```
Data: A text with annotations, stored as a String-Array
   Result: A Graph (as described above)
1 initialization
_{2} foreach w in words do
      if w is annotation then
         v ←new Vertex(previousWord.getCenter())
         v.setAnnotation(w)
5
6
         Graph.addVertex(v)
         UpperVerticesList.addVertex(v)
7
8
      else
9
         if w is too big for the line then
             startNewLine()
10
             connectBasedOnPosition(UpperVerticesList)
11
             UpperVerticesList \leftarrow LowerVerticesList
12
13
             emptyList(LowerVerticesList)
         end
14
         v1 ←new Vertex(w.getTopLeft())
15
         v2 ←new Vertex(w.getTopRight())
16
         v3 ←new Vertex(w.getBottomLeft())
17
         v4 \leftarrow new Vertex(w.getBottomRight())
19
         Graph.addAll(v1,v2,v3,v4)
20
         UpperVerticesList.addAll(v1,v2)
21
         LowerVerticesList.addAll(v3,v4)
22
23
         Graph.createEdgeBetween(v1,v3)
         Graph.createEdgeBetween(v2,v4)
24
25
      end
26 end
```

Algorithm 1: TODO

```
Data: A single annotation's source and its Graph
   Result: A List of vertices describing the Leader's Path
 1 initialization
 {f 2} while currentVertex not at right text border {f do}
         ({\sf Graph.getTopNeighbourOf(currentVertex}) \neq null) \land \neg {\sf backtracking}
            Path.addVertex(currentVertex)
 4
            currentVertex \leftarrow Graph.getTopNeighbourOf(currentVertex)
 \mathbf{5}
 6
       \mathbf{else} \ \mathbf{if} \ \mathsf{Graph}. \mathtt{getRightNeighbourOf} \ (\mathtt{currentVertex}) \neq null \ \mathbf{then}
 7
            Path.addVertex(currentVertex)
 8
 9
            currentVertex <- Graph.getTopNeighbourOf(currentVertex)</pre>
            \mathsf{backtracking} \leftarrow \mathrm{False}
10
11
       else
12
            \mathsf{backtracking} \leftarrow \mathsf{True}
            repeat
13
                \mathsf{oldVertex} \leftarrow \mathsf{currentVertex}
14
                currentVertex ← Path.getLastEntry()
15
16
                Path.RemoveVertex(currentVertex)
            until currentVertex's Position is below oldVertex or
17
               Path is Empty
18
            if currentVertex not below oldVertex then //No path found
19
                break
20
21
            end
       end
22
23 end
```

Algorithm 2: TODO