



$$a = (a_1, a_2, a_3)$$

$$b = (b_1, b_2, b_3)$$

(a, b, z)

$$a \times b = (a_1 e_1 + a_2 e_2 + a_3 e_3) \times (b_1 e_1 + b_2 e_2 + b_3 e_3)$$

$$= (a_1 b_1 \frac{e_1 \times e_1}{0} + \cancel{a_1 b_2} \frac{e_1 \times e_2}{\sqrt{e_3}} + a_1 b_3 \frac{e_1 \times e_3}{\cancel{e_2}} + a_2 b_1 \frac{e_2 \times e_1}{-\sqrt{e_3}} + a_2 b_2 \frac{e_2 \times e_2}{0} + a_2 b_3 \frac{e_2 \times e_3}{e_1} + a_3 b_1 \frac{e_3 \times e_1}{e_2} + a_3 b_2 \frac{e_3 \times e_2}{-\sqrt{e_1}} + a_3 b_3 \frac{e_3 \times e_3}{0})$$

自分軸の要素がはい

$$= \begin{pmatrix} (a_2 b_3 - a_3 b_2) \vec{e}_1 \\ (a_3 b_1 - a_1 b_3) \vec{e}_2 \\ (a_1 b_2 - a_2 b_1) \vec{e}_3 \end{pmatrix}$$