.001 | 130 | 4 | 330,330,330,330 | 89.33 |

Table 2. Hyperparameters for Each Model

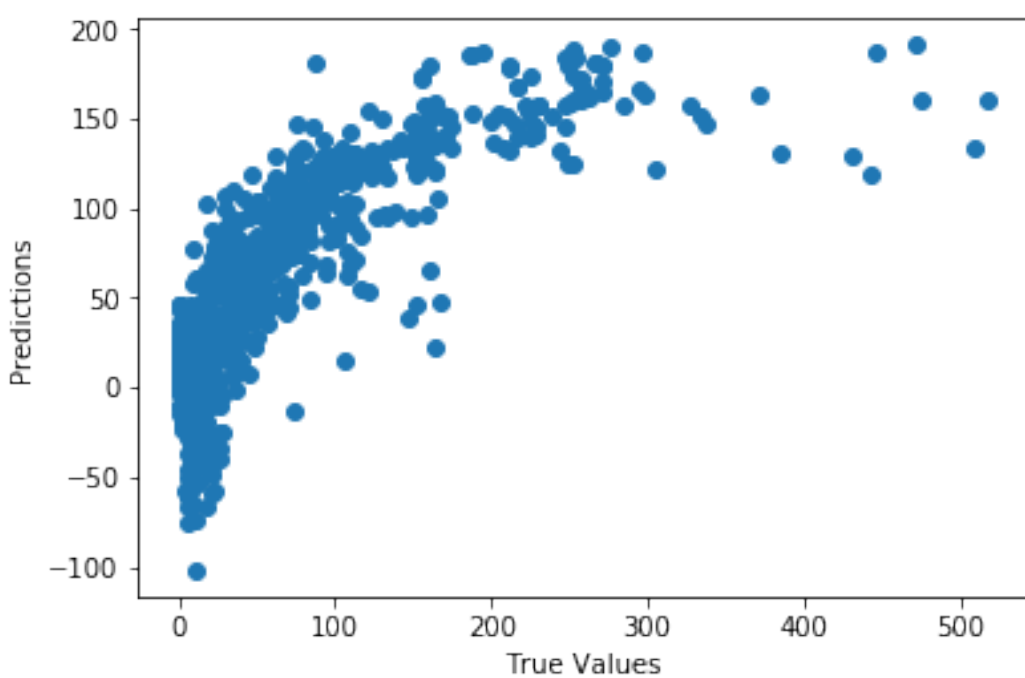


Fig. 4 Prediction for Linear Regression

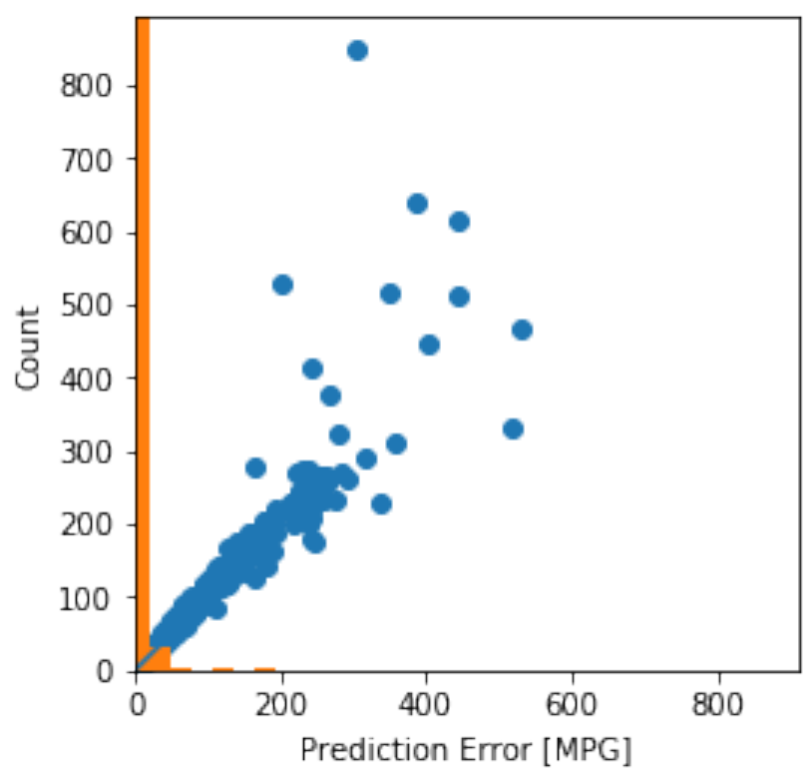


Fig. 5 Prediction for NN Model D

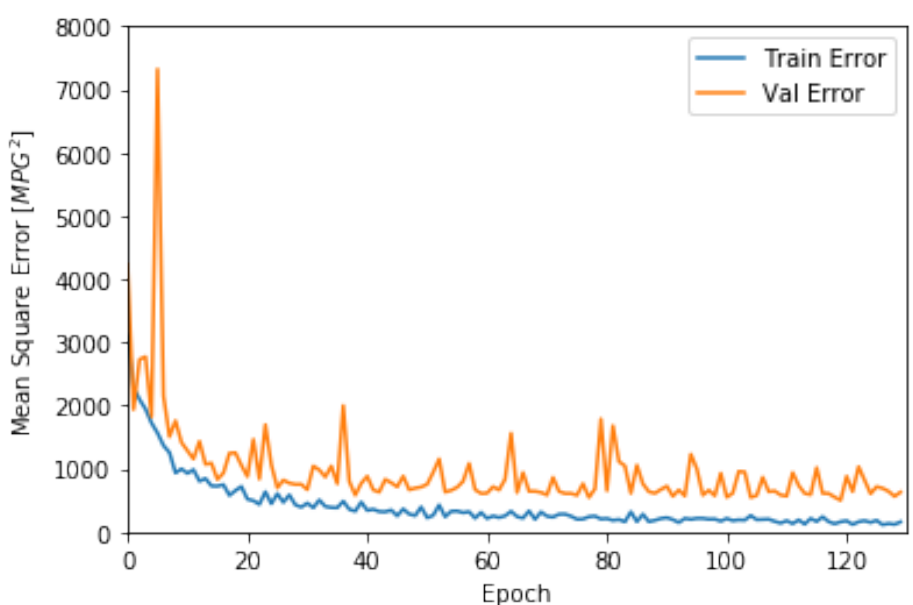


Fig. 6 Graph of MSE over Epoch for NN Model D

Results

| Model | Training Error | Test Error |
|-------------------|----------------|------------|
| Linear Regression | 132 | 402.02 |
| NN Model A | 2122.2996 | 1690.693 |
| NN Model B | 817.5392 | 2006.672 |
| NN Model C | 293.29 | 512.43 |
| NN Model D | 233.2 | 839 |

Table 3. Training and Test Errors for Each Models

Discussion and Future Work

Insights

- Model D with 4 hidden layers and 330 neurons in each layer has the best accuracy rate.
- Expected, because it is the most complex model to predict a non-linear relationship.
- Acceptable, because it has an accuracy rate close to 90%.
- Nonetheless, the loss graph indicates modest to high variance.

Future work:

- More data in a variety of regions because we want to increase our variability
- More data from other cars

References

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