

EDUARDO DE JESÚS DÁVILA MEZA, PH.D.

AI/ML • Computer Vision • Embedded Systems • ROS/ROS2

Engineer • Researcher • Educator

✉ eduardodavila94@hotmail.com • ☎ +52 33 2969 2743 • 📁 Professional Portfolio • 🌐 [EduardoDavila-AI](#) • 🐼 [eDavila-DrRaccoon](#) • 🎓 Federal Professional Certificates: Bachelor's Degree: 12027207 • Master's Degree: 14043743 • Ph.D. Degree: 15067339

TECHNICAL SKILLS

Operating Systems: Linux (Ubuntu), Windows
Programming Languages: Python, C++, SQL, MATLAB, MPLAB (XC8), Arduino
Libraries and Frameworks:
C++ and Python: OpenCV, TensorFlow, ROS & ROS 2
Python: FastAPI, JSON, Keras, Matplotlib, NumPy, Pandas, PIL, Scikit-learn, Seaborn, SQLAlchemy, Tkinter
Development Tools: VS Code, Jupyter Notebook, Git, GitHub, GitLab
Embedded System Tools: SOLIDWORKS, PROTEUS, LabVIEW
Document Preparation and Office Tools: LaTeX, Markdown, MS Office, Dia (diagram editor)

SOFT SKILLS

- Self-taught
- Goal-oriented
- Proactive
- Teamwork
- Communication
- Positive attitude
- Responsible
- Customer Support

LANGUAGES

Spanish | Native: full professional proficiency.
English | Advanced B2: professional working proficiency. Fluent in reading, writing, and technical comprehension; intermediate spoken; proficient for research publications, documentation, and international collaboration. Certified by Cinvestav, Guadalajara Campus, February 2023.

WORK EXPERIENCE & PROJECTS

Geovoy, Busmen Group

Mathematical Analyst in Information Technologies

Applying advanced mathematical and ML methods for data analysis, predictive modeling, and algorithm design to enhance decision-making and technological efficiency. Collaborating with development teams to integrate models into software solutions, primarily for geolocation applications and inventory management.

💎 Python • SQLAlchemy • FastAPI • Data analysis & cleaning • Time series & LSTM for route optimization • API-powered LLM for reporting

September 2025 – Present

Tlajomulco de Zúñiga, Jalisco

Tecnológico de Monterrey (ITESM), Guadalajara

Professor – ROS/ROS2 & Python

Led courses on ROS/ROS2 (Robot Operating System) with Python and C++ for differential drive robots, as well as a course on Python fundamentals. Recognized as a top-rated professor (See recognition [🔗](#)). See repository [🔗](#).

💎 Python • C++ • ROS/ROS2 • Code debugging • Computer science • Software development • Technical instruction

April 2024 – September 2025

Zapopan, Jalisco

Recognition of Fundus Pathologies — Medical Image Segmentation

AI/ML Engineer

Collaborated with German eye hospitals to develop a Mask R-CNN model aimed at identifying fundus pathologies in medical images, managing the complete AI/ML lifecycle, from data preprocessing and augmentation to model training and validation.

💎 AI/ML • Computer vision / Image processing • Mask R-CNN • TensorFlow-Keras • Data labeling, augmentation, and visualization

May 2021 – July 2024

Zapopan, Jalisco

Intelligent Visual Guide System (OJO SMART) — Modular Navigation Device

Computer Vision & ROS Developer

Built ROS nodes for real-time recognition of colors, objects, signs, banknotes, and text, integrating them into a modular visual navigation device designed to support users with visual impairments.

💎 Computer vision / Image processing • Python • C++ • ROS • Tesseract OCR • OpenCV • TensorFlow

December 2019 – October 2023

Zapopan, Jalisco

[Full List](#) [🔗](#)

PUBLICATIONS & PATENTS

Meeting Abstract | **June 2024** | “Deep-learning based quantification of RPE65-mutation inherited retinal degeneration”, presented at *Investigative Ophthalmology & Visual Science*, vol. 65(7), 1392, **i** ID: 2794864 [🔗](#).

💎 AI/ML lifecycle • Computer vision / Medical image analysis • Data visualization • Mask R-CNN • Feature extraction • Research

Journal Article | **September 2023** | “Quaternion and Split Quaternion Neural Networks for Low-Light Color Image Enhancement”, in *IEEE Access*, vol. 11, 108257-108280, **doi** 10.1109/ACCESS.2023.3312234 [🔗](#).

💎 AI/ANN lifecycle • Computer vision / Image color analysis • Quaternion algebras • Color spaces • EKF

Patent | **March 2017** | “Device for controlling underactuated two-link systems with one actuator”, filed under the Invention Support Program, University of Guadalajara. Application no. MX/a/2017/016436.

💎 Embedded systems • Control theory • Digital and power electronics • PICs • SPI & I2C communication protocols

ACADEMIC DEGREES

Ph.D. in Electrical Engineering — AI/ML | Cinvestav, Guadalajara

September 2019 – May 2024

Thesis | Deep learning for recognition and quantification of fundus pathologies using instance segmentation, and quaternion neural networks for low-light image enhancement.

💎 AI/ML lifecycle • Computer vision / Image analysis • CNN/NN • Robotics • Research • Science Communication

M.Sc. in Electrical Engineering — AI/ANNs | Cinvestav, Guadalajara

September 2017 – August 2019

Thesis | Quaternion neural networks for low-light image enhancement, and identification of an electromechanical system.

💎 AI/ANNs • Computer vision • Linear algebra • Control theory • Robotics • Probability & statistics • Research • SciComm

B.Eng. in Mechatronics — Embedded Systems | University of Guadalajara

August 2012 – December 2016

Social service & Professional Internship | Assistance and development of electronic and mechatronic projects in the electronics and telecommunications laboratory.

💎 Embedded systems • Linear algebra • Calculus • Control theory • Digital and power electronics • HMI • PICs & Arduino

CERTIFICATIONS

AI/DL [🔗](#)
Python [🔗](#)

AI/ML [🔗](#)
R for DS [🔗](#)

Data Cleaning [🔗](#)
ROS [🔗](#)

LLMs [🔗](#)
Scikit-learn [🔗](#)

NLP [🔗](#)
SQL [🔗](#)

OpenCV [🔗](#)
TF-Keras [🔗](#)

Pandas [🔗](#)
Full list [🔗](#)