

Lecture 4

summarize duality for LP

$$\begin{aligned}
 (P) \quad \min c^T x & \equiv \min f_0(x) \equiv c^T x \\
 \text{s.t. } Ax &= b \\
 x &\geq 0 \\
 & \text{("standard form")}
 \end{aligned}
 \quad \equiv \quad
 \begin{aligned}
 \min f_0(x) &\equiv c^T x \\
 \text{s.t. } f_1(x) &\equiv -x \leq 0 \\
 h(x) &\equiv Ax - b = 0
 \end{aligned}$$

$$\begin{aligned}
 \text{Lagrangian: } L(x, \lambda, \nu) &= c^T x - \lambda^T x + \nu^T (Ax - b) \\
 &= x^T (c - \lambda + A^T \nu) - \nu^T b
 \end{aligned}$$

$$\text{LDP} \equiv g(\lambda, \nu) = \inf_x L(x, \lambda, \nu) = \begin{cases} -\nu^T b & \text{if } c - \lambda + A^T \nu \leq 0 \\ -\infty & \text{otherwise} \end{cases}$$

LDP

$$\begin{aligned}
 & \sup_{\lambda \geq 0} g(\lambda, \nu)
 \end{aligned}$$

NOTE

$$\equiv \max b^T y \quad (\text{change } y = -\nu)$$

$$\text{s.t. } A^T y + \lambda = c$$

$$\lambda \geq 0$$

"dual slack variable" in LP parlance

$$\begin{aligned}
 (D) \quad & \equiv \max b^T y \\
 & \text{s.t. } A^T y \leq c
 \end{aligned}$$

What is the dual of the dual? Next page.

Apply same argument to (D): easier to use the version w/o slack variable λ .

$$(\tilde{D}) \equiv (D) \max b^T y \quad \equiv \min -b^T y \\ \text{s.t. } A^T y \leq c \quad \text{s.t. } A^T y - c \leq 0$$

Lagrangian $\tilde{L}(y, \pi) = -b^T y + \pi^T (A^T y - c)$
 playing role of x \nearrow playing role of λ (no v) $= y^T (-b + A\pi) - \pi^T c$

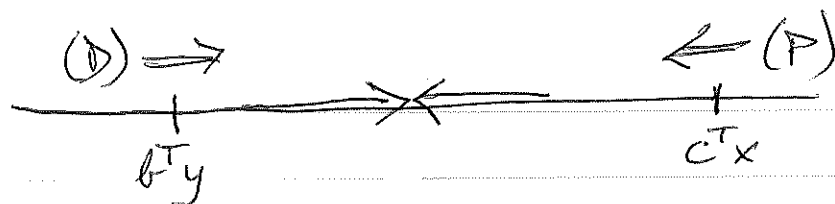
$$\text{LDF} \quad \tilde{g}(\pi) = \inf_y \tilde{L}(y, \pi) = \begin{cases} -\pi^T c & \text{if } A\pi = b \\ -\infty & \text{otherwise} \end{cases}$$

$$\text{LDE} \quad \sup \tilde{g}(\pi) = \min_{\pi \geq 0} -c^T \pi \\ \text{s.t. } A\pi = b$$

NOTE \rightarrow

$$\pi \geq 0$$

Exactly (D)!



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For feasible x, y we have

$$b^T y = (Ax)^T y = x^T (A^T y) \leq x^T c = c^T x$$

↑
WEAK DUALITY.

Strong duality holds for LP without Slater assumption (relies on SHP thm / Farkas lemma). It says we always have $d^* = p^*$ unless both (P), (D) are infeasible: then $d^* = -\infty, p^* = \infty$.

Could have $d^* = p^* = -\infty$ (primal unbounded, dual infeasible)
or $d^* = p^* = \infty$ (dual unbounded, primal infeasible)

Otherwise $\exists x^*, y^*$ with zero duality gap: $b^T y^* = c^T x^*$

So, letting $\lambda^* = c - A^T y^*$ "dual slack"

$$\text{we have } (x^*)^T \lambda^* = 0$$

Since $x^* \geq 0, \lambda^* \geq 0$ this implies complementarity:

$\forall j \in \{1, \dots, n\}$ either $x_j^* = 0$ or $\lambda_j^* = 0$ (or both).

↑
"active constraint"

↑
"inactive constraint" (or degenerate)

Goldman-Tucker theorem for LP:

$\exists x^*, \lambda^*$ with STRICT COMPLEMENTARITY:

not both $x_j^* = \lambda_j^* = 0$

$$\text{LDP} \quad d^* = \sup_{\Lambda, v \succeq_{K^*} 0} g(\Lambda, v) \leq p^* \quad (\text{weak duality})$$

If f_0 is convex, F_i are K -convex, and $h(x) = Ax - b$,

$$F_i(\theta x + (1-\theta)y) \leq_K \theta F_i(x) + (1-\theta)F_i(y)$$

+ Slater cond holds, i.e. $\exists \tilde{x}$ (interior D) with

$$F_i(\tilde{x}) \prec_{K^*} 0, \quad A\tilde{x} = b$$

then strong duality holds: $d^* = p^*$.

Example SDP in primal standard form.

$$(P) \quad \inf \langle C, X \rangle \quad \text{tr } CX = \sum_{i,j} C_{ij} X_{ij}$$

$$\text{s.t. } \langle A_i, X \rangle = b_i \quad i=1, \dots, p$$

$$X \in S^n$$

$$X \succeq 0$$

JUST ONE LINE

$$v^T X v \geq 0 \quad \forall v.$$

PSD.

$$L(X, \Lambda, v)$$

$$g(\Lambda, v)$$

$$\langle C, X \rangle$$

$$=$$

$$\langle \Lambda, X \rangle$$

$$+ \sum_{i=1}^p v_i$$

$$\langle A_i, X \rangle - b_i$$

$$\rightarrow$$

$$\inf_X \langle C - \Lambda, X \rangle + \sum_{i=1}^p v_i \langle A_i, X \rangle - \sum_{i=1}^p v_i b_i$$

$$= \begin{cases} -v^T b & \text{if } \left(\sum_{i=1}^p v_i A_i = \Lambda - C \right) \\ -\infty & \text{otherwise} \end{cases}$$

$$\text{LDP is } d^* = \sup_{\Lambda, y} g(\Lambda, y)$$

$\Lambda \succeq 0$
(PSD, as $K=K^*$ for semidefinite cone)
 $y = -v$

$$(D) \equiv \sup_{\Lambda, y} b^T y$$

s.t. $\left(\sum_{i=1}^p y_i A_i \right) + \Lambda = C$

$\Lambda \succeq 0$ ↑ "SLACK MATRIX"
↑ PSD

Just as in LP, C in primal obj \leftrightarrow dual constr.
 b " " constr. \leftrightarrow dual obj.

Version without slack matrix:

$$\sup_y b^T y$$

s.t. $\sum_{i=1}^p y_i A_i \preceq C$

(means $C - \sum y_i A_i \succeq 0$).

As in LP, let's take dual of dual.

$$\text{Lagrangian } \tilde{L}(y, \pi) = -b^T y + \langle \pi, \sum_{i=1}^p y_i A_i - C \rangle$$

(no v)

$$\text{LDF } \tilde{g}(\pi) = \inf_y \tilde{L}(y, \pi) = \begin{cases} -\langle C, \pi \rangle & \text{if } \langle A_i, \pi \rangle = b_i \quad i=1, \dots, p \\ -\infty & \text{otherwise.} \end{cases}$$

$$\text{LDP } \sup_{\pi \succeq 0} g(\pi) \equiv \inf_{\pi} \langle C, \pi \rangle$$

s.t. $\langle A_i, \pi \rangle = b_i \quad i=1, \dots, p$
 EXACTLY (P)!! $\pi \succeq 0$

As with LP $\Rightarrow (D)$ $\Leftarrow (P)$

$$f^T y = \sum_{i=1}^n \langle A_i, X \rangle y_i = \left\langle \sum_{i=1}^{C-1} y_i A_i, X \right\rangle = \langle C, X \rangle - \langle X, \Lambda \rangle$$

What is sign of $\langle X, \Lambda \rangle = \text{tr} X \Lambda$ We know $X \succeq 0, \Lambda \succeq 0$ $(Q^T Q = I) (D \text{ diagonal})$ Let $X = M^2$ (sym sq. root: if $X = Q D Q^T$ ($D \succeq 0$))
then $M = Q D^{1/2} Q^T$

$$\langle X, \Lambda \rangle = \text{tr} X \Lambda = \text{tr} M \Lambda M$$

$$= \text{tr} \underbrace{M \Lambda M}_{\geq 0} \geq 0$$

so $f^T y \leq \langle C, X \rangle$ when X, y feasible
weak duality.DOES NOT
ALWAYS HOLD \rightarrow Strong duality says $d^* = p^*$, so assuming these
are both attained, $\exists X^*, y^*, \Lambda^*$ s.t. $f^T y^* = \langle C, X^* \rangle$
i.e. $\langle X^*, \Lambda^* \rangle = 0$.

$$\text{Let } X^* = M^2, \Lambda^* = P^2 \quad M = M^T \quad P = P^T$$

$$\langle X^*, \Lambda^* \rangle = \langle M^2, P^2 \rangle = \text{tr} M P P = \text{tr} (M P) (P M)$$

$$= \|P M\|_F^2 = 0$$

$$\text{so } P M = 0 = M P$$

$$\text{so } X^* \Lambda^* = M P P = 0 = \Lambda^* X^*$$

so X^*, Λ^* share common system of eig-vectors

$$\exists Q \text{ s.t. } Q^T Q = I$$

$$\text{with } Q^T X^* Q = D = \begin{bmatrix} d_1 & & \\ & \ddots & \\ & & d_n \end{bmatrix}, \quad Q^T \Lambda^* Q = \begin{bmatrix} e_1 & & \\ & \ddots & \\ & & e_n \end{bmatrix}$$

 $\forall j \in [1, n]: d_j = 0 \text{ or } e_j = 0 \text{ or both}$

(eigenvalue complementarity).

MORE GENERALLY

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The KKT Equations + Complementary Slackness

Suppose that P & D optimal values are attained + equal (so strong duality holds),
(BV p. 242).

for the convex program

$$\begin{array}{ll} \min_{x \in D} f_0(x) & \text{s.t. } f(x) \leq 0 \quad f = \begin{bmatrix} f_1 \\ \vdots \\ f_m \end{bmatrix} \text{ all convex} \\ & Ax = b \quad \text{affine equality const.} \end{array}$$

Then $\exists x^*, \lambda^*, v^*$ s.t. $\lambda^* \geq 0, f(x^*) \leq 0$ &

$$\begin{aligned} f_0(x^*) &= g(\lambda^*, v^*) \\ &\stackrel{\text{No}^*}{\downarrow} \equiv \inf_x (f_0(x) + \sum_{i=1}^m \underbrace{\lambda_i^*}_{\geq 0} \underbrace{f_i(x)}_{\leq 0} + (v^*)^T (Ax - b)) \\ &\quad \text{(by defn of the dual problem)} \\ &\leq f_0(x^*) + \sum_{i=1}^m \underbrace{\lambda_i^*}_{\geq 0} \underbrace{f_i(x^*)}_{\leq 0} + (v^*)^T \underbrace{(Ax^* - b)}_0 \\ &\leq f_0(x^*). \end{aligned}$$

i.e. "that is" $\lambda_i^* f_i(x^*) = 0 \quad i=1, \dots, m$
COMPLEMENTARITY.

Nonzero Lagrange multipliers must correspond to "ACTIVE" constraints.

"Inactive" constraint must correspond to zero Lagrange multipliers.

But STRICT COMP does not necessarily hold.
IT DOES FOR LP.

Suppose f, f_i are all differentiable as well as convex. Then since x^* minimize $L(x, \lambda^*, \nu^*)$ over x , we have:

$$(KKT): 0 = \nabla f_0(x^*) + \left(\sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) \right) + A^T \nu^*$$

History: Lagrange for equality constraints only

Karush 1939: unpublished Master's thesis!

Fritz John 1948 (with the "Fritz John" multiplier for f_0)

Kuhn + Tucker 1951.

We see that (KKT) along with feasibility
 $(f_i(x^*) \leq 0, Ax^* = b, \lambda^* \geq 0)$

and complementarity: $\lambda_i^* f_i(x^*) = 0$ (or $d^* = p^*$)
 shows primal & dual optimality.

KKT also extends to nonconvex case too (BV, p. 243) but in this case they are only NECESSARY condition for optimality, not sufficient

(e.g., unconstrained case: $\min f_0(x) = x^3$
 $\nabla f_0(x) = 0 \not\Rightarrow x$ is optimal).

Saddle Point Interpretation. Assume for simplicity there are no equality constraints.

$$\begin{aligned} \text{Note } \sup_{\lambda \geq 0} L(x, \lambda) &= \sup_{\lambda \geq 0} f_0(x) + \lambda^T f(x) \\ &= \begin{cases} f_0(x) & \text{if } f(x) \leq 0 \\ \infty & \text{otherwise.} \end{cases} \quad (f_i(x) \leq 0, i=1, \dots, m) \end{aligned}$$

$$\text{Thus } p^* = \inf_{x \in D} \sup_{\lambda \geq 0} L(x, \lambda).$$

while by def'n

$$d^* = \sup_{\lambda \geq 0} \inf_{x \in D} L(x, \lambda).$$

Weak Duality: ~~p~~ $d^* \leq p^*$

does not actually depend on properties of L ,
we have

$$(*) \quad \sup_{z \in Z} \inf_{w \in W} h(w, z) \leq \inf_{w \in W} \sup_{z \in Z} h(w, z)$$

for any function $h: \mathbb{R}^m \times \mathbb{R}^m \rightarrow \mathbb{R}$, and any $W \subseteq \mathbb{R}^m$,
 $Z \subseteq \mathbb{R}^m$ (as long as not both W and Z are empty!)

Pf (from RTR'70) (also see ex. 5.24)

$$\text{Let } H(z) = \inf_{w \in W} h(w, z)$$

$$\text{and } \alpha = \sup_{z \in Z} H(z) \quad (\text{LHS of } (*))$$

For all $w \in W$, we have

$$\{ h(w, z) \geq H(z) \quad \forall z \in Z \}$$

so

$$\{ \sup_{z \in Z} h(w, z) \geq \sup_{z \in Z} H(z) = \alpha. \}$$

continued on next page

(Pf that $\sup \inf \leq \inf \sup$, cont'd)

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This is true for all $w \in W$, so

$$\text{of } (*) \quad \text{RHS} = \inf_{w \in W} \sup_{z \in Z} h(w, z) \geq \alpha.$$

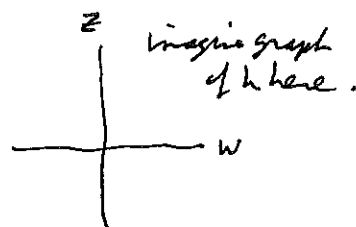
(easy proof once you see it!).

The biggest gap between LHS & RHS:

$$\text{let } W = Z = \mathbb{R}, \quad h(w, z) = -w^2 + z^2.$$

concave in w , convex in z

then LHS = $-\infty$, RHS = ∞ .



Strong duality (LHS = RHS) occurs in the opposite case: when h is CONVEX in w and CONCAVE in z .

$$\text{e.g. } h(w, z) = w^2 - z^2$$

then LHS = RHS = 0.

GAME INTERPRETATION (goes back to Morgenstern & Von Neumann)

choiced $w = \text{Player 1}$, $z = \text{Player 2}$ (wants to $\sup h$).

In general, Player 1 wants Player 2 to "go first" (FIX z)

~~so~~ so he can take account of ~~his~~ ^{her} choice. ~~His choice~~

* But if strong duality holds, he knows that Player 2 will choose the z that maximizes the best that Player 1 can do (LHS).