CPSC532W - Homework 2

1 Importance Sampling

I implemented importance sampling using algorithm 7 in the evaluation-based approach. A critical, if not the only critical, aspect of this implementation is the addition of algorithm 7 in an if-else statement in evaluate_program which determines whether or not to do importance sampling or prior sampling. The implementation of algorithm 7 looks like:

```
print('Importance Sampling')
_{2} L = prog_{args}
importance_out = []
 for l in range (L):
      r_l, sigma_l = eval(ast[-1], {'logW': 0}, {})
      importance_out.append([r_l,sigma_l['logW']])
8 return importance_out
     Program 1
 Importance Sampling
 elapsed time: 2.9012100999999997
 expectation after 10000 samples is: tensor(7.2841)
 variance is: tensor(0.7555)
     Program 2
 Importance Sampling
 elapsed time: 14.776718100000004
 expectation after 10000 samples is: tensor([ 2.1579, -0.5967])
 variance is: tensor([0.0575, 0.8448])
     Program 3
 Importance Sampling
 elapsed time: 17.359110200000003
 expectation after 10000 samples is: tensor(0.9277)
 variance is: tensor(0.0670)
     Program 4
 Importance Sampling
 elapsed time: 6.129940199999993
 expectation after 10000 samples is: tensor(0.3189)
 variance is: tensor(0.2172)
     The histograms of the outputs are:
```

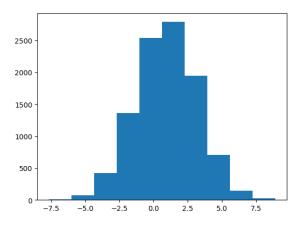


Figure 1: Program 1

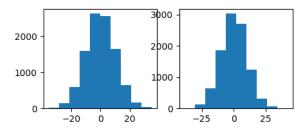


Figure 2: Program 2

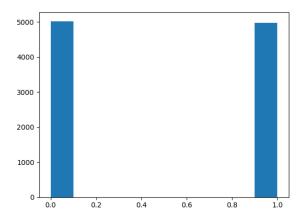


Figure 3: Program 3

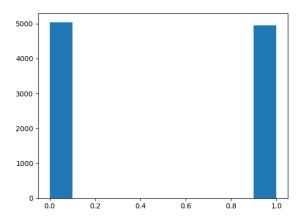


Figure 4: Program 4

2 MH in Gibbs

I implemented Metropolis Hasting within Gibbs from algorithm 1 using the graph-based evaluator. Critical aspects of this implementation were the functions gibbs, gibb_step, and accept below:

```
def gibbs (graph, S):
       procs, model, expr = graph[0], graph[1], graph[2]
       nodes, edges, links, obs = model['V'], model['A'], model['P'], model['Y']
       sorted_nodes = topological_sort(nodes, edges)
       full_output = sample_from_joint(graph)
      X0 = full_output[2]
      Q = \{\}
8
      Q_{temp} = \{ k : links[k] \text{ for } k \text{ in } set(links) - set(obs) \}
9
       for q_key in sorted_nodes: # sort Q topologically
           if q_key in list(Q_temp.keys()):
12
               Q[q_key] = Q_temp[q_key]
      X = [\{k : X0[k] \text{ for } k \text{ in } list(Q.keys())\}]
13
       X_{out} = [deterministic_eval(plugin_parent_values(expr, X[0]))]
14
       for q_key in list (Q.keys()):
           q = Q[q_key]
16
           q = nested_search('sample*', 'sampleS', q)
           Q[q_{key}] = plugin_{parent_values}(q, obs)
       for s in range (1,S+1):
19
           X. append(gibbs\_step({**X[s-1]},Q))
20
           X_out.append(deterministic_eval(plugin_parent_values(expr,X[s])))
       return X_out
22
```

```
def gibbs_step(X,Q):
    for x in list(Q.keys()):
        q = Q[x]
        q = plugin_parent_values(q, X)
        x_sample = deterministic_eval(q)

alpha = accept(x,x_sample,X,Q)
        u = torch.distributions.Uniform(0,1).sample()
```

```
if bool(u < alpha):
                X[x] = x\_sample
            return X
12
  def accept (x, x-sample, X0,Q):
1
       Xp = \{**X0\}
       Xp[x] = x\_sample
3
       q = Q[x] \# q is the same for both X and X'
       q_{expr0} = ["observeS", q[1], X0[x]]

q_{expr1} = ["observeS", q[1], x_sample]
6
       log_alpha = deterministic_eval(q_expr0) - deterministic_eval(q_expr1)
       Vx = [x]
9
       for X_key in list(X0.keys()):
10
            if child(x,Q[X_key]):
11
12
                Vx. append (X_key)
       for v in Vx:
           v_{expr1} = ["observeS", plugin_parent_values(Q[v][1], Xp), X0[v]]
14
           v_{expr0} = ["observeS", plugin_parent_values(Q[v][1], X0), X0[v]]
           log_alpha = log_alpha + deterministic_eval(v_expr1)
16
           log_alpha = log_alpha - deterministic_eval(v_expr0)
17
       return torch.exp(log_alpha)
     Program 1
  elapsed time is: 5.9493032
  expectation after 10000 samples is: -1.6739925
  variance after 10000 samples is: 42.757023
     Program 2
  elapsed time is: 5.811423700000006
  expectation after 10000 samples is: [4.5246744, 11.137395]
  variance after 10000 samples is: [497.57785, 0.0]
     Program 3
  elapsed time is: 5.824858800000001
  expectation after 10000 samples is: 1.0
  variance after 10000 samples is: 0.0
     Program 4
  elapsed time is: 7.756563999999997
  expectation after 10000 samples is: 0.0
  variance after 10000 samples is: 0.0
     The histograms of the outputs are:
```

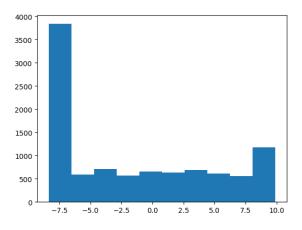


Figure 5: Program 1

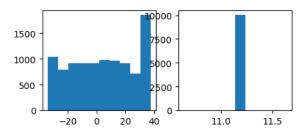


Figure 6: Program 2

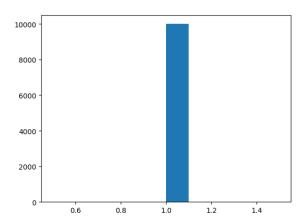


Figure 7: Program 3

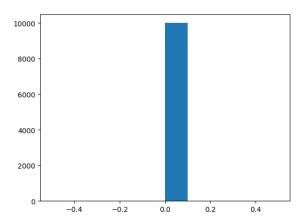


Figure 8: Program 4

And the plots of the trace for programs 1 and 2 are:

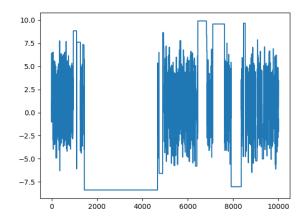


Figure 9: Program 1

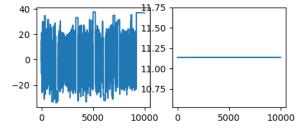


Figure 10: Program 2

Note: the plots don't look at all like the ones from importance sampling, and I'm more inclined to

trust the importance sampling results.. So, there's at least one thing wrong in my MH in Gibbs code somewhere.

3 HMC and program 5

I didn't have time to get to these.

Appendix A - Code

https://github.com/e-vic/cpsc532hw